Advanced Algorithms Final Notes

Recurrences

Master Method

$$T(n) = aT(rac{n}{b}) + f(n)$$
 $f(n) = egin{aligned} O(n^{log_b^a}) & ext{if } f(n) = O(n^{log_b^a - \epsilon}) \ O(f(n)logn) & ext{if } f(n) = O(n^{log_b^a}) \ O(f(n)) & ext{if } f(n) = O(n^{log_b^a + \epsilon}) \end{aligned}$

Sum of Sequences

$$\frac{n(a_1+a_{50})}{2}$$

Order Notation

O = Upper Bound $\Theta = \text{Tight Bound}$ $\Omega = \text{Lower bound}$

Binary Search

- 1. Sorted Sequence
- 2. Check if middle value is the value you want
- 3. If not, rerun alogrithm on the top or bottom partition based on the number you wants value
- 4. if low < hi then the value is not found

Power function

```
power(X,n)
if n == 0
    return 1
else if n == 1
    return X
else
    S = power(x, n/2)
    if n is odd
        return S*S*X
```

```
if n is even
return S * S
```

Merge sort

```
Merge(A,B,P,q,r)
//Precondition: A[p...q], A[q+1...r)] are sorted
//B is for temp work
Copy A[p...r] into B[p...r]
i = p
j = q+1
for k=p to r
    if j > r or (i <= q and B[i] <= B[j])
        A[k] = B[i++]
    else
        A[k] = B[j++]</pre>
```

Mergesort use merge after spliting each side into two parts, then run mergesort of them

Rod-Cutting problem

Input: n, P[1...n]

Output: max revenue from rod of length n

Recurrence

$$r(n) = egin{cases} max(p_i + r(n-i)) & & ext{if } n > 0 \ 0 & & ext{if } n = 0 \end{cases}$$

Dynamic program

```
cutRod(Price[], int n)
    price[0] = 0
    for i = 1 to n
        for j = 0 to i
            max_val = max(max_val, price[j] + val[i-j-1])
    val[i] = max_val
return val[n]
```

Longest Common Subsequence

Recurrence

$$LCS(i,j) = egin{cases} 0 & ext{if } i=0 ext{ or } j=0 \ 1 + LCS(i-1,j-1) & ext{if } x[i] = y[i] \ max(LCS(i-1,j),LCS(i,j-1)) & ext{if } x[i]
eq y[i] \end{cases}$$

Dynamic program

```
for i = 0 to m
   L[i,0] = 0
for j = 0 to n
   L[0,j] = 0
for i = 1 to m
   for j = 1 to n
        if x[i] = y[j]
            L[i,j] = 1 + L[i-1,j-1]
        D[i,j] = 1
   else if L[i,j-1] > L[i-1,j]
        L[i,j] = L[i-1,j]
        D[i,j] = 2
   else
        L[i,j] = L[i,j-1]
        D[i,j] = 3
```

Reconstructing

```
\\Input: x,y,L,D
\\Output: Z[1...k]
K = L[m,n]
i = m
j = n
while k > 0
    if D[i,j] = 1
        Z[k] = x[i]
        k--
        i--
        j--
    else if D[i,j] = 2
        i--
    else
        j--
return Z
```

Activity Selection

Input: StartTimes s, FinishTimes f, Values v Output: Find a compatable subset Q

Recurrence

$$ASP(i) = egin{cases} 0 & ext{if } i = 0 \ max(ASP(i-1), v_i + ASP(j)) & ext{if } i > 0 \end{cases}$$

Dynamic program

```
A[0] = 0
for i = 1 to n
    j = i-1
    while f[j] > s[i]
        j--
        A[i] = max(A[i-1], v[i] + A[j])
return A
```

Adjacency list representation

Each vertex has a list of its neighbors (In a directed graph, outbound neightbors only)

Breadth First Search (BFS)

```
//s is the source vertex
BFS(G,s)
    for each u in V
        u.color = white
        u.d = infinity
        u.pi = null
    s.d = 0
    s.color = grey
   Create a queue<vertex> Q contatining s
   while Q is not empty
       u = Q.remove()
        for each edge e =(u,v) in Adj[u]
            if v.color == white
                v.pi = u
                v.d = u.d + 1
                v.color = grey
```

```
Q.add(v)
u.color = black
```

Depth First Search (DFS)

```
DFS(G)
    for u in V
        u.color = white
        u.pi = null
   time = 0
    topNum = |v|
    for u in V
        if u.color == white
            DFS_Visit(u)
DFS_Visit(u)
    u.color = grey
    u.dis = ++time
    for each edge e=(u,v) in Adj[u]
        if v.color == white
            v.pi = u
            DFS Visit(v)
    u.color = black
    u.fin = ++time
    u.top = topNum--
```

Generic MST Algorithm

```
A = Null Set
While A is not a spanning tree
   Find a cut (S, V-s) not crossed by any edge of A
   Let e=(u,v) be a light edge for (S,V-s)
   A = AU{e}
```

Prim's Algorithm

```
Input: G=(V,E) weights w, Root s

Prim(G,w,s)
    for each u in V
        u.d = infinity
        u.pi = null
```

```
s.d = 0
Set = null
wmst = 0
Create a priority queue Q with all vertices (priority = u.d)
while Q is not empty
    u = Q.remove()
    Set = Set U {u}
    wmst = wmst + u.d
    for each v in adj[u]
        if v is in Q and w(u,v) < v.d
            v.d = w(u,v)
            v.pi = u</pre>
```

Kruskal's Algorithm

```
A = null
for each edge e=(u,v) in sorted order of weight
  ru = Find(u)
  rv = Find(v)
  if ru != rv
      Union(ru,rv)
      A = A U {(u,v)}
```

Disjoint Set ADT (Union-Find)

```
Find(u) - If u and v are in the same subset, Find(u) = Find(v)
```

```
Find(u)
    return u.rep
```

Union(u,v) - Merge subsets conatining u, containing v into a single subset

```
Union(u,v)
    for x in V
        if x.rep == v.rep
            x.rep = u.rep
```

Makeset(u) - Create a singleton set {u} represented by u

Submethods for dynamic programs used below

```
Initialize(s)
    for u in V
        u.d = 0
        u.pi - null
    s.d = 0

Relax(u,v)
    if v.d > u.d + w(u,v)
        v.d = u.d + w(u,v)
        v.pi = u
```

Bellman-Ford algorithm

Let $d_k(u)$ = Length of a shortest path from s to u that uses at most k edges

Recurrence

$$d_k(u) = egin{cases} 0 & ext{if } u = s ext{ and } k = 0 \ \infty & ext{if } u
eq s ext{ and } k = 0 \ min(d_{k-1}(u), d_{k-1}(p) + w(p, u)) & ext{if } k > 0 \end{cases}$$

Dynamic program

This program uses the Initialize and Relax methods described above

DAG-shortest paths

```
Input: A directed, acyclic graph G 
Output: u.d = \delta(s, u) for all u in V
```

```
DAG(G,s)
    Initialize(s)
    Find a topological ordering of G
```

Dijkstra's algorithm

This only works when there are no negative edge weights

Floyd-warshall's algorithm

 $d_k(u,v) = Length of a shortest path from u to v in which its internal nodes can only be chosen from {1,2,...,k}$

Output: $d = \delta(s, u)$

Recurrence

$$d_k(u,v) = egin{cases} w(u,v) & ext{if } k=0 \ min(d_{k-1}(u,v),d_{k-1}(u,k)+d_{k-1}(k,v)) & ext{if } k>0 \end{cases}$$

Dynamic program

Ford-Fulkerson

```
for each edge(u,v) in E f(u,v)=0
```

2. Find the residual networks $G_f = (v, E_f)$ of this flow

```
for each edge (u,v) in E
   Add edge (u,v) to E_f with residual capacity c[f] = c(u,v) - f(u,v)
   Add edge (u,v) to E_f with residual capacity c[f] = f(u,v)
   Parallel edges need to be aggregated into a single edge
   Drop edges with 0 capacity
```

3. Find a path p from s to t in G_f (use BFS) if no such path exists, output f as max flow

```
4. Let C_f(p) = min(c_f(e))

for each edge(u,v) in p
   if(u,v) is a foward edge in G
      f(u,v) += cf(p)
   else
      f(v,u) -=cf(p)

Go back to step 2
```

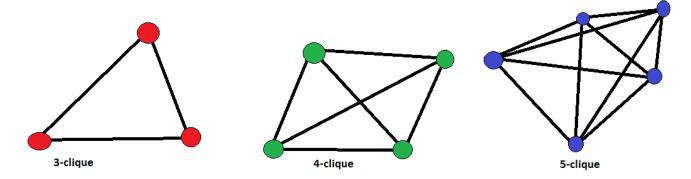
Below is a different way of looking at the problem

Input: given G=(V,E) with capacity c, source s, sink t, and path p Output: compute a flow f from s to t of maximum value

```
f(u,v) = 0 for all edges
while there is a path p from s to t in Gf such that cf(u,v) > 0 form all edges (u,v) in p
 Find cf(p) = min(cf(u,v)) across all u,v in p
 for each edge e=(u,v) in p
 f(u,v) = f(u,v) + cf(p)
 f(v,u) = f(v,u) - cf(p)
```

Clique examples

A subgraph where every node is connected to every other node in the subgraph



Vertex cover examples

A subset of vertices in an undirected graph where each of the vertices in the entire graph connects to at least one of the vertices in the subset

