


Yigao Fang

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EDUCATION

University of Pennsylvania

Philadelphia, PA

- Master of Science in Engineering, Data Science | Computer and Information Science Department *Dec. 2023 (Expected)*
- Coursework: Web Developing, Big Data Analytics, Statistics for Data Science

University of Michigan (UM)

Ann Arbor, MI

- Bachelor of Science in Engineering, **Computer Science** | Minor: Mathematics **GPA: 3.98/4.00** *May 2022*
- Coursework: Software Engineering, Data Structures, Algorithms, Operating Systems, Database Management, Machine Learning, Parallel Programming with GPUs, Game Design and Development, Computer Vision, Linear Programming, Numerical Methods

Shanghai Jiao Tong University (SJTU)

Shanghai, China

- Bachelor of Science in Engineering, Electrical and Computer Engineering (ECE) **GPA: 3.84/4.00** *Aug. 2022*
- Scholarships: China National Scholarship, Lums Scholarship, Yu Liming Scholarship

TECHNICAL SKILLS

Programming: Python (pandas, PyTorch, OpenCV, scikit-learn, gurobipy), Java, C++, JavaScript, SQL, HTML, CSS, C#, C

Framework and Tools: React, API, MATLAB, TensorFlow, Linux, Git, LaTeX, CUDA, Jupyter Notebook, R Studio, Jira

SOFTWARE ENGINEERING EXPERIENCE

Full Stack Developing Research Internship: Shanghai Jiao Tong University

May 2022 – Aug. 2022

- Founded a platform that predicts the force and energy of a catalyst using artificial intelligence with **Mean Avg. Error < 0.30 eV**.
- Innovated a **Colab** pipeline that preprocesses the **ASE** dataset and improves the **GemNet** model by adding 4 embedding layers.
- Architected the Back End with **Python** that imports catalyst structures as input and trains on 2 million data points.

Software Developing Research Internship: Peisen's Lab

May 2021 – Sep. 2021

- Realized an innovative VR system based on computer vision and simulated the player movement with **deviation < 0.1 mm**.
- Generated a 256 * 256 binary graph based on **de Bruijn** to provide a unique pattern for each 2-dimension position.
- Employed **OpenCV** with **Python** to calculate the real-time 6 degrees of freedom coordinates of the VR helmet based on the 24-frame video clips captured by the onboard camera, and imported the position indexes into **Unity**.

SELECTED PROJECTS

3D Adventure Game: Asylum 7 ([www-personal.umich.edu/~fgsepter/Asylum7\(Web\)2/](http://www-personal.umich.edu/~fgsepter/Asylum7(Web)2/))

Feb. 2022 – Apr. 2022

- Led a team of five and published a first-person adventure game with 6 scenes based on **Unity** and **C#**.
- Spearheaded the game's core mechanisms with **Coroutine**, such as scene transitions and player movement, and trap controls.
- Managed the 3-stage (alpha, beta, gold) **iterative process** on **Jira** and **GitHub**, following design, implementation, and test circles.

Operating Systems Implementation (<https://github.com/fgsepter/OSimpl>)

Jan. 2022 – Apr. 2022

- Utilized **C++** to implement **threads** and monitors (**mutex** and **conditional variable**) on uniprocessor and multiprocessor systems.
- Conceptualized states diagram and clock algorithm to develop a **pager** that manages application processes' virtual address space.
- Simulated a **multi-threaded** network file system that connects between server and client sides using **sockets**.

Birdcall Soundscape Classification (www.kaggle.com/competitions/birdclef-2021)

Apr. 2021 – Jun. 2021

- Preprocessed the audio dataset of **62.9K** birdcalls and conveyed them into trainable spectrum maps using **librosa** with **Python**.
- Strengthened **DenseNet-121** convolutional neural network (**CNN**) and visualized the prediction result with **F1-score = 64.49**.

Intention Estimation for Autonomous Driving (gitlab.eecs.umich.edu/xsh/eecs442_pi)

Feb. 2021 – May. 2021

- Transformed the **res-Net18** model into **PyTorch** Recurrent Neural Network (**RNN**) pipelines by adding drop-out layers followed by fully connected layers to match **LSTM** cells, and estimated pedestrians' crossing-road intention with accuracy up to **77.5%**.
- Applied **OpenCV** Multiple Object Tracking (**MOT**) to extract 3 * 128 * 128 images for pedestrian from high-resolution **PIE** dataset.

LEADERSHIP AND ADDITIONAL EXPERIENCE

Leadership: Department Minister, UM-SJTU Joint Institute Student Union; Club President, Monarch Drama Troupe at SJTU

Coding Competitions: Golden Medal, University Physics Competition; Meritorious Winner, Mathematical Contest in Modeling

Teaching Assistant: VP 160 Honors Physics & VE 230 Electromagnetics, Shanghai Jiao Tong University

Teaching Assistant: EECS498/598 - 008, Deep Learning for Vision, University of Michigan