

Informal deformation theory (Michele V)

- deforming smth like $F(X) = \underline{a}_0 X^{d_0} + \underline{a}_1 X^{d_1} + \dots$
 → deforming coefficients is not a good idea, it might no longer be a curve

- infinitesimal family:

$$k \subset k(\mathbb{C}), A \cong k[t_1, \dots, t_n] / \mathfrak{a}, \sqrt{\mathfrak{a}} = (t_1, \dots, t_n)$$

$$X = \text{Spec } B \hookrightarrow \mathbb{A}_k^n, T = \text{Spec } A$$

- family (Ξ, φ) s.t.

$$\begin{array}{ccc} X \cong \text{Spec } k \times_T \Xi & \rightarrow & \Xi \\ \downarrow & & \downarrow \text{flat} \\ \text{Spec } k & \rightarrow & T \end{array}$$

Lemma. $\mathbb{Z}_0 \hookrightarrow \mathbb{Z}, N \subseteq \mathbb{G}_{\mathbb{Z}}$ nilpotent.

\mathbb{Z}_0 affine implies \mathbb{Z} affine.

→ so we can take $\Xi = \text{Spec } \dots$

$$\begin{array}{ccc} k \otimes_A A_2 \hookrightarrow "A_2" & & \\ \uparrow & \uparrow & \uparrow \\ \text{Rmk. } k \leftarrow A & & 0 \end{array}$$

- why flatness? it "preserves relations":

$$\begin{array}{ccccccc} P^n & \rightarrow & P^m & \rightarrow & P & \rightarrow & P/I \rightarrow 0 \\ & & \searrow & \nearrow & & & \\ & & I & & & & \\ & & \nearrow & \searrow & & & \\ & & 0 & & 0 & & \\ & & & & & & \nearrow \otimes k \\ P_A^n & \rightarrow & P_A^m & \rightarrow & P_A & \rightarrow & P_A/I_A \rightarrow 0 \\ & & \searrow & \nearrow & & & \\ & & I_A & & & & \\ & & \nearrow & \searrow & & & \\ & & 0 & & 0 & & \end{array}$$

Def. $X \subset \mathbb{A}^n$ is a complete intersection
if $I_X = (f_1, \dots, f_m)$ where $\text{codim}_{\mathbb{A}^n}(X) = m$.

- we would like to deform these?

- start with 1st order deformations: $A = k[t]/(t^2)$

$$\Rightarrow I_X = (f_1, \dots, f_m) \quad k[[\varepsilon]]$$

$$\Rightarrow I_A = ((f_1 + \varepsilon g_1), \dots, (f_m + \varepsilon g_m), \varepsilon g_{m+1})$$

forbidden by flatness?

- if $J_A = ((f_1 + \varepsilon \tilde{g}_1), \dots, (f_m + \varepsilon \tilde{g}_m))$
also a deformation - is it the same? when?

CLAIM. $I_A = J_A \iff g_i - \tilde{g}_i \in I_X$.

- we will not define a "change of coordinates"
explicitly beyond this, but use the term:

$$x_i \mapsto x_i' = x_i + \varphi_i(x_1, \dots, x_n) \varepsilon$$

$$\Rightarrow f_i(x) + g_i(x) \varepsilon \mapsto f_i(x) + \varepsilon \left[\sum_j \frac{\partial f_i}{\partial x_j} \varphi_j(x) + g_i \right]$$

$$k[x_1, \dots, x_n]$$

Jacobian
ideal, J

- now look,

$$\underbrace{P_k \times \dots \times P_k}_{n\text{-d times}} / I_X^{nr} = G_X \oplus \dots \oplus G_X / J$$

Remark. for locally complete intersections,
if X is smooth $\Rightarrow X$ is RIGID.

\rightarrow because not all derivatives vanish,
 $J \supset 1$.

- now look at d -vector spaces ($d = \text{length}$)

in $H^0(\mathbb{Z}, \mathcal{O}_{\mathbb{Z}})$		dim	length
$\rightarrow k[z]$	$= \langle 1, z \rangle$	0	2
$k[t](t^3)$	$= \langle 1, t, t^2 \rangle$	1	3
$k[x, y]/(x^2, y^2, xy)$	$= \langle 1, x, y \rangle$	2	3

$$\mathbb{Z} \hookrightarrow \mathbb{P}^{n \geq 3}, d \geq 4.$$

- e.g. let's deform $y^2 - x^2(x-1)$

$$\Rightarrow A[x, y]/(y^2 - x^2(x-1) + \varepsilon P(x, y))$$

$$\Rightarrow (I, J) = (y^2 - x^2(x-1), y, -3x^2 - 2x)$$

$$\xrightarrow{\text{chinese remainder}} = (x, y)(x^2(x-1), y, -3x-2)$$

$$\Rightarrow P_{k/(x, y)} \times P_{k/\underbrace{(\quad)}_{=0}} \simeq \mathbb{C}$$

\uparrow sing. locus
 $\underline{=0}$ since $-3x-2$ & $x^2(x-1)$ doesn't $=0$ at the same time

\rightarrow so $P[x, y] = \lambda \in \mathbb{C}$, just a scale.

$$\begin{array}{l} P^R(r_{ij}) \xrightarrow{p^m(f_i)} P \rightarrow P/I \rightarrow 0 \quad \text{exact} \\ \text{deform} \rightarrow P_A^R(r'_{ij}) \xrightarrow{p^m(f'_i)} P_A \rightarrow P_A/I_A \rightarrow 0 \end{array}$$

$$\text{s.t. } r'_{ij} = r_{ij} + \varepsilon s_{ij}$$

$$f'_i = f_i + \varepsilon g_i$$

and exact

$$\Rightarrow r'_i f'_i = \underbrace{r_i f_i}_{\substack{\text{so } 0 \\ \text{exactness}}} + \varepsilon (g_i r_i + f_i s_i) \stackrel{0}{=} 0$$

$$\Rightarrow g_i r_i = -f_i s_i$$

$$g: I \rightarrow P/I \in \text{Hom}_P(I, P/I)$$

$$\text{— note that } \text{Hom}_{P/I}(I/I^2, P/I) \cong N_{X/\mathbb{A}^n}$$

$$\text{— for smooth } x, \quad 0 \rightarrow T_x \rightarrow T_{\mathbb{A}^n}|_x \rightarrow N_{x/\mathbb{A}^n} \rightarrow 0$$

$$\text{— for nonsmooth, } \dots \dots \dots \rightarrow T_x^1 \xrightarrow{\sim} 0$$

\uparrow
 Schlessinger
 sheaf