BIELEFELD UNIVERSITY

Masters Thesis

Simulating sedation-induced unconsciousness in a Neural-Mass-Model to improve algorithms for state-of-consciousness detection in patients with unresponsive wakefulness syndrome

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Abstract

Faculty of Technology Neuroinformatics Groups

Master of Science

Simulating sedation-induced unconsciousness in a Neural-Mass-Model to improve algorithms for state-of-consciousness detection in patients with unresponsive wakefulness syndrome

by Felix Friese

Patients with severe Traumatic Brain Injuries (TBI) often remain in a state of unresponsive wakefulness. Brain-Computer-Interface (BCI)-based systems promise to improve the state assessment and to open a communication channel for patients to express their intent while in conscious states. Developing such a BCI-System (e.g. with EEG), including the necessary algorithms to assess a patients current wakefulness or consciousness state from EEG data is a challenging task. Development, testing and evaluation of these algorithms requires labeled data (ground truth), which is almost impossible to obtain given the patients' lack of communication capabilities. Therefore, it would be desirable to generate a synthetic signal, which should ideally resemble real EEG data in all relevant features.

We previously developed a simple ICA-based model, which generates a multichannel EEG from base-signals with configurable spectral features. While this proved useful for testing numerous components of our signal-analysis framework, it lacks biological plausibility and explanatory power to model the changes in the signal's properties given an altered state of consciousness.

In this thesis, we propose an approach towards overcoming these issues while sticking with the original goal of generating realistic, practically useful surrogate data. A biologically motivated Neural Mass Model (NMM) on cortical-column level is implemented, which is able to approximate the effects of sedation-induced unconsciousness on the generated signal. The model is then shown to be able to reproduce the characteristic effects that sedation has on the EEG-Signals of real subjects. This is a first step to a model of consciousness-altering processes in the brain, which could ultimately be extended to realistically simulate other processes like sleep and trauma-induced DoC, facilitating better detection algorithms and furthering the goal to develop working BCI-Systems in the given context.

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List of Abbreviations

NMM Neural Mass Model

DoC Disorder of Consciousness
 TBI Traumatic Brain Injury
 BCI Brain Computer Interface

ICA Independent Component Analysis

 $\mathbf{PSP} \qquad \mathbf{Post\text{-}Synaptic\text{-}Potential}$

EPSP Excitatory Post-Synaptic-PotentialIPSP Inhibitory Post-Synaptic-Potential

 $\mathbf{GABA} \quad \mathbf{G}amma\text{-}\mathbf{A}mino\mathbf{b}utyric \ \mathbf{A}cid$

EEG Electroencephalography

PC Pyramidal Cell

EIN Excitatory Interneuron IIN Inhibitory Interneuron

Chapter 1

Introduction

TODO: go more into detail about the motivation and the challenges of developing stable signal processing algorithms for use cases with little (labeled) data

1.1 Related Work

TODO: Menon [9], Liang et al. [11], COALIA [14], ...

Chapter 2

Technical Concepts

2.1 States of Consciousness

2.1.1 Definition

TODO: which states of consciousness are commonly defined

2.1.2 State Transitions

2.1.2.1 Natural Transitions

TODO: how states transition into each other naturally

2.1.2.2 **Sedation**

TODO: how sedation differs from natural loss of consciousness

2.1.3 Disorders of Consciousness

TODO: the symptoms of DOCs

2.2 Neurobiology

TODO: straightforward recap of the basics, more focus on topic-relevant details

2.2.1 Membrane Potential

Nerve cells (neurons) have a resting membrane potential of roughly -70mV. This electric potential is the result of a multitude of factors that ultimately decide the different concentrations of ions inside and outside of the cell, which in turn cause the potential difference. The most important ions involved in this process are sodium (Na^+) , potassium (K^+) and chloride (Cl^-) .

These ions cannot simply cross the lipidbilayer of the cell membrane by themselves. To do that, they depend on special enzymes embedded into the membrane: ion-channels, ion-pumps and iontransporters. Ion-channels can either be permea

The most important ion-pumps are sodium-potassium pumps, which move potassium into the cell, while expelling sodium.

Sitting in the membrane are multiple kinds of ion-channels that can change the permeability for specific ions depending on certain factors. For example, voltage-gated channels open and close depending on the membrane potential, while ligand-gated channels are controlled by certain chemicals (neurotransmitters) binding to them.

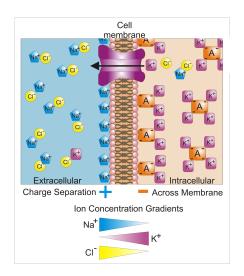


Figure 2.1: Membrane potential: Basic schema.

By Synaptidude - Own work, CC BY-SA 3.0 https://commons.wikimedia.org/wiki/File:Basis_of_Membrane_Potential2.png

A cell's resting potential primarily File:Basis_of_Membrane_Potential2.png depends on the equilibrium state of the potassium ions, where the influx of potassium ions due to the concentration gradient is equal to the efflux due the voltage gradient.

The membrane potential can leave it's resting state, when processes disturb this balance. Most commonly, when ligand-gated ion-channels open and let ions enter the cell. Depending on the type of ion, this can lead to depolarisation or hyperpolarization of the membrane potential. Because depolarization increases the chances of a neuron firing, this process is also described as *excitation*, while polarization, which in turn decreases that chance, is called *inhibition*.

2.2.1.1 Action Potential

When the membrane potential of a Neuron reaches a certain Threshold at the axon hillock, it triggers

2.2. Neurobiology 5

- 2.2.1.2 Synaptic Gap
- 2.2.1.3 Excitation and Inhibition
- 2.2.1.4 Post-Synaptic-Potential
- 2.2.1.5 Axon Hillock
- 2.2.1.6 Firing Rate
- 2.2.2 Consciousness on a neural level
- 2.2.2.1 Influence of GABA-A Sedatives

2.3 **EEG**

2.3.1 Measurement

TODO: how the EEG is measured technically and which neuronal processes it actually observes (signal amplification, pyramidal cells, ...)

2.3.2 Advantages/Disadvantages

TODO: spatial/temporal resolution, invasiveness, ...

2.3.3 States of Consciousness in the EEG Signal

TODO: how do the states differ in the signal

2.3.3.1 State Detection in healthy Subjects

TODO: rough explanation of prevalent algorithms

2.3.3.2 State Detection in Subjects with DOC

TODO: issues with data collection, structurally different source signal, ...

2.3.4 Simulation

2.3.4.1 Motivation

TODO: what can we hope to achieve by simulating an EEG signal

2.3.4.2 Approaches

TODO: which tools are at our disposal (naive frequency mixing, population models, simulating individual neurons, ...)

2.3.4.3 Model Choice

TODO: argue about models => why did we land on NMMs/population models?

2.4 Neural Mass Models

TODO: slightly deeper introduction (we already have this in the EEG section) to NMMs in general

2.4.1 The Jansen-Rit Model

The widely used Jansen-Rit Model [5], [6], is based on earlier models by Wilson & Cowan [1], Lopes da Silva et al. [2], [3] and Zetterberg et al. [4]. It represents a cortical column in the brain, which is made up of three main components, each modeling a population of neurons with distinct characteristics.

The basic schema of the model is visualized in Fig. 2.2, showing the connections

between the main components. There is a population of Pyramidal Cells which receives input from two populations of inter-neurons, one of which is excitatory while the other is inhibitory. Each of the inter-neuron-populations receives the output of the PC population. Additionally, there is external excitatory input to the PC population from other regions of the brain.

The Block Diagram (Fig. 2.3) shows the individual modules of the model. A population consists of two types of blocks: The *PSP-Block* models the behavior of the synapses and neuronal somata. It can be either excitatory or inhibitory and converts the incoming aver-

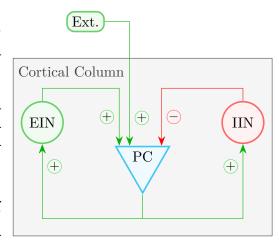


Figure 2.2: Basic Schema of the Jansen-Rit Model: Three populations of neurons

age pre-synaptic pulse density to an average post-synaptic membrane potential by convolving it with an impulse response function $(h_e(t))$ and $h_i(t)$, for excitation and inhibition respectively). The second block (sometimes called *Potential-To-Rate-Block* after it's functionality) calculates the populations response to this stimulation, transforming the incoming average membrane potential back into an average pulse density of action potentials. It may be roughly viewed as a functional counterpart to the axon hillock by establishing a firing threshold and is usually implemented by a Sigmoid Function (Sigm). External input from other regions of the brain is represented by p(t). The Connectivity Constants C_1 , C_2 , C_3 and C_4 are a proportional representation of the average number of synapses between the populations. The signal most closely related to the EEG and therefore the variable of interest, is the summed average membrane potential of the PC population $(y_1(t) - y_2(t))$ in Fig. 2.3).

TODO: explain neurophysiology why EEG $\approx y_1 - y_2$, or reference back to explanation in EEG section

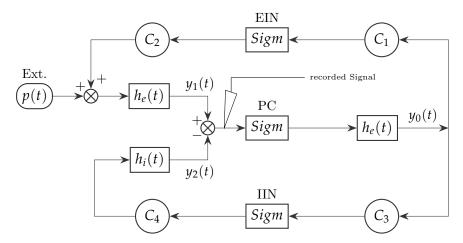


Figure 2.3: Simple Block Diagram after [6]: It's structure might be somewhat confusing when trying to visualize the biological analogy, where each population would have individual afferent PSP-Blocks. However, the fact that the two interneuron populations share a single excitatory PSP Block, because it produces identical results for both of them (disregarding their individual connectivity factor, which is simply applied afterwards), is a computational performance gain, thus likely explaining the authors' choice.

2.4.1.1 Potential-To-Rate Block

For a neuron to fire an action potential, its membrane potential needs to surpass a certain threshold. Since we are modeling not a single neuron but a whole population, we need an operator that can transform the mean membrane potential that the neurons of the population receive as input into an average firing rate for the whole population. While neurons within the population may have individual firing-thresholdit can be assumed due to their sheer number, that these thresholds are normally distributed around some mean value v_0 . An additional assumption that this approach rests on, is that the number of afferent (i.e. incoming) connections to the individual neurons is sufficiently large to justify the assertion that all neurons receive roughly the same stimulation. This must be modeled by a monotonically increasing function. The Potential-To-Rate Block represents this process with a Sigmoid. After multiple iterations by Zetterberg [4], Lopes da Silva [3] and others, Jansen and Rit [5], [6] landed on the following equation:

$$Sigm(v) = \frac{2e_0}{1 + e^{r(v_0 - v)}} \tag{2.1}$$

The parameter values (Table 2.1) are empirically determined [5]. The maximum firing rate the population can achieve is set at 5Hz. A mean membrane potential of 6mV (equal to the populations average firing threshold) elicits half of the maximum firing rate, while $\frac{0.56}{mV}$ defines the steepness. The plot in Fig. 2.4 visualizes these properties.

Parameter		Default Value	Unit
half of maximum firing rate	e_0	2.5	Hz
average firing threshold	v_0	6.0	mV
sigmoidal steepness	r	0.56	mV^{-1}

Table 2.1: Parameters of the Sigmoid Function

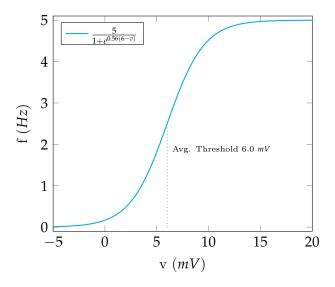


Figure 2.4: Sigmoid (Eq. 2.1) [5]

2.4.1.2 PSP-Blocks

In Physics, Linear Time-Invariant Systems (LTI systems) are oftentimes used to describe the response of electrical circuits to arbitrary input signals. They consist of a kernel function (or impulse-response function), that models the system's response to a single unit-impulse. The PSP-Blocks are an LTI system, fully represented by an impulse response function. It describes a PSP relative to the onset of a pulse. Since the PSP differs depending on the type of cell (excitatory or inhibitory) there are two different impulse-response functions. The parameters for the EPSP (Eq. 2.2) and IPSP (Eq. 2.3) are given in Table 2.2. The respective plots are visualized in Fig. 2.5.

Parameter	Default Value	Unit	
Exc \dot{m} ax \dot{a} mplitude / e	Α	3.25	mV
Lumped reprof sum of excdelays	а	100	Hz
Inh. max. amplitude / e	В	22	mV
Lumped reprof sum of inhdelays	b	50	Hz

Table 2.2: Parameters of the PSP Blocks

Excitatory impulse response:

$$h_e(t) = \begin{cases} Aate^{-at} & t \ge 0\\ 0 & t < 0 \end{cases}$$
 (2.2)

Inhibitory impulse response:

$$h_i(t) = \begin{cases} Bbte^{-bt} & t \ge 0\\ 0 & t < 0 \end{cases}$$
 (2.3)

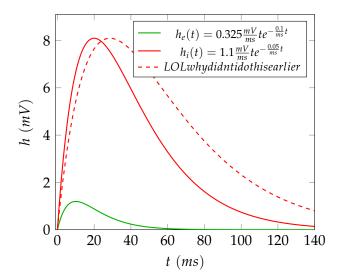


Figure 2.5: Impulse Response Functions: Note the small EPSP (Eq. 2.2) and the large IPSP (Eq. 2.3) [5]

Jansen and Rit [5] justify the difference in amplitude by referencing Lopes da Silva et al. [3] and stating that inhibitory neurons synapse closer to the somata of pyramidal cells (often on the cell body) than excitatory cells, increasing the effect of an inhibitory neuron about 10-fold.

TODO: maybe go more into detail about the reasons for stronger inhibition

The output of the Linear System defined by the PSP-Blocks is calculated by a convolution (denoted by *) of the incoming impulse density x(t) with the impulse response function h(t) (Eq. 2.4).

Remark (Convolution). The convolution of two functions f(t) and g(t) is defined as the integral of their product after one function has been reversed and shifted 1 :

$$f(t) * g(t) = \int_{-\infty}^{+\infty} f(\tau)g(t - \tau)d\tau$$

If f(t) is a unit-impulse $\delta(t)$ (in our case that would mean each cell of the previous population firing a single action potential at the same time) the result is just g(t) (in our case representing a single full-amplitude impulse response as the mean membrane potential):

$$\delta(t) * g(t) = \int_{-\infty}^{+\infty} \delta(\tau) g(t - \tau) d\tau = g(t)$$

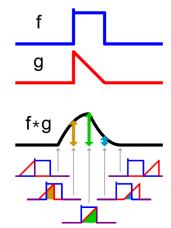


Figure 2.6: Convolution: The area enclosed by $f(\tau)$ and $g(t-\tau)$ is the value of (f*g)(t).

By $Cmglee - Own \ work, \ CC \ BY-SA \ 3.0$ https://commons.wikimedia.org/w/index. php?curid=20206883

¹There is a very intuitive explanation of convolutions by Kalid Azad on his website https://betterexplained.com/articles/intuitive-convolution/

In the general case, this process can be used to mathematically model the integration of incoming action potential densities in the soma.

Importantly, the Convolution Theorem states that the convolution of f(t) and g(t) becomes a simple multiplication when applying the Laplace Transform:

$$\mathcal{L}\lbrace f(t) * g(t) \rbrace = \mathcal{L}\lbrace f(t) \rbrace \mathcal{L}\lbrace g(t) \rbrace = F(s)G(s)$$

That means you can calculate a convolution with the inverse Laplace-Transform of the multiplication of the functions' individual Laplace-Transforms:

$$f(t) * g(t) = \mathcal{L}^{-1}{F(s)G(s)}$$

Since the convolution in the time-domain is a computationally heavy operation, it is oftentimes faster to transform the equation into the Laplace-Domain (see Eq. 2.5), apply the Convolution Theorem and perform the multiplication there, and transform the results back to the time-domain. This results in a second order differential equation (Eq. 2.6) that can be efficiently solved by numerical integration. To obtain this form, we need the Laplace transform $H_e(s)$ (in this context also called *Transfer Function*) of our response function $h_e(t)$:

$$H_e(s) = \mathcal{L}\{h_e(t)\} = \mathcal{L}\{Aate^{-at}\} = \frac{Aa}{(s+a)^2} = \frac{Aa}{s^2 + 2as + a^2}$$

With that, we can start to transform our initial equation into the desired Second Order System:

$$\underbrace{y(t)}^{\text{PSP}} = \underbrace{h_e(t)}^{\text{impulse response impulse density}}_{*} \times \underbrace{x(t)}^{*} \qquad (2.4)$$

applying the Laplace-Transform eliminates the convolution:

$$\stackrel{\mathcal{L}}{\iff} Y(s) = H_{e}(s) \cdot X(s) \qquad (2.5)$$

$$\iff Y(s) = \frac{AaX(s)}{s^{2} + 2as + a^{2}}$$

$$\iff (s^{2} + 2as + a^{2})Y(s) = AaX(s)$$

$$\iff s^{2}Y(s) + 2asY(s) + a^{2}Y(s) = AaX(s)$$

reversing the Laplace-Transform yields a differential equation in the time domain:

which can be expressed as a system of two coupled first order equations:

$$\dot{y}(t) = z(t) \tag{2.7}$$

$$\dot{z}(t) = Aax(t) - 2az(t) - a^2y(t)$$
 (2.8)

where y(t) is the resulting PSP and x(t) the incoming pulse density. This works analogously for the inhibitory case with $h_i(t)$.

TODO: maybe explain why
$$\mathcal{L}^{-1}\{sY(s)\} = \dot{y}(t)$$
 and $\mathcal{L}^{-1}\{s^2Y(s)\} = \ddot{y}(t)$

2.4.1.3 Full Linear System

Taking the two first order equations for $\dot{y}(t)$ (Eq. 2.7) and $\dot{z}(t)$ (Eq. 2.8), and the Block diagram (Fig. 2.7) as a base, we can now state the equations for the full Jansen-Rit Model with it's three populations. Each PSP-Block h(t) needs it's own system of coupled differential equations. The value of x(t) can be easily taken from the Block Diagram. $y_0(t)$ is the EPSP received by both the EIN and IIN population, while $y_1(t)$ is the EPSP and $y_2(t)$ the IPSP received by the PC population:

$$\dot{y}_{0}(t) = z_{0}(t)
\dot{z}_{0}(t) = AaSigm[y_{1}(t) - y_{2}(t)] - 2az_{0}(t) - a^{2}y_{0}(t)
\dot{y}_{1}(t) = z_{1}(t)
\dot{z}_{1}(t) = Aa(p(t) + C_{2}Sigm[C_{1}y_{0}(t)]) - 2az_{1}(t) - a^{2}y_{1}(t)
\dot{y}_{2}(t) = z_{2}(t)
\dot{z}_{2}(t) = Bb(C_{4}Sigm[C_{3}y_{0}(t)]) - 2bz_{2}(t) - b^{2}y_{2}(t)$$
(2.9)

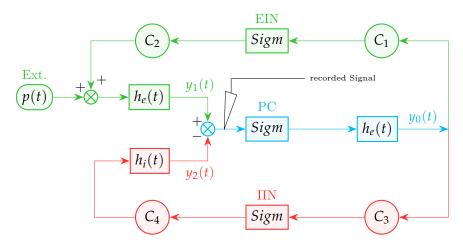


Figure 2.7: Colored Block diagram, visualizing the components of (Eq. 2.9)

2.4.1.4 Connectivity Constants

A sensible choice for the Connectivity Constants C_1 to C_4 was determined by Jansen and Rit empirically by defining a histologically motivated relationship between them $(C_1 = \frac{C_2}{0.8} = \frac{C_3}{0.25} = \frac{C_4}{0.25})$ and varying C_1 until the system produced the desired natural alpha-like activity at $C_1 = 135 \Rightarrow C_2 = 108$; $C_3 = C_4 = 33.75$. Varying C_1 can account for common synaptic phenomena like neurotransmitter depletion [6].

TODO: go more into detail about the biological motivation and the effects of these constants on the generated signal

2.4.1.5 Model Input

The model input p(t) represents the average activity of populations outside of the modeled column that synapse on the columns PC population. Since this activity's source is so diverse, it is modeled by white noise (120-320 Hz).

TODO: go more into detail why the input is modeled like this

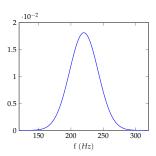


Figure 2.8: Input distribution. The input frequency representing p(t) is sampled from a normal distribution with $\mu = 220$ and $\sigma = 22$

2.4.1.6 Model Output

The simulated data from y_1-y_2 while varying C looks like this:

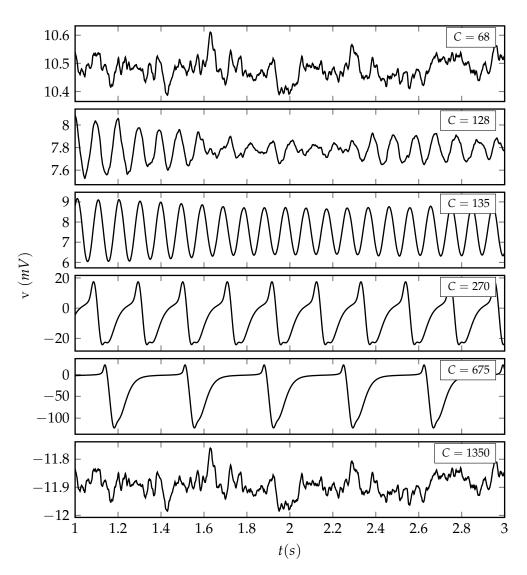


Figure 2.9: Model Output for varying C. Well defined alpha-activity is visible at C=135.

TODO: Explain Graph, generally provide more information to the systems output

2.4.2 The David and Friston Model

Section Incomplete the whole David-Friston-Section is still very much preliminary

While the Jansen-Rit model succeeds in generating realistic alpha activity, real EEG Signals contain much richer spectra [7]. David and Fristion [8] proposed a modification to the Jansen-Rit model, that could produce a more realistic frequency spectrum by introducing sub-populations to the model. They can be tuned individually to produce oscillations in different frequencies.

2.4.2.1 Introducing sub-populations

David and Friston slightly redefine h(t) by introducing the parameters H and τ (see Table 2.3), which is just a minor alteration of A and a.

$$h(t) = Aate^{-at} = > h(t) = \frac{H}{\tau} te^{-\frac{1}{\tau}}$$

Furthermore, as they are tweaking these parameters to produce slower or faster sub-populations, they define the products $H_e\tau_e=0.0325mVs$ and $H_i\tau_i=0.44mVs$ as constants. This is done to preserve the oscillatory behavior of each population [8]. When varying τ , H is therefore adjusted accordingly $(H_e=\frac{0.0325mVs}{\tau_e},\ H_i=\frac{0.44mVs}{\tau_i})$.

Parameter	Value	Unit	Relation to [6]	
Excitatory delays	$ au_e$	0.01	s	$ au_e = rac{1}{a}$
Inhibitory delays	$ au_i$	0.02	S	$ au_i = rac{1}{b}$
Excitatory synaptic gain	H_e	3.25	mV	$H_e = A$
Inhibitory synaptic gain	H_i	22	mV	$H_i = B$

Table 2.3: Parameters of the PSP Blocks after [8]

Attention: From now on, the indices [0,...,N] for y, h, τ and H refer only to the subpopulations within a single population. The indices used above in the formulation for the Simple Jansen-Rit Model (and the Block Diagram) should not be confused with these. However, e and i as indices still denote excitatory and inhibitory populations respectively.

By introducing subpopulations, we split up the general impulse response function h(t) in N individual subfunctions:

$$h_n(t) = \frac{H_n}{\tau_n} t e^{-\frac{1}{\tau_n}}$$

The previously defined general PSP-Block Equation:

$$y(t) = h(t) * x(t)$$

then becomes:

$$y(t) = \sum_{n=0}^{N} (w_n \cdot h_n(t) * x(t))$$
 with $\sum_{n=0}^{N} w_n = 1$ and $0 \le w_n \le 1$

with N individually weighted (w_n) and parameterized $(h_n(t))$ subpopulations. We can then declare:

$$y_n(t) = h_n(t) * x(t)$$
 and $y(t) = \sum_{n=0}^{N} (w_n y_n)$

which produces the following differential equations for a single PSP Block:

$$\dot{y}_{0}(t) = z_{0}(t)$$

$$\dot{z}_{0}(t) = \frac{H_{0}}{\tau_{0}}x(t) - \frac{2}{\tau_{0}}z_{0}(t) - \left(\frac{1}{\tau_{0}}\right)^{2}y_{0}(t)$$
...
$$\dot{y}_{N}(t) = z_{N}(t)$$

$$\dot{z}_{N}(t) = \frac{H_{N}}{\tau_{N}}x(t) - \frac{2}{\tau_{N}}z_{N}(t) - \left(\frac{1}{\tau_{N}}\right)^{2}y_{N}(t)$$

$$y(t) = w_{1}y_{1} + ... + w_{N}y_{N}$$

$$(2.10)$$

David and Friston further propose an example with two subpopulations for each population with the following parameters: $\tau_{e_1} = 10.8ms$, $\tau_{i_1} = 22ms$, $\tau_{e_2} = 4.6ms$, $\tau_{i_2} = 2.9ms$. While the kinetics for the first subpopulation were still close to those of the original populations ($\tau_e = 10ms$, $\tau_i = 20ms$, which produce alpha-activity), the second population's parameters were chosen to produce gamma activity.

TODO: put the values in a table

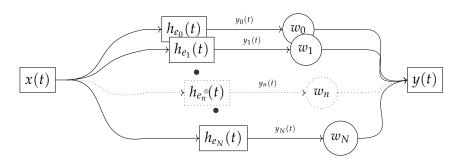


Figure 2.10: Example of subpopulations $(h_{e_0}(t),...,h_{e_N}(t))$ forming an excitatory population $h_e(t)$

2.4.3 New PSP Functions

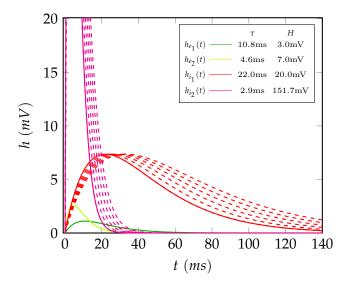


Figure 2.11: PSP functions for:

Chapter 3

Methodology

3.1 PyRates Framework

Section Incomplete The whole PyRates section is still very much preliminary

The PyRates Framework is a Python software framework, written by Richard Gast and Daniel Rose at the Max-Plank-Institute in Leipzig. It can simulate a wide range of graph-representable neural models, while setting a focus on rate-based population models [15]. It wraps computational backends like Numpy and Tensorflow and offers predefined nodes and edges (components that model units like cells or cell populations and the connections between them with mathematical equations) to be used, replaced or extended with custom equations. Furthermore it provides two simple ways to define these components and the derived network configurations: either by YAML-File or within Python code. These configurations are then compiled into optimized executable code with respect to the chosen backend before being executed. It comes with pre-configured model-definitions for some of the most frequently used models, e.g. the basic Jansen-Rit Circuit [6] and the Montbrio-Model [12], as well as some variations thereof. It's ease of use, the fact that it could easily reproduce the characteristics of the basic Jansen-Rit model out of the box, and the open-source character made it a sensible choice for this thesis.

3.1.1 Network Representations

3.1.1.1 YAML Representation

```
JansenRitSynapse: # name of the template
         description: ... # optional descriptive text
 2
         base: OperatorTemplate # parent template or Python class to use
 3
         equations: # unordered list of equations
         - 'd/dt * V = V_t'
         - 'd/dt * V_t = h/tau * r_in - (1./tau)^2 * V - 2.*1./tau*V_t'
         - 'd/dt * V_t = h/tau * r_in - (1./tau)^2 * V - 2.*1./tau*V_t'
         variables: # additional information to define variables in equations
             r_in:
                 default: input # defines variable type
10
             ۷:
11
                 default: output
12
             V_t:
13
                 description: integration variable # optional
                 default: variable
15
             tau:
16
                 description: Synaptic time constant
17
                 default: constant
19
                 default: constant
20
```

Figure 3.1: Example YAML Synapse

```
JansenRitCircuit:
1
         base: CircuitTemplate
         nodes: # list nodes and label them
3
             EIN: ExcitatoryInterneurons
             IIN: InhibitoryInterneurons
             PC: PyramidalCellPopulation
         edges: # assign edges between nodes
         # [<source>, <target>, <template_or_operators>, <values>]
         - [PC/PRO/r_out, IIN/RPO_e/r_in, null, {weight: 33.75}]
         - [PC/PRO/r_out, EIN/RPO_e/r_in, null, {weight: 135.}]
10
         - [EIN/PRO/r_out, PC/RPO_e/r_in, null, {weight: 108.}]
11
         - [IIN/PRO/r_out, PC/RPO_i/r_in, null, {weight: 33.75}]
```

Figure 3.2: Example YAML Circuit

3.1.1.2 Python Representation

```
from pyrates.frontend import OperatorTemplate
1
     from copy import deepcopy
2
3
     pro = OperatorTemplate(
         name='PRO', path=None,
5
         equations=[
6
              # R_{out} = \frac{2e_0}{1 + e^{r(v_0 - v)}}
              "rate_out = 2.*e_0 / (1 + exp(r*(v_0 - v)))"],
8
         variables={
9
              'rate_out': {'default': 'output'}, # output pulse density mout
10
              'v': {'default': 'input'}, # incoming avg. membrane potential v
11
              'v_0': {'default': 6e-3}, # avg. firing thresh. v_0 = 6mV
12
              'e_0': {'default': 2.5}, # half of max. firing rate e_0 = 2.5Hz
              'r': {'default': 560.0}}, # sigmoidal steepness r = 560V^{-1}
14
         description="sigmoidal potential-to-rate operator")
15
16
     rpo_e = OperatorTemplate(
^{17}
         name='RPO_e', path=None,
18
         equations=[
19
              # \dot{y}(t) = z(t)
20
              'd/dt * y = z',
21
              # \dot{z}(t) = \frac{H}{\tau}x(t) - \frac{2}{\tau}z(t) - \frac{1}{\tau}^2 y(t)
22
              'd/dt * z = H/tau * x - 2 * z/tau - y/tau^2'],
23
         variables={
24
              'y': {'default': 'output'}, # output membrane potential y(t)
25
              'z': {'default': 'variable'}, # helper variable z(t)=\dot{y}(t)
              'x': {'default': 'input'}, # incoming pulse density x(t)
27
              'tau': {'default': 0.01}, # exc. delays \tau_e = 0.01s
28
              'H': {'default': 0.00325}}, # exc. synaptical gain H_e = 3.25mV
         description="excitatory rate-to-potential operator")
30
31
32
     rpo_i = deepcopy(rpo_e).update_template(
         name='RPO_i', path='',
33
         variables={
34
              'tau': {'default': 0.02}, # inh. delays \tau_i = 0.02s
35
              'H': {'default': 0.022}}, # inh. synaptical gain H_i=22mV
36
         description="inhibitory rate-to-potential operator")
37
38
```

Figure 3.3: Python Example for the relevant Operators

3.1.2 Implementation of the Jansen-Rit Model

PyRates works with population models by compositing multiple operators, like the PSP- (or Rate-To-Potential-) and Sigmoid- (or Potential-To-Rate) Block into nodes. These nodes represent populations that can then be connected via edges (synapses). For example one might combine two PSP-Blocks (for excitatory and inhibitory input respectively) with a Sigmoid Block to create a PC-Node. This node can then receive

rate-input to each of it's PSP-Blocks and produces rate-output from it's Sigmoid-Block. The EIN- and IIN- nodes are functionally identical and just combine an excitatory PSP-Block with a Sigmoid Block. By connecting these Blocks (see Fig. 3.4) and adding random input to the excitatory PSP-Block of the PC-Node, the simple Jansen-Rit Circuit is already complete.

$$\frac{d}{dt}PSP_{EIN} = PSP_{t_{EIN}}$$

$$\frac{d}{dt}PSP_{t_{EIN}} = \frac{H_e}{\tau_e} \cdot C_1Sigm[PSP_{PC}] - \frac{2}{\tau_e} \cdot PSP_{t_{EIN}} - \left(\frac{1}{\tau_e}\right)^2 \cdot PSP_{EIN}$$

$$\frac{d}{dt}PSP_{IIN} = PSP_{t_{IIN}}$$

$$\frac{d}{dt}PSP_{t_{IIN}} = \frac{H_e}{\tau_e} \cdot C_3Sigm[PSP_{PC}] - \frac{2}{\tau_e} \cdot PSP_{t_{IIN}} - \left(\frac{1}{\tau_e}\right)^2 \cdot PSP_{IIN}$$

$$\frac{d}{dt}PSP_{PC_E} = PSP_{t_{PC_E}}$$

$$\frac{d}{dt}PSP_{t_{PC_E}} = \frac{H_e}{\tau_e} \cdot (p(t) + C_2Sigm[PSP_{EIN}]) - \frac{2}{\tau_e} \cdot PSP_{t_{PC_E}} - \left(\frac{1}{\tau_e}\right)^2 \cdot PSP_{PC_E}$$

$$\frac{d}{dt}PSP_{PC_I} = PSP_{t_{PC_I}}$$

$$\frac{d}{dt}PSP_{t_{PC_I}} = \frac{H_i}{\tau_i} \cdot C_4Sigm[PSP_{IIN}]) - \frac{2}{\tau_i} \cdot PSP_{t_{PC_I}} - \left(\frac{1}{\tau_i}\right)^2 \cdot PSP_{PC_I}$$

$$PSP_{PC} = PSP_{PC_E} - PSP_{PC_I}$$

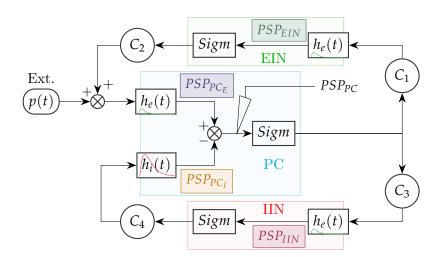


Figure 3.4: Jansen-Rit Block Diagram as implemented in PyRates: Each population can be clearly identified by one or more afferent PSP-Blocks and a single Sigmoid that calculates the populations output. This approach is more modular and simplifies conceptual understanding while staying mathematically equivalent. However, due to the explicit fourth PSP-Block it gives up the performance boost.

TODO: possibly the backend-graph-optimization takes care of this? maybe check this later on...

3.1.3 Implementation of the David & Friston extensions

```
rpo_e = OperatorTemplate(
 1
          name='RPO_e', path=None,
2
3
           equations=[
               #----
                # Subpopulation 0: h_0(t)
 5
                # \dot{y}_0 = z_0
 6
                'd/dt * y_0 = z_0',
               # \dot{z}_0 = \frac{H_0}{\tau_0} x - \frac{2}{\tau_0} z_0 - \frac{1}{\tau_0}^2 y_0
                'd/dt * z_0 = H_0/tau_0 * x - 2./tau_0 * z_0 - (1./tau_0)^2. * y_0'
9
10
               # Subpopulation 1: h_1(t)
11
                # \dot{y}_1 = z_1
12
                'd/dt * y_1 = z_1',
13
               # \dot{z}_1 = \frac{H_1}{\tau_1} x - \frac{2}{\tau_1} z_1 - \frac{1}{\tau_1}^2 y_1
                'd/dt * z_1 = H_1/tau_1 * x - 2./tau_1 * z_1 - (1./tau_1)^2. * y_1',
15
16
                # Population output:
^{17}
                \# y = \sum_{n=0}^{N} (w_n y_n)
18
                'PSP = w_0*y_0 + w_1*y_1'
19
20
                ],
21
           variables={
22
                'PSP': {'default': 'output'},
                **{var: {'default': 'variable'} for var in ['y_0', 'y_1', 'z_0', 'z_1']},
24
                'x': {'default': 'input'},
25
                'w_0': {'default': 1.0},
26
                'w_1': {'default': 0.0},
27
                'tau_0': {'default': tau_0},
28
                'tau_1': {'default': tau_1},
                'H_0': {'default': h_0},
30
                'H_1': {'default': h_1}},
31
           description="rate-to-potential operator")
```

Figure 3.5: PSP Block with two Sub-populations in PyRates

3.1.4 Simulating GABA-A Sedatives

TODO: why does the reduction of C represent inhibition of the whole system - what is the difference between thalamic regulation (natural sleep, etc) and GABA-A-receptor binding substances (sedation)?

TODO: do we have other ways of simulating sedatives in the system?

Chapter 4

Results

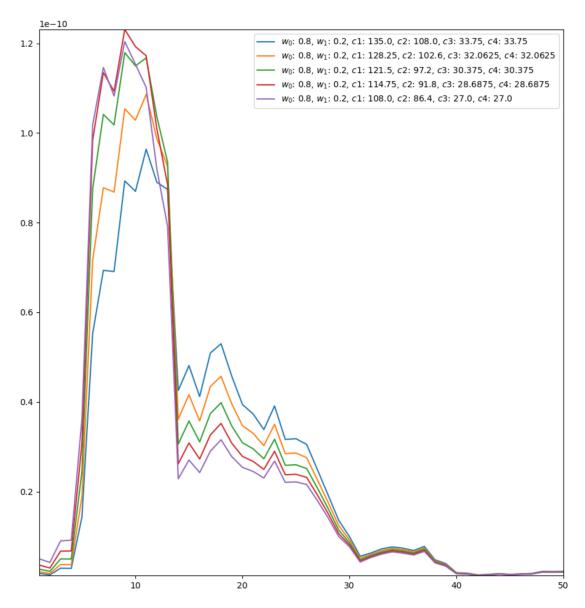


Figure 4.1: Power Spectral Density of Simulation Results: Reduction of the connectivity parameter C from 135 to 108 shows a tendency of reducing the strength of the frequency-bands above 12-14Hz, while increasing it below that value - especially around 8-12Hz.

TODO: objective description of simulation results

Chapter 5

Discussion

5.1 Comparison with real EEG Data during Propofol-Sedation

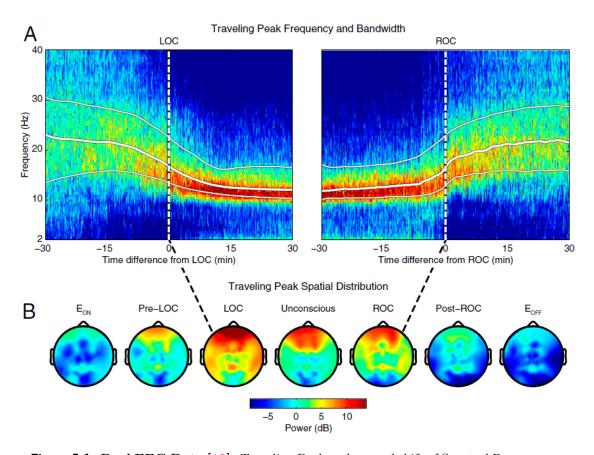


Figure 5.1: Real EEG Data [10]: Traveling Peak and general shift of Spectral Power from above 20 to the 10Hz Range during sedation. Also note the power increase in the very slow frequencies.

TODO: compare to Purdon [10], Lee [13]

5.2 Outlook

TODO: how this could be extended towards our goal (include thalamus like in COALIA, find ways to simulate TBI-induced DOC more specifically, create combination of conditions and states of awareness in the same model, ...)

Appendix A

PyRates Implementation Code

```
import numpy as np
      import matplotlib.pyplot as plt
       import scipy.signal
       from pyrates.frontend import OperatorTemplate, NodeTemplate, CircuitTemplate
      from pyrates.utility.data_analysis import fft
from pyrates.utility.grid_search import grid_search
10
      def create_pro(name):
11
         return OperatorTemplate(
              name=name, path='',
13
               equations=["rate_out = m_max / (1 + exp(r*(v_0 - PSP)))"],
               variables={'rate_out': {'default': 'output'},
15
                          'PSP': {'default': 'input'},
                          'v_0': {'default': 6e-3},
                          'm_max': {'default': 5.},
                          'r': {'default': 560.0}},
19
               description="sigmoidal potential-to-rate operator")
^{21}
      def create_rpo(name, tau_0, tau_1, h_0, h_1):
23
         return OperatorTemplate(
^{24}
               name=name, path='',
^{25}
               equations=['d/dt * y_0 = z_0'],
26
                          'd/dt * z_0 = H_0/tau_0 * rate_in - (1./tau_0)^2. * y_0 - 2. * 1./tau_0 * z_0',
27
28
                          'd/dt * z_1 = H_1/tau_1 * rate_in - (1./tau_1)^2. * y_1 - 2. * 1./tau_1 * z_1',
29
                          'PSP = w_0*y_0 + w_1*y_1',
30
               variables={'PSP': {'default': 'output'},
                          'y_0': {'default': 'variable'},
31
32
                          'y_1': {'default': 'variable'},
33
                          'z_0': {'default': 'variable'},
                          'z_1': {'default': 'variable'},
34
35
                          'rate_in': {'default': 'input'},
36
                          'w_0': {'default': 1.0},
37
                          'w_1': {'default': 0.0},
38
                          'tau_0': {'default': tau_0},
39
                          'tau_1': {'default': tau_1},
                          'H_0': {'default': h_0},
40
41
                          'H_1': {'default': h_1}},
42
               description="rate-to-potential operator")
43
44
       def subpopulation_model():
45
46
              Creates a Jansen-Rit Circuit with two subpopulations in each rate-to-potential operator
47
48
               as proposed by David and Friston
49
50
           pro = create_pro(name='PRO')
           pro_pc = create_pro(name='PRO_pc')
51
52
           # subpopulation parameters taken from the paper
53
54
           tau_e = [10.8e-3, 4.6e-3]
           tau_i = [22e-3, 2.9e-3]
55
56
           h_e = [3.25e-3 * 10e-3 / tau for tau in tau_e]
57
58
           h_i = [-22e-3 * 20e-3 / tau for tau in tau_i]
```

```
rpo_e = create_rpo('RPO_e', tau_e[0], tau_e[1], h_e[0], h_e[1])
 60
            61
 62
 63
            \label{eq:rpo_i} {\tt rpo\_i} = {\tt create\_rpo('RPO\_i', tau\_i[0], tau\_i[1], h\_i[0], h\_i[1])}
 64
            ein = NodeTemplate(name="EIN", path='', operators=[pro, rpo_e])
 65
            iin = NodeTemplate(name="IIN", path='', operators=[pro, rpo_e])
 66
            pc = NodeTemplate(name="PC", path='', operators=[pro_pc, rpo_e_pc, rpo_i])
 67
 68
 69
            for rp in [rpo_i, rpo_e, rpo_e_pc]:
 70
                print(rp.equations)
 71
                print(rp.variables)
 72
 73
            jrc = CircuitTemplate(
                name="JRC", nodes={'PC': pc, 'EIN': ein, 'IIN': iin},
 74
 75
                edges=[
 76
                       ("PC/PRO_pc/rate_out", "EIN/RPO_e/rate_in", None, {'weight': 135.}),
                        ("EIN/PRO/rate_out", "PC/RPO_e_pc/rate_in", None, {'weight': 108.}),
 77
                       ("PC/PRO_pc/rate_out", "IIN/RPO_e/rate_in", None, {'weight': 33.75}), ("IIN/PRO/rate_out", "PC/PRO_i/rate_in", None, {'weight': 33.75})],
 78
 79
                path='')
 80
 81
            return jrc
 82
 83
 84
        def simulate(template, step_size, sampling_step_size, seconds, cutoff):
 85
 86
               Performs a grid search for w (mix the subpopulations)
 87
 88
            ws = np.arange(0, 1.1, 0.2)
 89
            param_grid = {
                 'w_0': [round(w, 1) for w in ws],
 90
                'w_1': [round(1-w, 1) for w in ws],
 92
            param_map = {
 94
                 'w_0': {
 95
                    'vars': ['RPO_e/w_0',
                              'RPO_e_pc/w_0',
 97
                             'RPO_i/w_0'], 'nodes': ['PC', 'EIN', 'IIN']},
 98
 99
                     'vars': ['RPO_e/w_1',
100
101
                             'RPO_i/w_1'], 'nodes': ['PC', 'EIN', 'IIN']},
102
103
            size = (int(np.round(seconds / step_size, decimals=0)), 1)
104
105
            results, results_map = grid_search(circuit_template=template,
106
                                                param_grid=param_grid,
107
                                                param_map=param_map,
108
                                                simulation_time=seconds,
109
                                                step_size=step_size,
110
                                                sampling_step_size=sampling_step_size,
111
                                                inputs = \{ \begin{tabular}{ll} PC/RPO\_e\_pc/p': np.random.normal(loc=220.0, scale=22.0, size=size) \}, \end{tabular}
112
                                                outputs={'I0_pce': 'PC/RP0_e_pc/y_0',
113
                                                         'I1_pce': 'PC/RPO_e_pc/y_1',
114
                                                         'I0_pci': 'PC/RPO_i/y_0'
                                                        'I1_pci': 'PC/RP0_i/y_1'},
115
116
                                                init_kwargs={'backend': 'numpy', 'solver': 'scipy'},
117
                                                verbose=False,
118
                                                permute_grid=False)
119
            results = results.loc[cutoff:1
120
121
            results = (results['I0_pce'] + results['I0_pci'])*results_map.loc[:, 'w_0'].values + \
                      (results['I1_pce'] + results['I1_pci'])*results_map.loc[:, 'w_1'].values
122
123
124
            return results, results map, sampling step size
125
126
        def plot(results, results_map, sampling_step_size):
127
128
               Plot the resulting signals and their spectrum
129
130
131
            fig = plt.figure(figsize=(8, 12))
            fig.suptitle('David and Friston (2003) Fig.5')
132
            gs = fig.add_gridspec(len(results_map), 2)
133
134
135
            def periodogram(data, fs, freg range):
136
                _f, power = scipy.signal.periodogram(data, fs)
137
                selection = np.where((freq\_range[0] \leqslant \_f) \& (\_f \leqslant freq\_range[1]))
                f = _f[selection]
138
139
                power = power[selection]
                return f, power
140
```

```
141
             def welch(data, fs, freq_range):
142
143
                 w_{len} = min(4096, int(len(data) / 2))
                 win = scipy.signal.windows.hamming(w_len)
144
                 _f, power = scipy.signal.welch(data, fs, nperseg=w_len,
145
                                                  noverlap=int(w_len / 2), window=win)
146
147
                 power ⊨ np.sum(power)
                 selection = np.where((freq\_range[0] \leq _f) & (_f \leq freq\_range[1]))
148
149
                 return _f[selection], power[selection]
150
151
152
             def simple_fft(data, fs, freq_range):
153
                 n = len(data)
154
                 # Get closest power of 2 that includes n for zero padding
155
156
                 n_{to} = 1 if n = 0 else 2 ** (n - 1).bit_length()
157
158
159
                 data_tmp = data_tmp - np.mean(data_tmp)
160
161
                 freqs = np.linspace(0, fs, n_two)
162
                 spec = np.fft.fft(data_tmp, n=n_two, axis=0)
163
164
                 # Cut of PSD and frequency arrays since its mirrored at N/2
                 power = np.abs(spec[:int(len(spec) / 2)])
166
                 10 * np.log10(np.power(power, 2))
                 _f = freqs[:int(len(freqs) / 2)]
167
                 \texttt{selection = np.where((freq\_range[0] \leqslant \_f) \& (\_f \leqslant freq\_range[1]))}
169
                 f = _f[selection]
                 power = power[selection]
171
                 return f, power
173
             for row, key in enumerate(results_map.index):
174
175
176
                 ws = [results_map.at[key, c] for c in results_map.columns]
177
                 v_{b} = ", ".join([f'${key} = {w}$' for key, w in zip(results_map.columns, ws)])
178
179
                  \begin{tabular}{ll}      \#psp\_0 = results.loc[:, ('I0\_pce', key)] + results.loc[:, ('I0\_pci', key)] \\      \#psp\_1 = results.loc[:, ('I1\_pce', key)] + results.loc[:, ('I1\_pci', key)] \\      \end{tabular} 
180
181
182
                 \#v = psp_0*ws[0] + psp_1*ws[1]
183
                 \#v = psp\_0 + psp\_1
184
                 #v = results.loc[:, (key,)]
185
                 v = results.iloc[:, row]
186
                 ax = fig.add_subplot(gs[row, 0])
187
                 {\tt ax.plot(results.index,\ v,\ label=v\_lb,\ color=f'C\{row\}')}
188
                 ax.legend(loc='upper right')
189
                 ax.margins(0.0)
190
191
                 ax2 = fig.add_subplot(gs[row, 1])
192
                 ax2.margins(0.0)
193
                 ax2.plot(*simple_fft(data=np.squeeze(v.values), fs=1/sampling_step_size, freq_range=(0.1, 100)),
194
                          label=v_lb, color=f'C{row}')
195
                 ax2.legend(loc='upper right')
196
                 row += 1
             plt.tight_layout()
197
198
             plt.show()
199
200
        if name = ' main ':
201
202
203
             res = []
204
             for i in range(1):
205
                 results, results_map, sampling_step_size = simulate(template=subpopulation_model(),
206
                             step_size=1e-4, # choosing 1e-3 here does not really make a difference
207
                             sampling step size=1e-3.
                             seconds=2.0, cutoff=1.0)
208
                 res.append(results)
209
210
             results = sum(res) / len(res)
211
212
             plot(results, results_map, sampling_step_size)
213
             # plot(*simulate(template=subpopulation_model(),
                               step_size=1e-4, # choosing 1e-3 here does not really make a difference
^{214}
                               sampling_step_size=1e-3,
215
216
                              seconds=2.0, cutoff=1.0))
```

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