## STOCHASTIC FEM

## 4th Assignment

## Bayesian Inference

To perform Bayesian updating to the prior of E which it a normal  $NN(10^5, 2\times10^4)$ , we also have to know the "observation model" pdf or  $P(D|\Theta)$ . However, we only have  $P(D|\Theta)$  for the measurement of u. For u:

Pu(Pl0) ~ N(0.1, 0.01),

a normal with 0.1 m mean and standard deviation of 0.01 m.

Based on the previous assignments, we run the deterministic FEM for P=10 kN and get that for

\*  $E = 1.32 \times 10^5$ , we get  $u = 0.100286 \Leftrightarrow (\mu)$ 

\*  $E = 1.47 \times 10^{5}$ ,  $u = 0.0900523 \leftrightarrow (\mu - \sigma)$ 

\*  $E = 1.20 \times 10^{5}$ ,  $u = 0.110314 \iff (\mu + \sigma)$ 

Therefore, we can assume that  $P(D|\Theta)$  for E follows a normal distribution with mean  $\mu = 1.32 \times 10^5$  and Standard deviation  $\sigma = 0.135 \times 10^5$ .

Then, we perform Bayesian updating using the ARS algorithm, with:

prion: P(0) ~ N(105, 2×104)

observation needel:  $P(D10) \sim N(1.32 \times 10^5, 0.(35 \times 10^5))$ 

We used an condidate: q(u) ~ N(1.2×105, 0.2×105) with  $M = C3 \times 10^{-5}$ : Mg(x) ] p(D(0) p(0), \ u. The implementation, as well as the posterior pdf, it shown in the Mathematica notebook. Also, a companison between the prior and the updated (posterior) polf it shown at the end.