

A Derivative-free Optimization Approach for Automated As-built 3D Modelling

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Outline







Background & Opportunity



As-built Modeling via Optimization



Discussion & Future Research

Section 1 **BACKGROUND & OPPORTUNITY**



1.1 As-built 3D modeling of civil infrastructures







- Construction management
- Facility management
- Built env. conservation
- Business with VR/AR, etc.





- Photogrammetry (videogrammetry)
- Point cloud
- 3D Geographic information system
- Others (statistical rules, deep learning [3], etc.)











An example of photogrammetry: Kowloon Wall City (Source: patrick-@sketchfab.com)



An example of point cloud: Pompei City (Source: MAP-Gamsau lab, CNRS, France)



An example of GIS-based: 3D Berlin (Open Data, source: berlin.de)



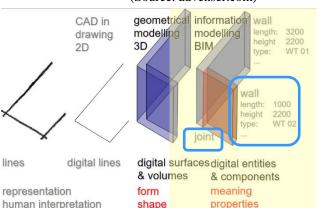
1.1 Final goal: Semantically rich as-built BIM



- ♦ BIM (building information model, narrow sense)[2]
 - The digital representation of physical and functional characteristics of a facility
 - A shared knowledge resource for information about a facility serving as a reliable basis for decisions making
 - ♦ Two types of semantic information in BIM^[2, 4-5]
 - Attributes of an individual construction component
 - geometric (e.g., size, position, shape, & textures)
 - o non-geometric (e.g., type, material, & functions)
 - *Relationships* between components
 - o *E.g.*, dependency, topology, and joints



A word cloud of BIM (Source: advenser.com)



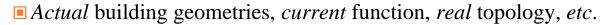
An evolution view of CAD model/BIM [6]



1.1 Final goal: Semantically rich as-built BIM



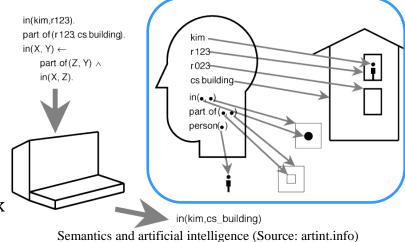




o In addition to the surface of the building envelope

• Advancing the knowledge frontiers of

- Smart city applications
- Heathy aging scenarios
- Robotics and computer vision
- Artificial intelligence, *etc*.
- Downward compatibility
 - Methods and technologies should also work with as-built 3D building models
- Relating standards
 - LOD (CityGML level of details^[7]), IFC^[8], *etc*.

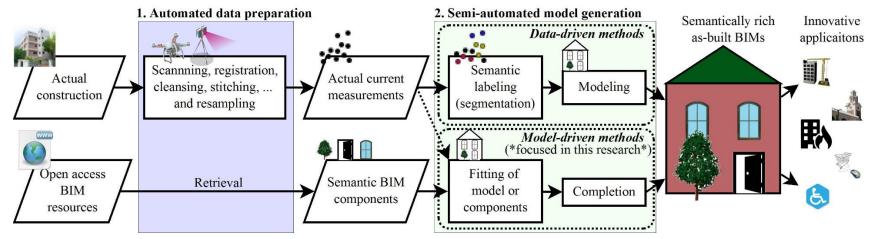




1.2 The (semi-)automated modeling methods



- ♦ Two categories of methods (for both)
 - Data-driven: On (pre-processed) point clouds or images
 - o Poisson mesh surface, RANSAC planes/spheres, edge detection, image segmentation, etc.
 - Model-driven: Recognizing & fitting the known (BIM) components against the data
 - Evolutionary fitting of components, context-based region growing, VR of pipes/ribbons...





1.2 The limitations





- Data-driven
 - Unsatisfactory semantic/abstraction discovery
 Huge model size
 - Automation level of modeling
 Tedious and error-prone manual work
 - High requirement on measurement data
 Expensive equipment
- Model-driven
 - Ad-hoc project setting/ context
 Poor reusability
- ♦ Thinking out of the box
 - Exposing the modeling process to general decision science/OR study





1.3 Derivative-free Optimization in OR[†]





Optimization (a.k.a. Mathematical programming)

 $\max f: \mathbb{R}^n \mapsto \mathbb{R}$

An example of optimization

- the selection of a *best* element (with regard to some criteria) from *some* set of available alternatives.
- ♦ Nonlinear optimization
 - When *objective function* or some *constraints* are nonlinear
- ♦ Derivative-free Optimization (DFO)
 - Objective function or constraints are unknown



DFO: Manipulating a black-box (Figure adapted from Wikipedia)

- E.g., model selection, parameter tuning in simulations
- Especially when function is *very expensive* or *unanalyzable*
- Challenging (*NP*-hard), but achieved significant success
 - o In applied science and engineering such as *molecular biology* and material sciences

^{†:} Operations Research



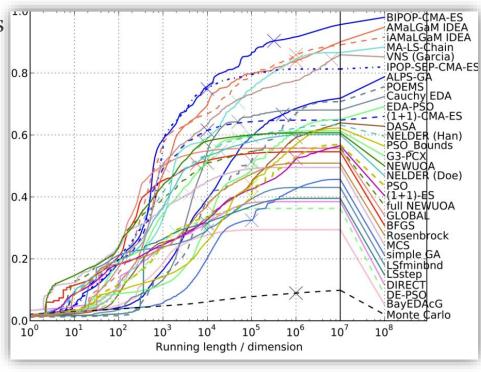
1.3 Derivative-free Optimization methods





♦ A long list of off-the-peg algorithms for solving optimization problems as a black-box:

- Surrogate methods
 - CMA-ES (Covariance matrix adaptation with evolution strategy) [11]
 and its variants are competitive
- Trust-region methods
- Metaheuristics (GA, PSO, VNS, etc.)
- Hyper-heuristics, data mining
- ... and Monte Carlo



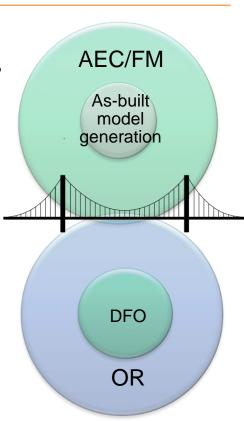
Comparison of algorithms for BBOB-2009 (Black-Box Optimization Benchmarking, higher is better) [10]



1.4 An opportunity



- ♦ The questions
 - Can the model generation be generally solved by DFO methods?
 - o If true, can semantic data be discovered at the same time?
- ♦ If all true, we can
 - Map between a typical problem in AEC/FM and a class of powerful algorithms in OR
 - Also expose as-built model generation to many other nonlinear methodologies
 - Discover semantic (abstraction) information



Section 2 **AS-BUILT MODELING AS OPTIMIZATION**



2.1 A meta-model of as-built 3D modeling



Given a reference measurement, a set of parametric components







♦ A meta-model of constrained optimization is from such a formulation:

Meta-model of constrained optimization & its solution space

Tells computers:

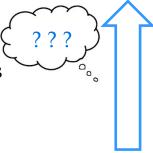
What to change

The What is good

Rules to follow

 \blacksquare The **variables** (X) are the parameters of the components;

■ The **objective function** (f) is to maximize the similarity (or minimize dissimilarity) between the 3D model (as combinations of the parametric components) and the measurement; and



 \blacksquare The **constraints** (\mathcal{C}) over the variables are the topological relationships between components.



■ from Greek prefix μετά-, "beyond"



Reference measurements





Parametric (& semantic) components

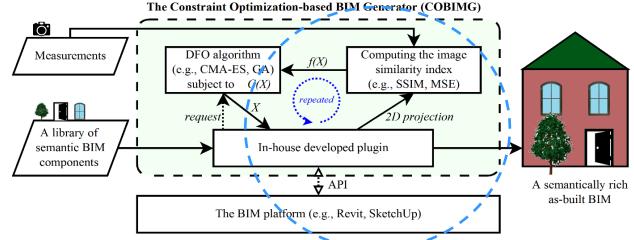


2.1 The framework: A bird's-eye view





- Input 1: Reference measurements (photos)
- Input 2: Semantic and parametric components
- Process: Systematically finding the fittest model by solving meta-model with DFO methods
- Output: A semantic as-built model





2.1 Formulation of the meta-model



♦ The variables

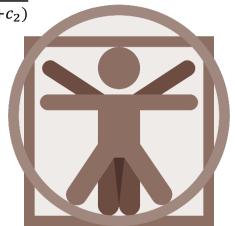
- $\blacksquare X_i = \langle cl, l, s, r_z \rangle$ for each *i*-th component instance
 - o *cl*: class, *l*: location, *s*: scaling, r_z : rotation-z
- \diamond The objective function^[12] (similarity between $A \& \hat{A}$)

$$\blacksquare SSIM = structure \cdot luminance \cdot contrast = \frac{(2\mu_{\hat{\mathbf{A}}}\mu_{\mathbf{A}} + c_1)(2\sigma_{\hat{\mathbf{A}}\mathbf{A}} + c_2)}{(\mu_{\hat{\mathbf{A}}}^2 + \mu_{\mathbf{A}}^2 + c_1)(\sigma_{\hat{\mathbf{A}}}^2 + \sigma_{\mathbf{A}}^2 + c_2)}$$

♦ The constraints

$$C(X) = \{C_{\mathbf{I}}(X_i)\} \cup \{C_{\mathbf{R}}(X_i, X_j), i \neq j\},$$

- o C_{I} : about individual component X_{i}
- C_R : the topological relationships between any (*i*-th, *j*-th) components



Restructuring and formulation



2.1 Details of the topological relationships



♦ Topological relationships

- Categories
 - o Adjacency: ON_TOP_OF, BELOW, NEXT_TO, ...
 - Separation: SEPERATED
 - Containment: CONTAINS_ON, CONTAINS_IN
 - Intersection: INTERSECTS_WITH
 - Connectivity: CONNECTS_TO
- Semantic definition
 - Adding properties like *scaling* and *topological relationships* to their SketchUp dictionaries
 - E.g., ON_TOP_OF, BELOW, CONTAINS_ON, etc.



An example of the dictionary of component in SketchUp



2.2 A pilot: A demolished building at campus



- ♦ The pilot case
 - A demolished baroque-style two-storey building
 - Once occupied by School of Tropical Medicine and School of Pathology, HKU
 - Input: A photo
- Preparing parametric components
 - Only apparent (>1m) components
 - 1 door portico, 1 tree (unknown type), 2 storeys of walls (...)
 - 5 identical windows on 1/F, 4 on G/F (all unknown types)
 - 7 components were collected from 3D Warehouse of SketchUp
 - With a keyword filter "baroque"
 - With limited (3) pairs of conflicting components
- o Adjustment: Removing extra parts, alignment F Xue: Auto as-built 3D modeling, HK PolyU, 17 Aug 2017



A historical photo (Source: MTR HKU Station, re-photographed by an Android phone)



Door portico



■ Wall × 2

■ Windows × 2



(Contributors: Mohamed EL Shahed, Richard, KangaroOz 3D, Yoshi Productions, 3dolomouc, Architect, Ben @ 3D Warehouse)



2.2 The problem



- Meta-model of as a constrained optimization problem
 - Minimize the dissimilarity
 - Between the projected image of model and the input photo
 - Similarity metric is the SSIM
 - With respect to topological constraints
 - Computational functions implemented on SketchUp (2016 Pro) Ruby API
 - Objective function interface
 - Variables as parameters (per component)

Manifolds (0, 1) + scaling
$$(xyz)$$
 + location (xyz) + rotation $(\alpha\beta\gamma)$ = 4 ~ 6 variables

- Constraints of topological relationships
- An invisible *Ground* object is placed at first

min f = SSIM

s.t. Semantic constraints of *position*, *scaling*, and *ABOVE*/ *BELOW*/ *CONTAINS_ON* for each component



2.2 A computational experiment

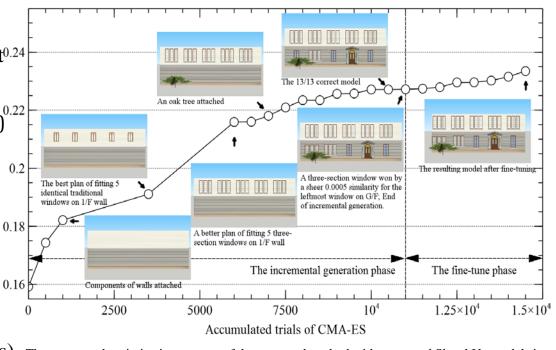




■ 200 trials per target component^{0.24}

■ Two phases:

- o Incremental (11,000 trials)^{v.}
- Refinement (3,500 trials)
- The Solver: CMA-ES (C++ code [13] in a Ruby wrapper)
- Time: 5,012.6s
- Observation
 - Fully automatic
 - Fault-tolerant (see the windows)
 - Semantic/grammar-enhanced



The automated optimization process of the proposed method with annotated SketchUp models in the test with 500 trials for fitting each component (The incremental generation phase: 1~11,000; The fine-tuning phase: 11,001~14,500)



2.2 Results and post-processing





- The facade in the photo
- **■** Semantic links
- Post-processing
 - Manual completion
 - Copy & paste
 - Georeferencing and display in 3D



(a) Direct result: The façade in the photo



Traditional 2

Traditional 2

Traditional 3

Tradit

(b) The semantic links illustrated in Stanford Protégé (Circle denotes a component class and a



(d) Georeferencing and illustration on Google Earth, near MTR Exit A (~5 minutes)

F Xue: Auto as-built 3D modeling, HK PolyU, 17 Aug 2017 (c) Manually completed approximate model (~15 minutes)

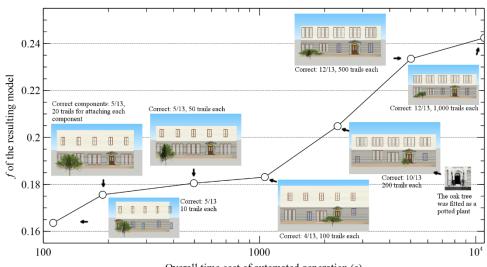


2.2 The number of trials is critical





- When increasing the number of trials per component 10 to 1,000
 - both the similarity and overall time cost were *monotonically* increasing
 - Similarity
 - From 0.16 to over 0.24
 - Correct components
 - From 4~5/13 to 12/13
 - Time cost: From 100+s to 10,000+s
 - Over 97% was consumed by BIM environment
 - 1. Manipulations
 - 2. Projections



Overall time cost of automated generation (s) The trends of similarity, overall time cost, and correctly generated components when changing the trails of CMA-ES for fitting each component

Used by	Functions	%time
SketchUp	Manipulating components; 3D to 2D projection	97.67%
Similarity	Computing the image similarity index	1.45%
DFO	Optimizing the parameters of a component	0.00%
System	Reading/writing of temporary image files	0.88%



3.3 COBIMG & live demonstration





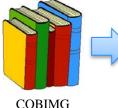
♦ A library COBIMG (constrained optimization-based BIM generator) is under development



- SketchUp, Revit (soon), etc.
- Multiple meta-models with various
 - Objective functions
 - Measurement types, and
 - Solving algorithms
- Multiple modeling options
 - Ontology-guided, free discovery, finetuning, etc.
 - Extended the earlier pilot study
- Demo (Known sum of types for a quick demo)











One click





Section 3 **DISCUSSION & FUTURE RESEARCH**



3.1 Discussion



- Meta-modeling of as-built 3D modeling as constrained optimization
 - Pros: General, simple, no explicit object recognition/segmentation (also challenging)
 - Cons: A larger search space (slower), slow full projection, limited by pixels, less accurate
- Semantic definitions of components
 - Pros: Realized 'grammar' of components, simplified optimization
 - Cons: Some manual work needed, subject to redefinition from a project to another
- ♦ The framework as a whole
 - Pros: High automation, linearly incremental time, reusing components and abstractions, less requirements on equipment, tolerant to errors, (hopefully) semantically rich
 - Cons: Less accurate in geometry, still in its *infancy*
 - Answers to the question: 1) True; 2) Applicable to some relations
 - Semantic recognition/segmentation is another pillar for semantic BIM



3.2 Future research





- More domains (e.g. infrastructures, etc.)
- Advanced DFO methods
- More objective functions
- On real BIM/CIM models instead of surface models



We are still on the way (Source: clipartpanda.com)

Efficiency

- Efficient ways of manipulating point clouds (working...)
 - E.g., *k*d-tree, approximate *k*NN, convex hull, planar and object detection

Extensions

- Shared component libraries for reusability (e.g., IFC-compatible)
- Handling other challenging AEC/FM problems







The Roman aqueduct Pont du Gard (Source: Wikipedia/ 3Dwarehouse.com)²⁵



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