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| Mercury System |
| Slaves Generic Command Set |
| IoT and Connectivity Made Simple |

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| Francesco Ficili  19/11/2018 |

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**SUMMARY**

[1. Introduction 4](#_Toc530413282)

[2. Mercury System Slave Board 5](#_Toc530413283)

[3. Slaves Generic Command Set 6](#_Toc530413284)

# Introduction

This manual provides a description of the Mercury System Slaves Generic Command Set.

# Mercury System Slave Board

In order to develop applications, the Mercury System provides several different Slave Boards, each of them containing a specific peripheral (could be a particular sensor, an actuator, a communication device, etc.), managed by a local controller.

Each of these Slaves Devices implement a specific command set, used to virtualize the access to the specific sensor or actuator. This command set change from device to device and is strictly connected with the slave FW version (each FW version implements a specific set of Specific Commands or Services).

Apart from the specific command set, there is a second set of commands implemented by each Slave (SB or EB equipped with a local controller) in the same way, the so-called “Generic Command Set”. These are basic services that must be implemented by each slave and are strictly connected with the Slave Framework version used (each framework version implements a specific set of Generic Commands or Services).

# Slaves Generic Command Set

The following list of Generic Commands refers to the following Slaves Framework Version: **1.1.00**

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| --- | --- | --- | --- |
| Code | Cmd Name | Parameters | Description |
| 0x10 | Ping Cmd | None | Make a ping request to the addressed slave. The addressed slave prepares an “ECHO” string in response to this command (must be read with an appropriate read request if on I2C bus). Used to verify that the slave is present on the network. |
| 0x20 | Request Board ID Cmd | None | Request the Board ID (or name) string. The addressed slave prepares a 5 byte ID string in response to this command (must be read with an appropriate read request if on I2C bus). |
| 0x21 | Request Fwk Version Cmd | None | Request the Board Framework Version string. The addressed slave prepares an 8 byte Fwk Version string in response to this command (must be read with an appropriate read request if on I2C bus). |
| 0x22 | Request App Version Cmd | None | Request the Board Application Version string. The addressed slave prepares an 8 byte App Version string in response to this command (must be read with an appropriate read request if on I2C bus). |
| 0x30 | Board Reset | None | Request and hard reset to the board. After the reception to this command the addressed slaves immediately execute a SW reset. |
| 0x31 | Board LP Mode | None | Request the addressed slave to switch to low-power mode. The addressed slave can be woke-up with any other message. If the user wants to put the entire network in sleep, then the general call broadcasting scheme (address 0x00) could be used. |
| 0x41 | Control LED Behav. | LED Behav. (1 byte) | Set the board LED behavior:  0 = always off  1 = I2C Rx pulse (default)  2 = LED automatic blink  3 = Master direct control  The option 3 (master direct control) is implemented via service 0x42. |
| 0x42 | Control LED Direct | LED Sts (1 byte) | Control the user LED directly (0 = OFF; 1 = ON). |
| 0x45 | Request Die Temp Raw | None | This command requests the preparation of the DIE temperature ADC reading data in binary format, without any conversion in temperature scale. |
| 0x46 | Request Die Temp ASCII | None | This command requests the preparation of the DIE temperature data in ASCII format. The board will prepare 2byte of data containing the DIE temperature value in ASCII format, in Celsius scale. |