

Relief Clipping Planes for Real-Time Rendering

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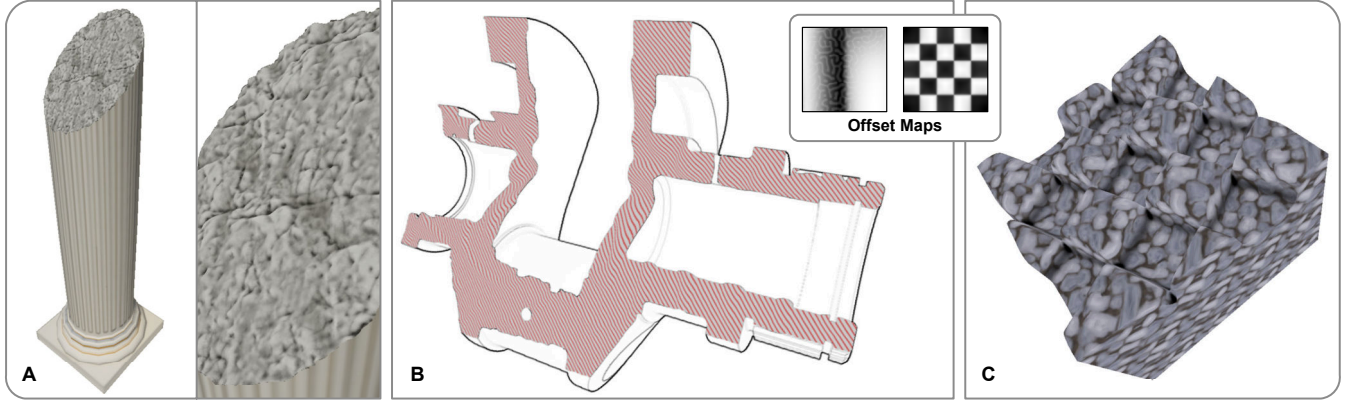


Figure 1: Results of our rendering technique: A: A clipped and capped Roman column. The close-up shows the non-regularity and shading of the cut-surface to create the impression of a solid column. B: Application of relief clipping planes to a non-convex mesh. The crank is rendered using edge enhancement and a hatched texture is applied to the cap. C: shows a clipped, capped, and solid textured convex object.

Introduction

The concept of clipping planes is well known in computer graphics and can be used to create cut-away views. But clipping against just analytical defined planes is not always suitable for communicating every aspect of such a visualization. For example, in hand-drawn technical illustrations, artists tend to communicate the difference between a cut and a model feature by using non-regular, sketchy cut lines instead of straight ones.

To enable this functionality in computer graphics (Figure 1), we present a technique for rendering *relief clip planes* (RCP) in real-time. Therefore, we extend the clip plane equation with an additional *offset map* (OM), which can be represented by a texture map that contains height values. Clipping is then performed by varying the clip plane equation with respect to such an offset map. Further, we propose a capping technique that enables the rendering of caps onto the clipped area to convey the impression of solid material. It avoids a re-meshing of a solid polygonal mesh after clipping is performed. Our approach is pixel precise, applicable in real-time, and takes fully advantage of graphics accelerators.

Relief Clipping Planes

Briefly, a $RCP = (N, P, OM, s)$ is defined by a normal vector $N = (A, B, C)$ and origin P , which are required to construct the respective normal form, an offset map OM , and a height value scaling factor s . Given an arbitrary shaped solid mesh and a RCP, clipping is performed on fragment level as follows. For each fragment with the clip space coordinate $C = (x, y, z)$ the function:

$$clip(RCP, C) = xA + yB + zC - f(C, P, OM) > 0$$

is evaluated using a fragment shader program. Therefore, f delivers a scalar $D \in \mathbb{R}$ by first generating texture coordinates into the offset map, then samples OM , and finally scales the resulting height sample by s . If the above equation is satisfied, the fragment program discards the tested fragment. This step can be performed for a number of clipping planes within a single rendering pass.

Capping Solid Meshes

Due to the possibly non-regularity of the clip surface, capping techniques based on stencil buffer capabilities [Blythe et al. 1999] cannot be applied. Especially for non-convex shapes, the association of a cap to a clipped area cannot be made definitely in image space using stencil masks.

Our image-based approach works for every clipped arbitrary solid. Therefore, a *volumetric depth sprite* [Trapp and Doellner 2008] of the polygonal mesh is created in a preprocessing step. Following to that, two steps are performed per frame: First, the solid mesh is rendered into the frame buffer with applied relief clipping. Second, the capping meshes is rendered using per-vertex displacement mapping. In this step, a *volumetric depth test* is performed per fragment that determines if it lies inside the volume and thus associated with a gap, or if it located outside the volume and therefore is discarded. GPU based-mesh refinement [Boubekeur and Schlick 2005] is applied to fit the subdivision of the cap mesh to the resolution of the offset map.

Conclusions & Future Work

We presented a new rendering technique for performing clipping and capping of arbitrary solid meshes against relief clip planes in real-time. For future work, we adapt this technique for apply capping for clipping against volumes [Trapp and Doellner 2008]. Further, we want to replace displacement mapping with parallax mapping to increase performance.

References

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