Brilliant: Group Theory

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Note: Latex reference: http://tug.ctan.org/info/undergradmath/undergradmath.pdf

1 Chapter 1.2

1.1 Page 1

 $R(R_1(x)) = A \to B, B \to A, C \to C$. So reflection about CE.

1.2 Page 2

 $R_2(R_1(x)) = A \to B, B \to C, C \to A$. So rotation clockwise 120°

1.3 Page 5

 $R \star R = H \star H = V \star V = I$ on the letter "I".

1.4 Page 6 - 9

Cayley table for rotating letter "I":

	Ι	Н	V	R
Ι	Ι	Н	V	R
Н	Η	Ι	R	V
V	V	R	Ι	Н
R	R	V	Н	Ι

Note: check out https://www.tablesgenerator.com/ here.

1.5 Page 10

- Klein four group: $(+, [0,1] \times [0,1])$ is equivalent to the "I" rotation.
- First coord could be: Does it rotate?

• Second coord could be: Does it flip?

2 Chapter 1.3

Group Properties

- Some binary operation (\cdot)
- Identity (not e.g., even integers)
- Inverse (not e.g. multiplication modulo non-prime p)
- Associativity (not e.g. an average f(x,y) = (x+y)/2)?

3 Chapter 1.4

Cube symmetries

One way to think about it:

- Corner A maps to one of eight new corners
- Each mapping has three orientations of that corner spin (0 degrees, 120, 240)
- Therefore 24

Another way:

- One identity = 1
- Type I: Rotate around line joining two opposite face centers: 3 pairs * 3 non-identity spins = 9
- Type II: Spin around line joining two opposite corners. 4 pairs * 2 non-identity spins = 8
- Type III: Spin 180 degrees around line from front upper edge to back lower edge. Combo of a spin and a rotate. 6 pairs = 6.
- Sum to 24.

Another way:

- There are four diagonals to a cube.
- Their permutations are in 1:1 correspondence with the transformations possible. (24)
- Type I keeps none fixed. 90 degrees: Chain = 4!/4 = 6. 180 degrees: two pairs. Select who A matches = 3.

- Type II rotates three, keeps one fixed = 8
- Type III does one swap, keeps two fixed = $\binom{4}{2}$ = 6

Note also: There are 24 reflection symmetries as well. (1:1 correspondence with rotations via "swap top center labels?")

4 Chapter 2.1

4.1 Page 2-3

The integers under multiplication are not a group, as they have no inverse. The set of rationals with multiplication as the group operation is not a group as 0 has no inverse

4.2 Page 5 - 7

- Dihedral group D_n has 2n elements, is not commutative, not cyclical.
- If n is even, there is exactly one rotational symmetry $R \neq I$ which commutes with all the other elements of D_n (the 180 degree rotation)

4.3 Page 8 - 9

- Symmetric group S_n is the set of permutations on n elements.
- "in-shuffle" of a deck of four cards is "split in half, interleave top half with bottom half, top card second", or $\phi = (1, 2, 4, 3)$. $\phi^4 = I$

4.4 Page 10-11

- Cyclic group Z_n is the set of integers modulo n under addition.
- Note that though usually multiplication is the default group operation, this usually uses "+".

5 Chapter 2.2: More Group Examples

5.1 Page 1-2

• Order of an element g is smallest k such that $g^k = e$. Otherwise infinite order

5.2 Page 3

Quaternion group Q_8 rules:

- $i^2 = j^2 = k^2 = ijk = -1$
- Implies ij = k, jk = i, ki = j
- implies ji = -k, kj = -i, ik = -j
- So this is not only non-commutative but anti-commutative
- $Q = \pm 1, \pm i, \pm j, \pm k$
- So one element of order 1, one of order 2 (element -1), remaining six of these elements have order 4

5.3 Page 4

Note that musical notes (Z_{12}) has only generators 1, 5, 7, 11. These corresponding to chromatic, circle of fourths (anti-fifths), circle of fifths, downwards chromatic scales!

5.4 Page 55

- $GL_n(\mathbb{R})$ is invertible n x n matrices in R.
- $SL_n(\mathbb{R})$ is determinant 1 n x n matrices in R.
- $A = \begin{pmatrix} -1 & 1 \\ 0 & 1 \end{pmatrix}$ has order 2, $B = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$ has order 2, but $AB = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$ has infinite order! Non-commutativity strikes.

5.5 Page 6-11

- isomorphism is a bjiection preserving group operations.
- Can think of it as a relabeling of the Cayley table.
- Example given is Klein-four and symmetries of tall serif letter "I", or of a diamond/non-square rhombus.
- Z_{12} is isomorphic to rotational symmetries of a 12-gon.
- Q_8 is isomorphic under matrix multiplication to $\left\{\pm\begin{pmatrix}1&0\\0&1\end{pmatrix},\pm\begin{pmatrix}i&0\\0&-i\end{pmatrix},\pm\begin{pmatrix}0&1\\-1&0\end{pmatrix},\pm\begin{pmatrix}0&1\\i&0\end{pmatrix}\right\}$ $\subset GL_2(\mathbb{R})$
- D_3 is isomorphic to S_3 since any permutation is possible in D_3 and no more.

6 Chapter 2.3: Subgroups

6.1 Page 1 - 3

- Subgroups are closure-bound subsets of groups.
- Easy test: $H \subset G$ if for every $h_1, h_2 \in H$, $h_1h_2 \in H$, and for any $h \in H$, $h^{-1} \in H$.

6.2 Page 4

• Cartesian product of groups G, H is also a group: $G \times H = (g,h) \cdot (g',h') = (gg',hh'), g \in G, h \in H$. Is this also called the **direct product**?

6.3 Lagrange's theorem

Theorem: Order of every subgroup divides the containing group.

Lemma: $H \subset G.r, s \in G.Hr = Hs \iff rs^{-1} \in H$. Otherwise, Hr, Hs have no element in common.

One direction: $rs^{-1} \in H \to Hr = Hs$

- $rs^{-1} = h \in H$ by supposition
- $Hh = Hrs^{-1} = H$
- Hr = Hs

Other direction: $Hr = Hs \rightarrow rs^{-1} \in H$

- Hr = Hs by supposition
- $Hrs^{-1} = H, soh_1 rs^{-1} = h_2$ for some h_1, h_2 .
- $rs^{-1} = h_1^{-1}h_2 \in H$

Therefore, if Hr and Hs have some element in common, meaning $h_1r = h_2s$, then $rs^{-1} = h_1^{-1}h_2 \in H$. So, by the first direction above, Hr = Hs.

Lagrange construction:

- Take $r_1 \in G$, so $Hr_1 = H$.
- If $H \neq G$, take $r_2 \in G Hr_1$ to create Hr_2 .
- Repeat. We will thus create disjoint $Hr_1, Hr_2, ...$ of the same size.

6.4 My take on Lagrange

- If $t \in Hr$ since $t = h_1r$ and $t \in Hs$ since $t = h_2s$, then $r = h_1^{-1}h_2s \in Hs$ and likewise for s, so Hr = Hs. So every element is in both or neither.
- Therefore H(x) = Hx is a partition relation on the elements of G.
- Size of Hr equals size of H for obvious group reasons.
- Every element g of G is in some coset Hg.
- Therefore G is partitioned into cosets of equal size, which is size of H.
- Therefore size of subgroup H divides size of group G

6.5 Page 7-12

- Note that if H and K are subgroups, so is $H \cap K$.
- Z_6 has subgroups $Z_6, 0, 2, 4, 0, 3, 0$, all divisors of 6 in this case.
- Z_p , p prime, has only subgroups Z_p , 0
- $Z_p \times Z_p$ has p + 3 subgroups
 - $-Z_p \times Z_p$
 - Generator (0,0)
 - Generator (0,1)
 - All generators $(1, n), n \in [0, p 1]$. p of those.
- Another way to think about $Z_p \times Z_p$: Outside of (0,0), the remaining $p^2 1$ elements each have order p. They are generate a group of size p, minus the identity. So $(p^2 1)/(p 1) + 2 = p + 3$.
- Subgroup count of $Z_4 \times Z_2$: a counting exercise, based on generators.
 - Look at all cyclic groups of each of the elements.
 - (0,0) generates 1 group
 - Order 2: Three elements, which generate three distinct cyclic subgroups
 - Order 4: Four elements, which generate two distinct subgroups
 - Order 8: $Z_4 \times Z_2$, non-cyclic
 - And there's one distict $Z_2 \times Z_2$ group.
 - Note: Is there a good (even recursive) formula for this?

7 Chapter 2.4: Abelian Groups

7.1 Page 1-3

- Theorem: $Z_a \times Z_b$ is isomorphic to Z_{ab} iff a and b are relatively prime.
- DF Proof: If a and b are relatively prime, (1,1) is of order ab. If a and b share factor c, then Z_{ab} has an element of order ab, but $Z_a \times Z_b$ will have cycled by a * b/c.
- So decompose e.g. Z_{12} into $Z_4 \times Z_3$, for example.

7.2 Page 4-6

- Theorem: Every finite abelian group is isomorphic to a direct product of cyclic groups.
- Therefore, the number of these groups of order n is the product of the partitions of each of its prime factors' powers.
- Therefore, the number of abelian groups of size $24 = 3 * 2^3 = p(3) * p(1) = 3 * 1 = 3, Z_3 \times Z_8, Z_3 \times Z_4 \times Z_2, Z_3 \times Z_2 \times Z_2 \times Z_2$
- Therefore, the number of abelian groups of size 2310 = 2 * 3 * 5 * 7 * 11 is one.

7.3 Page 7-11: Z_n^* or U(n)

- Group Z_n^* : elements of Z_n relatively prime to n, under multiplication.
- $|Z_n^*| = \phi(n)$, the totient function.
- This is a group even if n not prime because there is ax + bn = 1 if x, n are relatively prime.
- $Z_8^* = \{1, 3, 5, 7\}$ is isomorphic to $Z_2 \times Z_2$ since every element squared is 1.
- $Z_10^* = \{1, 3, 7, 9\}$ is isomorphic to Z_4 since it is generated by 3.
- $Z_15^* = \{1, 2, 4, 7, 8, 11, 13, 14\}$ is isomorphic to Z_4xZ_2 by counting element orders.
- Note: Primitive roots of n are those that generate Z_n^* . There are primitive roots mod n if and only if $n = 1, 2, 4, p^k, 2p^k$.
- TODO: read https://brilliant.org/wiki/primitive-roots/ and why these are the only solutions. Also, look up *Legendre symbol*

8 Chapter 2.5: Homomorphisms

8.1 Page 1 - 6

- Homomorphism $\phi: \phi(a)*'\phi(b) = \phi(a*b)$. Note that * and *' are different operations.
- This means, "translate each via the function, then combine" yields the same result as "combine first, then translate". So structure is preserved.
- Note this is like isomorphism, except homomorphism can squash some items to zero.
- Also, this can change to an entirely separate domain, e.g. det(AB) = det(A)det(B)
- Easy to prove homomorphism preserves identities and inverses.
- Order of transformed element $\phi(g)$ divides order of g, since $g^k = e$ and $\phi(g)^k = \phi(e)$, but consider that $\phi(g)$ could hit e at some divisor of k we could map everything to the identity and make that 1!

8.2 Page 7- 10: Counting homomorphisms

- Main idea: Knowing where we send identity determines entire homomorphism for a cyclic group.
- Homomorphism count for $Z_4 \to Z_{10}$: There are 10 places to send identity, but recall that $\phi(1)$ has to have order 4 since $\phi(1+1+1+1) = \phi(0) = 0$. Therefore, $\phi(1)$ has to be 0 or 5. So 2 possibilities.
- Homomorphism count for $Z_{99} \to Z_{100}$: Since $\phi(99) = 0$ and $\phi(1) \times 100 = 0$, and order of $\phi(1)$ must divide both, only one possibility: $\phi(1) = 1$,.
- Homomorphism count for $Z_{99} \to Z_{99}$: 99, since $99 \cdot \phi(1) = 0$, so $\phi(1)$ can go anywhere.
- Homomorphism count for $D_3 \to Z_3$: 1, since D_3 has 3 elements of order 2, 2 of order 3, 1 of order 1. Only mapping everything to 0 works.

8.3 Page 11: Counting automorphisms

- Automorphism is isomorphism from group to itself.
- Count of automorphisms of \mathbb{Z}_8 : If 1 maps to an order-8 element, we're isomorphic. There are four: 1, 3, 5, 7
- $Aut(Z_8)$ is isomorphic to $Z_2 \times Z_2$, since $\phi_3(1)^2 = \phi_5(1)^2 = \phi_7(1)^2 = 1$, where ϕ_a maps a to 1. Three elements of order 2 means it's the Klein 4 group.

- Count of automorphisms (meaning, we need all the elements in the codomain) of $Z_2 \times Z_2 \times Z_2$: Think of $\phi((1,0,0)), \phi((0,1,0)), \phi((0,0,1))$ as the basis for the group. There are seven choices for the first, six for the next, and four for the third.
- The above group is $(\phi(e_1)|\phi(e_2)|\phi(e_3)) = GL(\mathbb{F}_2)$, invertible matrices of 3x3.

9 Chapter 2.6: Quotient Groups

9.1 Aside: Complex multiplication

- Complex modulus (size) of a + bi is defined as $root(a^2 + b^2)$
- Complex multiplication: Angles add, moduli multiply
- One proof of moduli: (a+bi)(c+di) = (ac-bd) + (ad+bc)i and $\sqrt{a^2 + b^2}\sqrt{c^2 + d^2} = \sqrt{a^2c^2 + b^2d^2 2abcd + ad^2 + bc^2 + 2adbc}$
- One proof of angles: Convert to $r_1(\cos(a) + \sin(a))r_2(\cos(b) + \sin(b))$ and multiply
- More visual proof: Think of $c_1(a+bi) = c_1a + i(c_1b)$. a scales original vector, and bi rotates by 90 degrees and scales.

9.2 Page 1-6

- S^1 , is defined as the group of complex numbers with modulus 1.
- The coset zS^1 is any complex number multiplied by S^1 , which is a circle about the origin. z=2 and z=2i would be in the same coset. These cosets are members of C^* with the same modulus (length).
- These are disjoint cosets that fill out \mathbb{C}^* (don't include the zero, since no inverse).
- If you consider H = x + iy, x > 0, y = 0 (positive reals) then the cosets are rays from the origin. Any zH is just the different sizes of that (say, unit) vector. These cosets are members of C^* with the same angle.
- quotient group of \mathbb{C}^* by S^1 :
 - Members are cosets
 - Multiplying is defined as $aH \times bH = abH, H \in S^1, a, b \in \mathbb{C}^*$
 - $-S^1$ is therefore the identity.
 - This group is isomorphic to R^+ under multiplication (or really, like H).
 - "A ray of angle A and a ray of angle B multiply to a ray of angle AB, forget about the size".

- This is like collapsing out the divisor, in this case, S^1 .
- size |G/H| = |G|/|H| since cosets are equally sized.
- Gotcha: Only works (meaning, $g_1, g'_1 \in C_1, g_2, g'_2 \in C_2$ implies g_1g_2 in same coset as $g'_1g'_2$) if H is **normal** in G.
- Note: Normal means xH = Hx, so that makes sense that $g_1Cg_2C = g_1g_2C*C = g_1g_2C$
- So \mathbb{C}^*/H is all the rays with the same modulus, or S^1 .
- "A ray of size X and a ray of size Y multuply to a ray of size XY, and forget about the angles".
- So $\mathbb{C}^*/S^1 = H$ and $\mathbb{C}^*/H = S^1!$

9.3 Page 7-12

- Another example: $\mathbb{Z}/10\mathbb{Z} = \mathbb{Z}_{10}$ under addition. Forget about the non-unit digits!
- Another example: \mathbb{Q}/\mathbb{Z} is $\overline{q} = q + \mathbb{Z}$, so $\overline{1/2} + \overline{2/3} = \overline{1/6}$
- Another example: if N is the **center** (omni-commuter subgroup) of D_4 , then N is two elements I, R_{180} . Forgetting about those we have cosets $(I, R_{180})N, (R_{90}, R_{270})N, (D_1, D_2)N, (V, H)N$. All non-identity are degree 2, so isomorphic to $Z_2 \times Z_2$
- Another example: Z_{13}^* with multiplication mod 13. N = 1, 12 is a normal subgroup. Z_{13}^*/N is "forget about the +/-1 of it and think of these as 1 through 6.
- Another example: **commutator subgroup** [a,b] is generated by all $aba^{-1}b^{-1}$ for all $a, b \in G$. Note: group members are products of these guys, not necessarily all of that form. This is just e for an Abelian group. Its size measures "how far" the group is from being Abelian.
- Main idea of quotients: "what do we force to the identity?" If we say every $\overline{aba^{-1}b^{-1}} = \overline{1}$, then you can multiply by ba to get $\overline{ab} = \overline{ba}$. So G/[G,G] is necessarily Abelian.

10 Chapter 3.1: Number Theory

10.1 Page 1- 7

- A Fermat's little theorem proof
 - Take prime p, and a not divisible by p.

- $-a, 2a, 3a..., (p-1)a \equiv 1, 2, 3, ...(p-1) \mod p$ since they're the same elements mod p.
- Take the product of each: $a^{p-1}(p-1)! \equiv (p-1)! \mod p$
- Divide (p-1)! out (there's an inverse mod p) and you get $a^{p-1} \equiv 1 \mod p$
- Another: Since the order of a in \mathbb{Z}_p^* is p-1, $a^{p-1} \equiv 1 \mod p$.
- Note: Generalization of Fermat's little theorem using same group argument: $a^{\phi(n)} \equiv 1$ if a and n relatively prime.

10.2 Page 8-11

- Wilson's theorem: $1 * 2 * ... * (p-1) \equiv -1 \mod p$.
- One proof: These all have inverses, except 1 and -1 mod p, which are self-inverting $(x^2 = 1 \text{ solutions})$.
- This also proves that the product of all elements of a finite Abelian group which has a single element g of order 2 is that element, g.
- A hard proof TODO. The powers of a **primitive root of p** yield all elements $a \mod p$. So \mathbb{Z}_p^* is cyclical for any prime p.
- One more proof: if k relatively prime to p-1, where p a prime > 2, then $1^k + 2^k + \dots + (p-1)^k \equiv 0 \mod p$, since each of these summands is a different member of the group, summing to $\frac{p(p-1)}{2}$

11 Chapter 3.2: Games

11.1 15 puzzle

I think this will go: - The board is a permutation of (1, 2, ... 15), read like a book, with a blank somewhere in there ,immaterial. - Sliding the blank left or right doesn't change the order. - Sliding it up or down skips three backward or forward.

Their proof: Think of this as a series of swaps with (j, 16), 16 being the blank tile. To return to the bottom right corner, 16 must make an even number of moves. So only even permutations allowed. So (14,15) is not a viable swap, nor any of the odd permutations.

12 Chapter 3.3: Peg solitaire

• Consider Klein four group: xy = yx = z, yz = zy = x, xz = zx = y.

- Label all pegs such that three consecutive are always, in some order: x, y, z
- Invariant: product of all occupied spaces. If x jumps over y to get to z, eliminating jumped peg, xy = z.
- 11 x's, 11 z's, 10 y's yield xz = y as the product.

13 Chapter 3.4: Rubix's Cube

- Each element is the state $(S_{12}, S_8, (Z_2)^{12}, (Z_3)^8)$, representing around a fixed set of centers: (middle selections, corner sleections, middle orientation, corner orientation).
- Invariant: First and second perms for all F,B,D,U,L,R are odd, so first two args need same permutation parit
- Invariant: (Not proven here): Sum of edge orientations (0,1) is zero, sum of corner orientations (0, 1, 2) is zero.
- Commutator: $ghg^{-1}h^{-1}$ measure how entangled g and h are. If they're commutatitive, it is e.
- For Rubix's cube, commutators $ghg^{-1}h^{-1}$ are great for only moving pieces where effects of g and h overlap.
- g and h are **conjugates** if some x such that $h = x^{-1}gx$. "h is same as g, just in a different location".
- Conjugate interpretation: "h is move via x, operate with g, move back via x."
- For Rubix's cube you can use conjugates to make whatever change to a different part of the cube (move it to the operating table, operate, move it back).

14 Chapter 4.1: Normal Subgroups

14.1 Normal definition

- Normal subgroup intuition: Every conjugacy $g^{-1}Hg$ moves a group to another subgroup. Normal subgroups $g^{-1}Ng = N$ are the ones that don't move when you conjugate them.
- Example of non-normal: Any one of the n sets of S_{n-1} among conjugates of S_n . Move it, mess with it, move it back it's broken free by then.
- Normal definition: Group N is normal if and only if (all equivalent):
 - -gN = Ng for all $g \in G$

- $-gNg^{-1} = N$ for all $g \in G$ (equiv to above)
- $-gng^{-1} \in N$ for all $g \in G$
- Theorem: Any subgroup of index 2 is normal. Proof: G has two distinct cosets N, gN, but also N and Ng so gN = Ng.
- Normal doesn't recursively nest.
 - If G has normal subgroup H and H has normal subgroup K, K is normal in H too (those elements also "pass through K)"
 - However, H can be normal in G (e.g. (I, R_{180}, F_v, F_h) in D_4 , K can be normal in H (e.g. I, V, but K is not normal in $G: VR_{90} = D_{ul}, R_{90}V = D_{ur}$
- Normal examples in $GL_2(\mathbb{C})$: $SL_2(\mathbb{C})$ (determinant 1) and non-zero diags zI_2 .
- Non-normal examples in $GL_2(\mathbb{C})$: $GL_2(\mathbb{R})$ and non-zero diags with different entries. Easy to throw some arbitrary ones in Wolfram Alpha and see everything messed up after conjugation.
- G's Center: Z(G) are the omni-commuters. Always normal.
- G's Commutator group [G, G]: Product of any $aba^{-1}b^{-1}$ for $a, b \in G$. is normal, since $g[a, b]g^{-1} = [gag^{-1}, gbg^{-1}]$.

14.2 Normal properties and examples

- S_3 has three normal subgroups: two trivial ones, and ([], [123], [321]) since it's of index 2.
- Q_8 has four non-trivial subgroups, all normal: those generated by I, j, or k, all of order 4, index 2. -1 also generates an order 2 group, but it's the center.
- Definition: Product $HK = hk : h \in H, k \in K$.
- Property: If $H \cap K = \{1\}$, and H, K are finite, $|HK| = |H| \cdot |K|$. Why? $h_1k_1 = h_2k_2 \Longrightarrow h_2^{-1}h_1 = k_1^{-1}k_2$, proving they're both e since left is in H, right in K.
- Property: If H, K subgrops of G, then HK is a subgroup too if H or K is normal, otherwise not always. Why?
 - Assume H is normal.
 - Identity: $e_h e_k = e$ is in there.
 - Inverse: If $hk \in HK$, then $k^{-1}h^{-1} = k^{-1}h^{-1}k^1 * k^{-1}$ is in H, K due to H's normality.

- Closure: $h_1k_1 * h_2k_2 = h_1k_1h_2(k_1^{-1}k_1)k_2 = h_1(k_1h_2k_1^{-1})k_1k_2 = h_1h_3 * k_1k_2$ for some h_3
- Property: If H, K are normal subgroups of G, HK is normal. Maybe not otherwise (e.g. take $H = \{1\}, G$ a non-normal subgroup). Why? More tricks. $ghkg^{-1} = gh(g^{-1}g)kg^{-1} = (ghg^{-1})(gkg^{-1}) = h'k'$ for some other $h' \in H, k' \in K$.
- Centralizer of G's subgroup H is a subgroup of G which commutes with all H: $C_G(H) = \{g \in G : gh = hg \text{ for all } h \in H\}$. This is G if and only if G is Abelian (almost definitional). May not contain H.
- Normalizer of G's subgroup H is a subgroup of G which makes H normal: $N_G(H) = \{g \in G : gH = Hg\}$. This is G if and only if H is normal in G (almost definitional). Largest subgroup of G where H is normal.
- Centralizer is a normal subgroup of normalizer with two different proofs:
 - With $n \in N_G(H)$, $c \in C_G(s)$, show that ncn^{-1} commutes with members of H, so it's in C_G , therefore normal. hn is some nh', and same for n^{-1} , so $ncn^{-1}h = nch'n^{-1} = nh'cn^{-1} = h'ncn^{-1}$ so ncn^{-1} passed through h, is therefore in the centralizer, and so $C_G(H)$ is normal.
 - Using First isomorphism theorem (later):
 - * $N_G(H)$ is the big "dividend" group, $C_G(H)$ is the "divisor", and Aut(H) the "quotient" (codomain of the homomorphism)
 - * The homomorphism $\phi: N_G(H) \to Aut(H)$ is $g \to \phi_g(x) = gxg^{-1}$.
 - * The kernel of this homomorphism is that which maps to $I \in Aut(H)$.
 - * The kernel is the centralizer, since $\phi_c(x) = cxc^{-1} = cc^{-1}x = x$, identity.
 - * Therefore, $N_G(H)/Ker(\phi) = N_G(H)/C_G(H) \rightarrow Aut(H)$. so $C_G(H)$ must be normal!
 - * (Kernels of homomorphisms always normal (DSF Proof): If $\phi : G \to H$ is a homormophism, and $g \in G, k \in Ker(\phi)$, then $gkg^{-1} \in K$ since $\phi(gkg^{-1}) = \phi(g)\phi(k)\phi(g^{-1}) = \phi(g)\phi(g^{-1}) = e$. So K is normal in G.

15 Chapter 4.2: Isomorphism theorems

• Example of intuitive isomorphism: $M_2(\mathbb{Z})/N \cong (\mathbb{Z}_2)^4$, where N is the subgroup with even entries. How? Can *either list all cosets* or construct a homomorphism $\phi\begin{pmatrix} a & b \\ c & d \end{pmatrix} = (a(\text{mod}2), b(\text{mod}2), c(\text{mod}2), d \text{ mod } 2)).$

15.1 First Isomorphism Theorem and example

- $-G = GL_2(\mathbb{R})$, invertible 2x2 real matrices
- $-N = SL_2(\mathbb{R})$ is subgroup of G with determinant 1.
- $-\varphi$ is det, since det(AB) = det(A)det(B).
- $-G/N \cong \mathbb{R}^*$ intuitively, since for any matrix, you can divide by the determinant scalar, and find the representative in the group N. Can think of N as the kernel of the homomorphism it doesn't matter, it's mapped to identity.
- **First isomorphism theorem**: given surjective homomorphism $\varphi : G \mapsto H$ with kernel $Ker(\varphi) = \{g \in G | \varphi(g) = e_H\}$, then $G/Ker(\varphi) \cong H$.
- Another example in the above, if $a = \begin{pmatrix} 0 & 1 \\ 2 & 3 \end{pmatrix}$, $b = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$, then (aN)(bN) is some cN, where det(c) = 4, like 2I

15.2 Third Isomorphism theorem

- \bullet Theorem: If G / N is abelian, then every subgroup H of G containing N is normal in G.
 - $-H/N \subset G/N$, and so H/N is abelian too.
 - Abelian means ghN = hgN
 - This also shows there is some n such that gh = hgn.
 - But since N is normal in G, $gn = n'g \rightarrow hgn = (hn')g$, and $hn' \in H$, therefore gh = (hn')g, and H is normal in G.
- Actual theorem says subgroups of G containing N correspond to subgroups of G/N.
- Also, $\frac{G/N}{H/N} \cong \frac{G}{H}$

15.3 Second Isomorphism theorem

- Actual theorem says: if H is a subgroup of G, and N is a normal subgroup of G, then $\frac{H}{H \cap N} \cong \frac{HN}{N}$
- In particular, if $H \cap N = \{1\}$, then $\frac{HN}{N} \cong H$.
- Why?
- \bullet HN contains both H and N since N is normal.
- Therefore (HN)/N is a group.

- $\varphi(h) = hN$ is a surjective homomorphism to (HN)/N
- The kernel is anything in N, which would be $H \cap N$.
- Result follows from first isomorphism theorem.

15.4 Examples using the first isomorphism theorem

- : Typically, in order to identify $G/N \cong K$, find the surjective homomorphism $G \to K$ where $Ker(\varphi) = N$.
- Example: $G = \mathbb{Z} \times \mathbb{Z}$ with addition, N = group generated by (1,0). $G/N \cong Z$ intuitively, since you're forgetting the first coordinate. To make it formal: $\varphi((x,y) = y)$.
- Harder example: $G = \mathbb{Z} \times \mathbb{Z}$ with addition, H = group generated by (2,3), or (2a,3a). $G/H \cong Z$, actually, since $\phi((x,y) = 3x 2y)$ is surjective (think of $\phi((a,a)) = a$ and its kernel is H.
- Harder example: $G = \mathbb{Z} \times \mathbb{Z}$ with addition, H = group generated by (2,4), or (2a,4a). $G/H \cong Z \times Z_2$, actually, since $\phi((x,y) = 2x y, x(mod2))$ is surjective and its kernel is H.
- TODO: Get a better intuition here. Is this group like, how far away from this null space line am I?

16 4.3a: Interlude; Group actions

16.1 Group Actions

Reference: https://brilliant.org/wiki/group-actions

- **group action** on group G, set X, is function $f: G \times X \to X$. It's often written $f(q,x) = q \cdot x$. which has some groupy properties.
 - $-f(e_G,x)=x$ for all $x\in X$, or $e_G\cdot x=x$
 - -f(g, f(h, x)) = f(gh, x) for all $x \in X$, or $g \cdot (h \cdot x) = (gh) \cdot x$.
 - Canonical Example: if G is S_n , and $X = \{1, 2, ...n\}$.
- fixed point of a group element $g \in G$ is $x \in X$ such that $g \cdot x = x$. So, f = g(x) is the (very straightforward) mapping, g is the function, and x would be a point that doesn't change.

- For point x, stabilizer of the point is called G_x , and is the set of $g \in G$ that map x as a fixed point: g(x) = x. of a of element $g \in G$ is $x \in X$ such that $g \cdot x = x$. So, it's the *subgroup* that makes x totally stable.
- fixed point of element $g \in G$ is $x \in X$ such that $g \cdot x = x$. So, f = g(x) is the (very straightforwardx) mapping, g is the function, and x would be a point that doesn't chagne.
- orbit of element $x \in X$ is how far x reaches, the set of $y \in X$ such that there's a $q \cdot x = y$.
- Example: So if $G = \mathbb{Z}_2 = e, g, X = \mathbb{Z}$, and the action is $e \cdot x = x, g \cdot x = -x$, then
 - Fixed points of e are all of them, of g is 0.
 - Stabilizers of x are e for all, e, q for 0.
 - Orbit of 0 is $\{0\}$, orbit of every other n is $\{n, -n\}$
 - orbits are an equivalency relation! So they partition X.
- Action is **transitive** if there is only one orbit in the relation (sounds like a regular group): for any $x, y \in X$, there is a g such that $g \cdot x = y$.
- Action is **faithful** If only e_G if the only omni-stabilizer element is e_G . Intersection of all G_x is e_G .
- Another way to think about faithful: Think of G as a homomorphism to Sym(X), permutations of the group. Faithful actions are injective / have a trivial kernel.
- Examples of actions
 - Every group acts on itself by left multiplication. It is transitive and faithful (since the Cayley table is a latin square). One orbit.
 - Every group acts on itself by conjugation $g \cdot x = gxg^{-1}$. Orbits are the conjugacy classes. The **centralizer** $C_G(x)$ is the stabilizer of x.
 - If H is a subgroup of G, then cosets G/H and left multiplication are a group action. They are a transitive action since there is one orbit: you can always get from gH to kH by $(kg^{-1})H$.
 - Core Group: The group $\bigcap_{g \in G} gHg^{-1}$ of G's subgroup H is the largest normal subgroup of H. Proof:
 - * It's contained in H since $hHh^{-1} \in H$, and it's an intersection.
 - * It's normal because $kCore_G(H)k^{-1} = k(\bigcap_{g \in G} gHg^{-1})k^{-1} = \bigcap_{g \in G} kgHg^{-1}k^{-1} = Core_G(H)$ since every kg is just a g but permuted.

- * It's the largest normal one since if there were another normal subgroup $N' \in H$, then $gn'g^{-1} \in N'$ and $gn'g^{-1} = h$ for some $h \in H$, so $n' = g^{-1}hg$, and therefore n' is somewhere in the core group.
- * Therefore, the core group is the kernel of the map $G \to Sym(G/H)$, since those map to H. So if H doesn't contain any trivial subgroups, it's faithful, and is called **simple**
- Another group action: $PGL_2(\mathbb{C}) = \text{projective linear group of } 2x2 \text{ matrices on}$ the complex plane (plus infinity), sending $\begin{pmatrix} a & b \\ c & d \end{pmatrix} \cdot z = \frac{az+b}{cz+d}$.
- Orbit stabilizer theorem: If G is finite, and $x \in G$ has a stabilizer G_x and orbit orb(x), then $|G| = |G_x||orb(x)|$. Proof:
 - Since stabilizer is a subgroup, the count of distinct cosets (index) times the subgroup is the size by Lagrange.
 - Consider homomorphism ϕ from $G/G_x \to orb(x) = gG_x \to g \cdot x$
 - And the set aG_x and bG_x are equal under ϕ iff a(x) = b(x), since $b^{-1}aG_x = G_x$, implying $b^{-1}a \in G_x \to b^{-1}a(x) = x \to a(x) = b(x)$.
 - Also, this map is onto since every element $y \in orb(x)$, meaning some $g \cdot x = y$ is in that gG_x .
 - Example: symmetric group: $S_n: G_x \cong S_{n-1}! \to |G_x| = (n-1)!$. orb(x) = n. So |G| = n!.
 - Example: cube symmetries: Vertex is x, rotation of adjacent vertices is G_x . $|G_x||O_x|=3*8=24$. Can also do with edges and faces. Turns out cube symmetries $\cong S_4$

17 Aside: Conjugacy classes

17.1 Conjugacy classes defined

- Note: It's easy to take a group to another group by conjugation group action $\phi(g, H)$: ghg^{-1} . Though the whole group gets mapped to another group, the elements inside get mapped to **conjugacy classes**.
- Within group G, elements h, h' in conjugacy class H have some $g \in G$ such that $h' = ghg^{-1}$ (and therefore, $g^{-1}h'g = h$. So, it's an equivalence relation, thus a partition.

- Note: if the group G is abelian, $h' = ghg^{-1} \to gg^{-1}h = h$, so all conjugacy classes there are of size one $(ghg^{-1} = gg^{-1}h = h)$
- Each one of these classes corresponds to the orbit of that element h under conjugation.
- Why useful? They can be used to show structure (and thus classify, look at isomorphisms, etc.) of groups.
- Example: In $GL_n(\mathbb{R})$, $A = PBP^{-1}$ is matrix similarity. B represents A under a change of bases.
- Example: In S_3 , there are three conjugacy classes: $\{()\}, \{(abc), (bac)\}, \{(ab), (bc), (ac)\}.$ Easy to think about with permutations this is just relabeling the members going in, doing the permutation, then reversing the labels.
- Example: $\mathbb{Z}/5\mathbb{Z} = \mathbb{Z}_5$ which is Abelian, so 5 classes (one for each element).

17.2 A_5 example and the class equation

- Examples: In A_5 , types are repped by (), (12)(34), (12)(23) = (123), and (12)(23)(34)(45) = (12345).
- Gotcha: Note that There are 5!/5 = 24 5-cycles, and that subgroup order has to divide 60, so there must be two conjugacy classes of 5-cycles. Makes sense that (12345) and (21345) can't be same class, since there's nowhere to "stash" during the relabeling.
- Theorem: Sum of conjugacy class orbits is size of group, or, for arbitrary class reps $g_1...g_k$, $|G| = \sum_{i=1}^k [G:C_G(g_i)]$. Note that |Z(G)| is all of the reps and classes of size one. Why does this work? Orbit-stabilizer says that $C_G(g_i)$ is the stabilizer, and the conjugacy classes form a partition.
- Class Equation: Just writing down the size of the equivalence classes. In A_5 , this would be 60 = 1 + 15 + 20 + 12 + 12 (second set of 5-cycles).
- Note that any *normal* subgroup in A_5 has to be union of those since conjugation by A_5 elements maps to the whole conjugacy class. BUT there are no sums that divide 60. So A_5 has no normal subgroups, so it is simple!