

Experimenting with the method Framework

May 12, 2022

1 Continuous ensemble training

Now that the data, the network frameworks and the training loops are set up, we can investigate further.

2 Setting everything up

```
[11]: # Reload module in case of changes
importlib.reload(utils)
```

```
[11]: <module 'lib.utils' from
'/net/projects/scratch/winter/valid_until_31_July_2022/fheitzer/BAThesis-
code/notebooks/./lib/utils.py'>
```

```
[ ]: import tensorflow as tf
import numpy as np
import pandas as pd

import sys; sys.path.insert(0, '..')
import importlib

from lib import data, networks, training, utils
```

```
[ ]: # load 10 class data
train_ds_pre, train_ds_post, test_ds, train_generator, test_generator = data.load_data(rotation=30)
dataset_shape = (tf.TensorSpec(shape=(28,28,1), dtype=tf.float64),
                 tf.TensorSpec(shape=(10,), dtype=tf.float32),
```

```

        tf.TensorSpec(shape=(), dtype=tf.int32),
        tf.TensorSpec(shape=(10,), dtype=tf.float32))

num_classes = 10
# Small model
model1 = networks.NN([128, 128], num_classes)
# Broad Model
model2 = networks.NN([512], num_classes)
# Mixed Model
#model3a = networks.NN([256, 256], num_classes)

model3b = networks.CNN([(32, 3), (64, 5)])
# cnn
model4 = networks.CNN([(32, 3), (64, 5), (128, 7)], num_classes)
# cnn small
model5 = networks.CNN([(16, 3), (32, 3), (64, 5)], num_classes)
# ensemble
ensemble = networks.Ensemble([model1, model2, model3b, model4, model5])

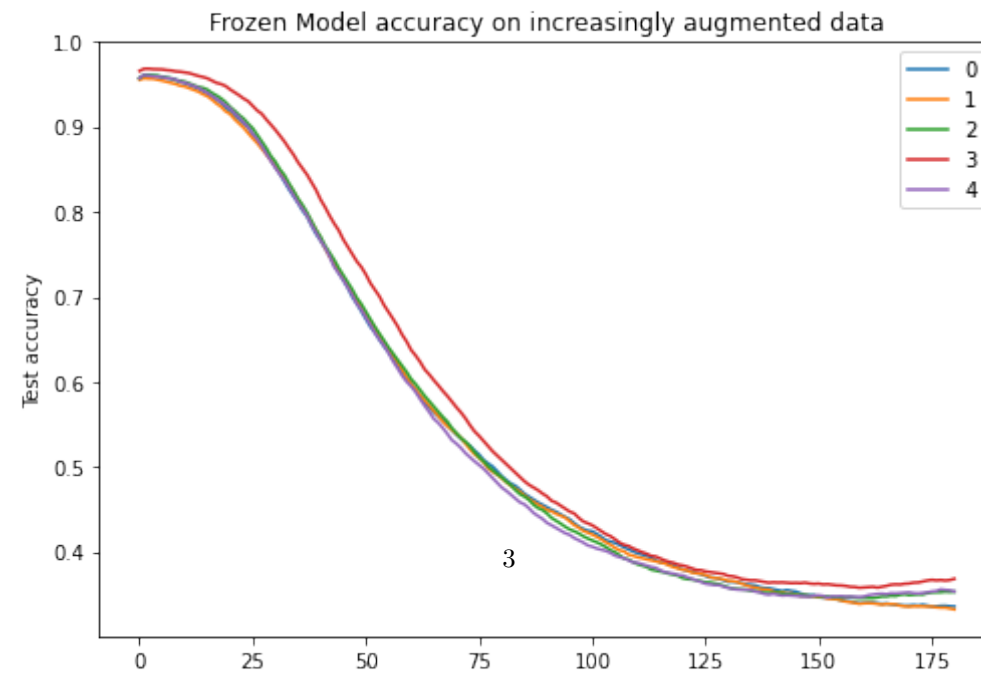
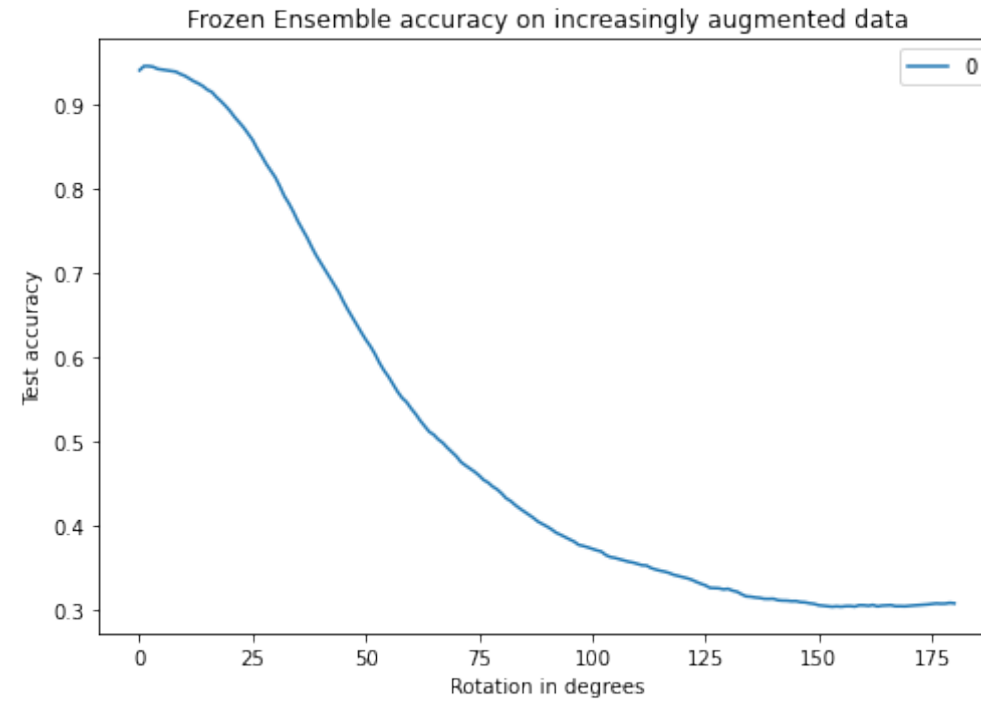
model1.load_weights('../models/NN128128extra')
model2.load_weights('../models/NN512extra')
model3b.load_weights('../models/CNN3264extra')
model4.load_weights('../models/CNN3264128extra')
model5.load_weights('../models/CNN163264extra')

```

3 Investigation

3.1 What happens if the model has to face increasingly augmented data?

```
[11]: utils.plot_frozen_model('Frozenmodel_r180_c180')
```



3.2 We should apply continuous ensemble training!

Starting off with a cycle size of 15.000

3.2.1 How does the method react to different jumps in augmentation?

```
[24]: jumpfiles = ["Jump_r5_e1_b1_c24_d15000",  
                  "Jump_r10_e1_b1_c24_d15000",  
                  "Jump_r20_e1_b1_c24_d15000",  
                  "Jump_r25_e1_b1_c24_d15000"]
```

```
[32]: utils.plot_multiple_ensemble_accuracies(jumpfiles, "Jump")
```

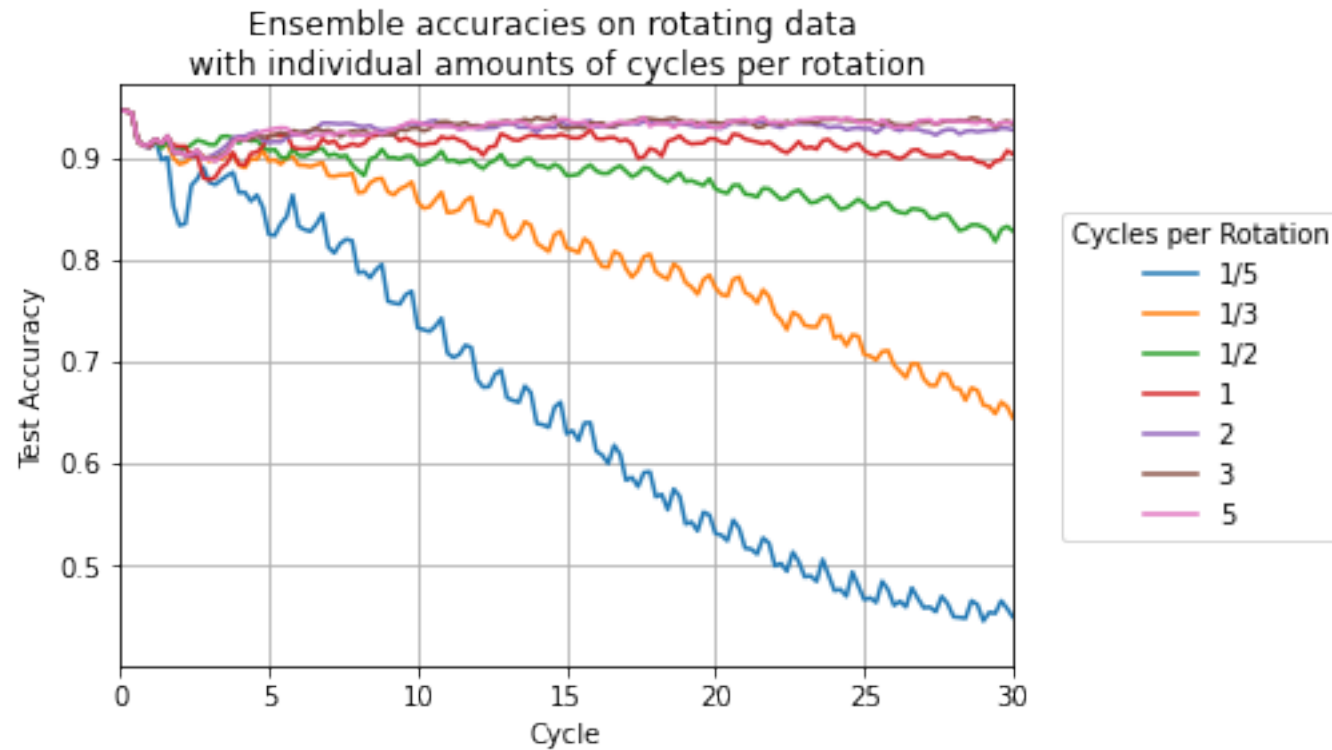
Frozen model on data with different amounts of rotation



3.2.2 What augmentation speed can the method handle?

```
[28]: files = ["Increment_r180_e1_b1_c36_d15000",  
              "Increment_r180_e1_b1_c60_d15000",  
              "Increment_r180_e1_b1_c90_d15000",  
              "Increment_r90_e1_b1_c90_d15000",  
              "Increment_r180_e1_b1_c360_d15000",  
              "Increment_r30_e1_b1_c90_d15000",  
              "Increment_r180_e1_b1_c900_d15000"]
```

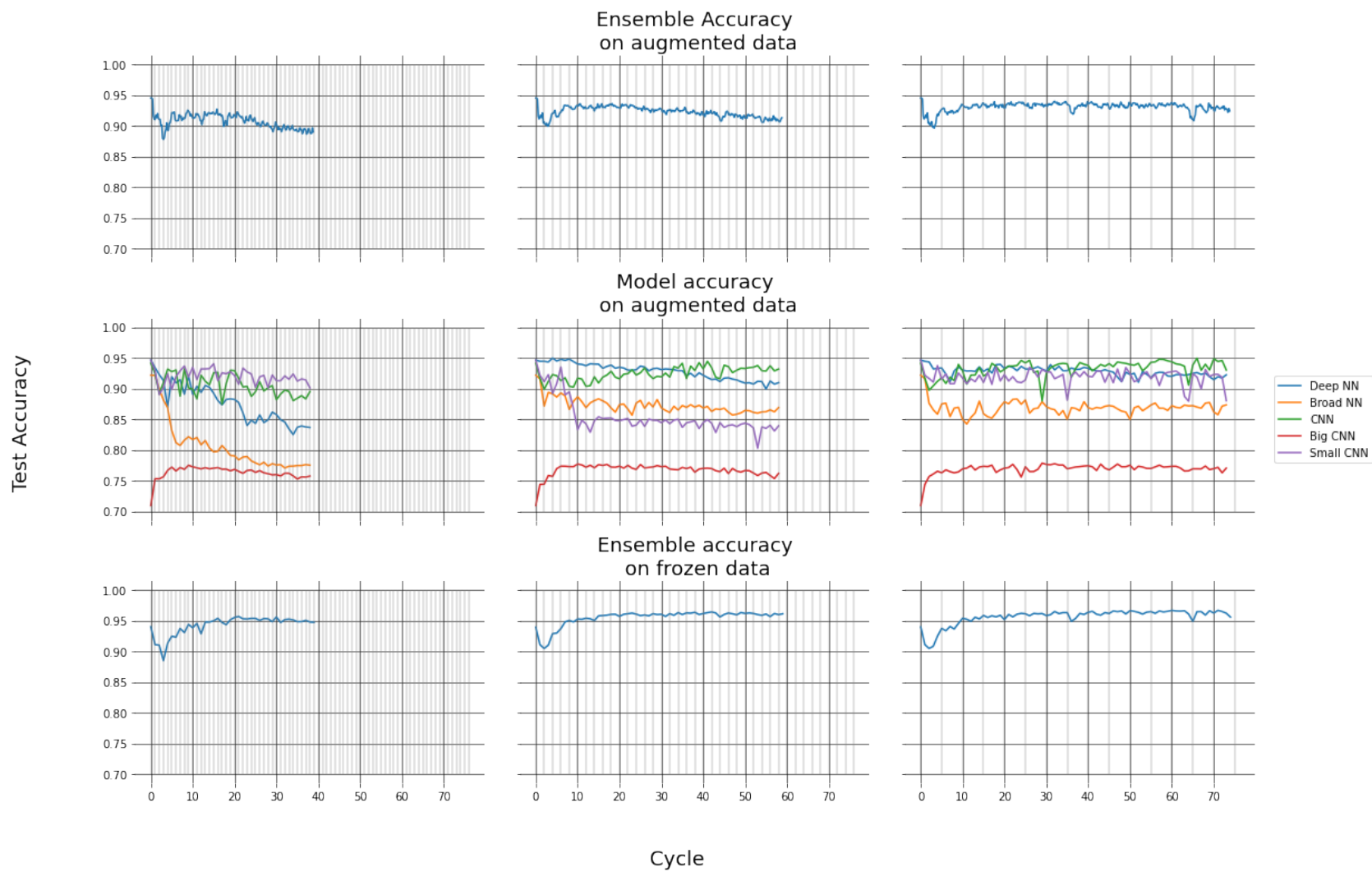
```
[30]: utils.plot_multiple_ensemble_accuracies(files, "Increment", xlim=30)
```



3.2.3 Does the continuously trained ensemble still perform well on the original data and how do the individual models cope with the augmentation?

```
[57]: utils.plot_cycle_accuracies_grid(files[3:-2] + [files[-1]])
```

Each column shows a separate simulation with 1, 2, and 5 cycles per rotation as indicated by the background grid



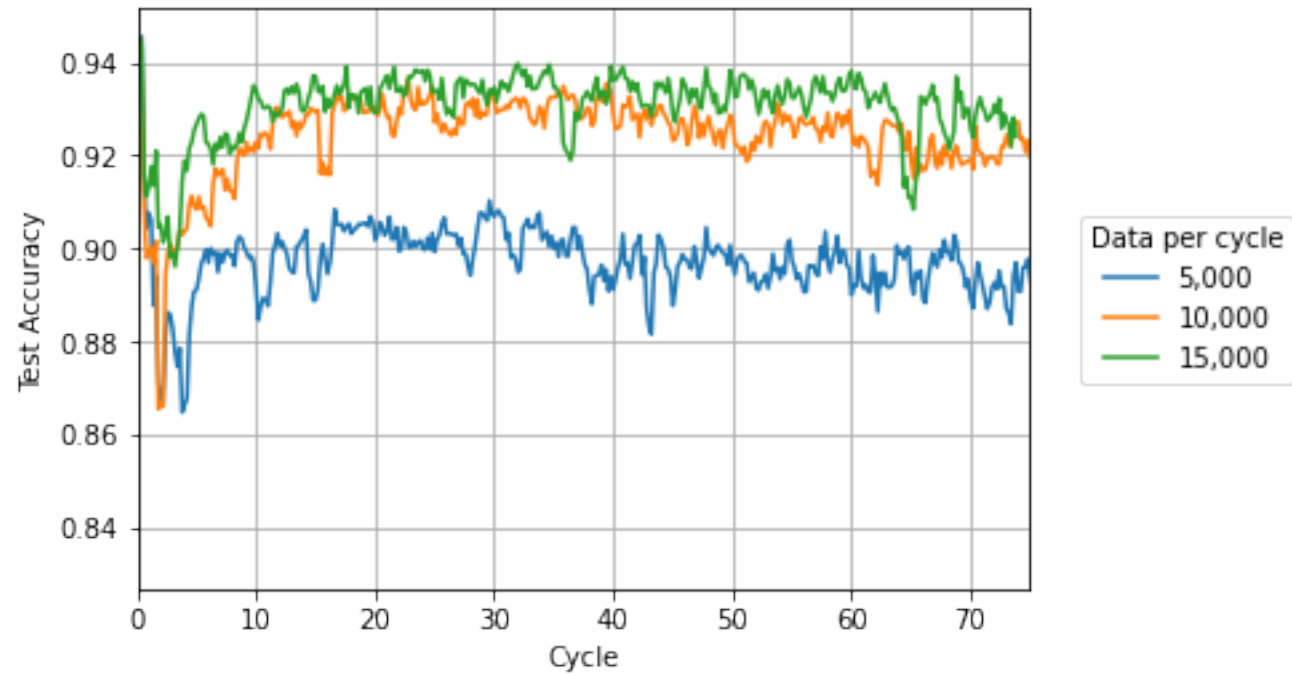
Continuous ensemble training allows for stable performance in a changing environment without a decrease in performance on the original data.

3.3 What if there is less or more data per cycle?

```
[27]: paths = ["datapercyclecomparison_r20_e1_b1_c100_d3000",  
              "Increment_r90_e1_b1_c90_d15000",  
              "lessdata_r50_e1_b1_c250_d5000",  
              "lessdata_r50_e1_b1_c250_d10000",  
              "Increment_r180_e1_b1_c900_d15000"]
```

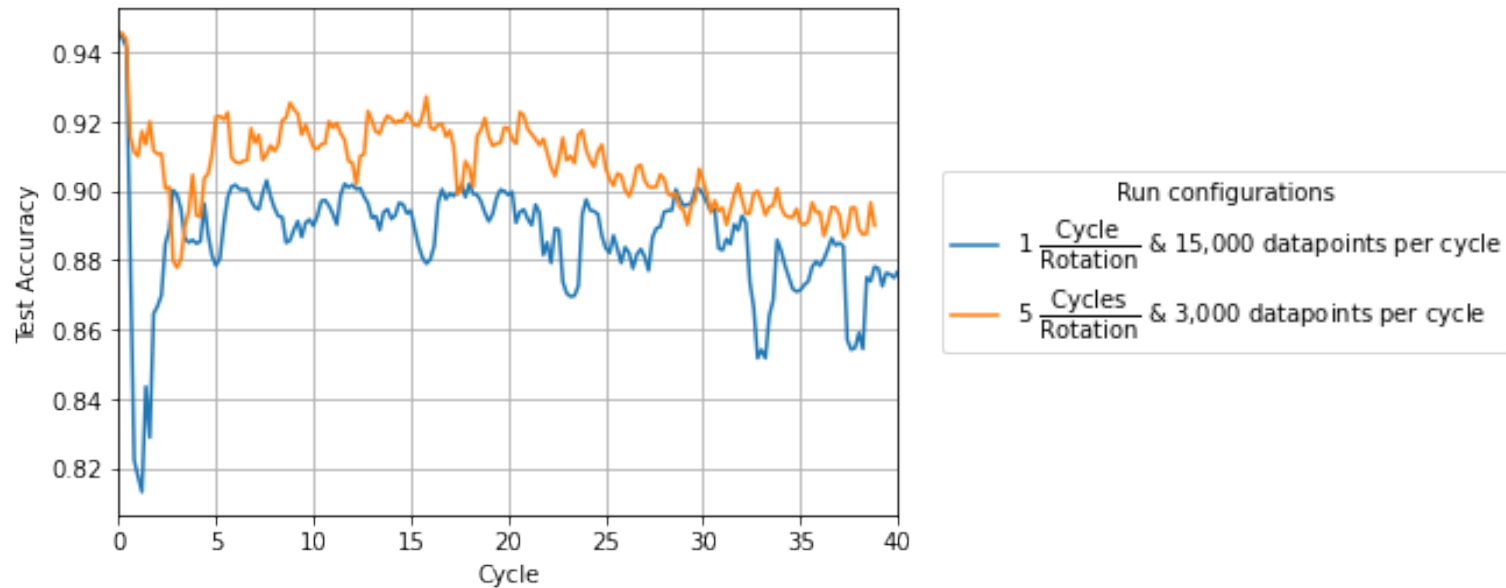
```
[13]: utils.plot_multiple_ensemble_accuracies(paths[2:], "5cr_comparison", xlim=75)
```


5 cycles per rotation runs with different amounts of data per cycle



```
[32]: utils.plot_multiple_ensemble_accuracies(paths[:2], "1cr15k_5cr3k", xlim=40)
```

One run has 5 times more cycles per rotation, the other has 5 times more data per cycle



3.4 What does the collected data show?

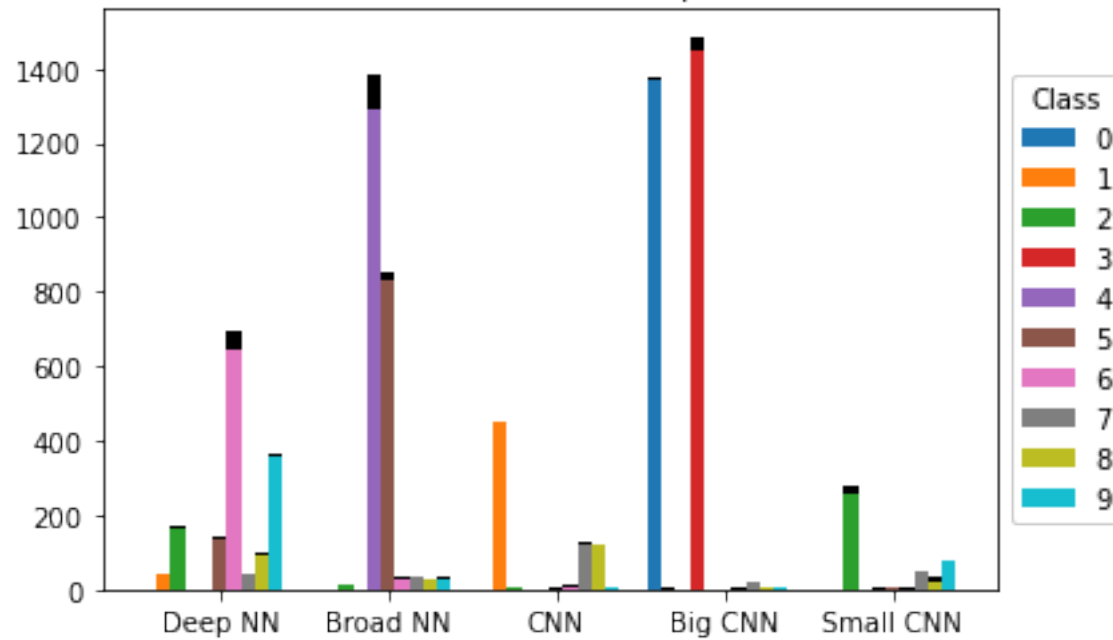
3.4.1 1 $\frac{\text{Cycle}}{\text{Degree of rotation}}$

(90 degrees in 39/90 cycles)

```
[20]: utils.plot_cycles_online(ensemble,  
                                "Increment_r90_e1_b1_c90_d15000", only_some=[-2,-1])
```

```
Cycle: 0  
7701.0 collected datapoints labeled correct  
328.0 collected datapoints were labeled wrong  
544 datapoints were not classified.
```

Amount of the collected data (8029) per model and class.

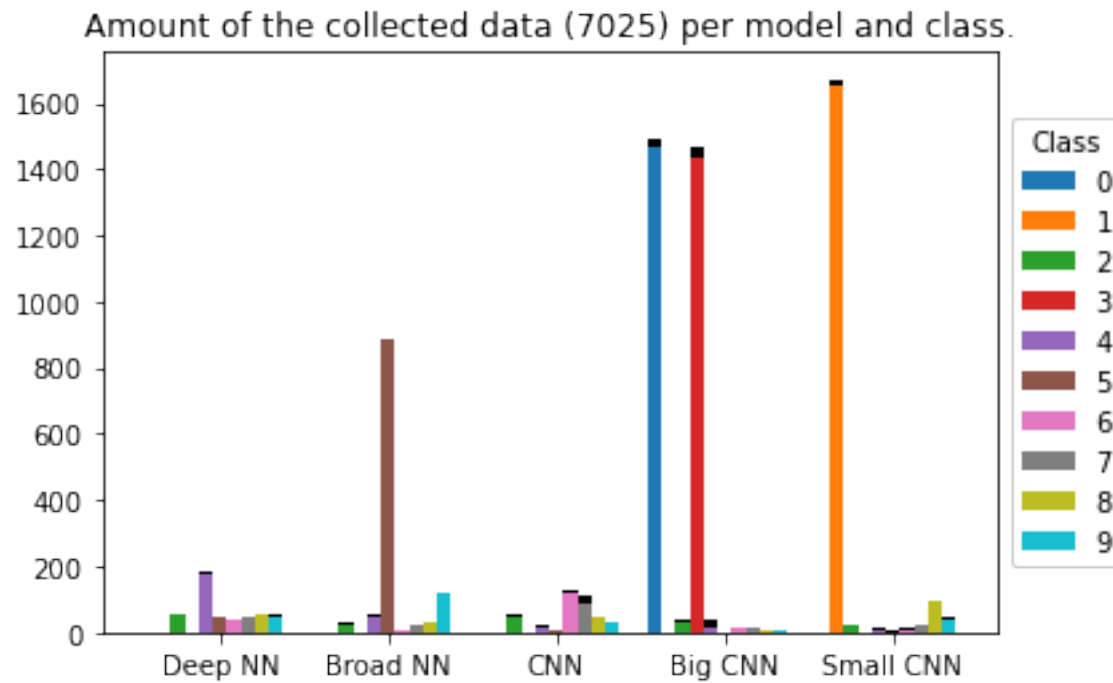


3.4.2 $2 \frac{\text{Cycles}}{\text{Degree of rotation}}$

(180 degrees in 59/360 cycles)

```
[19]: utils.plot_cycles_online(ensemble,
                                "Increment_r180_e1_b1_c360_d15000", only_some=[-2,-1])
```

Cycle: 0
6787.0 collected datapoints labeled correct
238.0 collected datapoints were labeled wrong
271 datapoints were not classified.

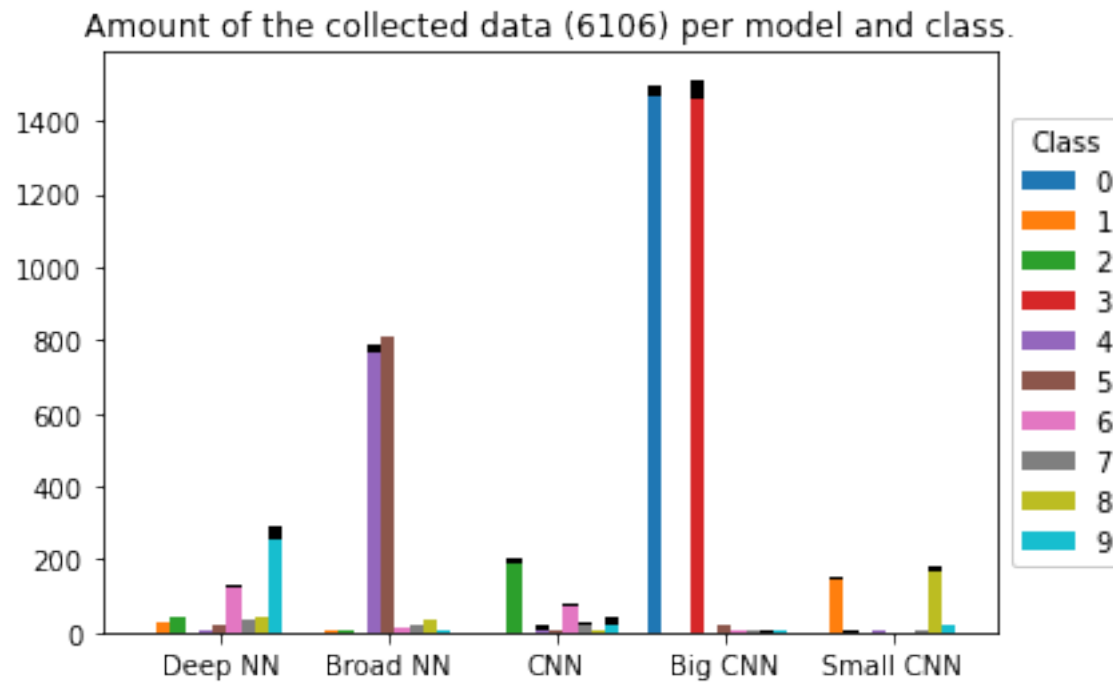


3.4.3 $3 \frac{\text{Cycles}}{\text{Degree of rotation}}$

(30 degrees in 48/90 cycles)

```
[18]: utils.plot_cycles_online(ensemble,
                                "Increment_r30_e1_b1_c90_d15000", only_some=[-2,-1])
```

```
Cycle: 0
5872.0 collected datapoints labeled correct
234.0 collected datapoints were labeled wrong
187 datapoints were not classified.
```



3.5 Can we evaluate the specialization?

```
[55]: utils.classification_specialization_mean(ensemble,  
      ["Increment_r90_e1_b1_c90_d15000",  
       "Increment_r180_e1_b1_c360_d15000",  
       "Increment_r30_e1_b1_c90_d15000"],  
      legend=["1", "2", "3"])
```

