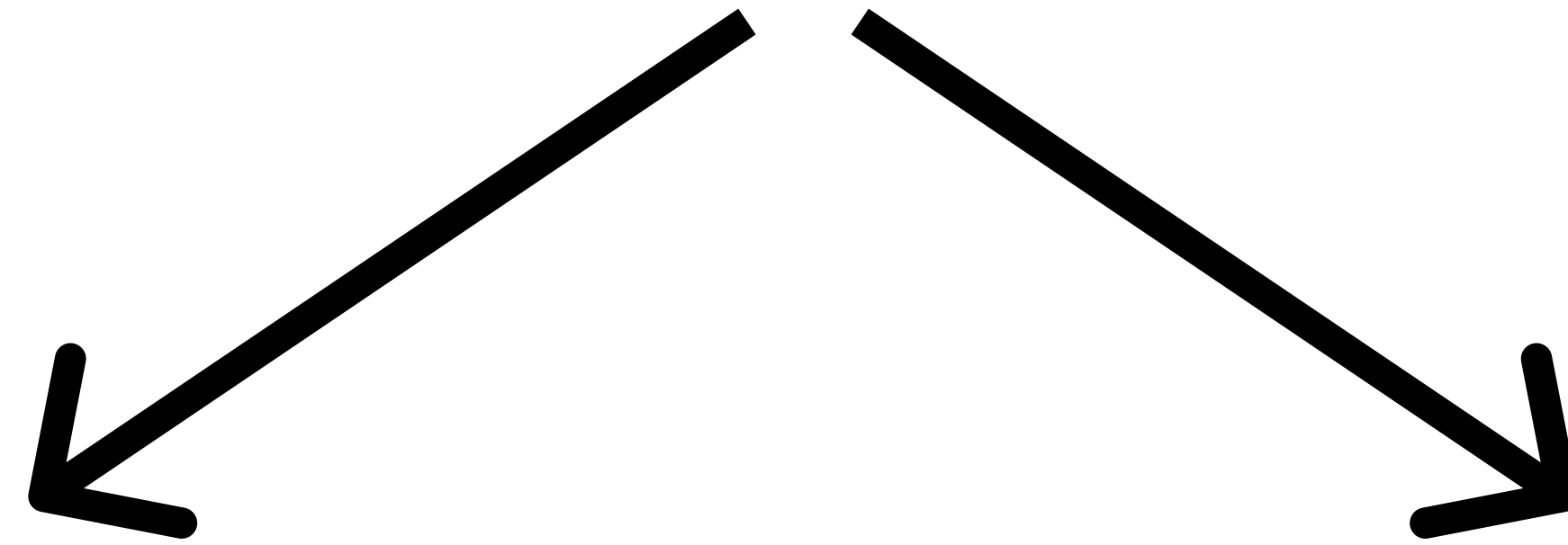
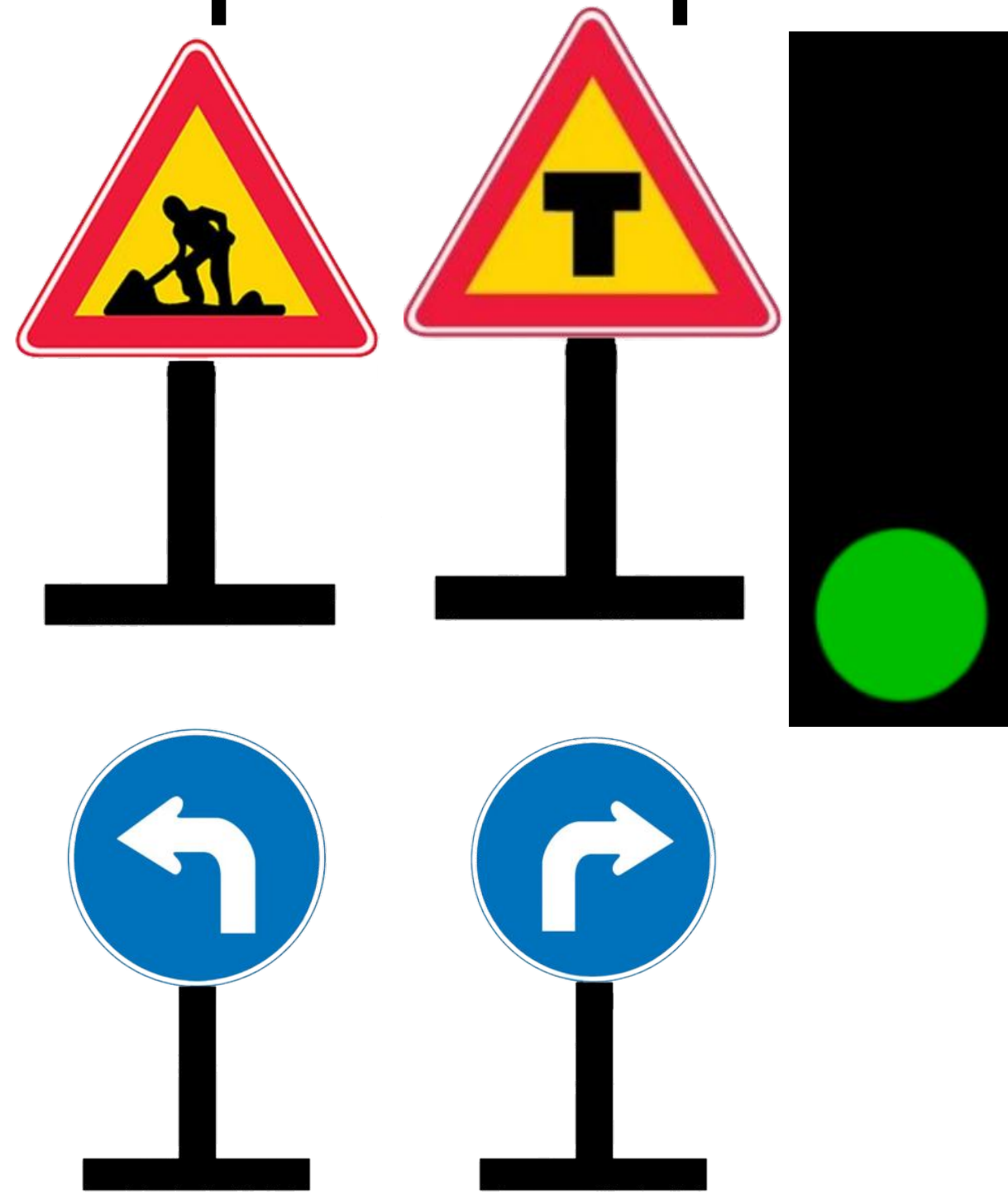


ROS-pypyni

Два ключевых узла



perception_node



lane_follower





