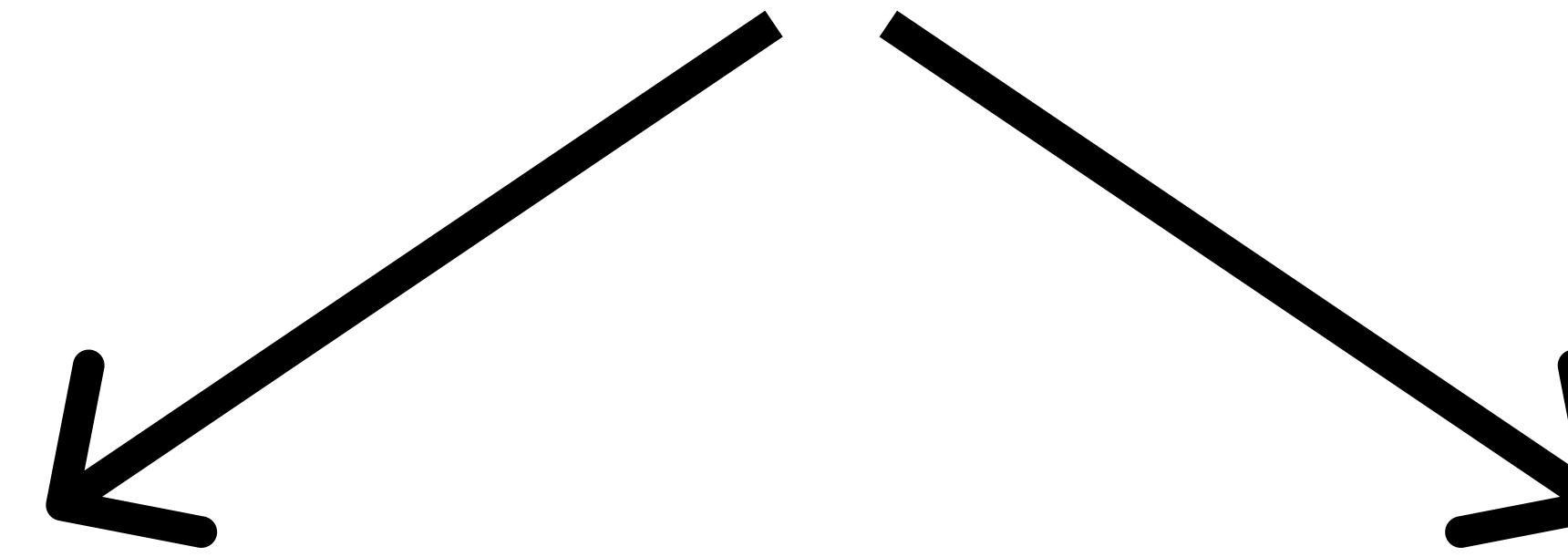
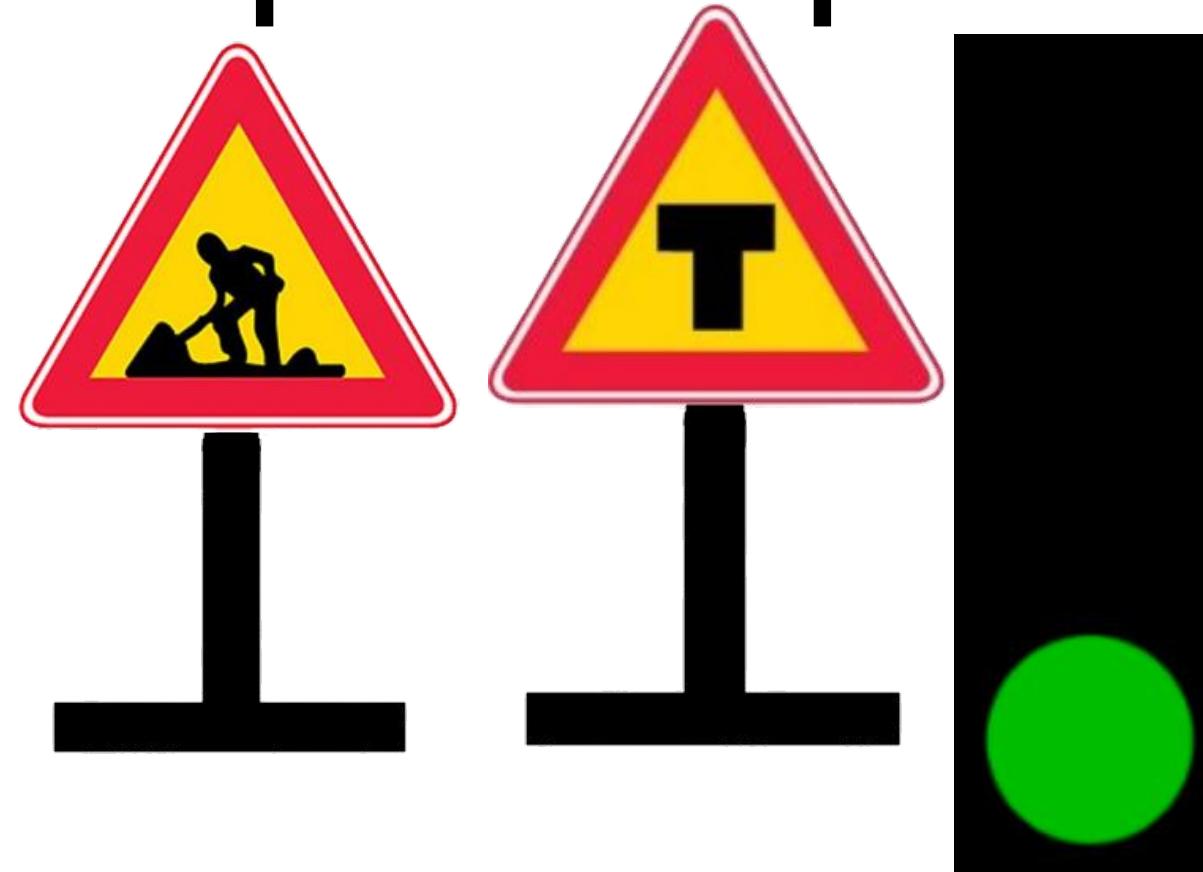


ROS-pypyjni

два ключевых узла



perception_node



lane_follower

