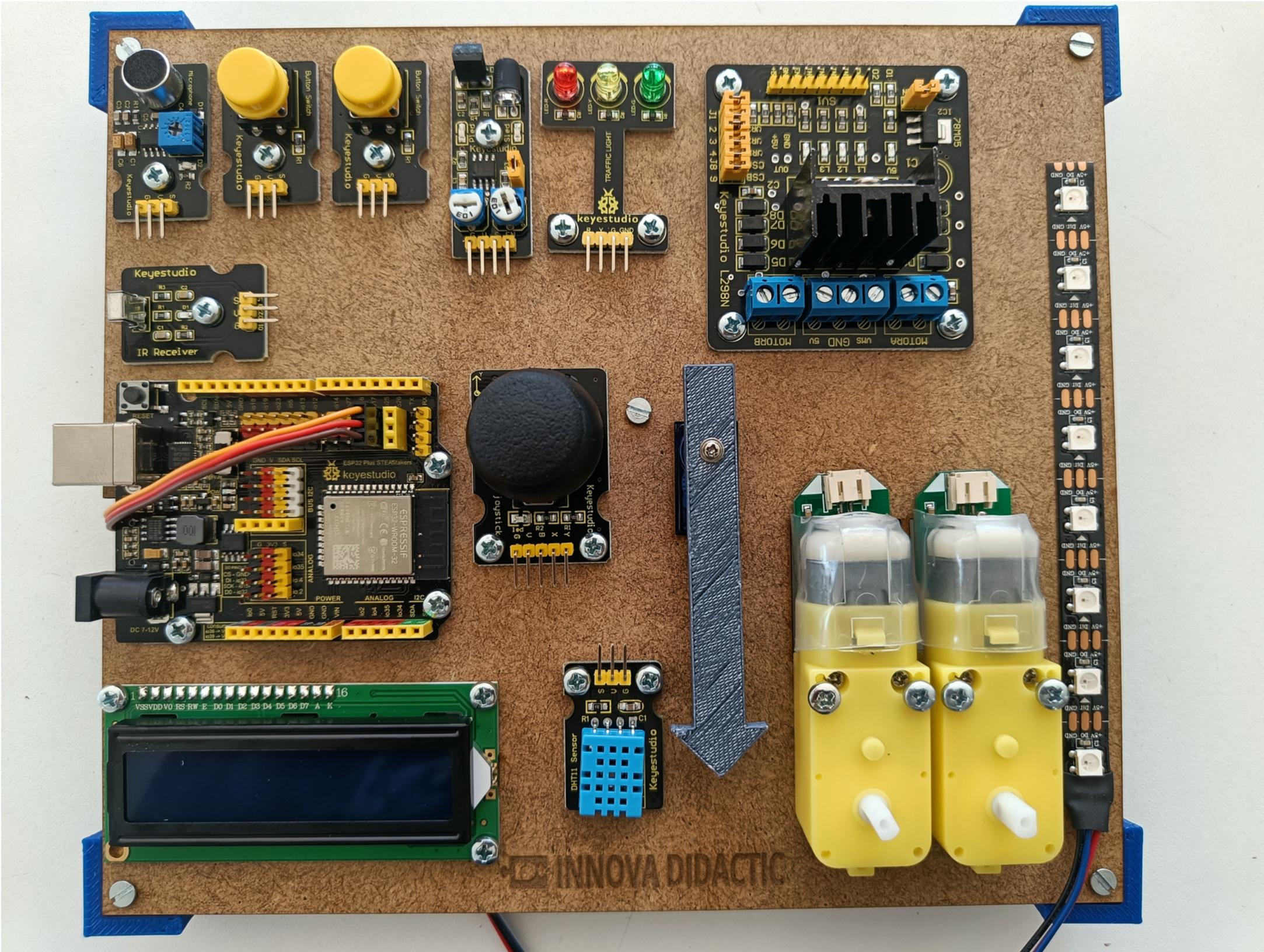
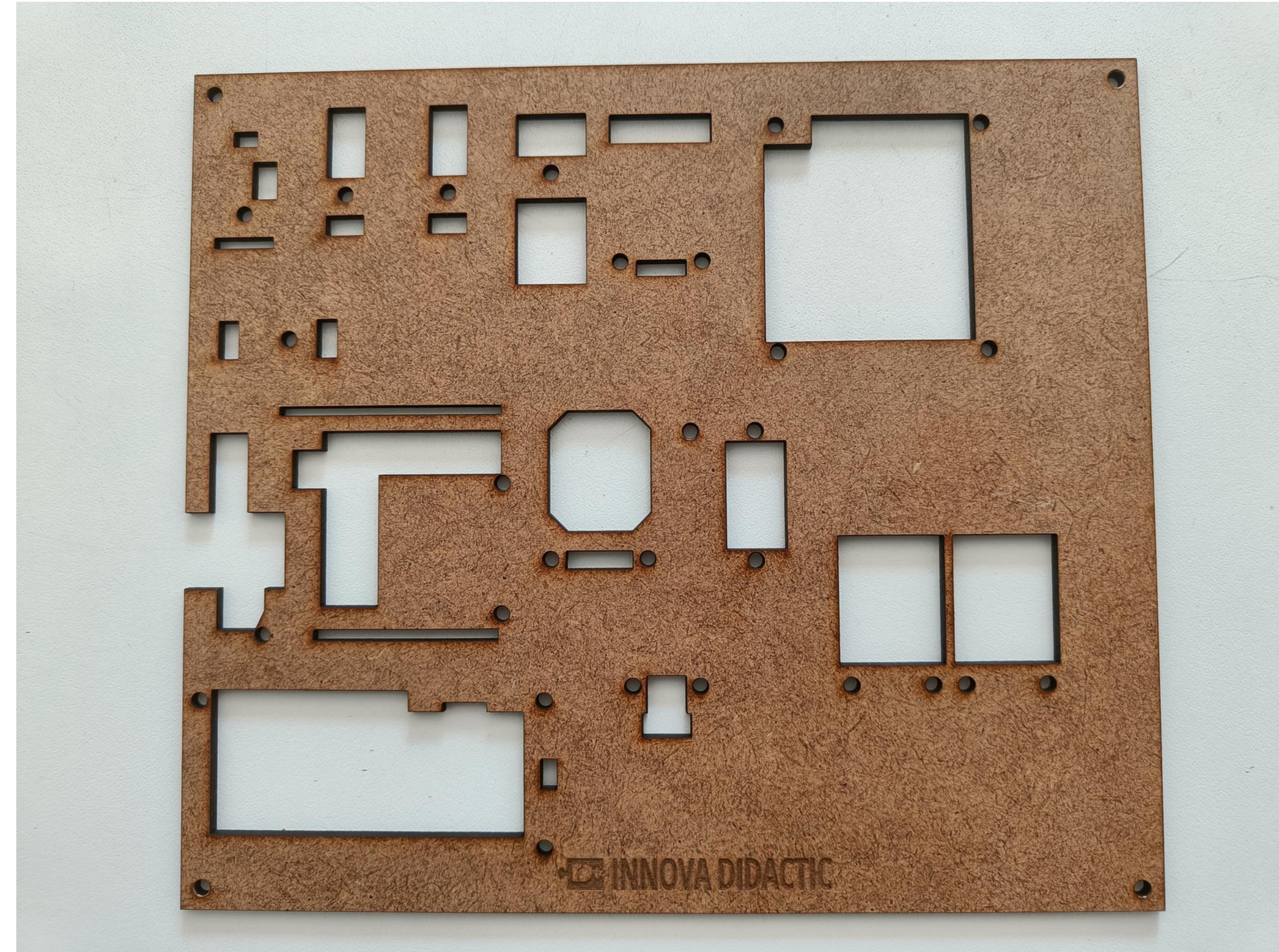


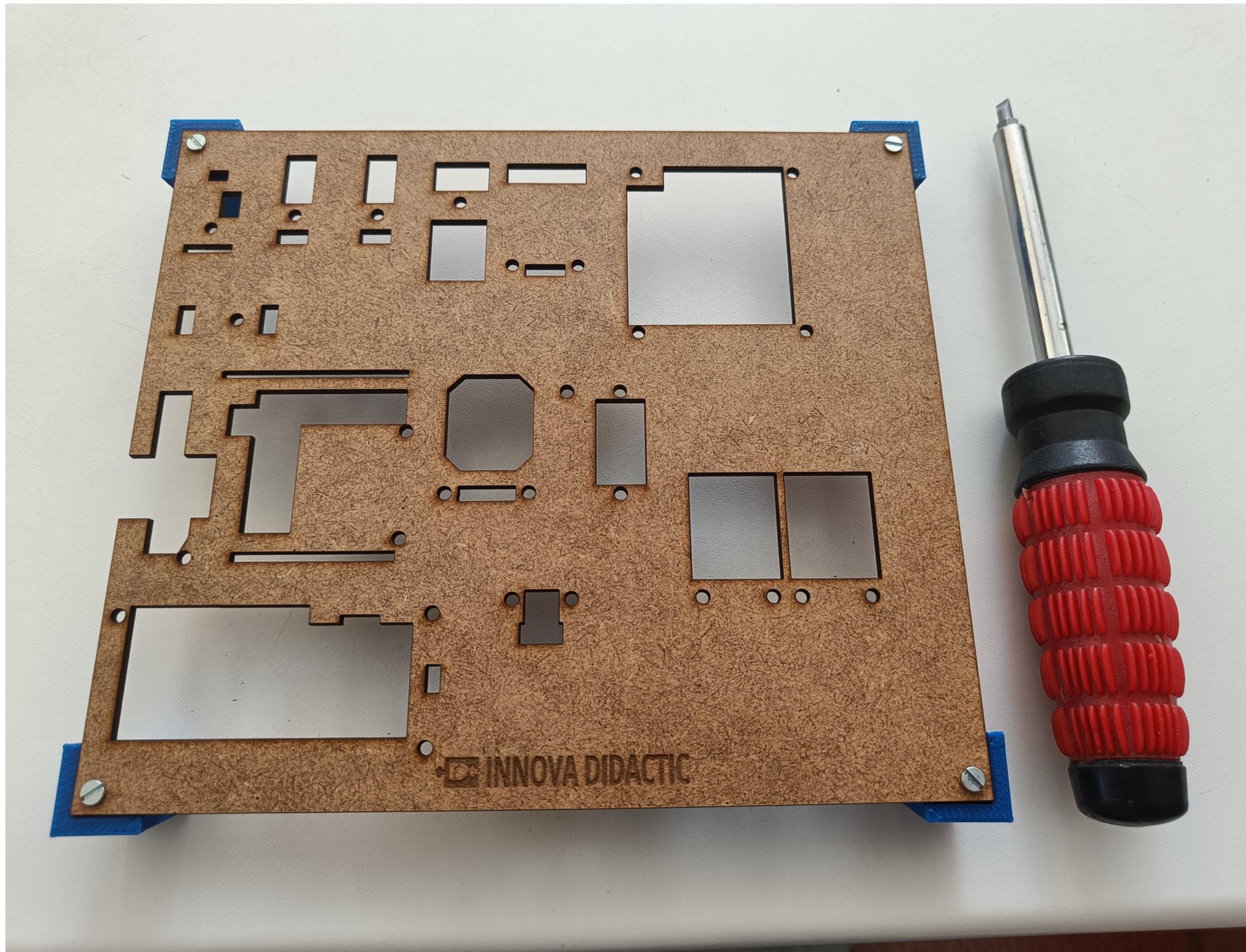
MONTAJE DEL KIT



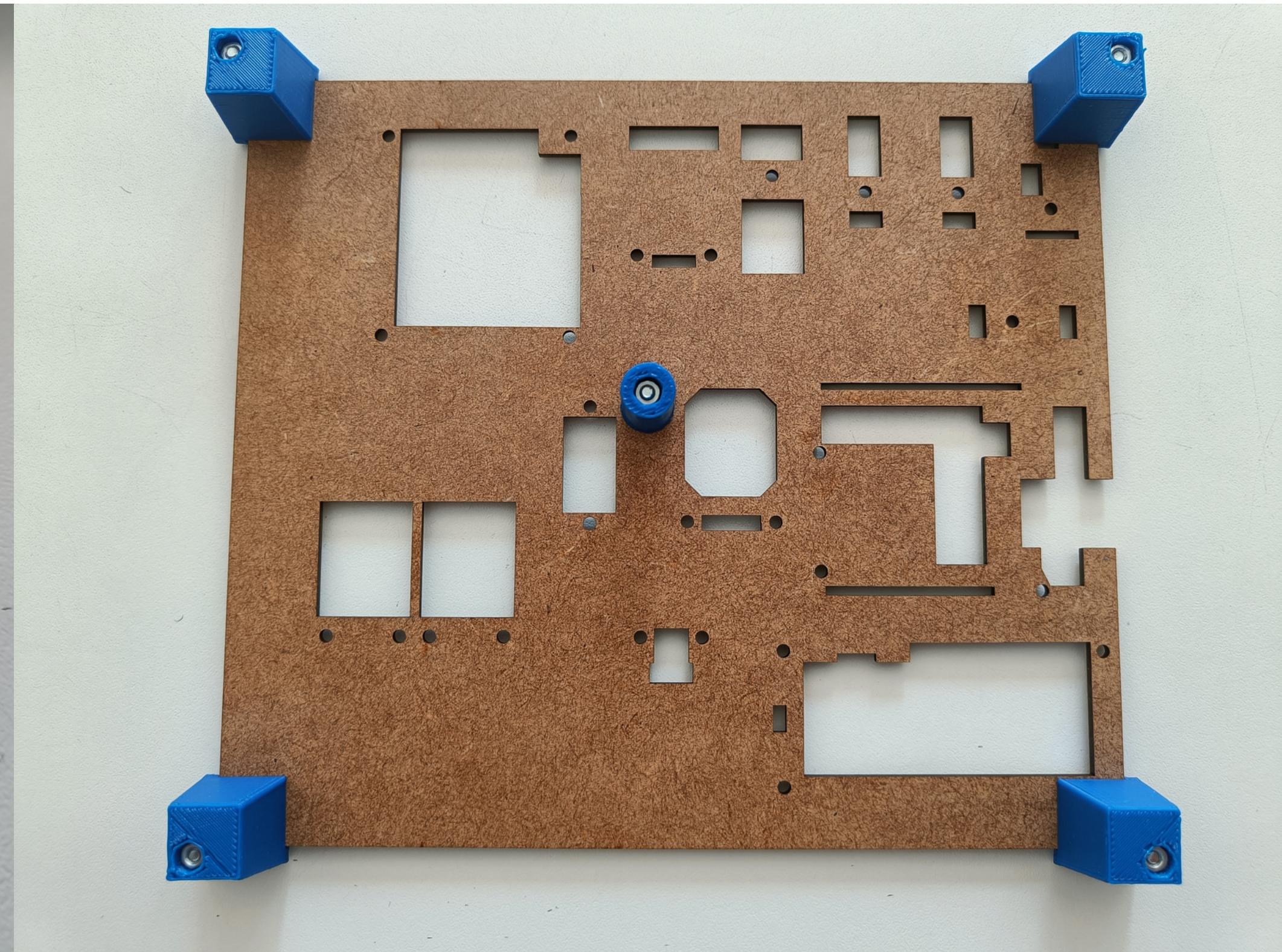
Paso 1: Preparamos las patas para la base



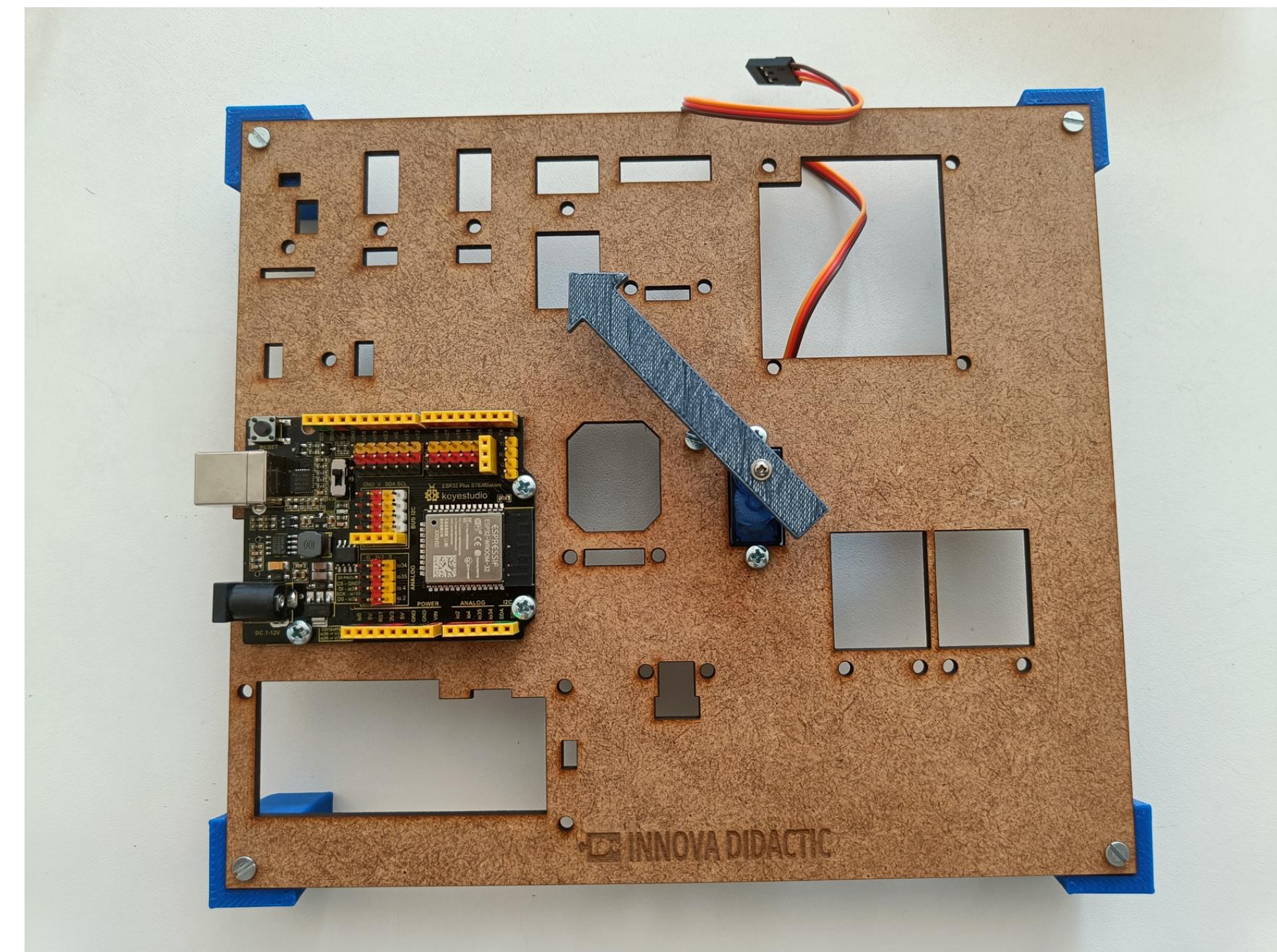
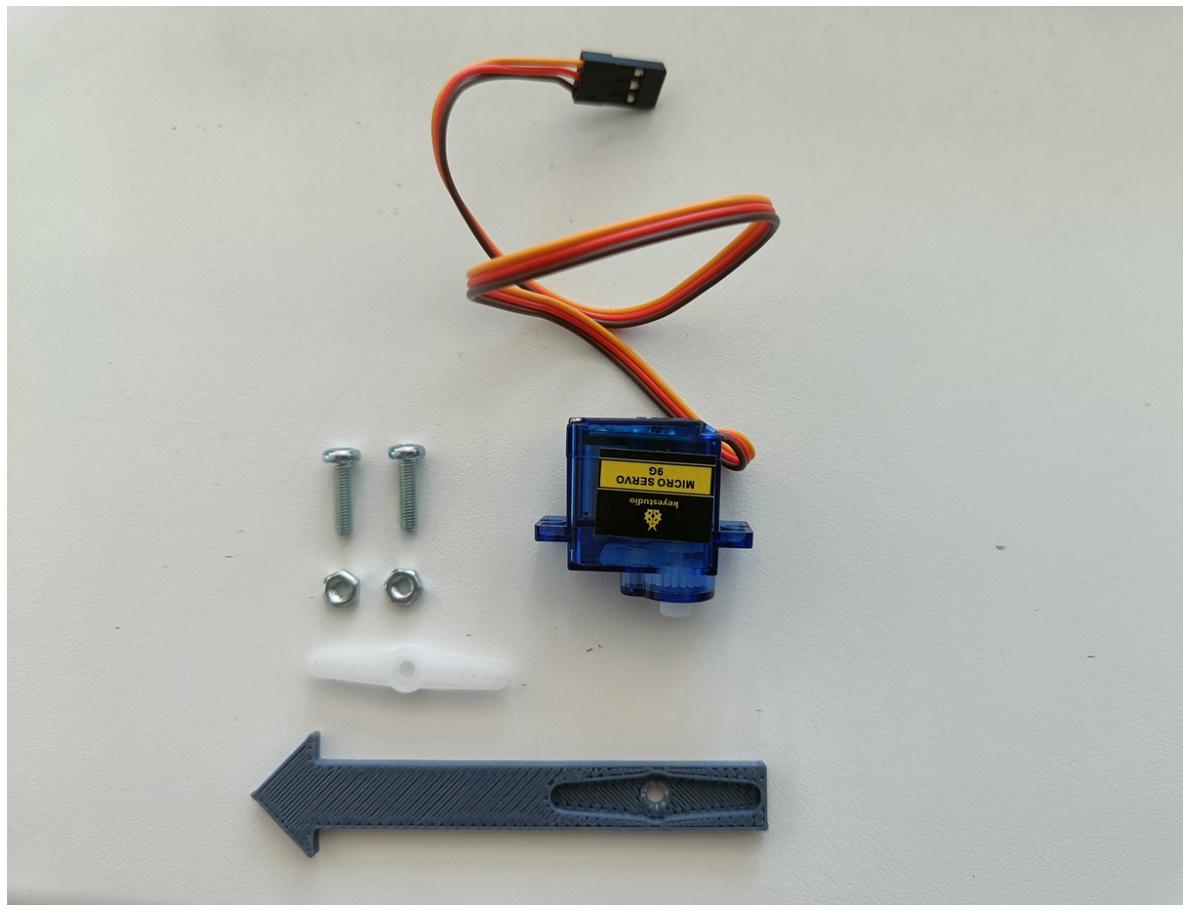
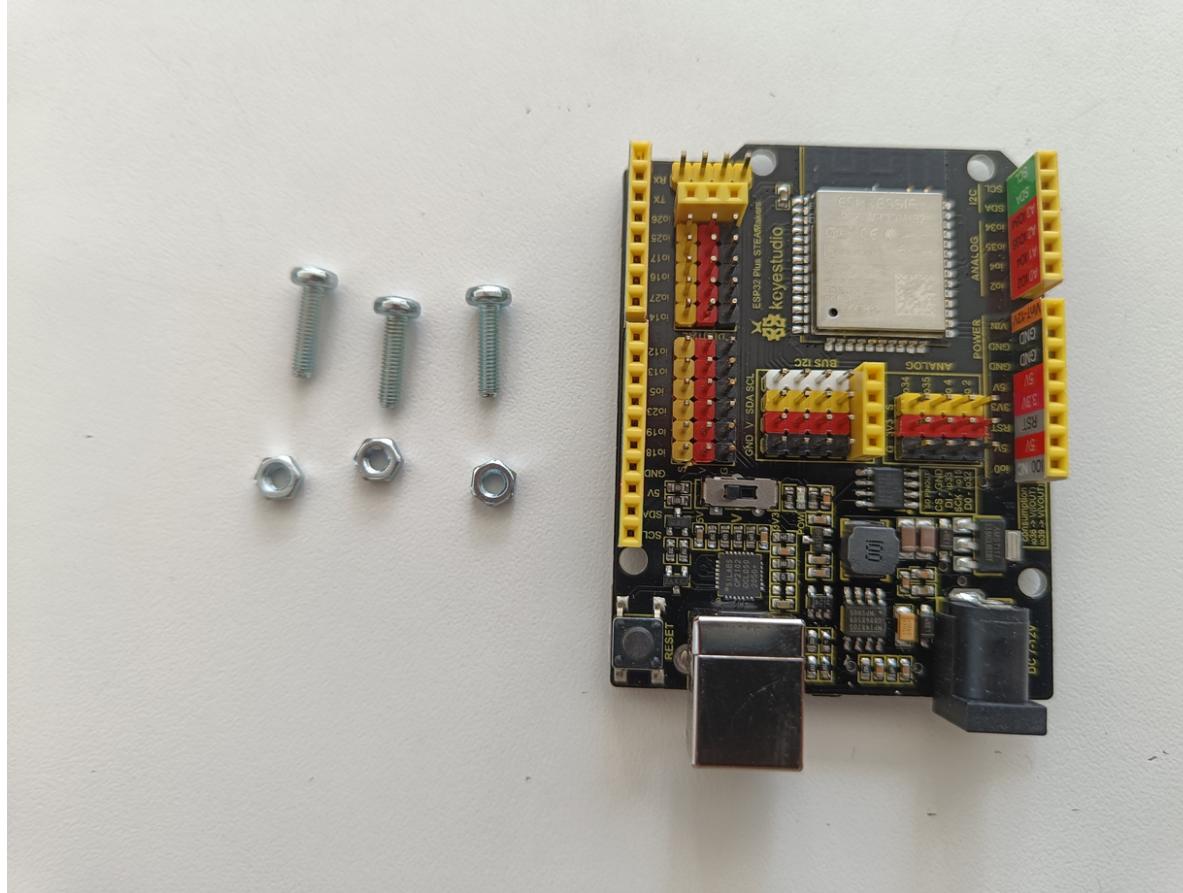
**Colocamos las 4 tuercas dentro de las patas y
las atornillamos a las 4 esquinas de la base**



Paso 2: Pie central

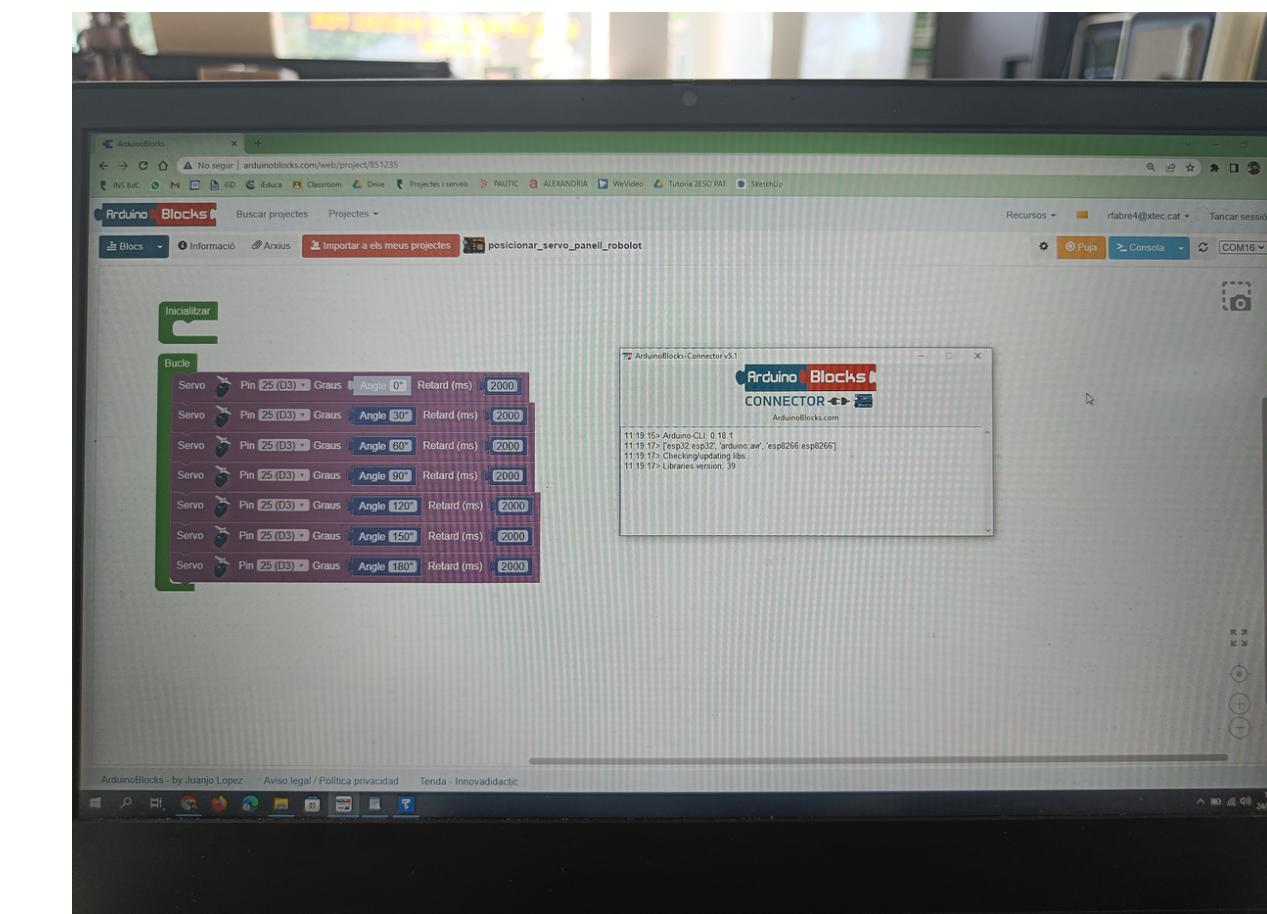
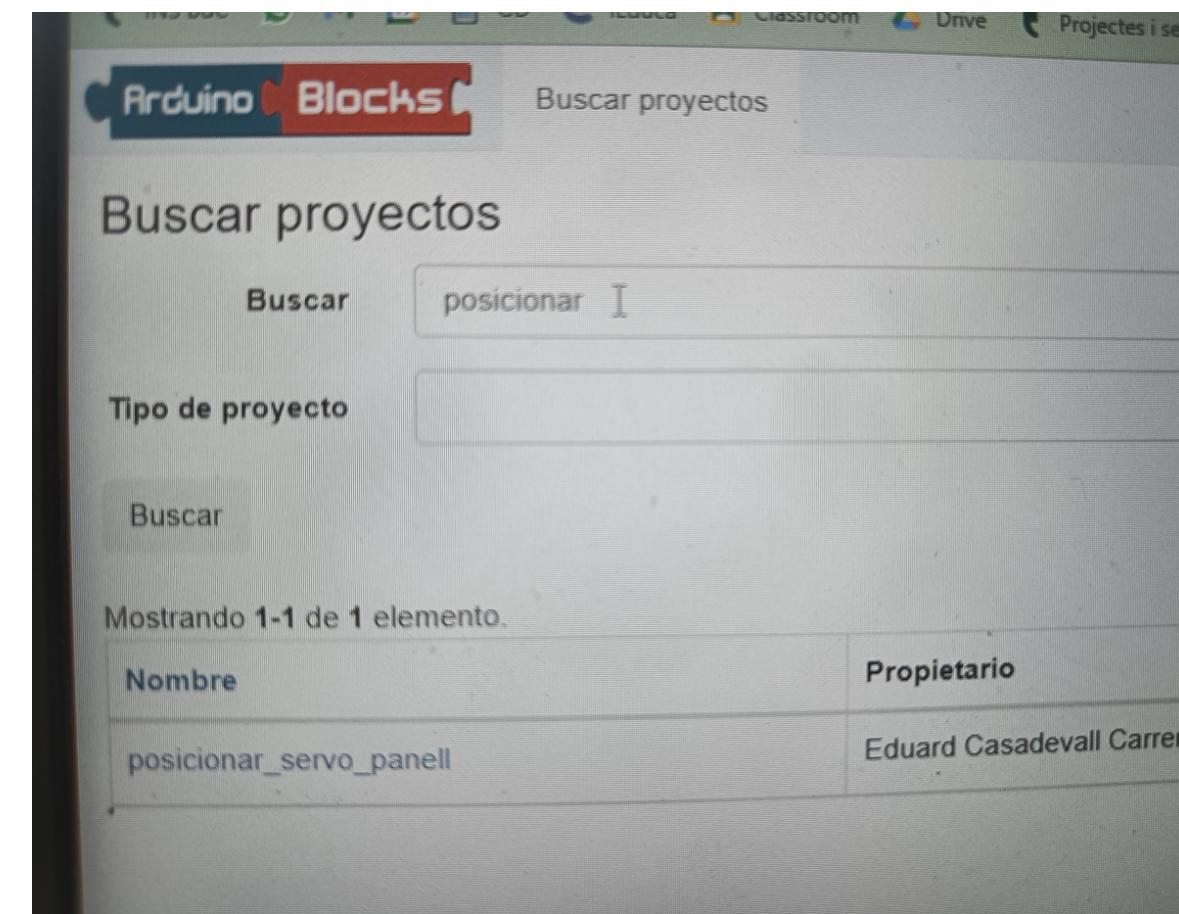
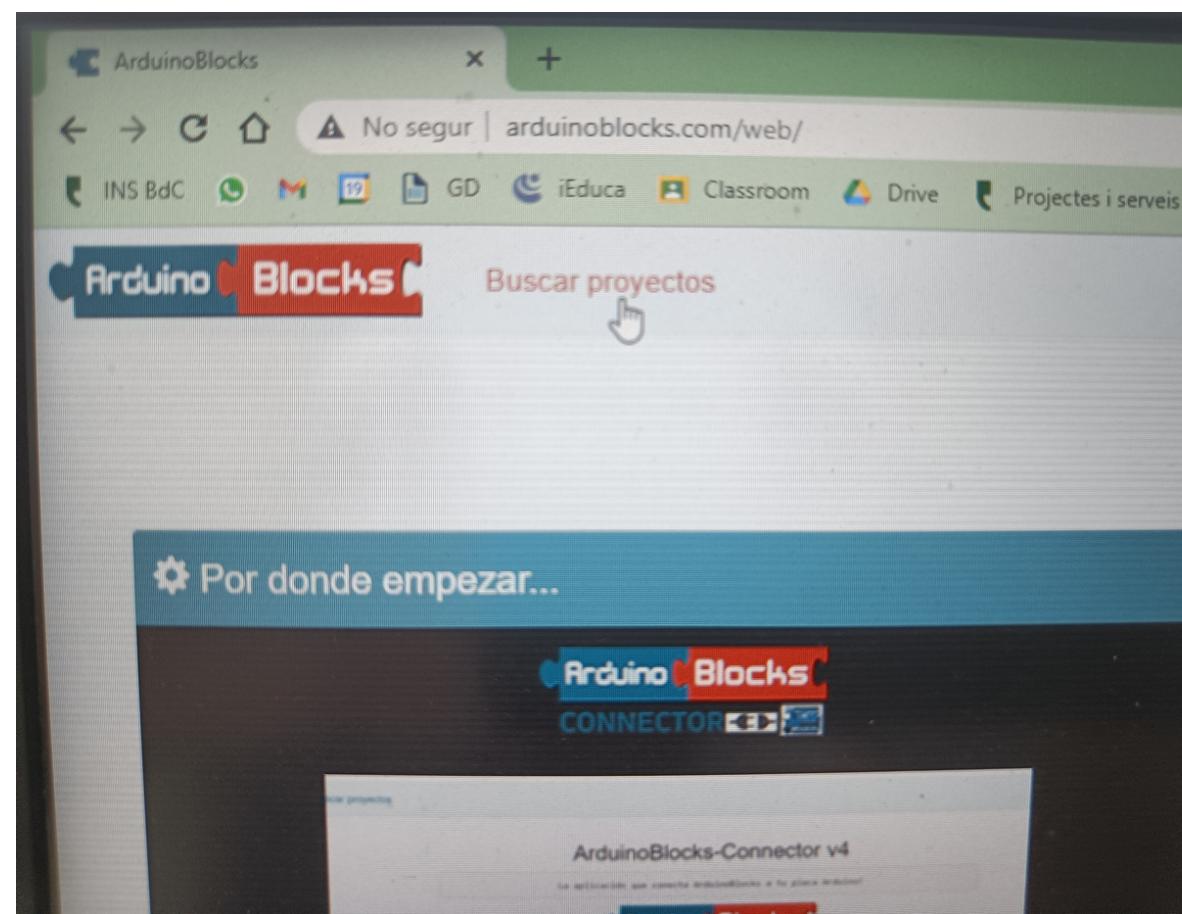


Paso 3: Placa ESP32 y servomotor



Paso 4: Posicionar el servomotor

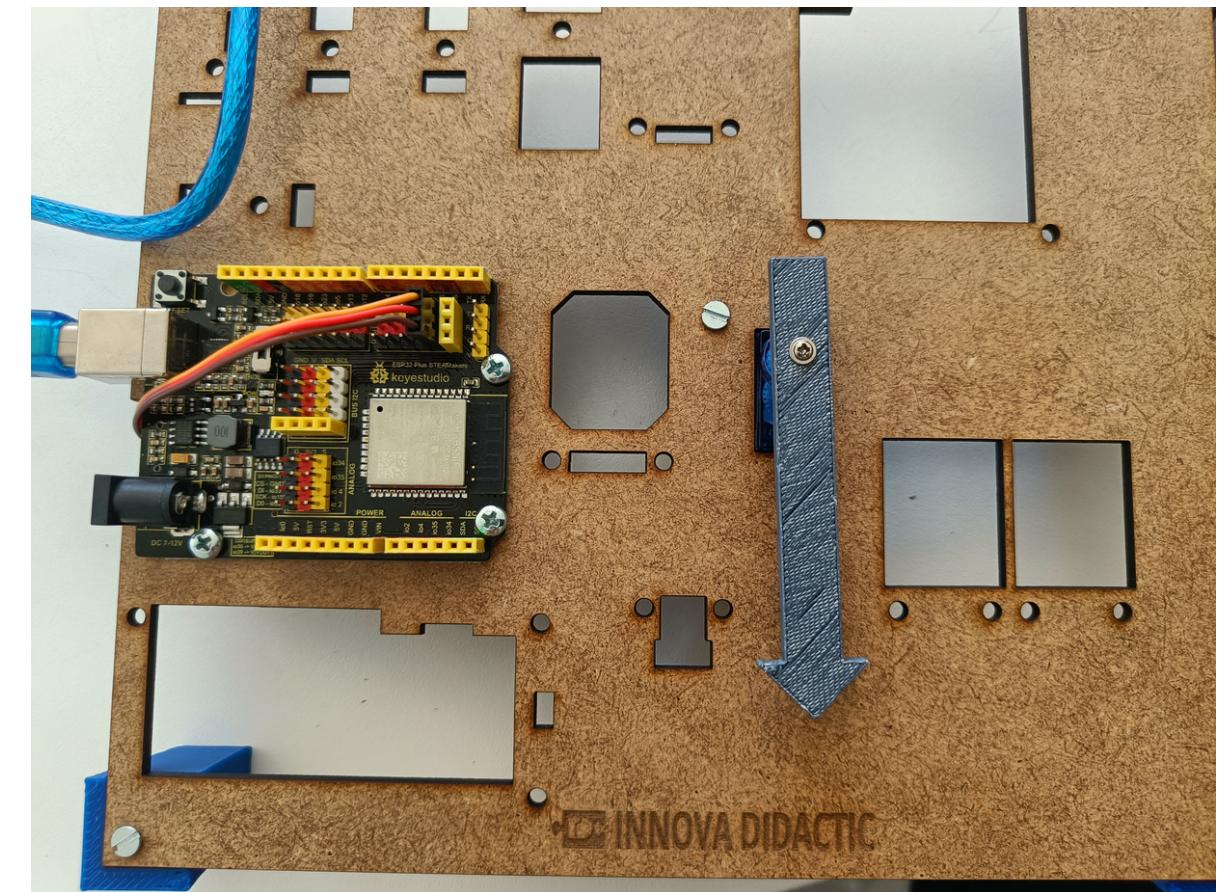
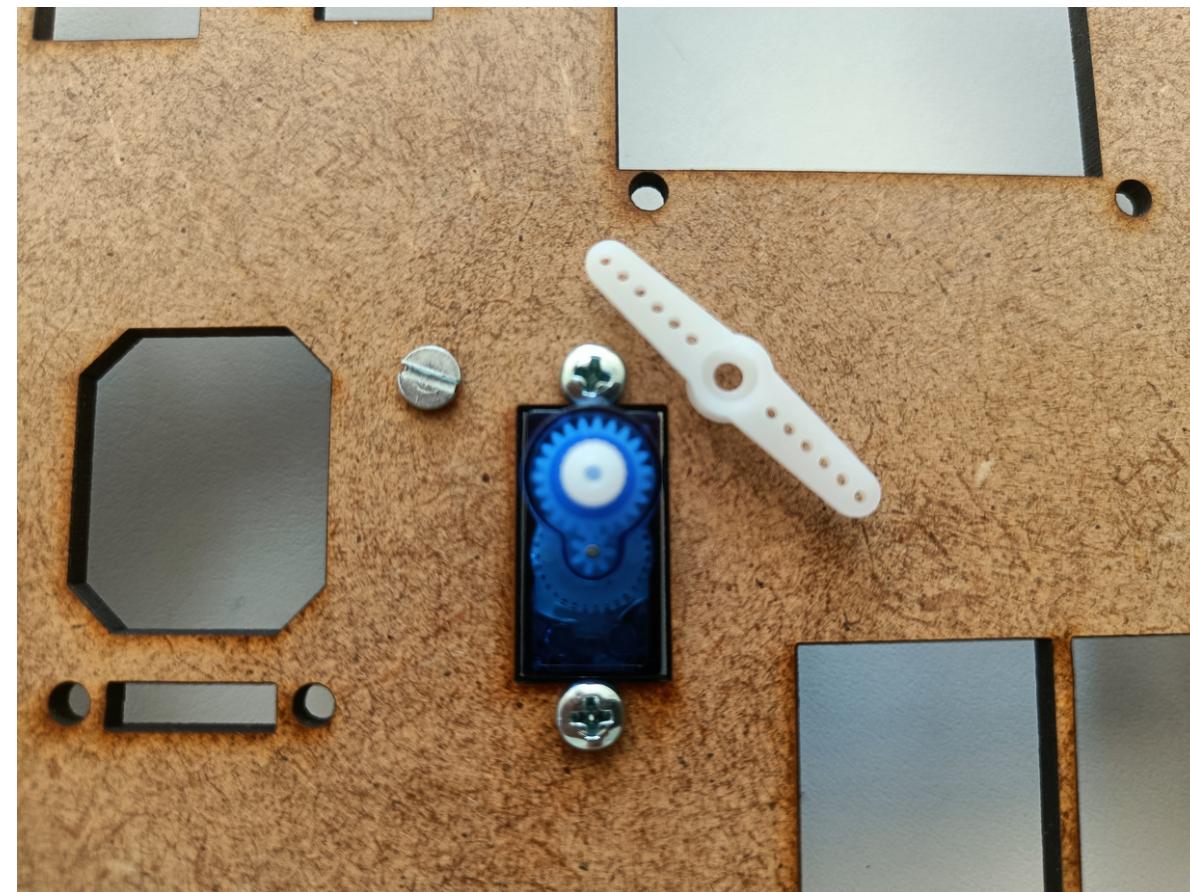
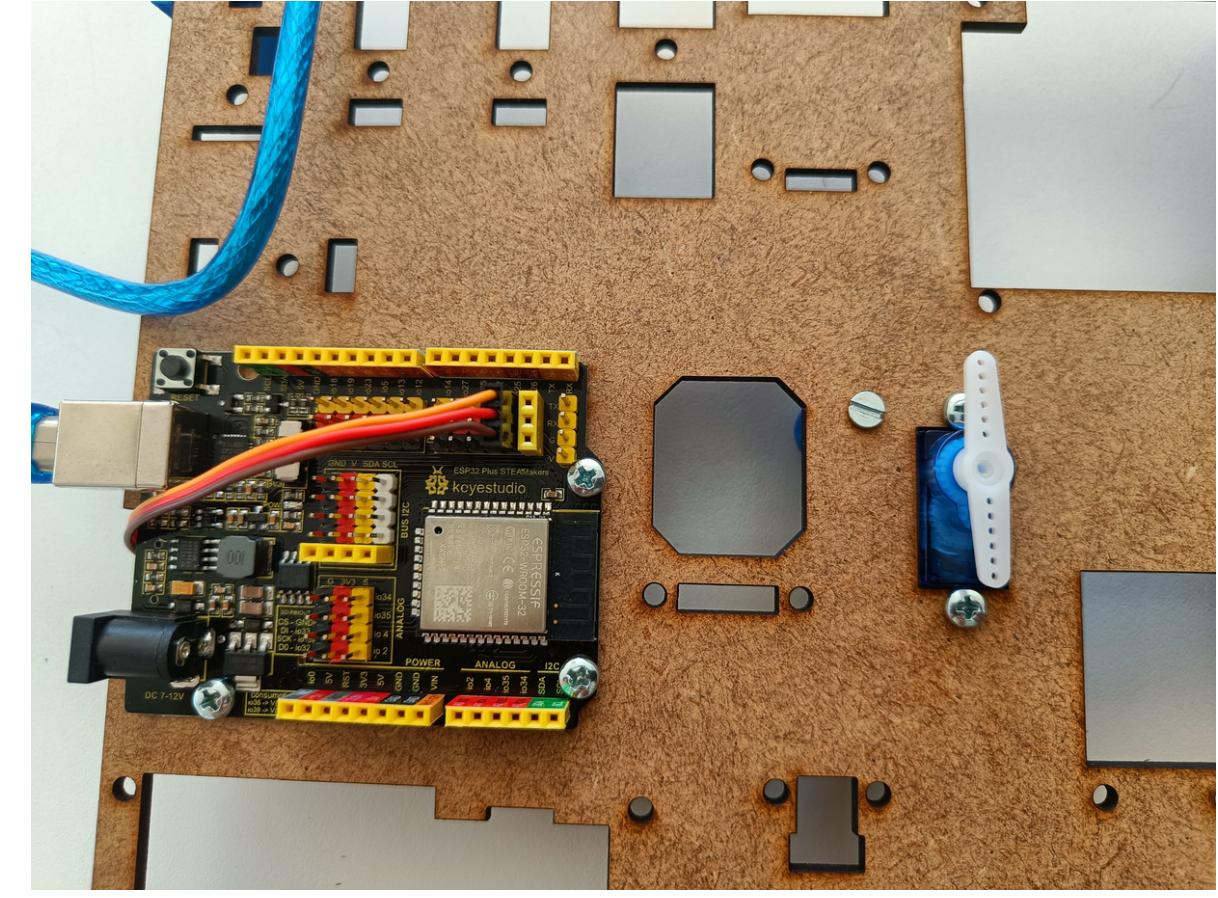
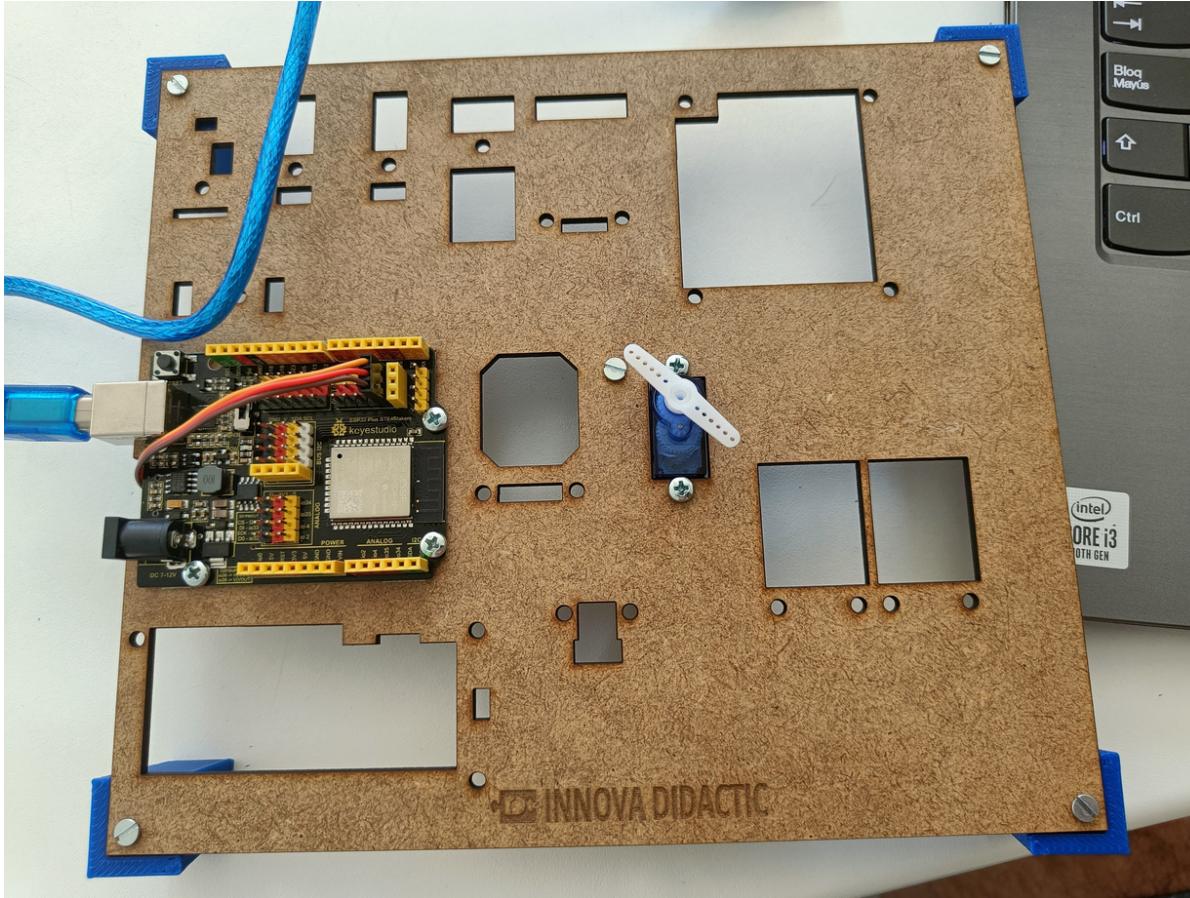
- Accedemos a "ArduinoBlocks" y buscamos el proyecto: **posicionar_servo_panell_robolot**
- Abrimos el conector "ArduinoBlocks Connector" y enviamos el programa a la placa



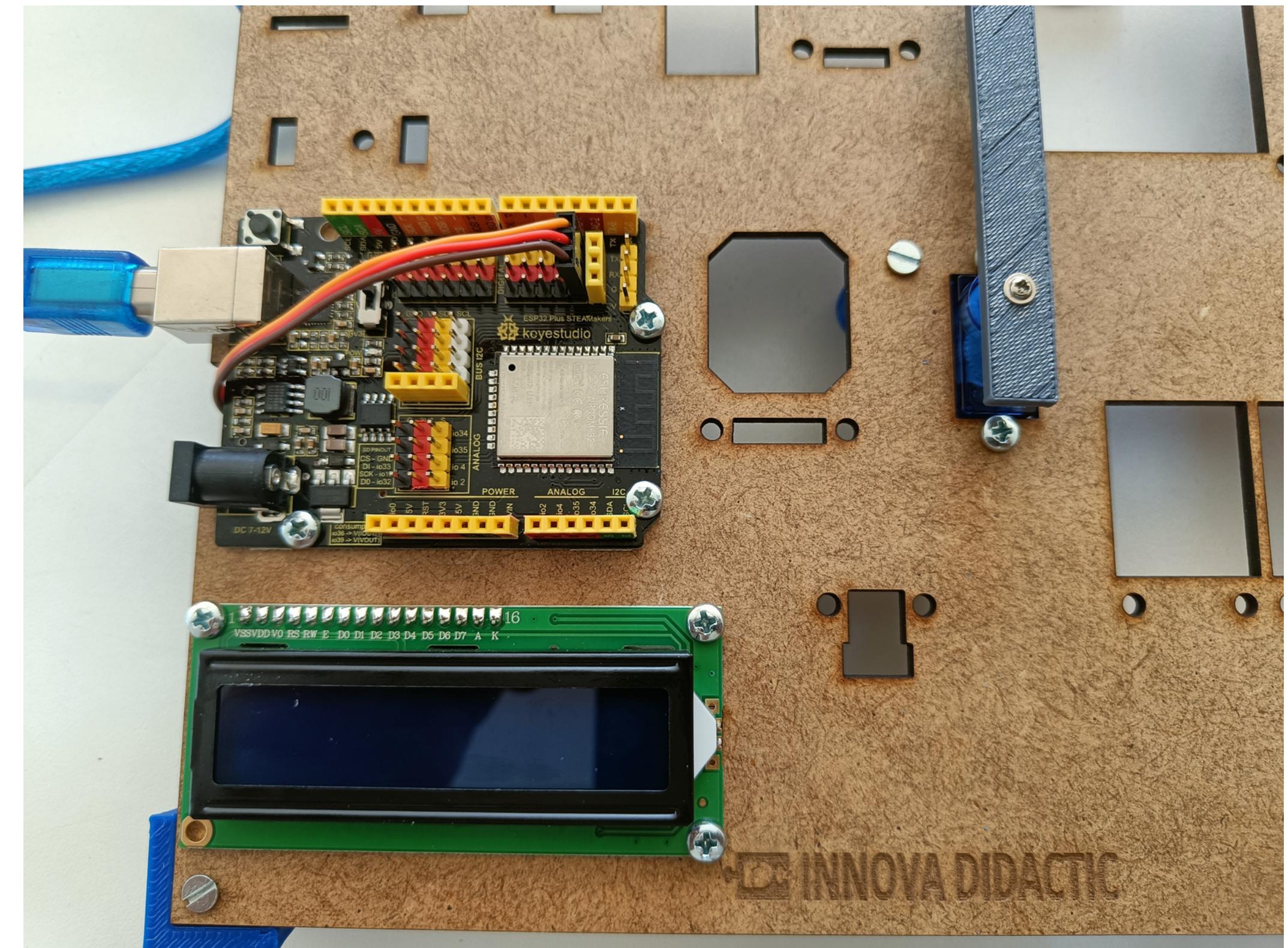
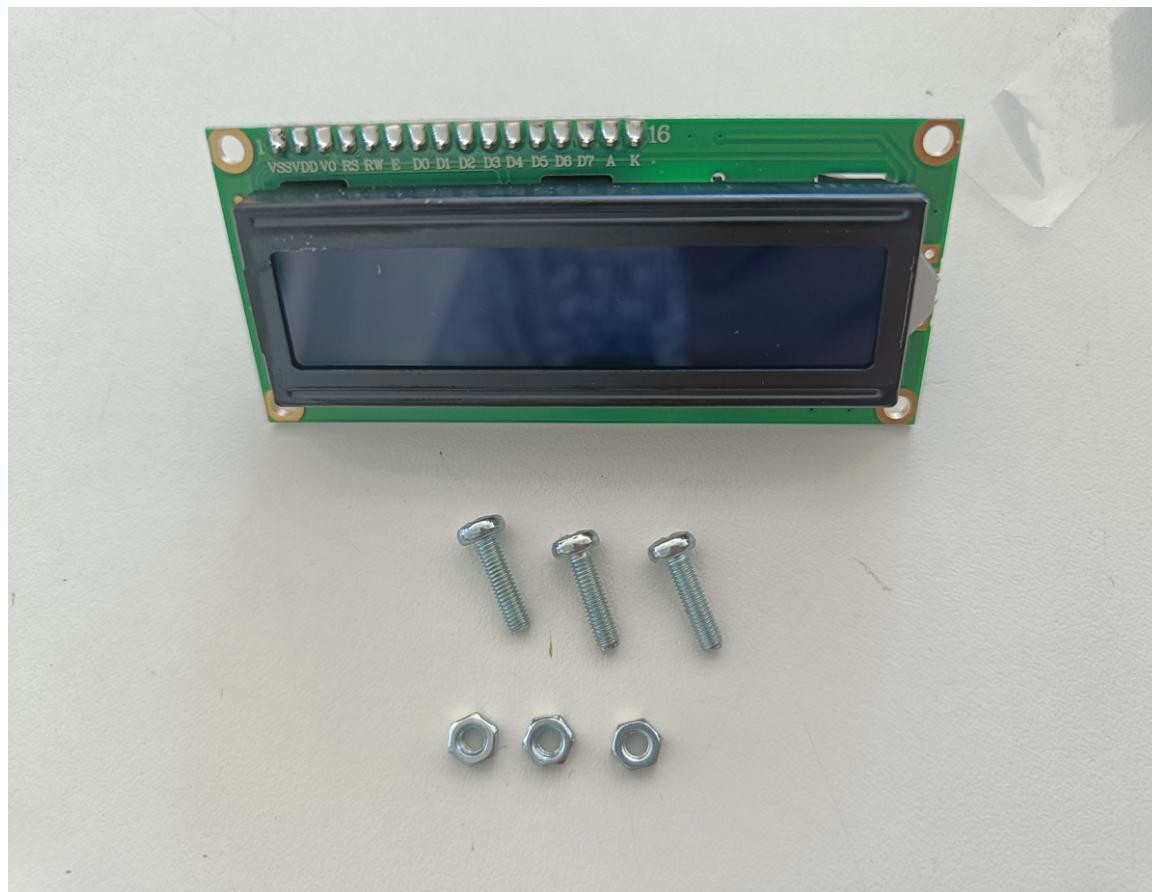
Ejecutamos el programa que hemos cargado en la placa, y lo tenemos que parar en el momento que el servo vuelve a la posición inicial (hace un giro repentino de 180°).

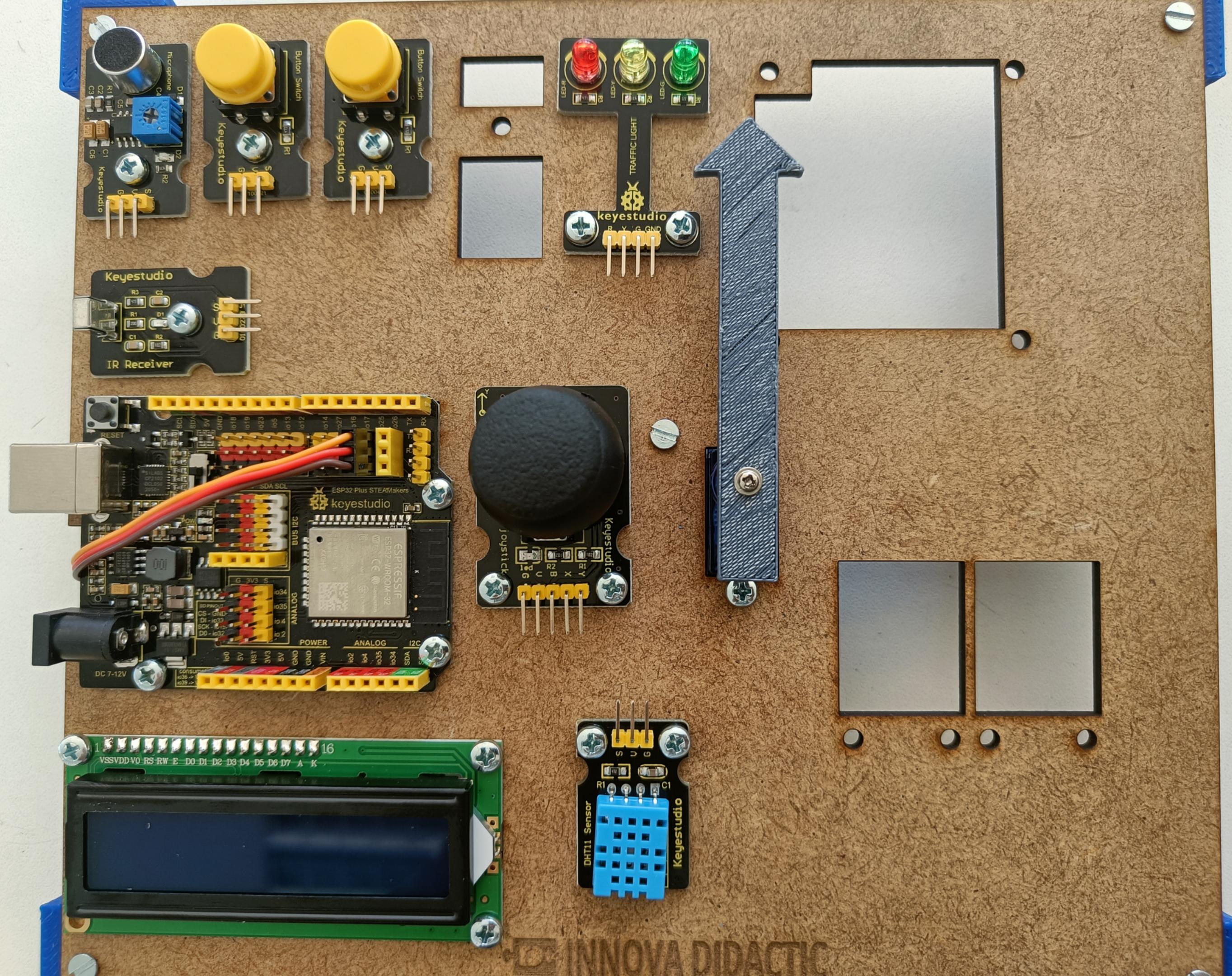
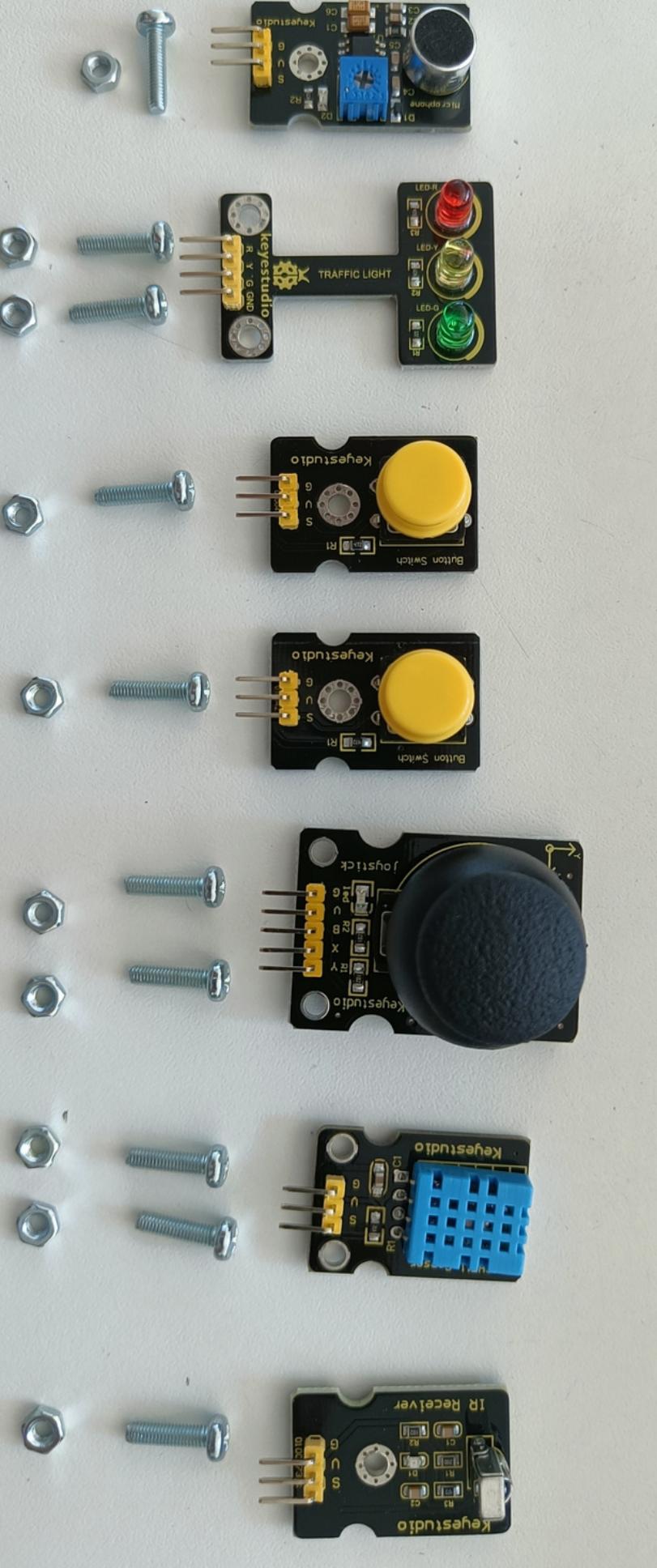
En ese momento, quitamos la flecha y el soporte **vigilando de no modificar la posición del servo** (se muestra en las imágenes de la derecha).

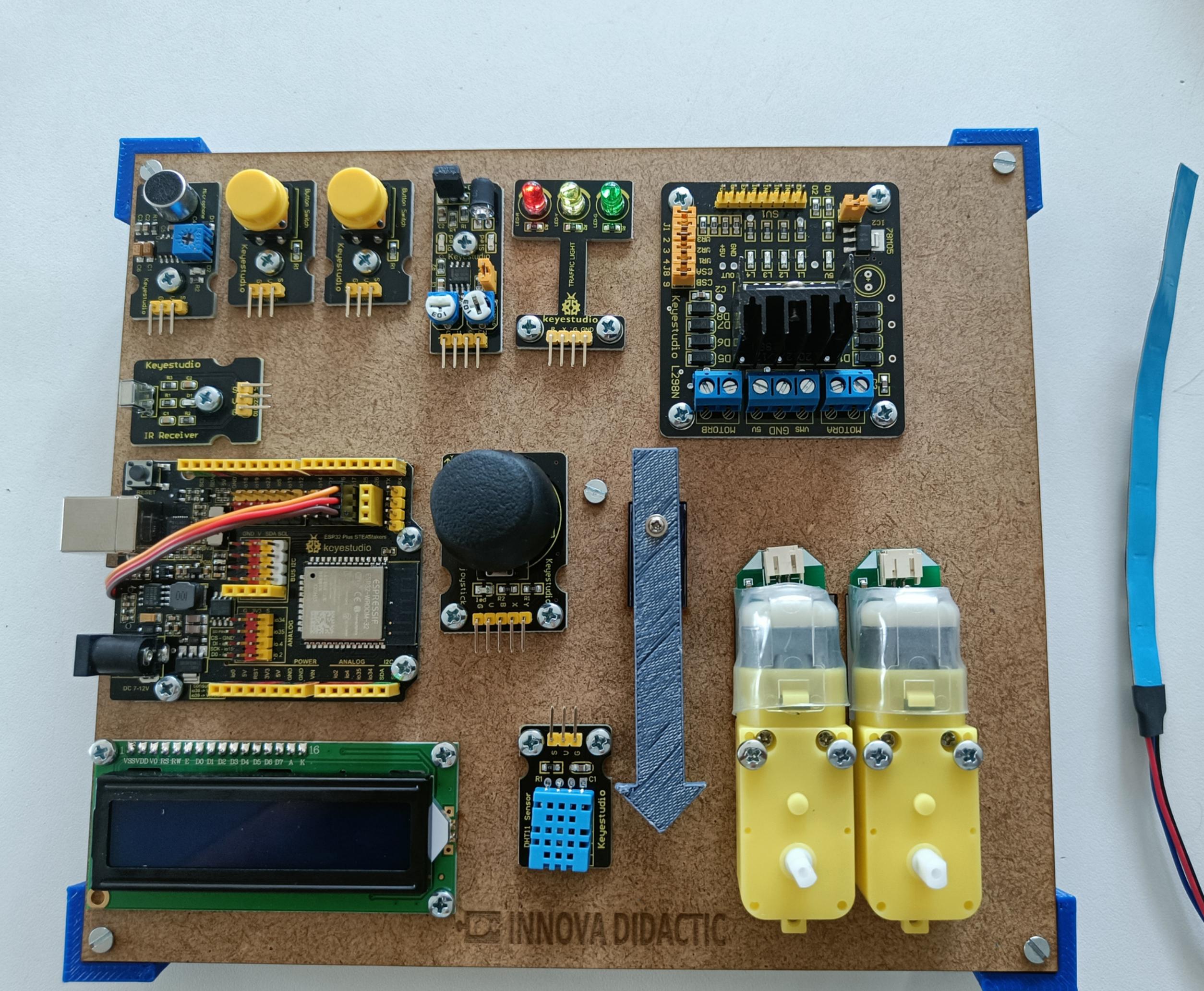
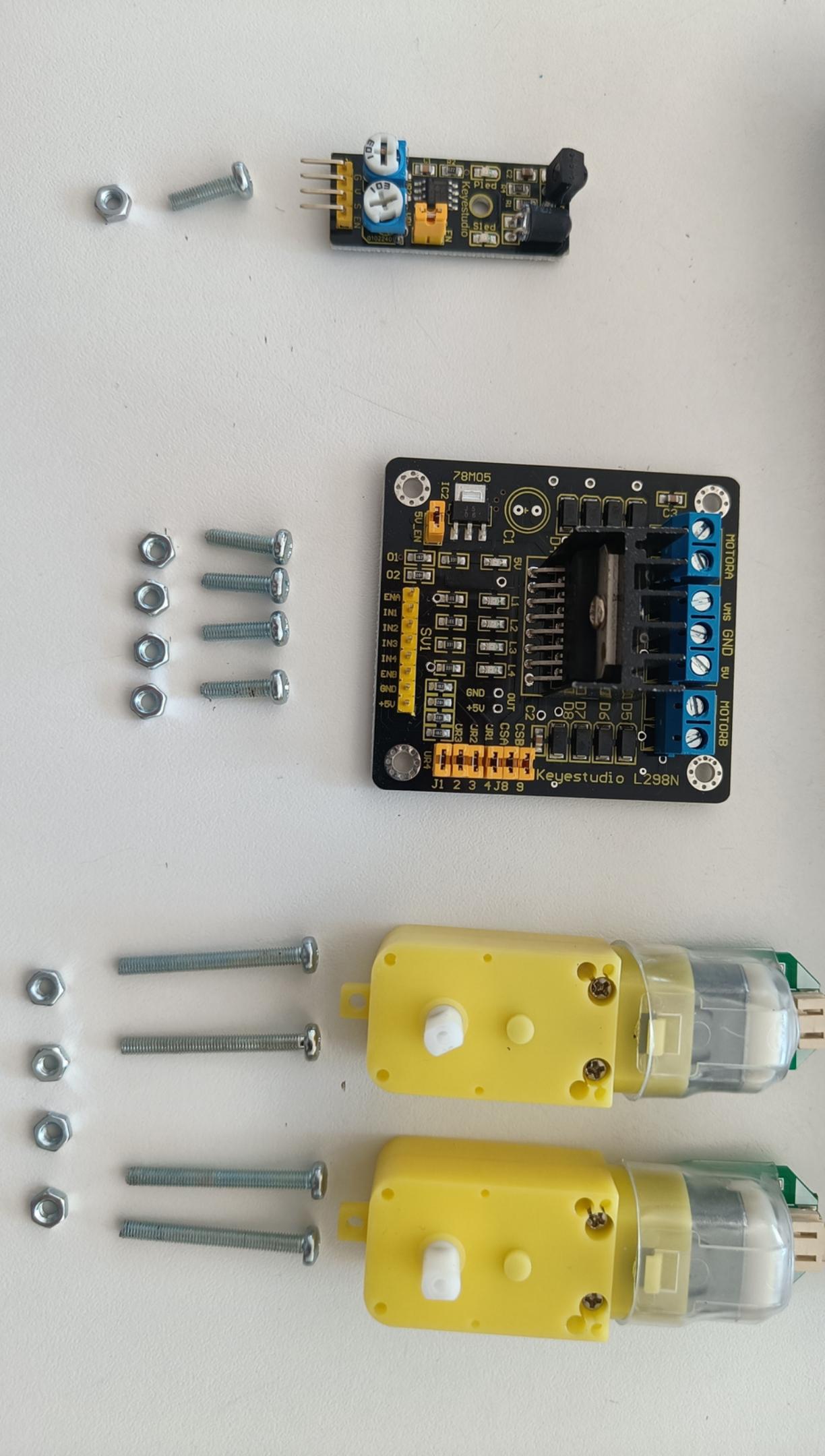
Sin que el servomotor se haya movido, montamos el soporte blanco y la flecha, de forma que la flecha apunte hacia abajo, tal y como se muestra en la imagen final.



Paso 5: Pieza a pieza, montamos todo el panel







Panel montado

