THE UNIVERSITY *of* EDINBURGH

Robotics: Science and Systems

Course Assignment 1

Henrique Ferrolho - s1683857
henrique.ferrolho@gmail.com

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1 Forward and inverse kinematics

1.1 (10 marks)

1.2 (10 marks)

1.3 (10 marks)

2 Signal filtering & State Estimation

2.1 (10 marks)

2.2 (10 marks)

2.3 (20 marks)

3 Computer Vision

3.1 (10 marks)

3.2 (10 marks)

3.3 (10 marks)