



COVERAGE PATH PLANNING

SYED MAZHAR

u1988609

Supervisor: Tamara Petrovic

Co-supervisor: Felix

A Final Year Report submitted to School of Physical and Mathematical Sciences, Nanyang Technological University in partial fulfilment of the requirements for the Degree of

Intelligent Field Robotic Systems

June 2024

Table of Contents

Table of Contents	3
1 Appendix	4
1.1 Experiment and Metrics Links	4
1.2 Videos	4



1 Appendix

1.1 Experiment and Metrics Links

1. Effect of Behavior Change Percent: [Click Here](#)
2. Lawnmower Algorithm Performance Metrics: [Click Here](#)
3. Behavioral Algorithm Performance Metrics: [Click Here](#)
4. Obstacle Avoidance Algorithm Performance Metrics: [Click Here](#)

1.2 Videos

1. Simulation Videos link: [Click Here](#)
2. Real Robot Videos Link: [Click Here](#)

Add the actual gdrivelinks and not zip files.