

# MTH 655, Finite Element Methods: Homework 1

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February 20, 2018

## Problem 1

Consider the following two point boundary value problem (BVP). Let  $\Omega = (0, 1)$ . Given  $f \in C^0(\Omega)$ , find  $u \in C^2(\Omega) \cup C^0(\bar{\Omega})$  such that

$$(D2) : \begin{cases} -\frac{d^2 u}{dx^2} + u = f; & 0 < x < 1, \\ u(0) = u(1) = 0. \end{cases}$$

Obtain the weak or variational formulation for the above problem using test functions  $v \in H_0^1(\Omega)$ .

## Solution

We begin by multiplying each side of (D2) by the test function  $v$  and then integrating over the domain,  $\Omega$ .

$$-\int_{\Omega} \frac{d^2 u}{dx^2} v \, dx + \int_{\Omega} uv \, dx = \int_{\Omega} f v \, dx$$

Using integration by parts on the first integral gives

$$\int_{\Omega} \frac{d^2 u}{dx^2} v \, dx = \frac{du}{dx} v \Big|_{v(0)}^{v(1)} - \int_{\Omega} \frac{du}{dx} \frac{dv}{dx} \, dx$$

Applying the boundary conditions and resubstituting then gives the final variational formulation of (D2)

$$\int_{\Omega} \frac{du}{dx} \frac{dv}{dx} \, dx + \int_{\Omega} uv \, dx = \int_{\Omega} f v \, dx; \quad v \in H_0^1$$

## Problem 2

Consider the space  $V_k^2$  of continuous piecewise quadratic functions on the interval  $[0, 1]$ .

(a) Show that this space has (nodal) basis functions that are defined at the nodes  $x_i$  as well as the midpoints  $\frac{x_i + x_{i+1}}{2}$  of a partition of  $[0, 1]$ .

(b) For the two point BVP considered in class, i.e., Given  $f \in C^0(\Omega)$ , find  $u \in C^2(\Omega) \cup C^0(\bar{\Omega})$  such that

$$(D) : \begin{cases} -\frac{d^2 u}{dx^2} = f; & 0 < x < 1, \\ u(0) = u(1) = 0. \end{cases}$$

compute the local stiffness matrix on any interior element and discuss how these element contributions are used to assemble the stiffness matrix.

## Solution

(a) We begin by defining the basis functions

$$\begin{aligned} V_k^2 &= \{v_I = \sum_{i=1}^k \alpha_i \phi_i(x_j); \phi_i(x_i) = 1; \phi_{i-\frac{1}{2}}(x_{i-\frac{1}{2}}) = 1; \phi_i(x) = \frac{(x - x_{i-1})(x - x_{i-\frac{1}{2}})}{(x_i - x_{i-1})(x_i - x_{i-\frac{1}{2}})}, x \in [x_{i-1}, x_i], \\ \phi_i(x) &= \frac{(x - x_{i+\frac{1}{2}})(x - x_{i+1})}{(x_i - x_{i+\frac{1}{2}})(x_i - x_{i+1})}, x \in [x_i, x_{i+1}], \text{ 0 otherwise;} \\ \phi_{i-\frac{1}{2}} &= \frac{(x - x_{i-1})(x - x_i)}{(x_{i-\frac{1}{2}} - x_{i-1})(x_{i-\frac{1}{2}} - x_i)}, x \in [x_{i-1}, x_i] \text{ 0 otherwise} \} \end{aligned}$$

To show that this is a nodal basis we first show linear independence by noting that

$$\sum_{i=1}^k c_i \phi_i(x_i) = 0$$

implies that  $c_i = 0$  since  $\phi_i(x_i) = 1$ .

We then show that  $\{\phi_i\}$  spans  $V_k^2$ . This is true if for  $v \in V_k^2 \Rightarrow v = v_I$ . Since

$$v_I = \sum_{i=1}^k v(x_i) \phi_i$$

we must show  $v - v_I = 0$  identically. This is determined by noting that  $v$  and  $v_I$  are both quadratic on each  $[x_{i-1}, x_i]$  and zero at the endpoints of the interval. Thus,  $v_I$  spans  $V_k^2$  and is a nodal basis function.

(b) We begin by defining the local stiffness matrix as

$$A^l = \begin{bmatrix} \int_{I_l} \left(\frac{dl_1}{dx}\right)^2 dx & \int_{I_l} \frac{dl_1}{dx} \frac{dl_2}{dx} dx & \int_{I_l} \frac{dl_1}{dx} \frac{dl_3}{dx} dx \\ \int_{I_l} \frac{dl_2}{dx} \frac{dl_1}{dx} dx & \int_{I_l} \left(\frac{dl_2}{dx}\right)^2 dx & \int_{I_l} \frac{dl_2}{dx} \frac{dl_3}{dx} dx \\ \int_{I_l} \frac{dl_3}{dx} \frac{dl_1}{dx} dx & \int_{I_l} \frac{dl_3}{dx} \frac{dl_2}{dx} dx & \int_{I_l} \left(\frac{dl_3}{dx}\right)^2 dx \end{bmatrix}$$

where we note  $A_{ij} = A_{ji}$ . We then shift each segment of the nodal basis functions  $l_1, l_2, l_3$  to the interval  $[0, h]$ . This gives

$$l_1 = \frac{x^2 - (\frac{3}{2})hx + \frac{h^2}{2}}{\frac{h^2}{2}}$$

$$l_2 = \frac{xh - x^2}{\frac{h^2}{4}}$$

$$l_3 = \frac{x^2 - (\frac{h}{2})x}{\frac{h^2}{2}}$$

Differentiating each of these basis functions with respect to  $x$  gives

$$\frac{dl_1}{dx} = \frac{4x}{h^2} - \frac{3}{h}$$

$$\frac{dl_2}{dx} = \frac{4}{h} - \frac{8x}{h^2}$$

$$\frac{dl_3}{dx} = \frac{4x}{h^2} - \frac{1}{h}$$

Then the integrals in the local stiffness matrix are as follows

$$\int_{I_l} \left(\frac{dl_1}{dx}\right)^2 dx = \int_0^h \frac{4x^2 - 6xh + \frac{9}{4}h^2}{\frac{h^4}{4}} dx = \frac{7}{3h}$$

$$\int_{I_l} \left(\frac{dl_2}{dx}\right)^2 dx = \int_0^h \frac{4x^2 - 4xh + h^2}{\frac{h^4}{16}} dx = \frac{16}{3h}$$

$$\int_{I_l} \left(\frac{dl_3}{dx}\right)^2 dx = \int_0^h \frac{4x^2 - 2xh + \frac{1}{4}h^2}{\frac{h^4}{4}} dx = \frac{7}{3h}$$

$$\int_{I_l} \frac{dl_1}{dx} \frac{dl_2}{dx} dx = \int_0^h \frac{-4x^2 + 5xh - \frac{3}{2}h^2}{\frac{h^4}{8}} dx = \frac{-8}{3h}$$

$$\int_{I_l} \frac{dl_1}{dx} \frac{dl_3}{dx} dx = \int_0^h \frac{4x^2 - 4xh - \frac{3}{4}h^2}{\frac{h^4}{4}} dx = \frac{1}{3h}$$

$$\int_{I_l} \frac{dl_2}{dx} \frac{dl_3}{dx} dx = \int_0^h \frac{-4x^2 + 3xh - \frac{1}{2}h^2}{\frac{h^4}{8}} dx = \frac{-8}{3h}$$

Thus, the local stiffness matrix is

$$A^l = \frac{1}{3h} \begin{bmatrix} 7 & -8 & 1 \\ -8 & 16 & -8 \\ 1 & -8 & 7 \end{bmatrix}$$

The global stiffness matrix would be assembled as follows to form a pentagonal matrix.

$$\begin{aligned}
A &= \begin{bmatrix} A_{22}^1 & A_{23}^1 & 0 & 0 & 0 & 0 & \dots \\ A_{32}^1 & A_{33}^1 + A_{11}^2 & A_{12}^2 & A_{13}^2 & 0 & 0 & \dots \\ 0 & A_{21}^2 & A_{22}^2 & A_{23}^2 & 0 & 0 & \dots \\ 0 & A_{31}^2 & A_{32}^2 & A_{33}^2 + A_{11}^3 & A_{12}^3 & A_{13}^3 & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots \end{bmatrix} \\
&= \begin{bmatrix} 16 & -8 & 0 & 0 & 0 & 0 & \dots \\ -8 & 14 & -8 & 1 & 0 & 0 & \dots \\ 0 & -8 & 16 & -8 & 0 & 0 & \dots \\ 0 & 1 & -8 & 14 & -8 & 1 & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots \end{bmatrix}
\end{aligned}$$

### Problem 3

Consider a uniform grid over the interval  $[0, 1]$  with step size  $h$  and an associated finite element space  $V_k^1$  of continuous piecewise linear functions that satisfy zero boundary conditions.

- (a) Find the linear interpolant  $I_h v$  for  $v(x) = x^2$ .
- (b) Compute analytically the norm of the interpolation error  $v - I_h v$  in the  $L^2$  and energy norms.

### Solution

(a) A linear interpolant using piecewise Lagrange polynomials may be represented as follows

$$\begin{aligned}
l_1(x) &= -\frac{x-h}{h} \\
l_2(x) &= \frac{x}{h}
\end{aligned}$$

which gives for  $I_i v$

$$I_i v = (x_i)^2 \frac{x}{h} - (x_{i-1})^2 \left( \frac{x-h}{h} \right)$$

Thus,  $I_h v = \cup_{i=1}^k I_i v$ .

(b) The  $L^2$  error was calculated with the aid of Mathematica as

$$\begin{aligned}
\|v - I_h v\|_{L^2} &= \left( \sum_{i=1}^k \left[ \int_0^h ((x + (i-1)h)^2 - i^2 hx + (i-1)^2 h(x-h))^2 dx \right] \right)^{\frac{1}{2}} \\
&= \left( \sum_{i=1}^k \frac{h^5}{30} \right)^{\frac{1}{2}} \\
&= \left( \frac{kh^5}{30} \right)^{\frac{1}{2}} = \frac{h^2}{\sqrt{30}}
\end{aligned}$$

Similarly, the Energy norm error was also calculated using Mathematica as

$$\begin{aligned}
\|v - I_h v\|_E &= \left( \sum_{i=1}^k \left[ \int_0^h \left( \frac{d}{dx} [v - I_i v] \right)^2 dx \right] \right)^{\frac{1}{2}} \\
&= \left( \sum_{i=1}^k \left[ \int_0^h (h^2 - 4hx + 4x^2) dx \right] \right)^{\frac{1}{2}} \\
&= \left( \sum_{i=1}^k \frac{h^3}{3} \right)^{\frac{1}{2}} = \left( \frac{kh^3}{3} \right)^{\frac{1}{2}} = \frac{h}{\sqrt{3}}
\end{aligned}$$

These error estimates correspond with the interpolation theory that states that the  $L_2$  and Energy errors are second-order and first-order in  $h$ , respectively.

### Problem 4

Consider the two point BVP that we studied in class, i.e.,

For  $\Omega = (0, 1)$ , given  $f \in C^0(\Omega)$ , find  $u \in C^2(\Omega) \cup C^0(\bar{\Omega})$  such that

$$(D) : \begin{cases} -\frac{d^2u}{dx^2} = f; & 0 < x < 1, \\ u(0) = u(1) = 0. \end{cases}$$

Compute  $f$  so that the exact solution for the BVP is  $u(x) = \sin(\pi x)$ . Write a MATLAB code that uses a uniform mesh and linear finite elements and plot the discrete solution for  $h = 2^{-j}, j = 1, \dots, 3$ . Also, plot the exact solution for comparison.

### Solution

$f$  may be found as follows

$$f = -\frac{d^2u}{dx^2} = -\frac{d^2}{dx^2}[\sin(\pi x)] = \pi^2 \sin(\pi x)$$

Solving (D) via MATLAB using finite elements produced the following solutions for the three mesh sizes,  $h$ .

The grid convergence in Figure 2 shows second-order convergence in the max norm.

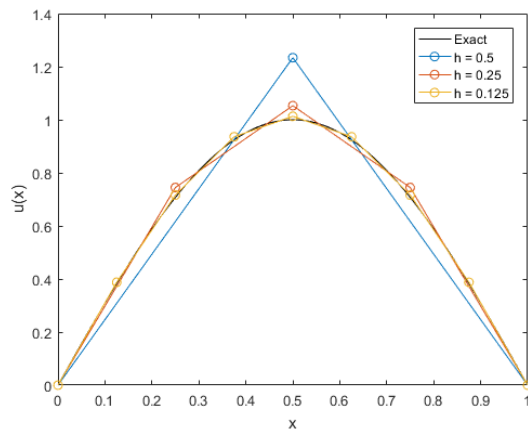


Figure 1: The FEM solution at various mesh sizes compared to the exact solution.

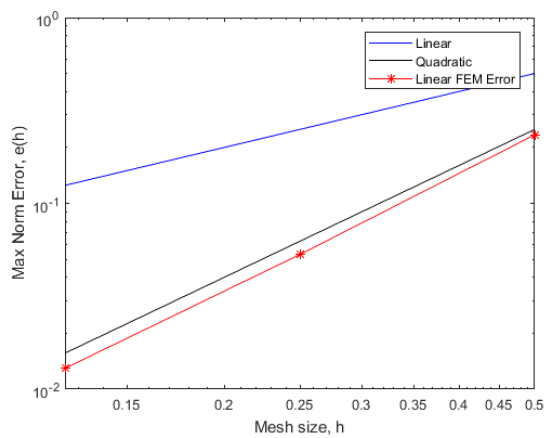


Figure 2: The FEM max norm error exhibits second-order behavior.