# Pràctiques de Programació Conscient de l'Arquitectura Lesson 2: Programming and Optimizing Tools Activities

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### 1

# Tools to Measure

In this lab you will analyze pi.c in all the exercises but the first one, where you will use popul.c. You have to run them without any parameter but be carefull beacuse popul.c prints out binary data. pi.c computes the first 10000 decimals of the  $\pi$  number and writes them in the stardard output. Download lab2\_sessions.tar.gz from the Racó. This file contains the source code of the two programs that you will use in your laboratory 2.

#### 1.1 Accounting Tools

- 1. Check that you have different versions of the time command, running, for instance, time 1s and /usr/bin/time 1s from different shells (bash, csh, tcsh,...).
- 2. I/O and the execution environment may affect the performance of the application. You will test that using popul.c program, compiled with gcc in your FIB account.
  - (a) Run the program and do timing with the GNU time command, redirecting the output to a file in your FIB account: under /home/... and under /dades/... (Note: at the FIB machines, your /home/... account disk is mounted by NFS, and your /dades/... account disk is mounted by CIFS).
  - (b) Repeat the experiment redirecting the output to a file located at /tmp.
  - (c) Do you see any difference? It may be significant and the %CPU may be very small if several runs are done, why? Reason your answer.
- 3. It is time to save the golden output of pi.c program:
  - (a) Compile pi.c program with gcc and O0 optimization level.
  - (b) Run the program doing timing with the GNU time command. Remember to save the output result of the original pi.c program to compare its result to future optimizations of the program in a first run (without timing). Note that you may want to repeat several times the measure in order to be sure that the timing results are similar. In order to explore different execution contexts, do the experiments redirecting the output to NFS, CIFS, Local disk and /dev/null. Is there any big difference in the results? Justify your answer.
  - (c) Keep the information of the timing executions and try to understand the obtained result: what is %CPU?.
  - (d) Which another accounting tool you could use to measure elapsed time that we can indicate it the number of times to execute the program? Which another accounting tool you could use to measure the total number of cpu cycles using the hardware counters, and then cpu time?
- 4. Now, compile the pi.c program using gcc and O0, O1, O2 and O3 optimization level flags
  - (a) Using the best execution context, run and **check** that pi obtained with O0-3 optimization levels obtain the same result.

- (b) Compute the speed-up of user time + system time of the program compiled using O3 compared to the program compiled with O0.
- (c) Compute the speed-up of *elapsed time* of the program compiled using O3 compared to the program compiled with O0.

#### 1.2 Profiling tools

#### 1.2.1 Profiling with gprof and Valgrind

- 5. Compile the pi.c program with gcc, O0 optimization level, gprof profiling option -pg for the gprof experiments, and the debug option (-g), with and without static link (-static). Using gprof and Valgrind answer the following questions. Note: Look at the pid number of the output of valgrind to know which is the callgrind.out.pid file that you should use in callgrind\_annotate or qcachegrind.
  - (a) Which is the most invoked routine (of the program or not) by the program?
  - (b) Which is the most CPU time consuming routine of the program?
  - (c) Which is the most CPU time consuming source code line of the program?
  - (d) Does it appear the system mode execution time in the gprof output? and in the Valgrind output?
- 6. Compile the pi.c program with O3 optimization level and profile the execution using gprof
  - (a) Which differences you can observe looking at the *flat profile* (significant changes on the routine weights, routines that disappear/appear,...)?
  - (b) Do you know why there are those differences? Hints: look at the assembler... using objdump, gcc, etc.

#### 1.2.2 Profiling with oprofile

- 7. Compile your pi.c program using gcc and O0 optimization level and the debug option. Perform two oprofile of the pi.c program varying the counter value that indicates the frequency of the sample of the event to count cpu cycles (look at the output of ophelp command to figure out which is the name of the event and the minimum sampling frequency). Use values 750000 and 100000: frequency is 1/counter. Compare the results obtained with opreport -1.
  - (a) Why do you think that there are those differences in the samples column?
- 8. Compile your pi.c program using gcc and O3 optimization level and the debug option. Perform a oprofile of the pi.c program that indicates the frequency of the sample of the event to count cpu cycles is 1/100000. Compare the results obtained with this profiling to the profiling obtained in previous exercise with the same frequency. Use opreport and opannotate to compare them.
  - (a) What are the main differences? Why?

#### 1.2.3 Profiling with perf

- 9. Compile your pi.c program using gcc and O3 optimization level and the debug option. Perform a perf of the pi.c program at the maximum frequency of sampling allowed for cycles. Compare the results obtained with this profiling to the profiling obtained in previous exercise with the same frequency. Use perf report and annotate. You should see the same kynd of differences than for oprofile.
  - (a) What are the main differences? Why?

#### 1.2.4 Profiling using pin

10. Using pin, indicates the number of instructions executed when compiling pi.c with gcc, using O0 and O3 optimization levels, when obtaining the first 10000 decimals of the  $\pi$  number.

	gcc O0	gcc O3
Total Instructions		
Stack Reads		
Stack Writes		
IDIV + DIV		
IMUL + MUL		

11. Looking at the previous pin output and the profiling and timing information, it is clear that there have been a significant change between the O0 and O3 binary. Previous table provides very interesting information about the possible optimizations that the compiler could do.

#### 1.2.5 Instrumenting with system calls and PAPI

- 12. The pi\_times.c program uses the system call times() in order to show the execution time (decomposed in user mode and system mode) for each call to calculate().
  - (a) Observe the differences between pi.c and pi\_times.c programs and how the system call times() is called. Indicate if the time shown by the program is CPU time or elapsed time. Can the system call times() provide both CPU and elapsed time?
  - (b) Modify pi\_times.c program so that clock\_gettime() system call is used instead of times() system call in order to compute elapsed time. Can clock\_gettime() provide both CPU and elapsed time? Do you have less or more precision compared to "times" results?
  - (c) (if installed at Lab) Modify  $pi\_times.c$  program so that PAPI is used in order to provide total number of cycles of the program PAPI\_TOT\_CYC and the CPU time of calculate function. Note that  $papi\_avail$  provides information about the frequency of the processor. You may have to specify -L and -I information at compile time with the information of the path where the library is installed (if not in the PATH environment variable), in addition to the -lpapi library.

## 1.3 Tracing Tools

#### 1.3.1 strace

- 13. Compute how many system calls are invoqued by the pi.c program. Compute how much time those system calls spend.
- 14. Which information show strace -e trace=write command, for pi.c program?

#### 1.3.2 ltrace

15. Compute how many times fprintf() library routine is called by an execution of the program pi.c.

# Automatization and data managment tools

16. The objective of this exercise is to prepare a script that can help you to automatize the following steps of the optimization methodology: execution of the original code (several executions) to obtain timing information and golden output, execution of the optimized code to check the result first, and then several executions to obtain timing information of the optimized code. Finally, speedup computation.

In order to achieve this objective, do the following steps:

- (a) Create a script that, given the name of optimized executable program (first argument of the script), executes the program N times (second argument of the script), and shows the minimum, maximum and average elapsed time and the minimum, maximum and average cpu time of the N executions at the end of the script.
- (b) Add a new feature to the script to accept arguments of the program.
- (c) Add a new feature to the script to accept a new argument with the original executable program. This original program will be used to generate the golden output, check the correct result of the optimized executable program, and also to compute the speedup of the optimized version compared to the original one. If the result check is ok, the script will show the minimum, maximum and average time of both programs, and the speedup of the optimized code compare to the original code, using the average time, for elapsed and cpu time. If the result check is not ok, the script should indicate this fact.

Test your script running it in the following cases:

- (a) Run your final script using popul.00.g (O0 optimization flag with debug information) as the original program, and pi.00.g as the optimized program. Number of executions N=3.
- (b) Run your final script using pi.00.g (O0 optimization flag with debug information) as the original program, and pi.00.g as the optimized program. Number of executions N=3.
- (c) Run your final script using pi.00.g (O0 optimization flag with debug information) as the original program, and pi.03.g as the optimized program. Number of executions N=3.
- 17. It is up to you if you want to introduce more features, use of perf stat, etc.