```
Atividade 03
        Com base no código de Image Retrieval apresentado durante a aula, modifique o código para que a imagem seja representada com os keypoints definidos em grid ao invés de usar detector de keypoints.
         1. Use a função da última atividade prática para definir kepoints em grid e keypoints de forma aleatória.
         2. Execute o código e calcule a acurácia média.
         3. Compare a acurácia média com a acurácia média do código apresentado durante a aula.
          4. Escreva uma pequena discussão (máximo 5 linhas) explicado o resultado encontrado.
         5. Use a partição de validação para encontrar o melhor tamanho do grid através do teste do cotovelo.
 In [1]: pip install -U scikit-learn & pip install tqdm
         Requirement already satisfied: tqdm in /home/luisa/Documents/faculdade/optativas/inf 492/inf492/lib/python3.10/site-packages (4.65.0)
         Requirement already satisfied: scikit-learn in /home/luisa/Documents/faculdade/optativas/inf 492/inf492/lib/python3.10/site-packages (1.2.2)
         Requirement already satisfied: joblib>=1.1.1 in /home/luisa/Documents/faculdade/optativas/inf 492/inf492/lib/python3.10/site-packages (from scikit-learn) (1.2.0)
         Requirement already satisfied: scipy>=1.3.2 in /home/luisa/Documents/faculdade/optativas/inf 492/inf492/lib/python3.10/site-packages (from scikit-learn) (1.10.1)
        Requirement already satisfied: numpy>=1.17.3 in /home/luisa/Documents/faculdade/optativas/inf 492/inf492/lib/python3.10/site-packages (from scikit-learn) (1.24.2)
        Requirement already satisfied: threadpoolctl>=2.0.0 in /home/luisa/Documents/faculdade/optativas/inf 492/inf492/lib/python3.10/site-packages (from scikit-learn) (3.1.0)
        Note: you may need to restart the kernel to use updated packages.
        Functions for random and grid-based keypoint detection
        Used in last activity
 In [2]: import random
         import cv2 as cv
         def random_keypoints(image, number_keypoints):
            keypoints =[]
            height, width = image.shape
            for i in range(number_keypoints):
                keypoint = cv.KeyPoint()
                h = random.randint(0, height - 1)
                w = random.randint(0, width - 1)
                keypoint.pt = (h,w)
                keypoint.size = 40
                keypoints.append(keypoint)
            return keypoints
         def grid_keypoints(image, grid_size):
            keypoints = []
            height, width = image.shape
            keypoints = []
            for i in range(width):
                if(i%grid_size == 0):
                    for j in range(height): #(0,0), (0,grid_size), ..., (grid_size,0), (grid_size,grid_size), ...
                        if(j % grid_size == 0):
                            keypoint = cv.KeyPoint()
                            keypoint.pt = (i, j)
                            keypoint.size = grid_size/2
                            keypoints.append(keypoint)
            return keypoints
        Code used in class with modifications
 In [3]: %matplotlib inline
         import matplotlib.pyplot as plt
         import cv2
        import numpy as np
        from tqdm import trange
         import random
        Image Display
 In [4]: def show_image_and_keypoints( image , kps ) :
            cv2.drawKeypoints( image, kps, image, flags=cv2.DRAW_MATCHES_FLAGS_DRAW_RICH_KEYPOINTS )
            plt.figure(figsize = (10,10))
            plt.imshow(image, aspect='auto')
            plt.axis('off')
            plt.title('Keypoints and descriptors.')
            plt.show()
In [5]: def show_top_images ( dataset_path, indices , id_test , ids , labels ) :
            label = (ids[id\_test] - 1) // 80
            name = dataset_path + '/jpg/' + str(label) + '/image_' + str(ids[id_test]).zfill(4) + '.jpg'
            image = cv2.imread( name )
            image = cv2.cvtColor( image , cv2.COLOR_BGR2RGB )
            show_image_label(top, image, labels[id_test], ids[id_test] )
            accuracy = 0
            for i in indices[0]
                label_i = labels[i]
                name = dataset_path + '/jpg/' + str(label_i) + '/image_' + str(ids[i]).zfill(4) + '.jpg'
                image = cv2.imread( name )
                image = cv2.cvtColor( image , cv2.COLOR_BGR2RGB )
                show_image_label(top, image, label_i, ids[i] )
                top = top + 1
         def show_image_label ( top, image, label , image_id ) :
            plt.figure(figsize = (5,5))
            plt.imshow(image, aspect='auto')
            plt.axis('off')
            plt.title(f'{top} - Image id {image_id} with label {label}.')
            plt.show()
        Generate descriptors
In [6]: def detect_and_describe_keypoints ( image, algorithm_descriptor='orb', algorithm_detector='orb', grid_size=15)
            image_gray = cv2.cvtColor( image , cv2.COLOR_BGR2GRAY )
            if algorithm_descriptor == 'sift' :
                keypoint = sift = cv2.xfeatures2d.SIFT_create()
            elif algorithm_descriptor == 'orb' :
                keypoint = cv2.0RB_create()
            #adding random and grid algorithms
            if algorithm_detector == 'sift' or algorithm_detector == 'orb':
               kps = keypoint.detect( image_gray, None )
            elif algorithm_detector == 'random':
               kps = random_keypoints(image_gray, 300)
            elif algorithm_detector == 'grid':
               kps = grid_keypoints(image_gray, grid_size)
                print('Error: algorithm not defined')
                return None
            # Describing Keypoints
            kps, descs = keypoint.compute( image_gray, kps )
            return kps, descs
In [7]: def create_bovw_descriptors (image, dictionary, algorithm_descriptor='orb', algorithm_detector='orb', grid_size=15) :
            descs = detect_and_describe_keypoints( image, algorithm_descriptor, algorithm_detector, grid_size)[1]
            predicted = dictionary.predict(np.array(descs, dtype=np.double))
            desc_bovw = np.histogram(predicted, bins=range(0, dictionary.n_clusters+1))[0]
            return desc_bovw
        Dictionary
 In [8]: from sklearn.cluster import MiniBatchKMeans
        # from sklearn.cluster import KMeans
         def create_dictionary_kmeans ( vocabulary , num_cluster ) :
            print( ' -> [I] Dictionary Info:\n',
                '\nTrain len: ', len(vocabulary),
                '\nDimension: ', len(vocabulary[0]),
                '\nClusters: ', num_cluster
             dictionary = KMeans( n_clusters=num_cluster )
            dictionary = MiniBatchKMeans( n_clusters=num_cluster, batch_size=1000)
            print ( 'Learning dictionary by Kmeans...')
            dictionary = dictionary.fit( vocabulary )
            print ( 'Done.')
            return dictionary
        Data
In [9]: import scipy.io
         def create_vocabulary ( dataset_path , algorithm_descriptor='orb', algorithm_detector='orb', grid_size=15,
                               show_image=False , debug=False ) :
            mat = scipy.io.loadmat( dataset_path+'/datasplits.mat' )
            ids = mat['trn1'][0] # 'val1' or 'tst1'
            if algorithm_descriptor == 'orb' :
               train_descs = np.ndarray( shape=(0,32) , dtype=float )
            elif algorithm_descriptor == 'sift':
               train_descs = np.ndarray( shape=(0,128) , dtype=float )
               print('Error:Algorithm not defined.')
                return None
            for id in tqdm.tqdm(ids, desc='Processing train set') :
                label = (id - 1) // 80
                name = dataset_path + '/jpg/' + str(label) + '/image_' + str(id).zfill(4) + '.jpg'
                image = cv2.imread( name )
                if image is None:
                   print(f'Reading image Error. Path: {name}')
                    return None
                kps, descs = detect_and_describe_keypoints ( image, algorithm_descriptor, algorithm_detector, grid_size )
                train_descs = np.concatenate((train_descs, descs), axis=0)
                if show_image :
                    show_image_and_keypoints(image, kps)
                if debug :
                    print( name )
                    print( 'Number of keypoints: ', len(kps) )
                    print( 'Number of images: ', len(ids) )
                    print( 'Descriptor size: ', len(descs[0]) )
                    print( type(descs[0]) )
            print( ' -> [I] Image Loader Info:\n',
              '\nTrain len: ', len(train_descs),
              '\nNumber of images: ', len(ids),
               '\nDescriptor size: ', len(descs[0])
            return train_descs
In [10]: def represent_dataset( dataset_path, dictionary , algorithm_descriptor='orb', algorithm_detector='orb', ids='tst1'
                            , grid_size=15 ) :
            mat = scipy.io.loadmat( dataset_path+'/datasplits.mat' )
            ids = mat[ids][0] # 'trn1' or 'val1'
            space = []
            labels = []
            for id in tqdm.tqdm(ids, desc='Processing train set') :
                label = (id - 1) // 80
                name = dataset_path + '/jpg/' + str(label) + '/image_' + str(id).zfill(4) + '.jpg'
                image = cv2.imread( name )
                desc_bovw = create_bovw_descriptors(image, dictionary, algorithm_descriptor, algorithm_detector, grid_size)
                space.append(desc_bovw)
                labels.append(label)
            print( ' -> [I] Space Describing Info:\n',
                '\nNumber of images: ', len(space),
                '\nNumber of labels: ', len(labels),
                '\nDimension: ', len(space[0])
            return space , labels
        Experimental evaluation
In [11]: from sklearn.neighbors import NearestNeighbors
         def run_test ( space , labels , dictionary , dataset_path,algorithm_descriptor='orb', algorithm_detector='orb',ids='tst1',
                      grid_size=15, top=10 ) :
            knn = NearestNeighbors(n_neighbors=top+1).fit(space)
            mat = scipy.io.loadmat( dataset_path+'/datasplits.mat' )
            ids = mat[ids][0] # 'trn1' or 'val1'
            accuracy_t = 0
            for id_test in tqdm.tqdm(ids, desc='running the test phase') :
                label = (id_test - 1) // 80
                name = dataset_path + '/jpg/' + str(label) + '/image_' + str(id_test).zfill(4) + '.jpg'
                image = cv2.imread( name )
                desc_bovw = create_bovw_descriptors(image, dictionary, algorithm_descriptor, algorithm_detector, grid_size)
                indices = knn.kneighbors(desc_bovw.reshape(1, -1))[1]
                labels_top = [ labels[i] for i in indices[0] ]
                accuracy = sum( np.equal(labels_top, label) )
                accuracy = ((accuracy-1)/(top)) * 100
                accuracy_t = accuracy_t + accuracy
            print(f'Average accuracy in the test set: {accuracy_t/len(ids):5.2f}%')
In [12]: def retrieve_single_image ( space , labels , dictionary , dataset_path, algorithm_descriptor='orb', algorithm_detector='orb',
                                  grid\_size = 15 , top=10 ) :
            knn = NearestNeighbors(n_neighbors=top+1).fit(space)
            mat = scipy.io.loadmat( dataset_path+'/datasplits.mat' )
            ids = mat['tst1'][0] # 'trn1' or 'val1'
            id_test = random.randrange( len(ids) )
            label = (ids[id\_test] - 1) // 80
            name = dataset_path + '/jpg/' + str(label) + '/image_' + str(ids[id_test]).zfill(4) + '.jpg'
            image = cv2.imread( name )
            desc_bovw = create_bovw_descriptors(image, dictionary, algorithm_descriptor, algorithm_detector, grid_size)
            distances, indices = knn.kneighbors(desc_bovw.reshape(1, -1))
            show_top_images(dataset_path, indices, id_test, ids, labels)
            labels_top = [ labels[i] for i in indices[0] ]
            accuracy = sum( np.equal( label , labels_top ) )
            accuracy = ((accuracy-1)/(top)) * 100
            print(f'Accuracy for image id {ids[id_test]}: {accuracy:5.2f}%')
            print(f'Image: {ids[id_test]} with label {labels[id_test]}')
            print(f'Closest image: {ids[indices[0][0]]} with distance {distances[0][0]} and label {labels[indices[0][0]]}')
            print('Distances: ', distances)
            print('Indices: ',indices)
            print('Labels: ',labels_top)
         Execution ORB detector and SIFT detector(during class)
In [13]: dataset_path = 'flowers_classes'
        algorithm_descriptor = 'sift'
         algorithm_detector = 'sift'
        vocabulary = create_vocabulary( dataset_path, algorithm_descriptor, algorithm_detector )
                                                                                                                                                                                                                                                            | 0/680 [00:00<?, ?it/s][ WARN:0@16.414] global shadow_sift.hpp:13 SIFT_create DEPRECATED: cv.xfeatures2d.SIFT_create() is deprecated due SIFT tra
        Processing train set: 0%|
        nfer to the main repository. https://github.com/opencv/opencv/issues/16736
                                                                                                                                                                                                                                             | 680/680 [01:58<00:00, 5.76it/s]
        Processing train set: 100%
         -> [I] Image Loader Info:
        Train len: 1233814
        Number of images: 680
        Descriptor size: 128
In [14]: num_clusters = 100
        dictionary = create_dictionary_kmeans( vocabulary , num_clusters )
        space, labels = represent_dataset ( dataset_path , dictionary, algorithm_descriptor, algorithm_detector,ids='tst1' )
        run_test ( space , labels , dictionary , dataset_path, algorithm_descriptor, algorithm_detector, ids='tst1')
         -> [I] Dictionary Info:
        Train len: 1233814
        Dimension: 128
        Clusters: 100
        Learning dictionary by Kmeans...
         /home/luisa/Documents/faculdade/optativas/inf 492/inf492/lib/python3.10/site-packages/sklearn/cluster/_kmeans.py:870: FutureWarning: The default value of `n_init` will change from 3 to 'auto' in 1.4. Set the value of `n_init` explicitly to suppress the warning
          warnings.warn(
         Processing train set: 100%|
         -> [I] Space Describing Info:
         Number of images: 340
        Number of labels: 340
        Dimension: 100
                                                                                                                                                                                                                                             | 340/340 [00:49<00:00, 6.86it/s]
        running the test phase: 100%
        Average accuracy in the test set: 21.09%
In [15]: dataset_path = 'flowers_classes'
        algorithm_descriptor = 'orb'
        algorithm_detector = 'orb'
        vocabulary = create_vocabulary( dataset_path, algorithm_descriptor, algorithm_detector )
        Processing train set: 100%|
         -> [I] Image Loader Info:
        Train len: 333473
        Number of images: 680
        Descriptor size: 32
In [16]: num_clusters = 100
        dictionary = create_dictionary_kmeans( vocabulary , num_clusters )
        space, labels = represent_dataset ( dataset_path , dictionary, algorithm_descriptor, algorithm_detector,ids='tst1' )
        run_test ( space , labels , dictionary , dataset_path, algorithm_descriptor, algorithm_detector, ids='tst1')
         -> [I] Dictionary Info:
        Train len: 333473
        Dimension: 32
        Clusters: 100
        Learning dictionary by Kmeans..
         /home/luisa/Documents/faculdade/optativas/inf 492/inf492/lib/python3.10/site-packages/sklearn/cluster/_kmeans.py:870: FutureWarning: The default value of `n_init` will change from 3 to 'auto' in 1.4. Set the value of `n_init` explicitly to suppress the warning
          warnings.warn(
                                                                                                                                                                                                                                               340/340 [00:03<00:00, 86.51it/s]
        Processing train set: 100%|
         -> [I] Space Describing Info:
         Number of images: 340
         Number of labels: 340
        Dimension: 100
                                                                                                                                                                                                                                             | 340/340 [00:22<00:00, 14.97it/s]
        running the test phase: 100%|
        Average accuracy in the test set: 17.00%
        Execution with random detector
         Selected 300 random keypoints for each image, like in short activity 2
In [17]: dataset_path = 'flowers_classes'
        algorithm_descriptor = 'orb'
        algorithm_detector = 'random'
        vocabulary = create_vocabulary( dataset_path, algorithm_descriptor, algorithm_detector )
                                                                                                                                                                                                                                               680/680 [00:04<00:00, 165.97it/s]
        Processing train set: 100%
         -> [I] Image Loader Info:
        Train len: 132363
        Number of images: 680
        Descriptor size: 32
In [18]: num_clusters = 100
        dictionary = create_dictionary_kmeans( vocabulary , num_clusters )
        space, labels = represent_dataset ( dataset_path , dictionary, algorithm_descriptor, algorithm_detector,ids='tst1' )
        run_test ( space , labels , dictionary , dataset_path, algorithm_descriptor, algorithm_detector, ids='tst1')
         -> [I] Dictionary Info:
        Train len: 132363
        Dimension: 32
        Clusters: 100
        Learning dictionary by Kmeans..
         /home/luisa/Documents/faculdade/optativas/inf 492/inf492/lib/python3.10/site-packages/sklearn/cluster/_kmeans.py:870: FutureWarning: The default value of `n_init` will change from 3 to 'auto' in 1.4. Set the value of `n_init` explicitly to suppress the warning
          warnings.warn(
                                                                                                                                                                                                                                               340/340 [00:01<00:00, 211.89it/s]
         Processing train set: 100%|
         -> [I] Space Describing Info:
         Number of images: 340
         Number of labels: 340
        Dimension: 100
                                                                                                                                                                                                                                               | 340/340 [00:07<00:00, 46.91it/s]
        running the test phase: 100%
        Average accuracy in the test set: 3.65%
        Using RANDOM method to detect keypoints and ORB to describe them, with a number of cluster of 100, we were able to achieve an average accuracy of 3.65%
In [19]: dataset_path = 'flowers_classes'
        algorithm_descriptor = 'sift'
        algorithm_detector = 'random'
        vocabulary = create_vocabulary( dataset_path, algorithm_descriptor, algorithm_detector )
        Processing train set: 100%
         -> [I] Image Loader Info:
        Train len: 204000
        Number of images: 680
        Descriptor size: 128
In [20]: num_clusters = 100
        dictionary = create_dictionary_kmeans( vocabulary , num_clusters )
        space, labels = represent_dataset ( dataset_path , dictionary, algorithm_descriptor, algorithm_detector,ids='tst1' )
        run_test ( space , labels , dictionary , dataset_path, algorithm_descriptor, algorithm_detector, ids='tst1')
         -> [I] Dictionary Info:
        Train len: 204000
        Dimension: 128
        Clusters: 100
        Learning dictionary by Kmeans...
         /home/luisa/Documents/faculdade/optativas/inf 492/inf492/lib/python3.10/site-packages/sklearn/cluster/_kmeans.py:870: FutureWarning: The default value of `n_init` will change from 3 to 'auto' in 1.4. Set the value of `n_init` explicitly to suppress the warning
          warnings.warn(
         Processing train set: 100%|
         -> [I] Space Describing Info:
         Number of images: 340
        Number of labels: 340
        Dimension: 100
                                                                                                                                                                                                                                                340/340 [00:31<00:00, 10.95it/s]
        running the test phase: 100%|
        Average accuracy in the test set: 17.15%
        Using RANDOM method to detect keypoints and SIFT to describe them, with a number of cluster of 100, we were able to achieve an average accuracy of 17.15%
        Execution with grid detector
        Use the validation partition to find the best grid size through the elbow test
        As the grid size increases, the number of detectable keypoints decreases. To perform the elbow test, I experimented with seven different grid sizes.
                                                                                                                                                                                                Grid Size Accuracy
                                                                                                                                                                                                150x150 15.02%
                                                                                                                                                                                                100x100 16.21%
                                                                                                                                                                                                90x90 16.53%
                                                                                                                                                                                                60x60 17.03%
                                                                                                                                                                                                45x45 18.56%
                                                                                                                                                                                                30x30 16.62%
                                                                                                                                                                                                15x15 16.06%
        Based on the results, it is evident that the highest accuracy is achieved with a grid size of 45x45. And, as we move beyond this size, the accuracy starts to decline. Therefore, we can infer that 45x45 is the optimal grid size.
In [21]: dataset_path = 'flowers_classes'
        algorithm_descriptor = 'sift'
        algorithm_detector = 'grid'
        vocabulary = create_vocabulary( dataset_path, algorithm_descriptor, algorithm_detector, grid_size=45 )
                                                                                                                                                                                                                                              | 680/680 [00:16<00:00, 41.12it/s]
        Processing train set: 100%|
         -> [I] Image Loader Info:
        Train len: 119412
        Number of images: 680
        Descriptor size: 128
In [25]: num_clusters = 100
        dictionary = create_dictionary_kmeans( vocabulary , num_clusters )
        space, labels = represent_dataset ( dataset_path , dictionary, algorithm_descriptor, algorithm_detector,
                                          ids='tst1', grid_size=45)
        run_test ( space , labels , dictionary , dataset_path, algorithm_descriptor, algorithm_detector,
                  ids='tst1', grid_size=45)
         -> [I] Dictionary Info:
         Train len: 119412
         Dimension: 128
        Clusters: 100
         Learning dictionary by Kmeans..
         /home/luisa/Documents/faculdade/optativas/inf 492/inf492/lib/python3.10/site-packages/sklearn/cluster/_kmeans.py:870: FutureWarning: The default value of `n_init` will change from 3 to 'auto' in 1.4. Set the value of `n_init` explicitly to suppress the warning
          warnings.warn(
        Processing train set: 100%
                                                                                                                                                                                                                                                | 340/340 [00:05<00:00, 61.48it/s]
         -> [I] Space Describing Info:
         Number of images: 340
         Number of labels: 340
        Dimension: 100
                                                                                                                                                                                                                                               340/340 [00:16<00:00, 20.73it/s]
        running the test phase: 100%|
        Average accuracy in the test set: 18.06%
        Using GRID method to detect keypoints and SIFT to describe them, with a number of cluster of 100 and grid size of 45x45, we were able to achieve an average accuracy of 18.06%
In [26]: dataset_path = 'flowers_classes'
        algorithm_descriptor = 'orb'
        algorithm_detector = 'grid'
        vocabulary = create_vocabulary( dataset_path, algorithm_descriptor, algorithm_detector, grid_size=45 )
                                                                                                                                                                                                                                                680/680 [00:03<00:00, 218.31it/s]
        Processing train set: 100%|
         -> [I] Image Loader Info:
        Train len: 89000
        Number of images: 680
        Descriptor size: 32
In [27]: num_clusters = 100
        dictionary = create_dictionary_kmeans( vocabulary , num_clusters )
        space, labels = represent_dataset ( dataset_path , dictionary, algorithm_descriptor, algorithm_detector,
                                           ids='tst1', grid_size=45)
        run_test ( space , labels , dictionary , dataset_path, algorithm_descriptor, algorithm_detector,
                  ids='tst1', grid_size=45)
         -> [I] Dictionary Info:
        Train len: 89000
        Dimension: 32
```

Clusters: 100

warnings.warn(

Dimension: 100

Learning dictionary by Kmeans...

Processing train set: 100%|
-> [I] Space Describing Info:

running the test phase: 100%

Average accuracy in the test set: 8.12%

Number of images: 340 Number of labels: 340

/home/luisa/Documents/faculdade/optativas/inf 492/inf492/lib/python3.10/site-packages/sklearn/cluster/_kmeans.py:870: FutureWarning: The default value of `n_init` will change from 3 to 'auto' in 1.4. Set the value of `n_init` explicitly to suppress the warning

Using GRID method to detect keypoints and SIFT to describe them, with a number of cluster of 100 and grid size of 45x45, we were able to achieve an average accuracy of 8.12%

| 340/340 [00:01<00:00, 283.31it/s]

340/340 [00:04<00:00, 81.18it/s]

Conclusion

clusion

The accuracy achieved through the SIFT and ORB detectors used in class is significantly higher than that achieved through the random and grid detector methods. This can be attributed to the fact that the latter methods often fail to identify a unique, informative, and unambiguous part of the image as a keypoint. Moreover, the SIFT descriptor consistently outperforms the ORB descriptor with all keypoint detection methods.