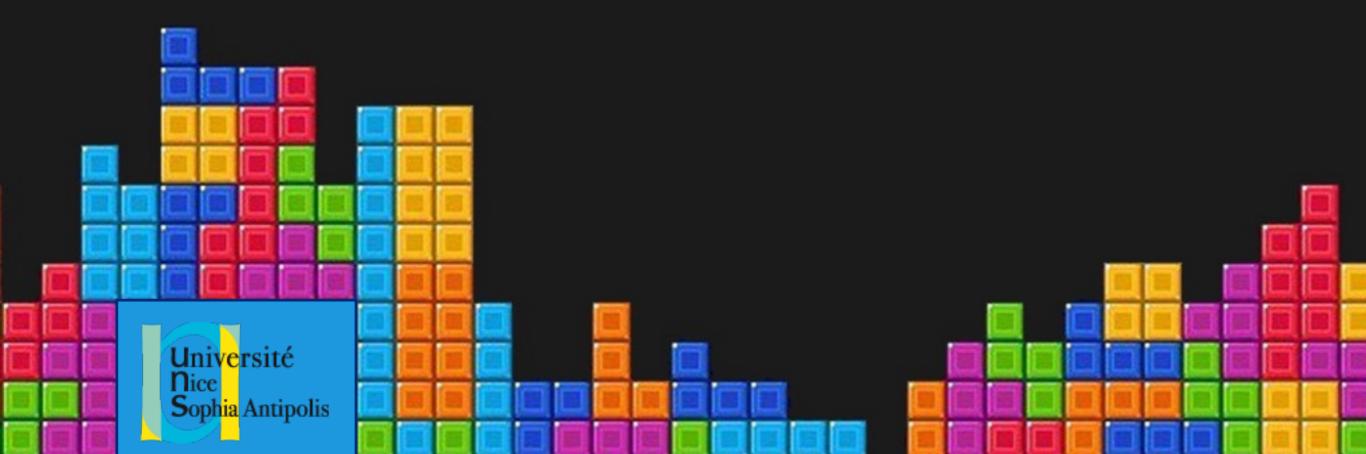
## Resource management in laaS cloud

Fabien Hermenier

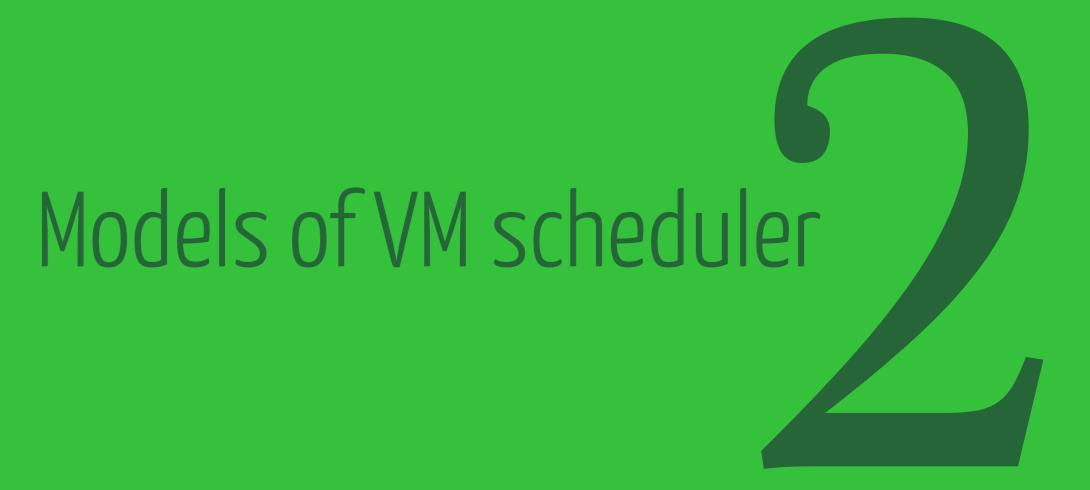


#### where to place the VMs



how much to allocate

# What can a resource manager do for you





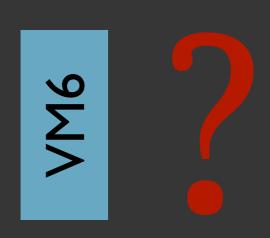
### Implementing VM schedulers

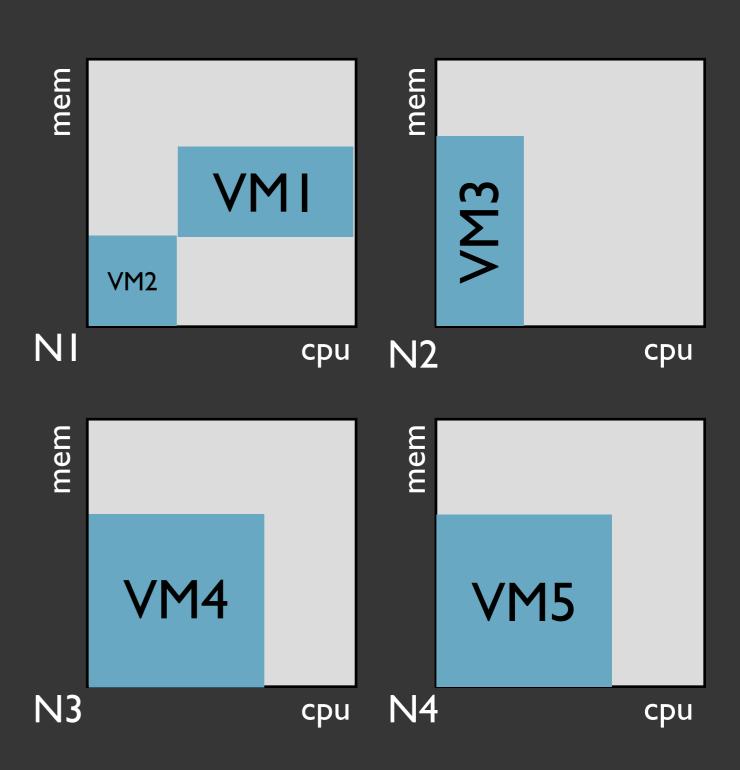
# What can a resource manager do for you



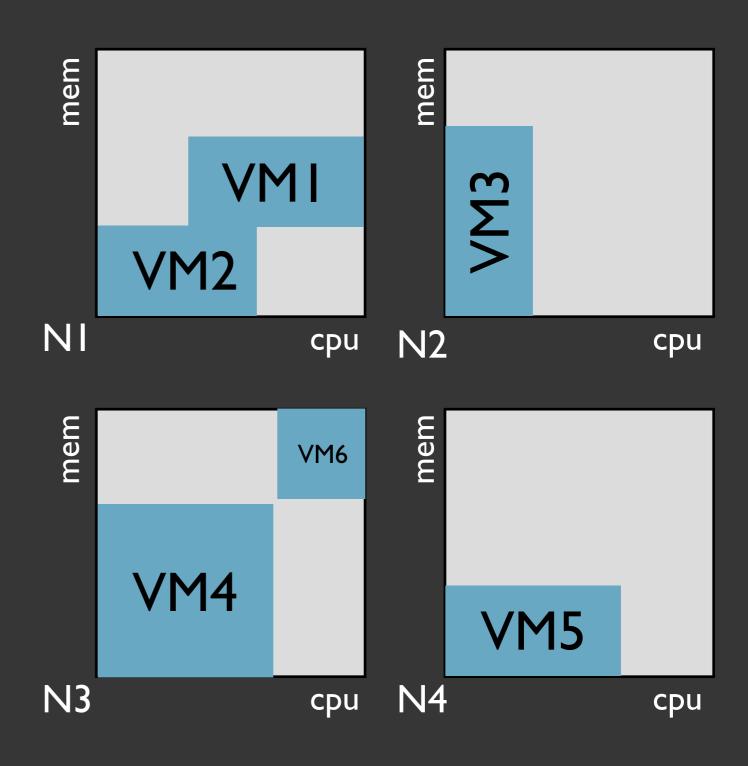
provide the awaited Quality of Service address the management objectives

#### the RM should solve that





#### the RM should prevent that



## Dervice Level Agreement

a contract where a service is formally defined

performance indicator
MTTR
MTBF
availability (MTBF/MTTR + MTBF)
pricing
penalties

#### Google Cloud Platform

| Monthly<br>uptime<br>percentage | Percentage of monthly bill for the respective Covered Service which does not meet SLA that will be credited to future monthly bills of Customer |
|---------------------------------|---|
| 99.00% - <<br>99.95%            | 10%   |
| 95.00% - <<br>99.00%            | 25%   |
| < 95.00%                        | 50%   |

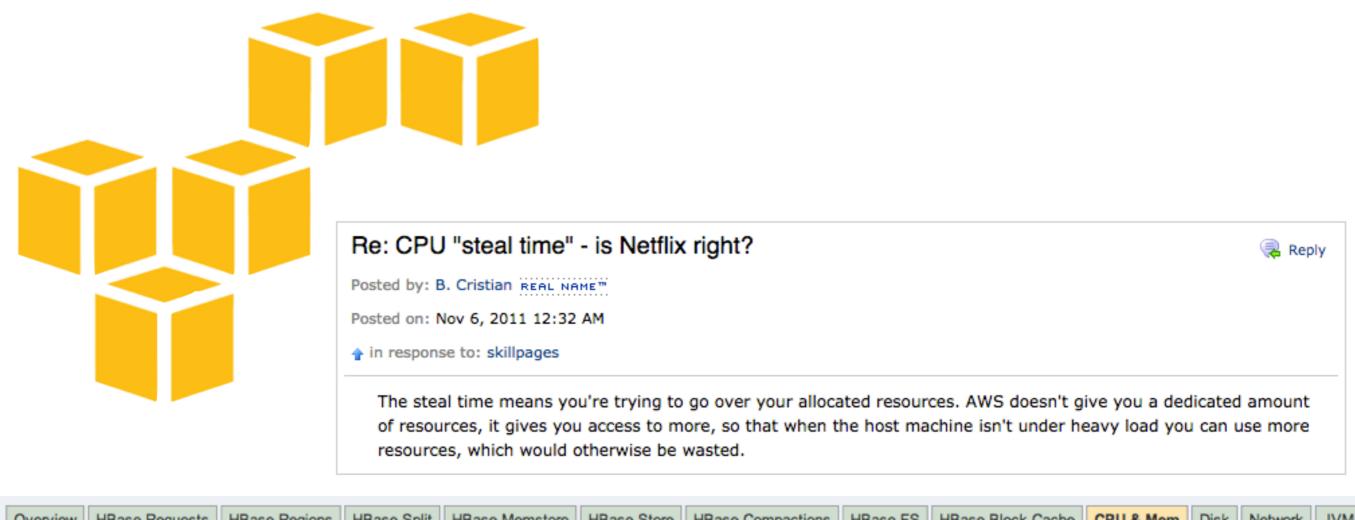
#### uptime as the only Key Performance Indicator (KPI)

#### Cloud Performance SLAs

#### What customers want

guaranteed capacities (CPU, memory, bw) guaranteed latencies/throughput (network, load balancer, disk)

What providers give





## the objective

provider side min(x) or max(x)

#### atomic objectives

```
min(penalties)
min(Total Cost Ownership)
min(unbalance)
```

#### composite objectives

using weights

$$min(\alpha x + \beta y)$$

How to estimate coefficients?

useful to model sth. you don't understand?

$$min(\alpha \ TCO + \beta \ VIOLATIONS)$$
 $\in$  as a common quantifier:

 $max(REVENUES)$ 



#### Should a client ask for an objective

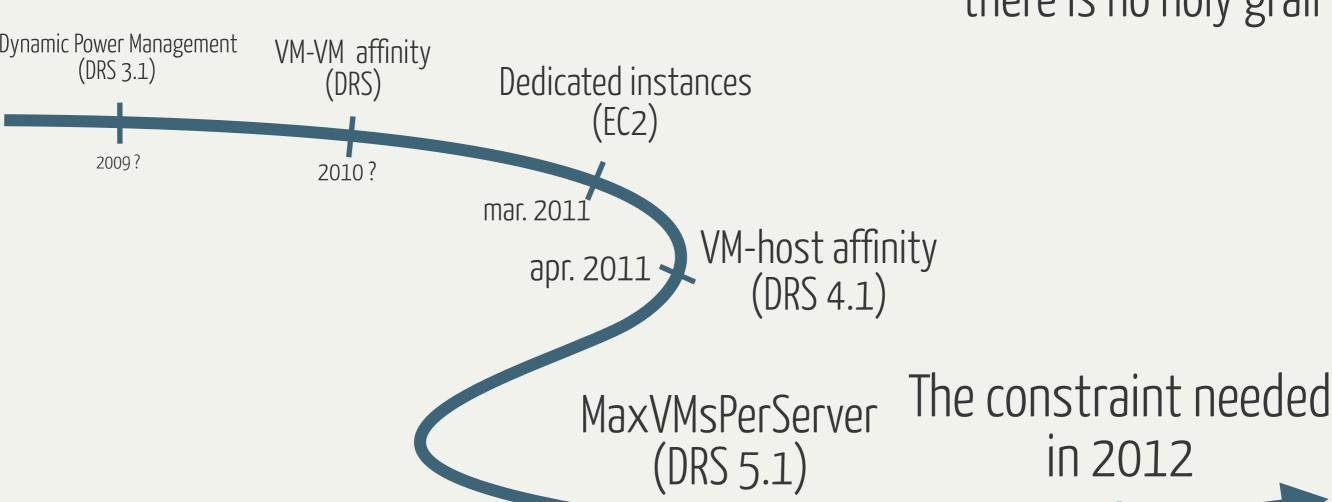
#### Should a client ask for an objective

no if the provider cannot prove it is achieved one can check the latency is below a threshold proving a latency is minimal ...

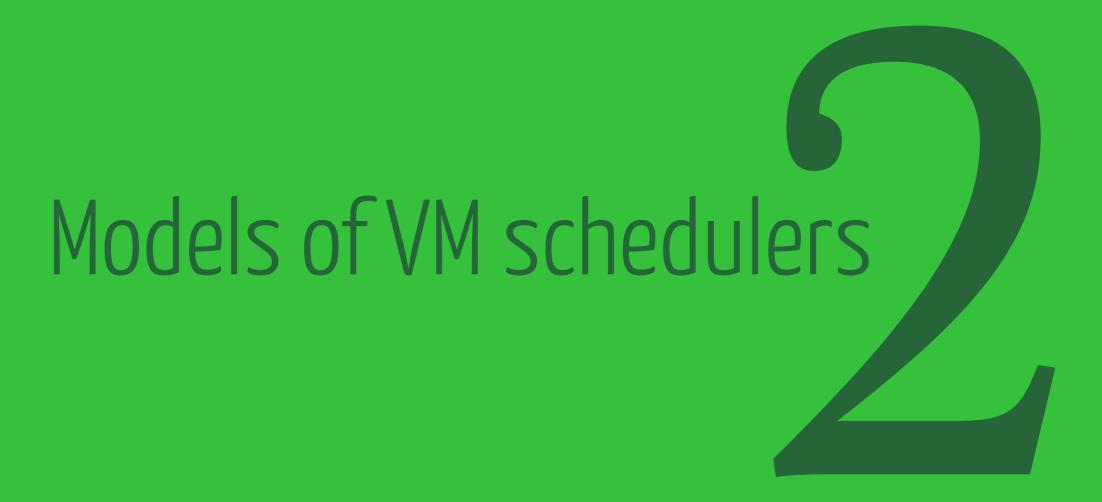
## SLOs and objectives are evolving

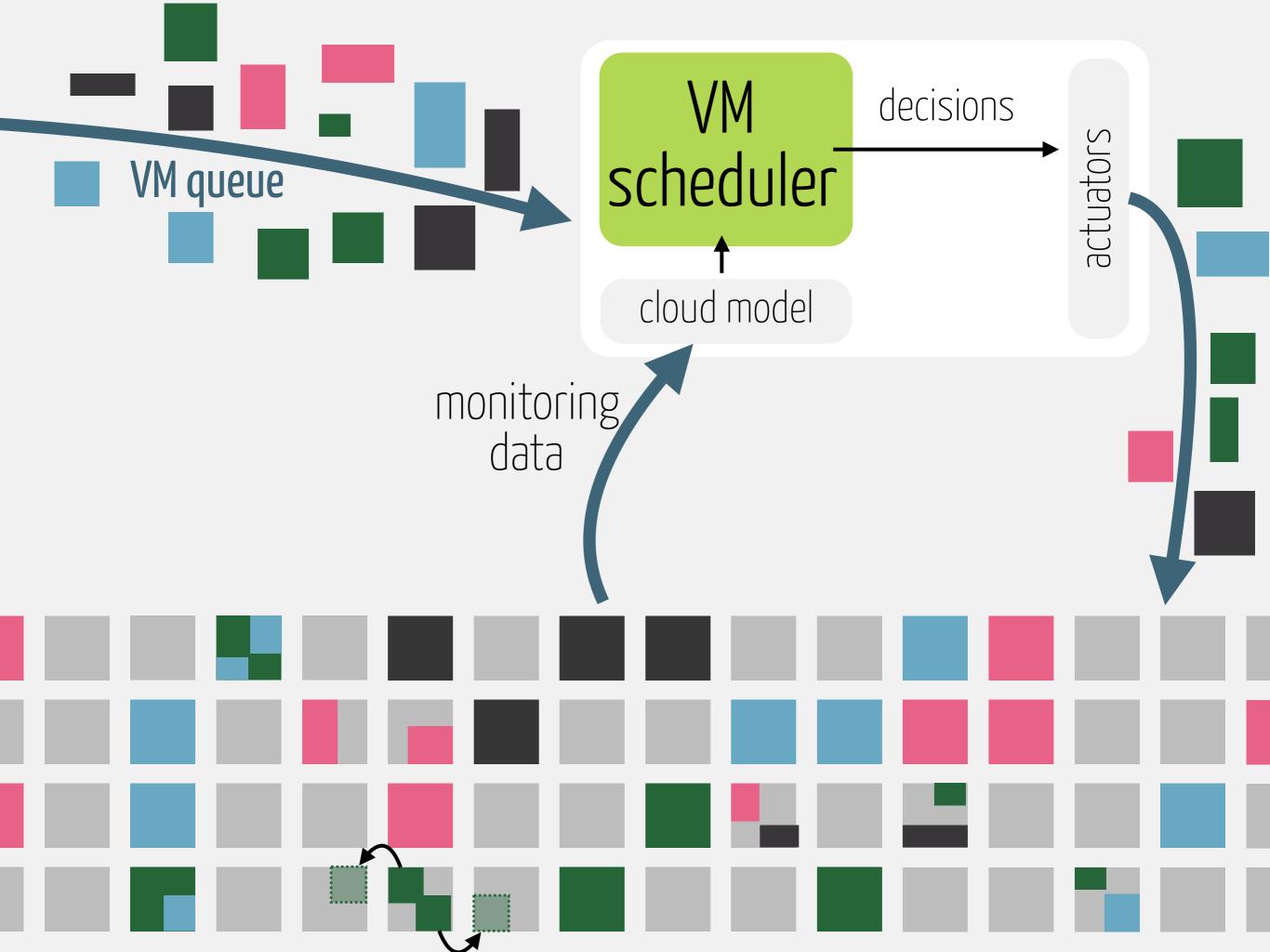
there is no holy grail

?? 2013

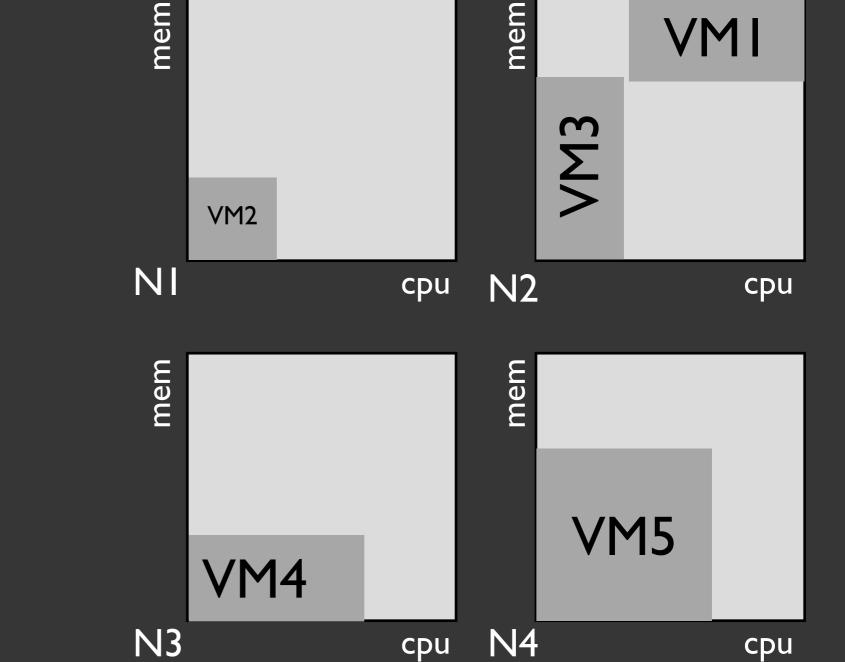


sep. 2012

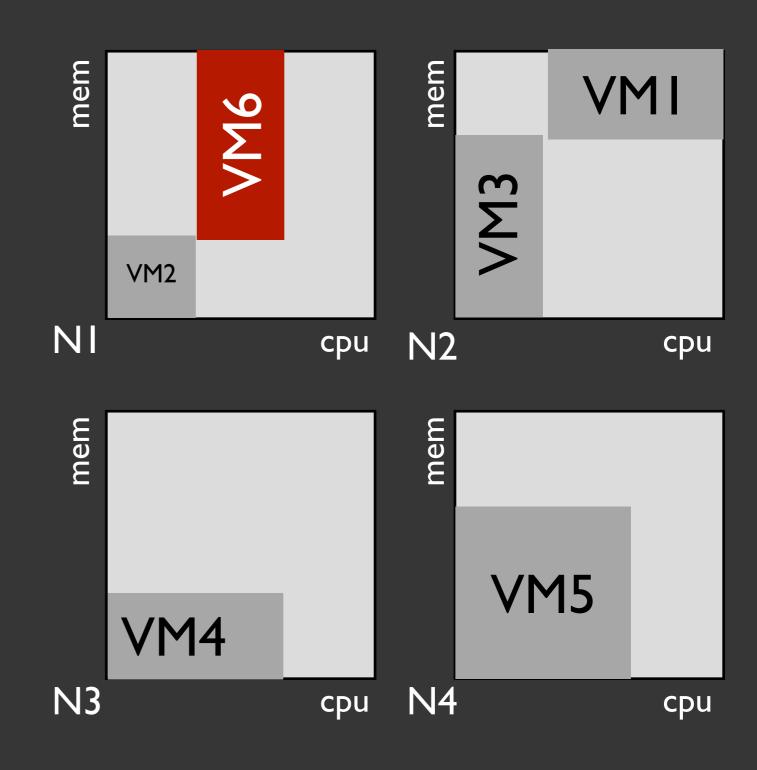




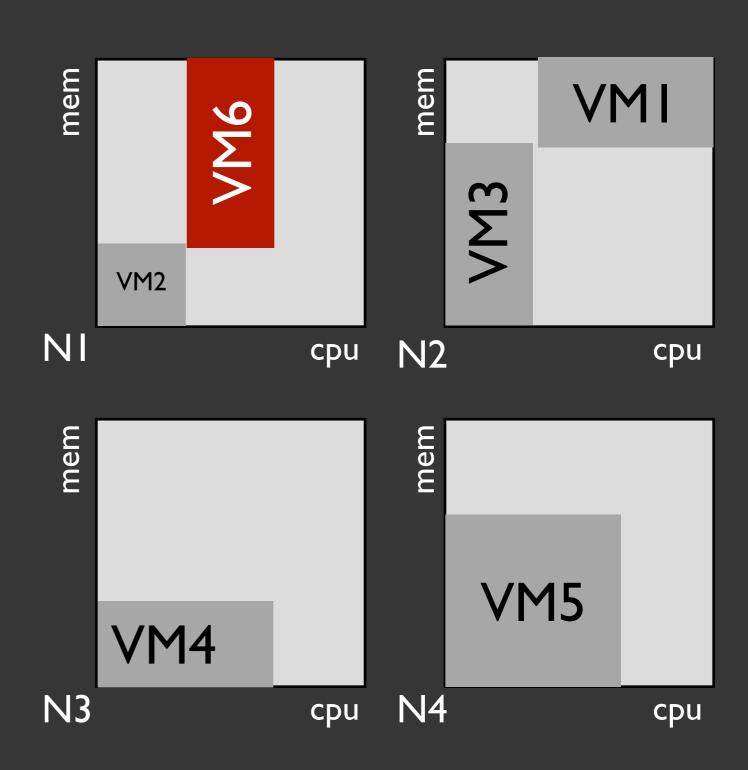
static resource allocation



9W/

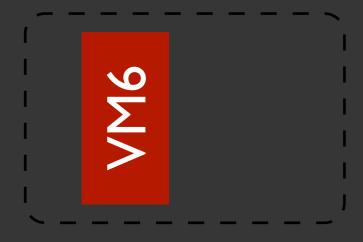


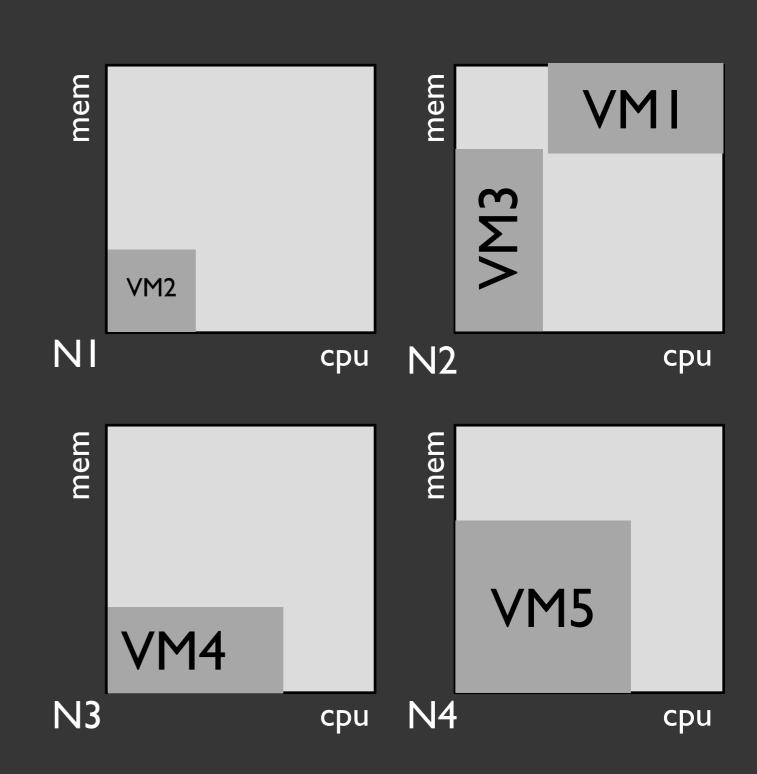




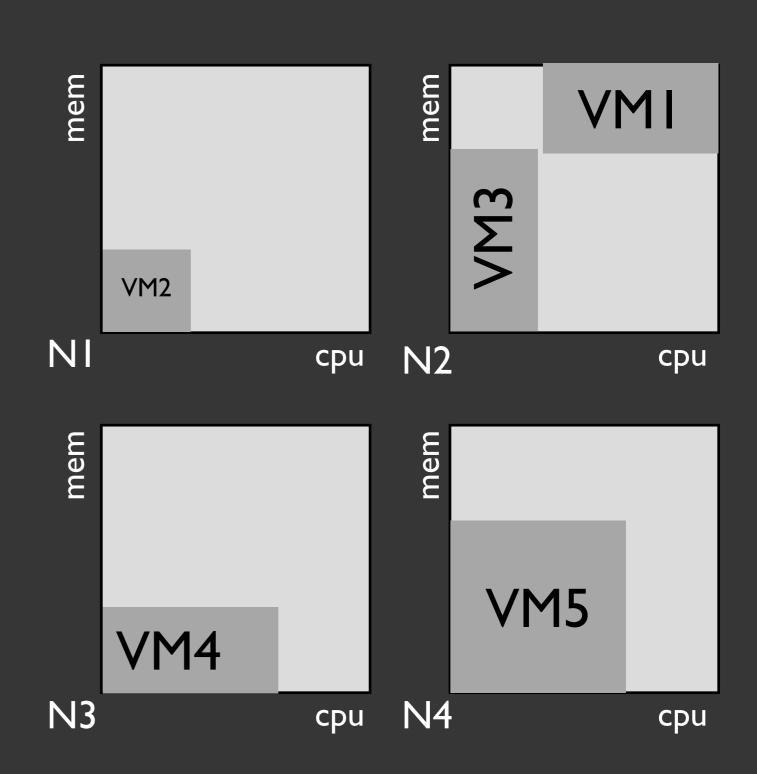
### Combinatorial problem!

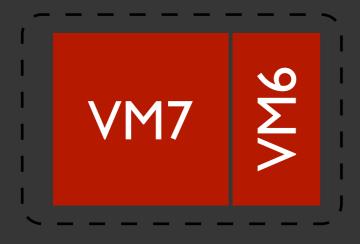
past decisions impact the future ones

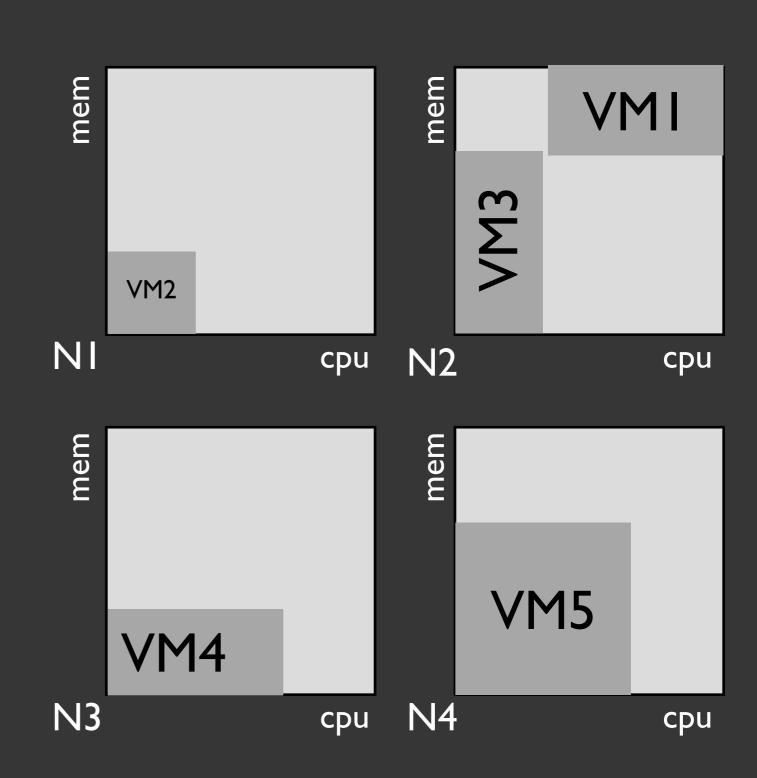


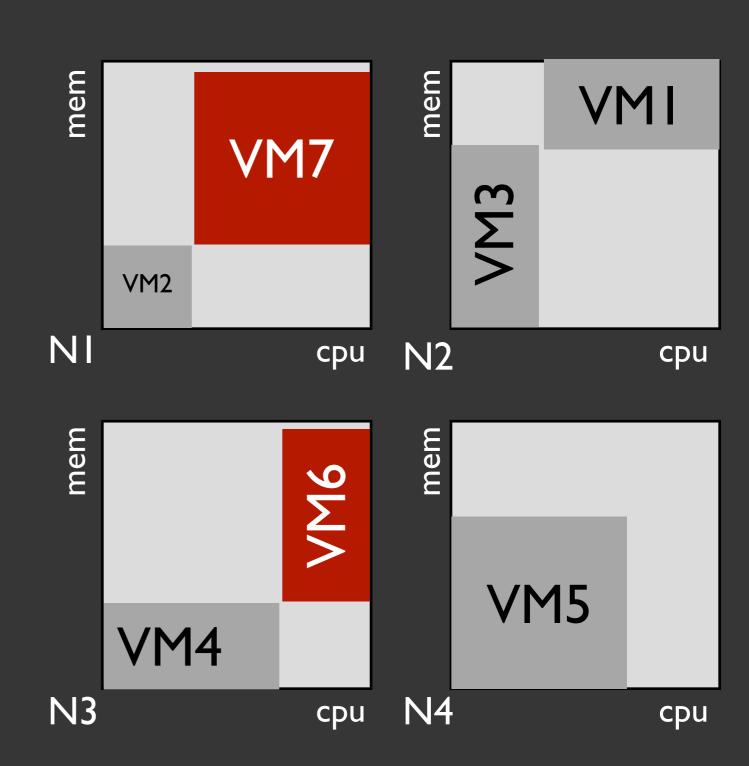






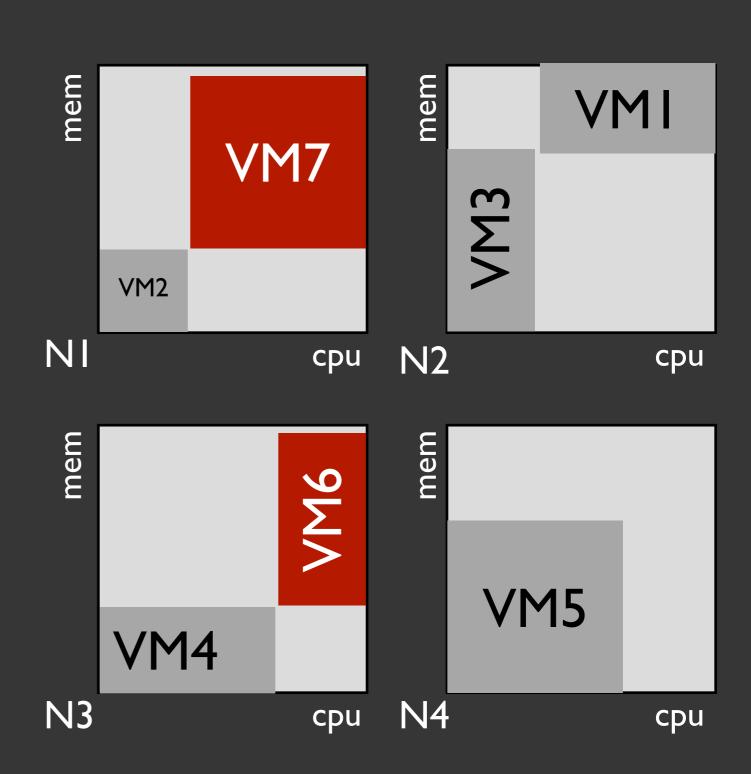






buffering might help

/ incoming rate starvation



manipulate the VM queue only react on VM arrival

#### Pros

easy to model simple standard actions manage a few elements

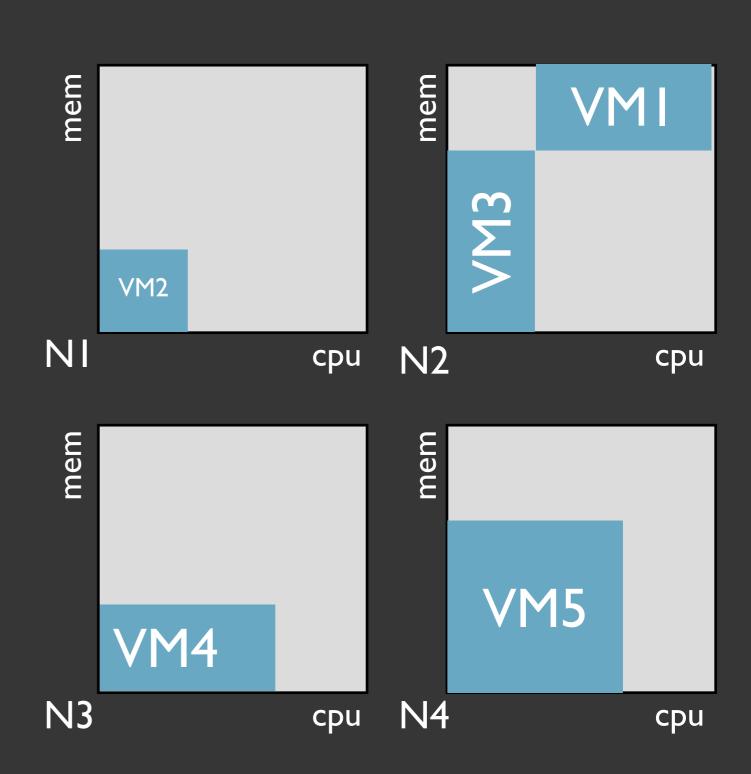
CONS

hard to perform fine grain optimisation

### dynamic schedulers

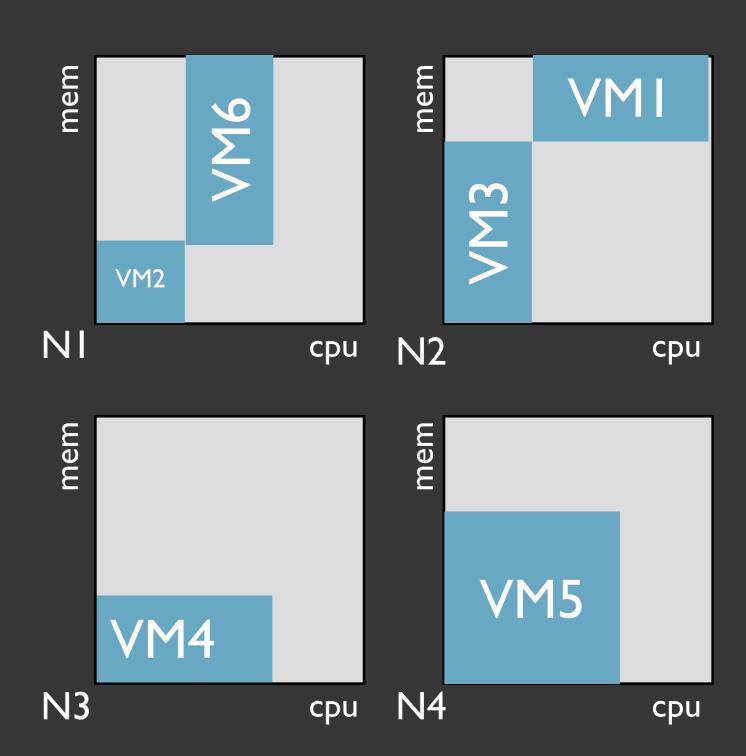
consider every VMs

9 | |



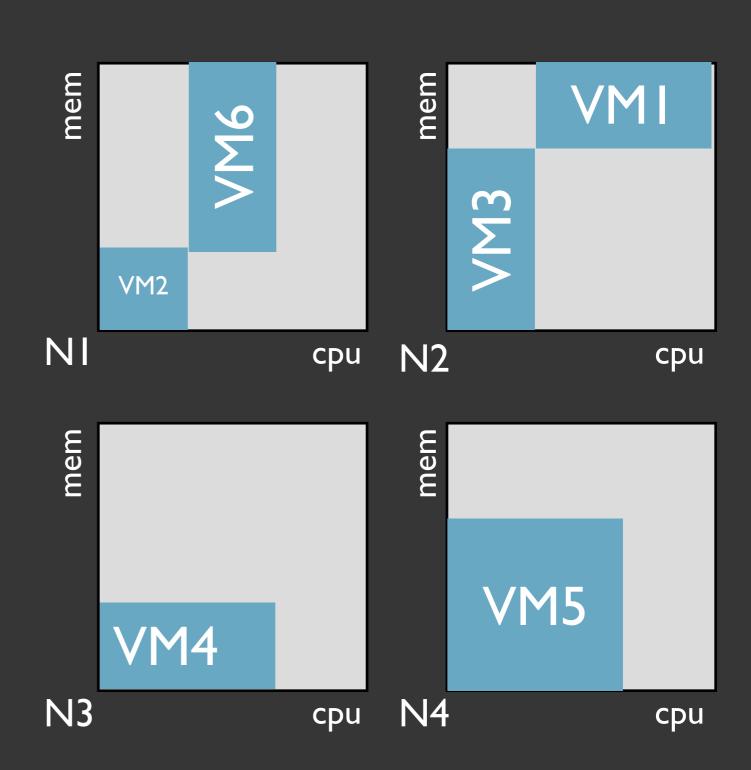
### dynamic schedulers

consider every VMs



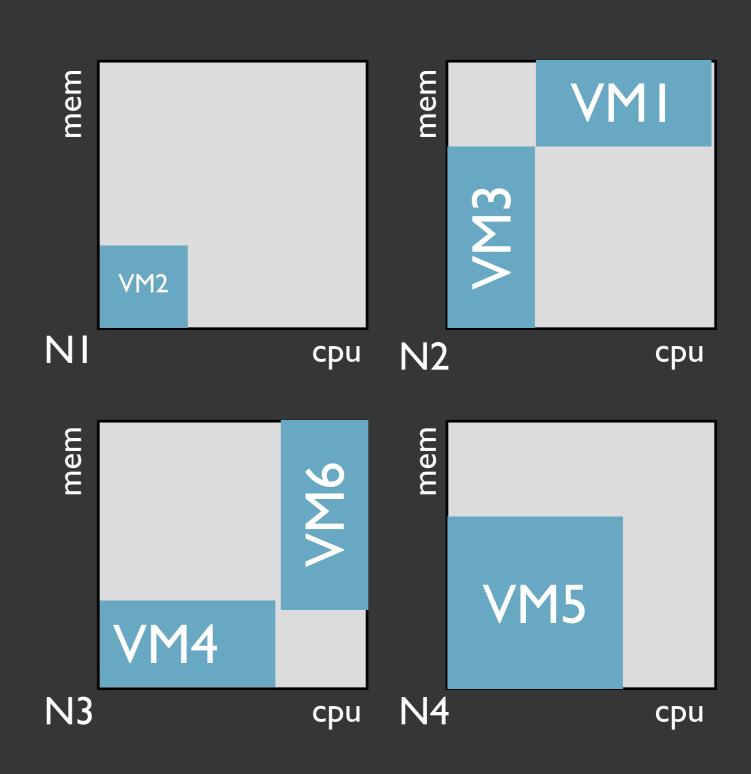
consider every VMs



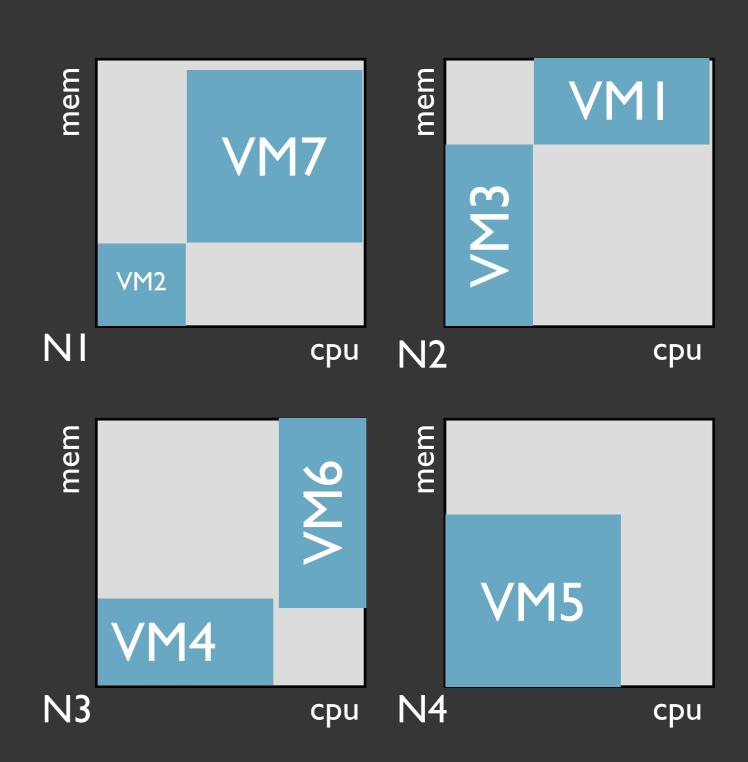


consider every VMs



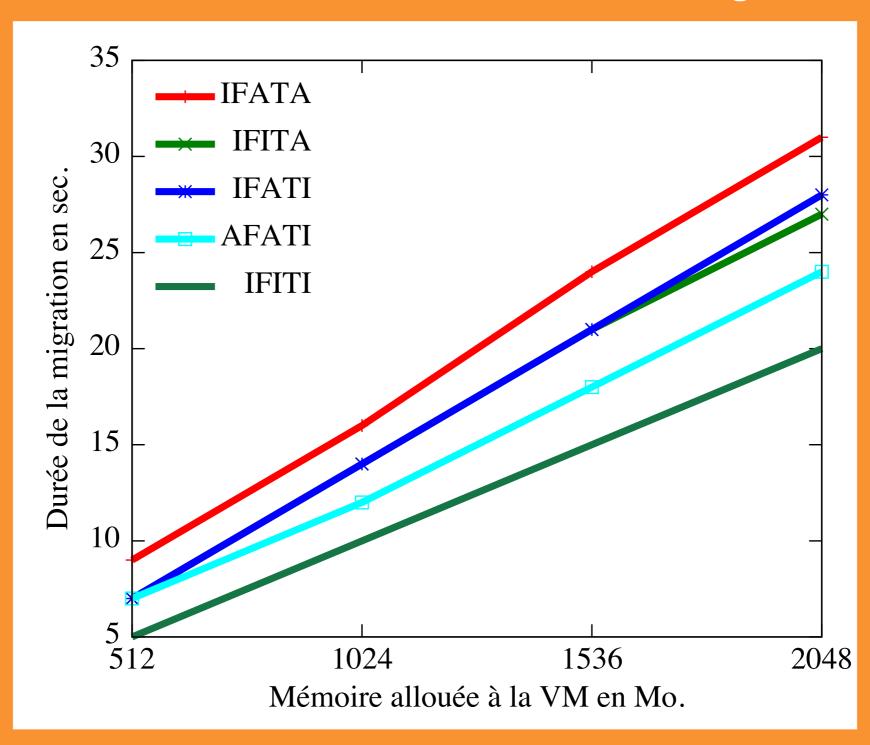


consider every VMs

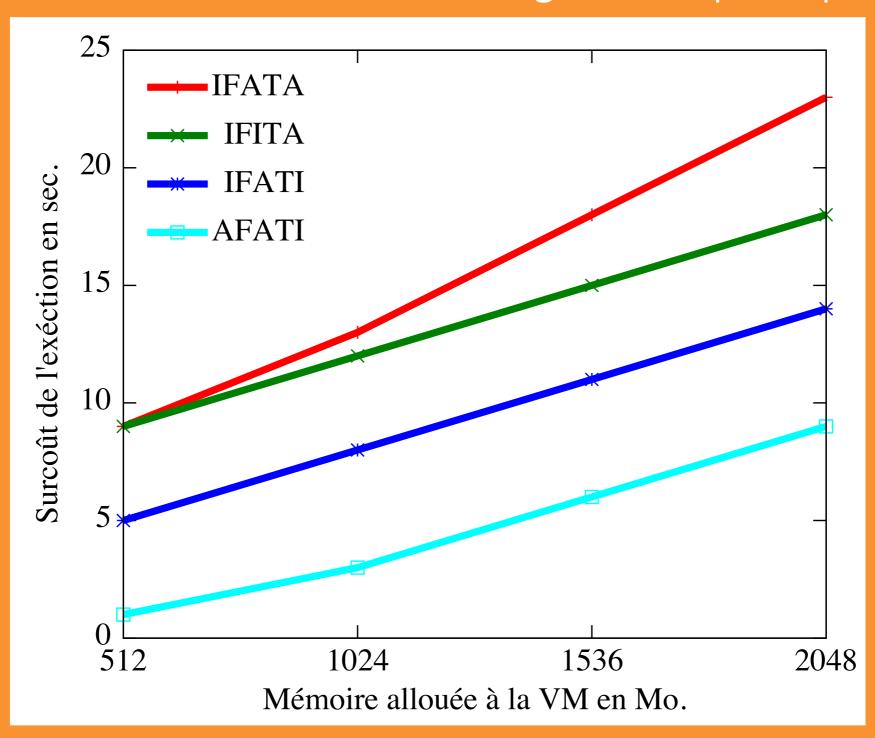


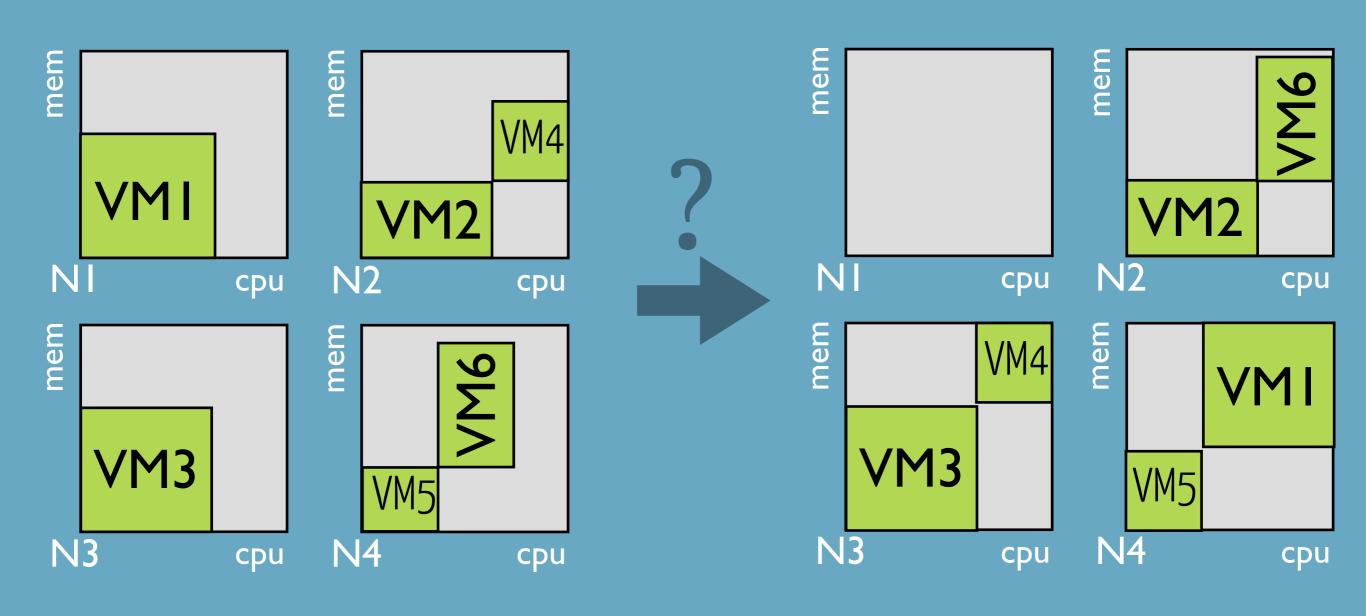
manipulate the VM queue reconfigure the schedule with migrations

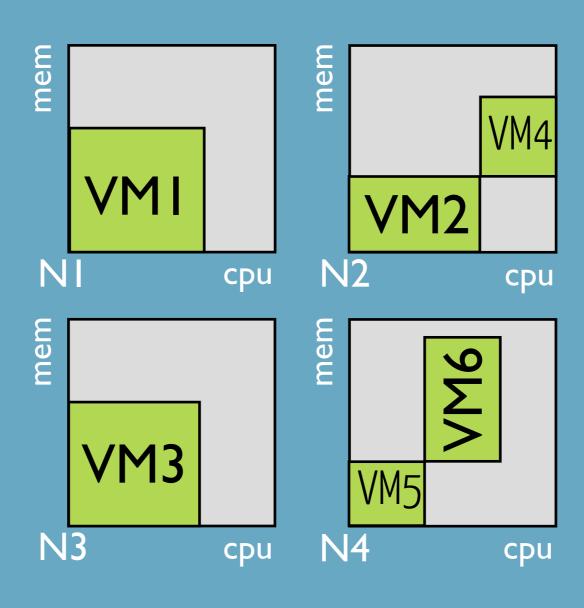
a migration takes time

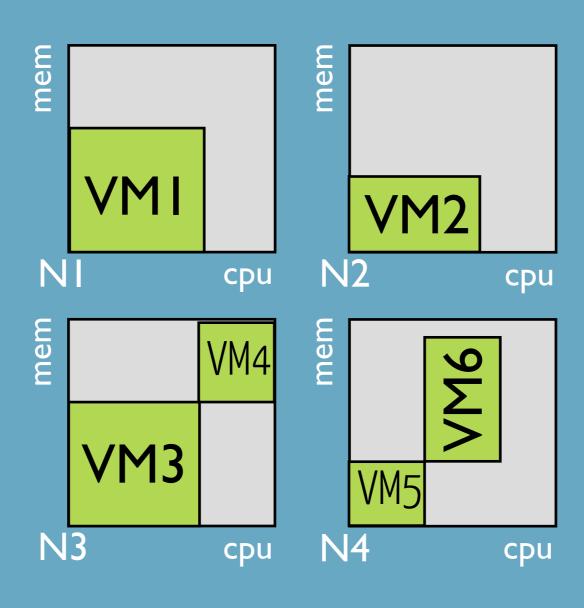


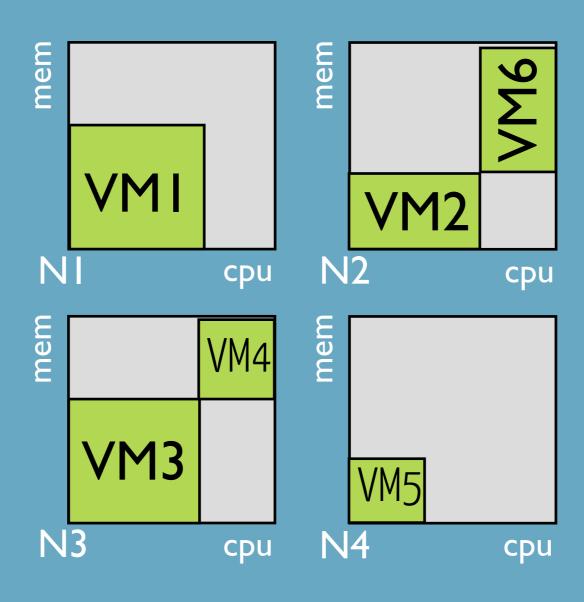
a migration impacts performance

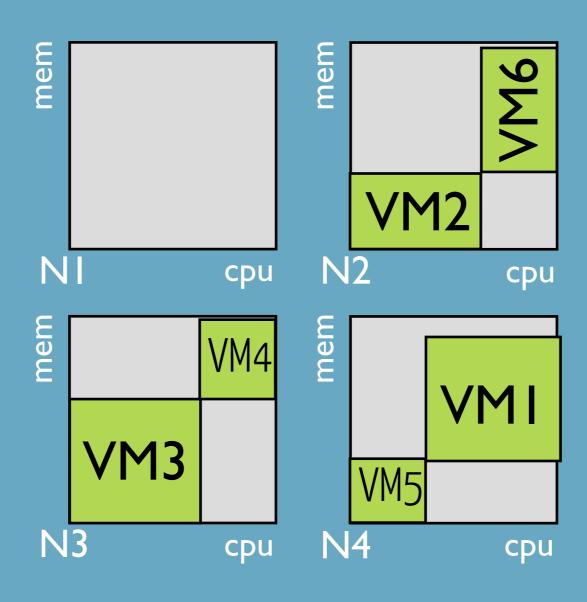








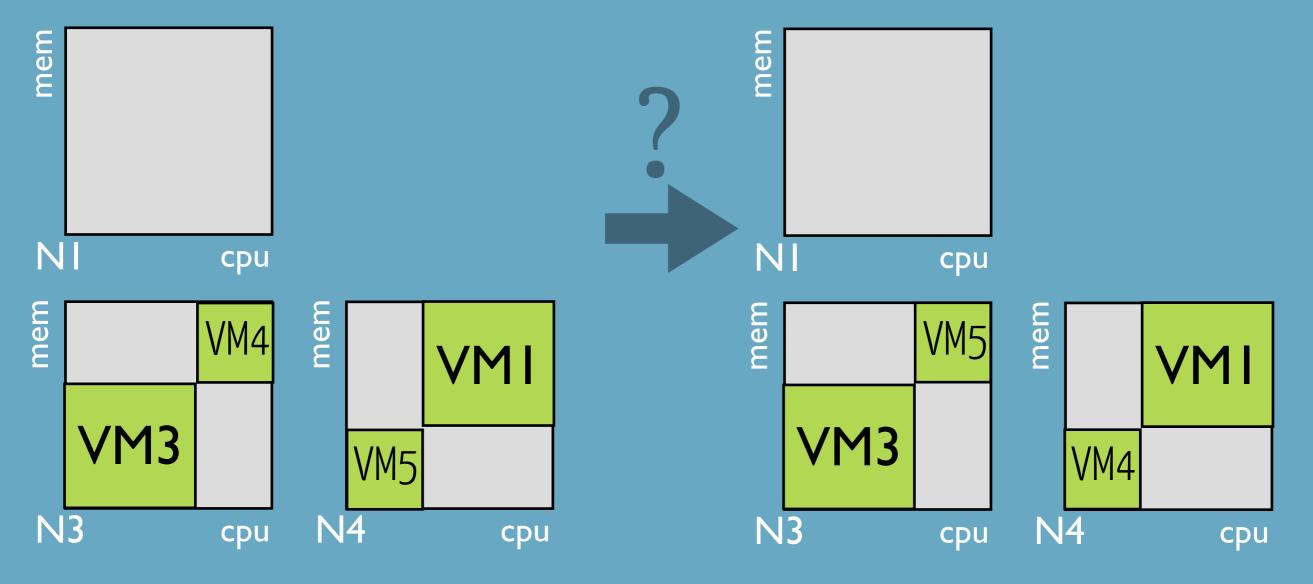




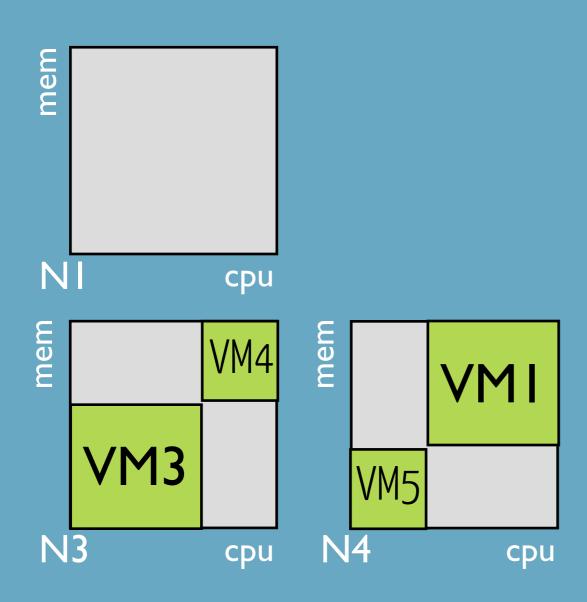
cyclic dependencies

anti-affinity(VM3,VM4)
min(#onlineNodes)

anti-affinity(VM3,VM4)
min(#onlineNodes)

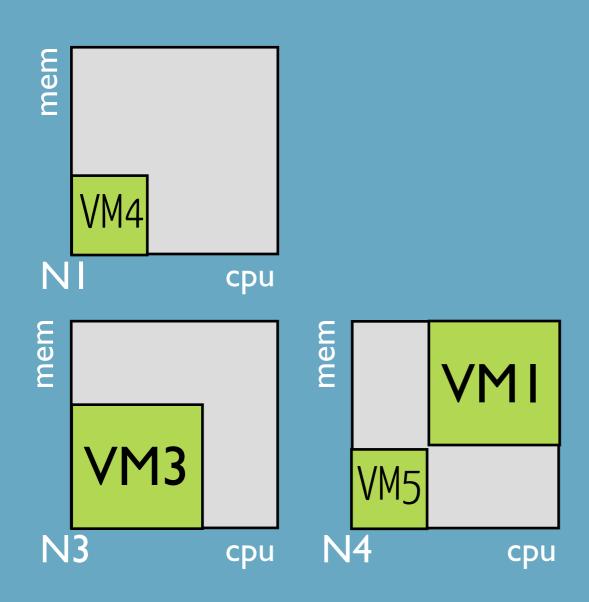


cyclic dependencies



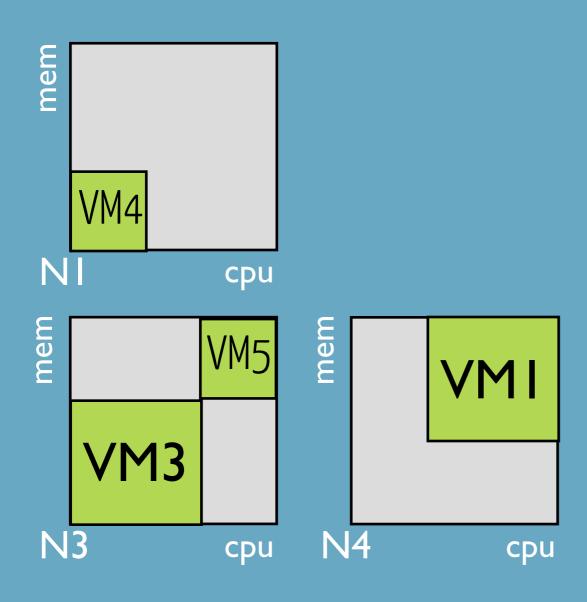
a pivot to break the cycle

cyclic dependencies



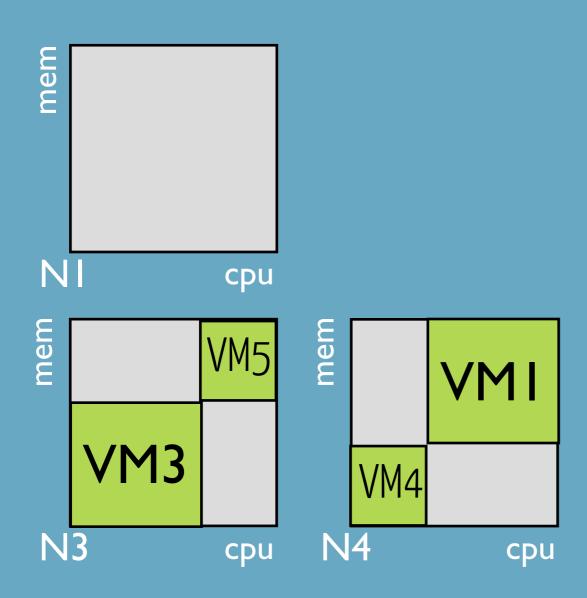
a pivot to break the cycle

cyclic dependencies



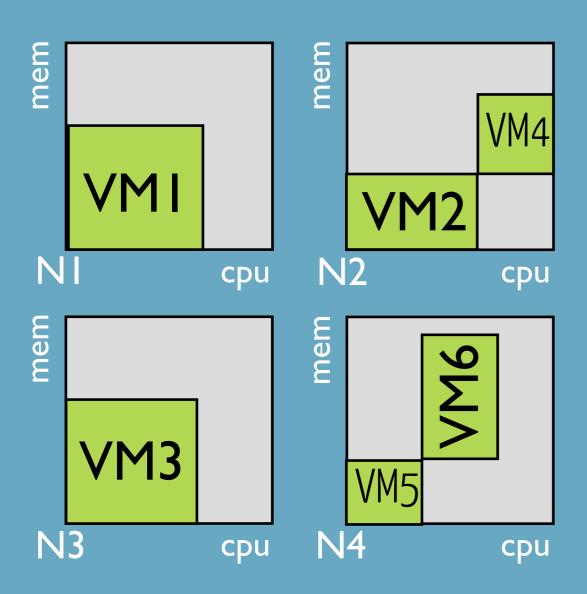
a pivot to break the cycle

cyclic dependencies

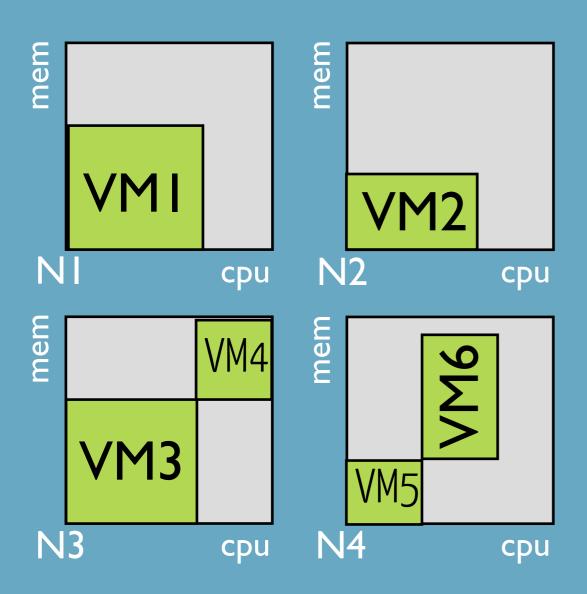


a pivot to break the cycle

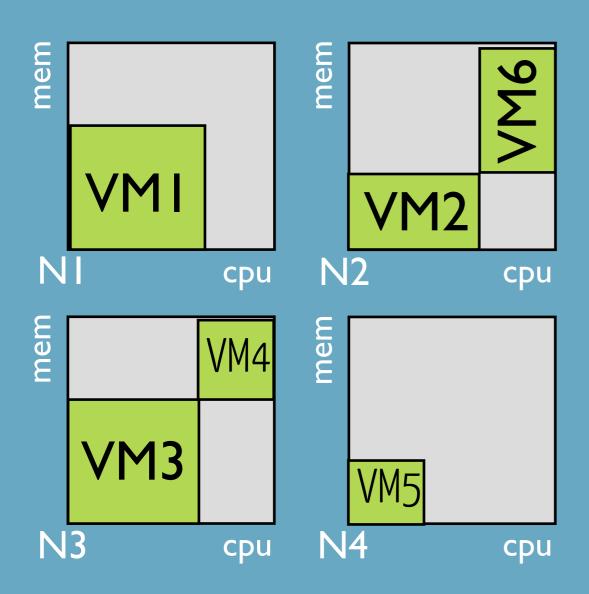
quality at a price



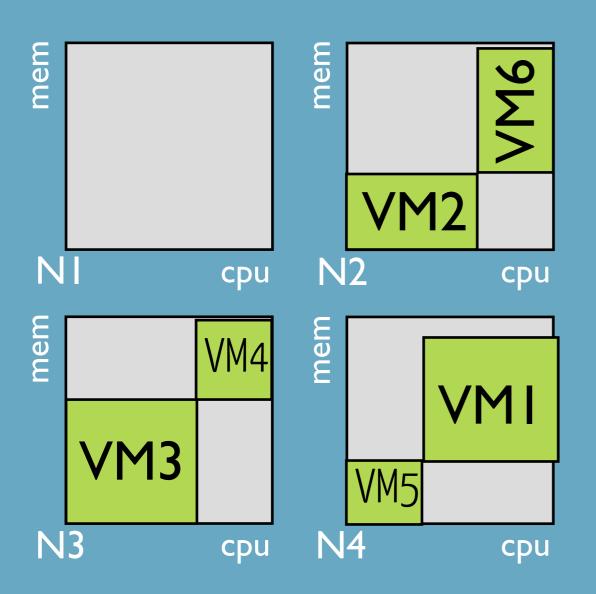
quality at a price



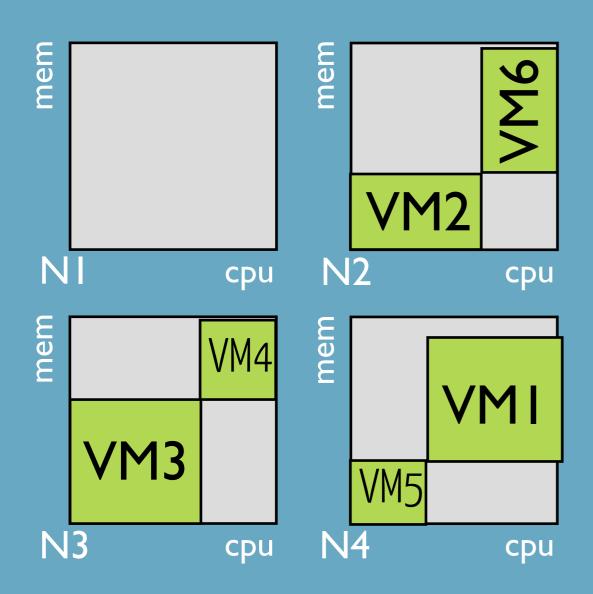
quality at a price



quality at a price

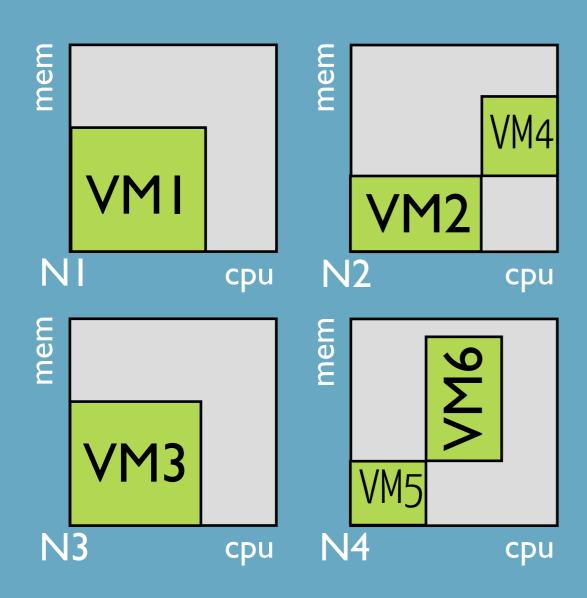


quality at a price



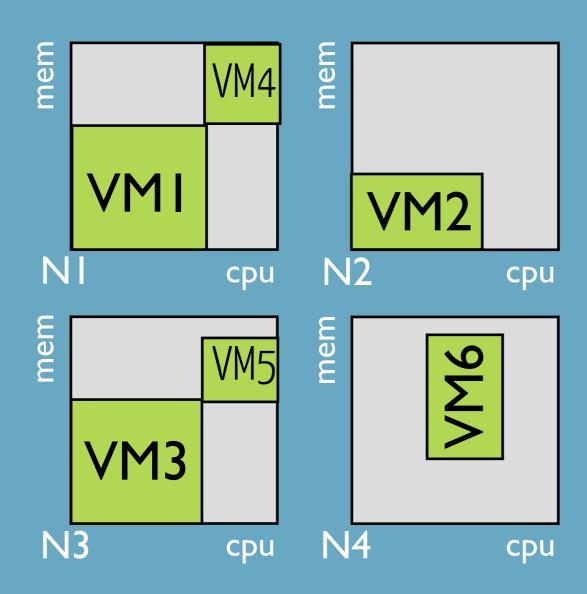
min(#onlineNodes) = 3

quality at a price



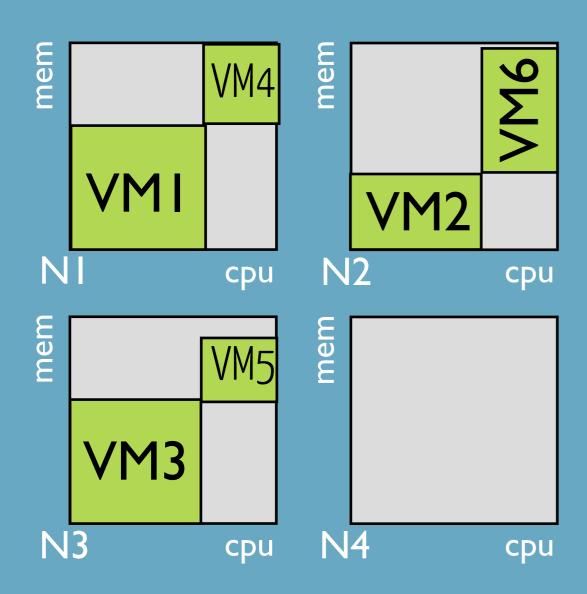
min(#onlineNodes) = 3

quality at a price



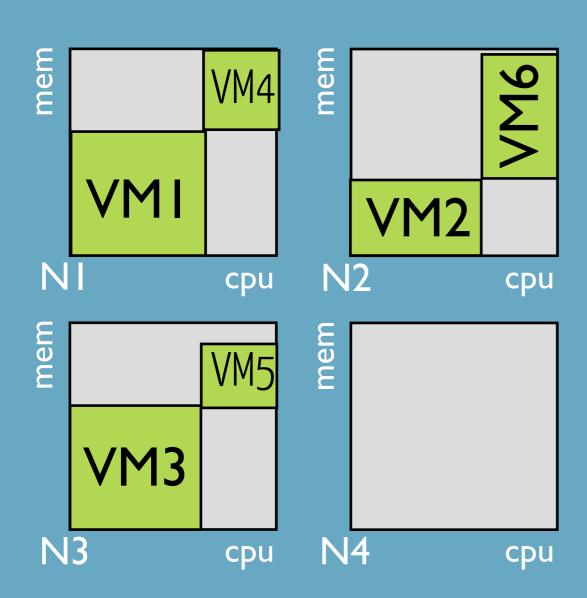
min(#onlineNodes) = 3

quality at a price



min(#onlineNodes) = 3

quality at a price

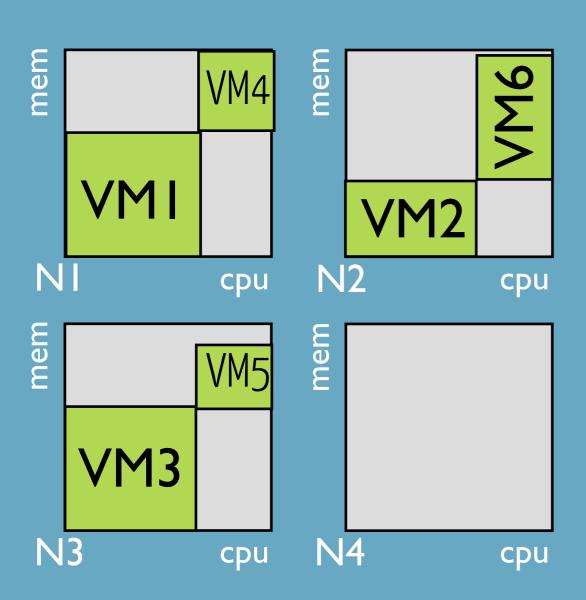


min(#onlineNodes) = 3

sol #1: 1m,1m,2m

sol #2: 1m,1m 1m

quality at a price



```
sol #1: 1m,1m,2m

sol #2: 1m,1m
1m
lower MTTR
(faster)
```

# dynamic schedulers quality at a price

# the objective should reflect reconfiguration costs

min(MTTR), min(#migrations),...

#### pros

continuous optimisation through reconfiguration

CONS

harder to model harder to scale technically expensive costly reconfiguration

# dynamic scheduling for the win

in theory yes but that's theory

benefits depends on the workload the objective/ SLAs the infrastructure

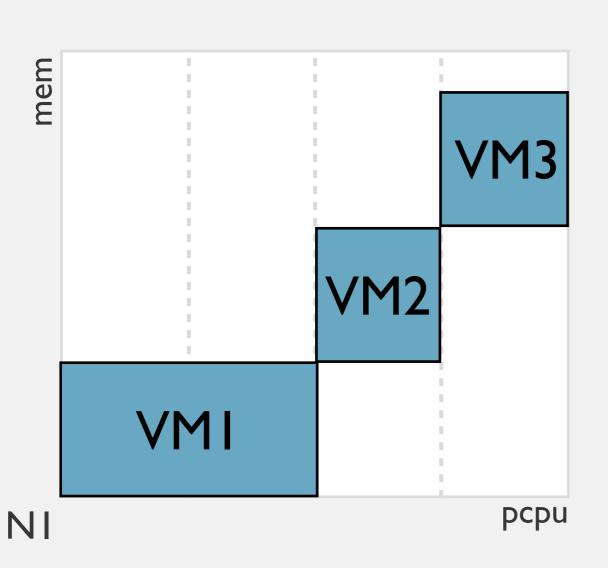
dynamic scheduling is rare in public or large clouds

static schedulers

allocation

dynamic resource allocation

#### static resource allocation



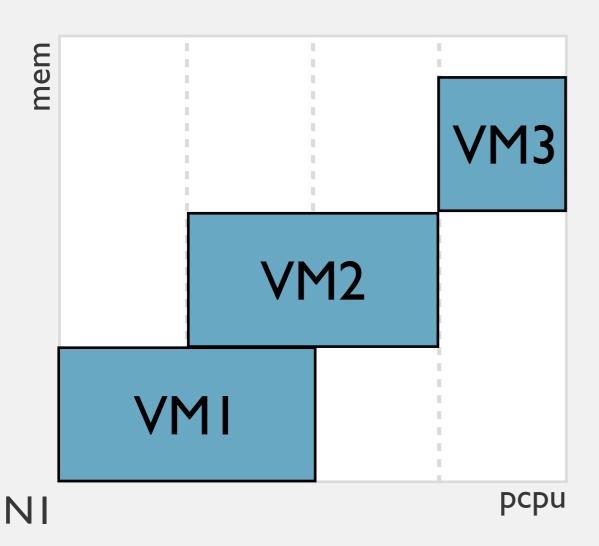
cpu, ram, i/o, bandwidth allocated once for all

allocation != utilisation

no sharing conservative allocation

#### static resource allocation

#### sharing (overbooking)

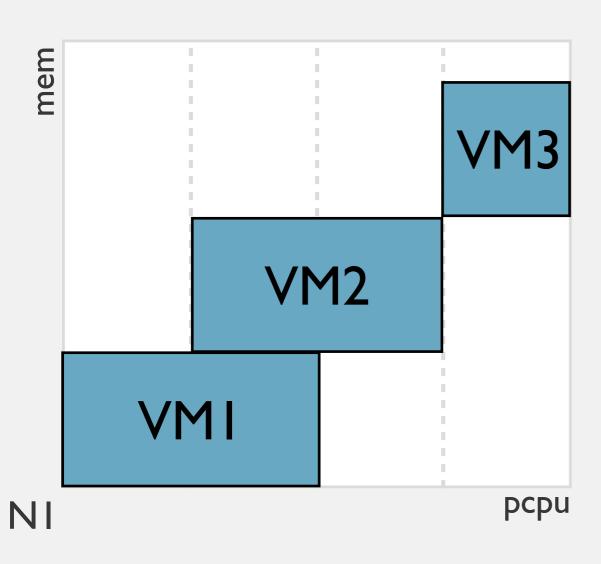


performance loss with concurrent accesses

acceptable if stated in the SLA

#### dynamic resource allocation

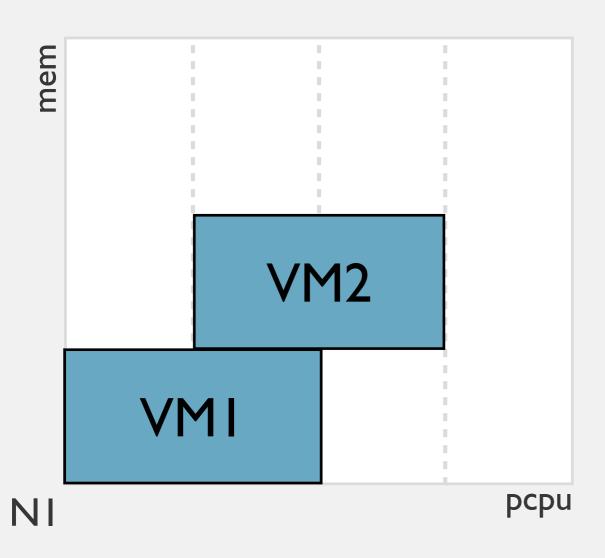
to fix violations



cpu, ram, i/o, bandwidth allocated can be revised

#### dynamic resource allocation

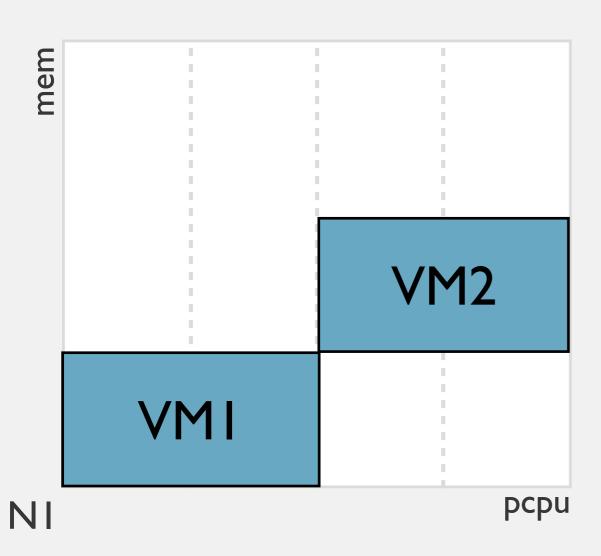
to fix violations



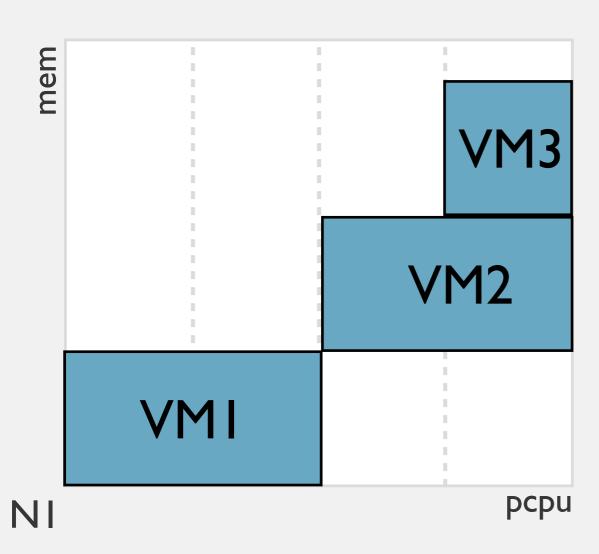
cpu, ram, i/o, bandwidth allocated can be revised

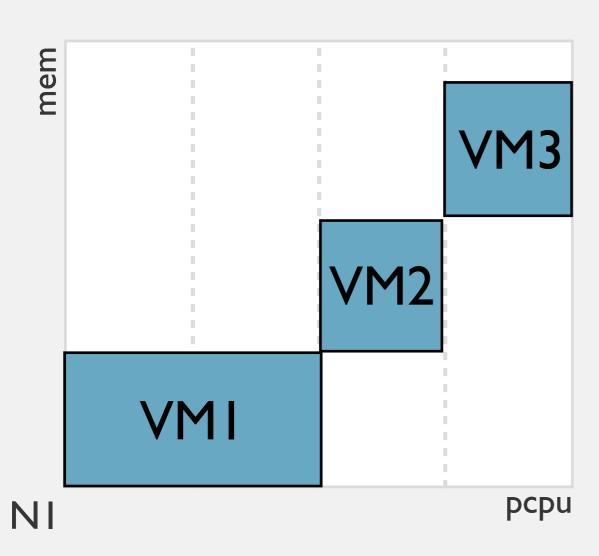
#### dynamic resource allocation

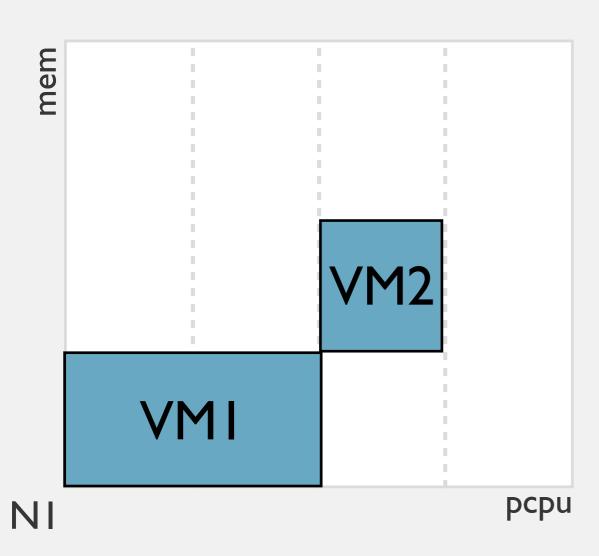
to fix violations

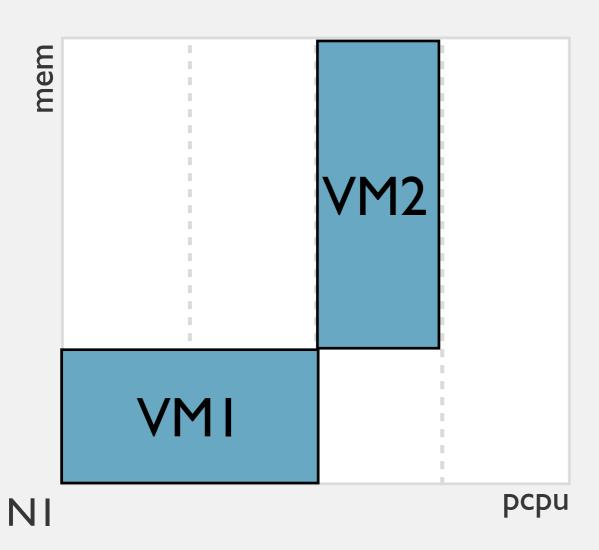


cpu, ram, i/o, bandwidth allocated can be revised









### dynamic resource allocation for the win

common on CPU + overbooking (inc. hosting capacity)

exceptional for memory (huge performance loss)

benefits depends on the workload the objective/ SLAs the infrastructure

## RECAP

### The VM scheduler mares coud henefits rea

### no holy grail

# think about what is costly

### Static scheduling for a peacefullife

# schedulingto cease the day

### with great power comes great responsibility





#### VM scheduling is hard

static or dynamic scheduler ? allocation

does the workload/SLA/objective ? requires migration

maximum duration to schedule?

#### VM scheduling is NP-Hard

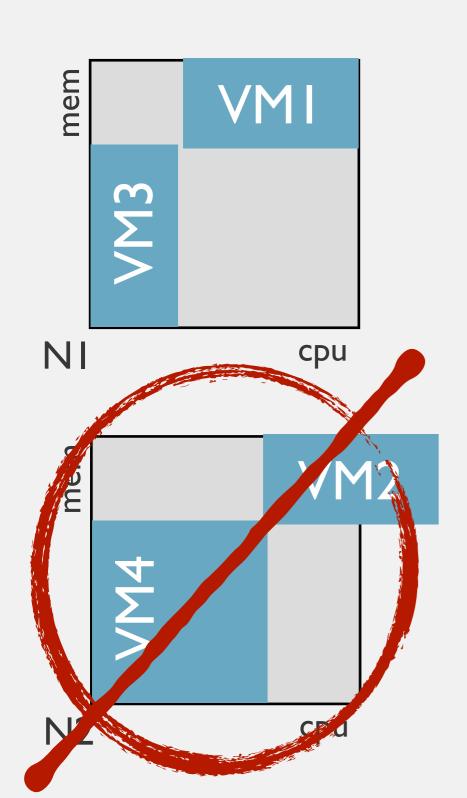
issues with large infrastructures or hard problems

fast adhoc heuristics despite corner cases

some use biased complete approaches (linear programming, constraint programming)



#### vector packing problem



items with a finite volume to place inside finite bins

a generalisation of the bin packing problem

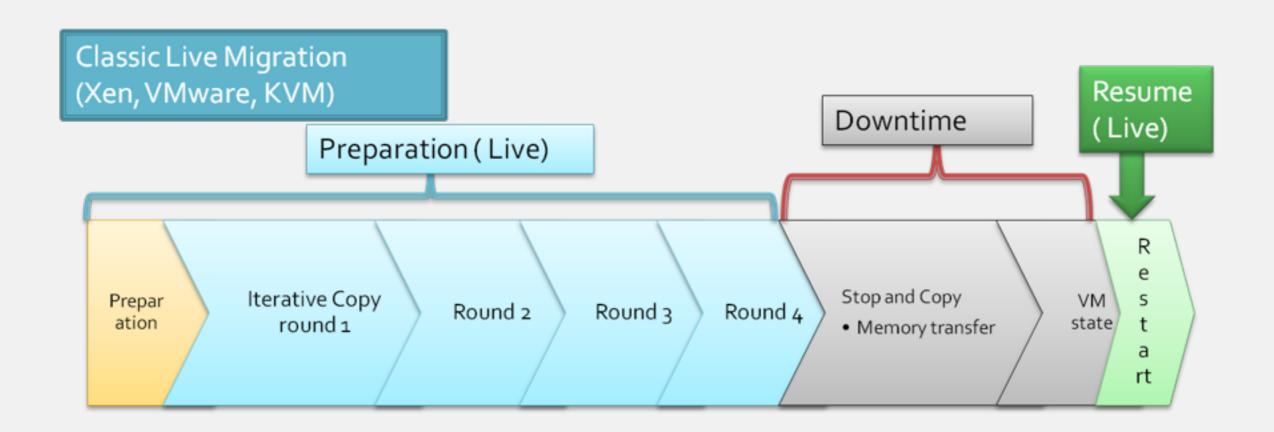
the basic to model the infra. 1 dimension = 1 resource



### Which resource can be modeled as a packing dimension

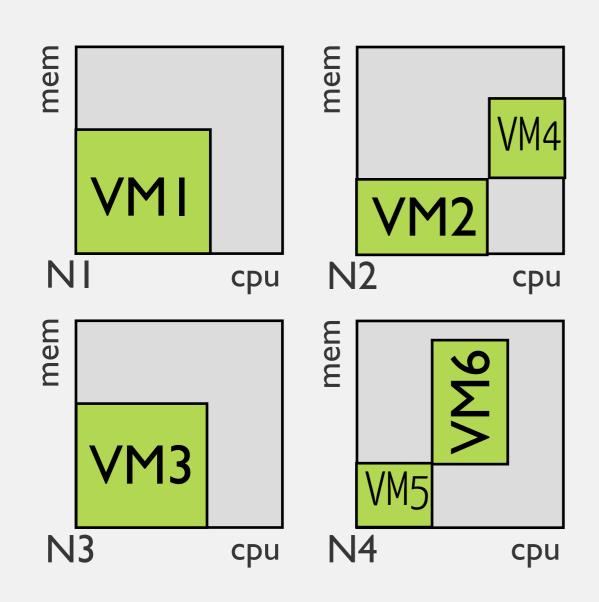
### Which resource can be modeled as a packing dimension

CPU, memory, disk IO, licences cardinality, network boundaries, ... end to end network



temporary, resources are used on the source and the destination nodes

a simple way

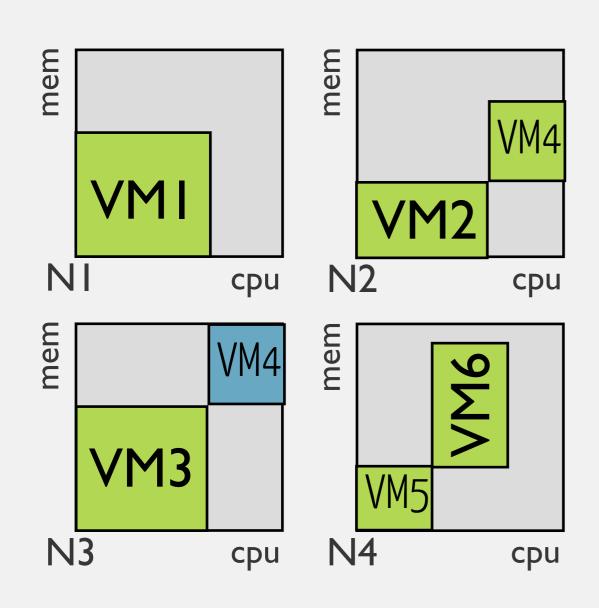


n-phases vector packing

VM duplication between 2 phases to simulate the migration

easy to implement

a simple way

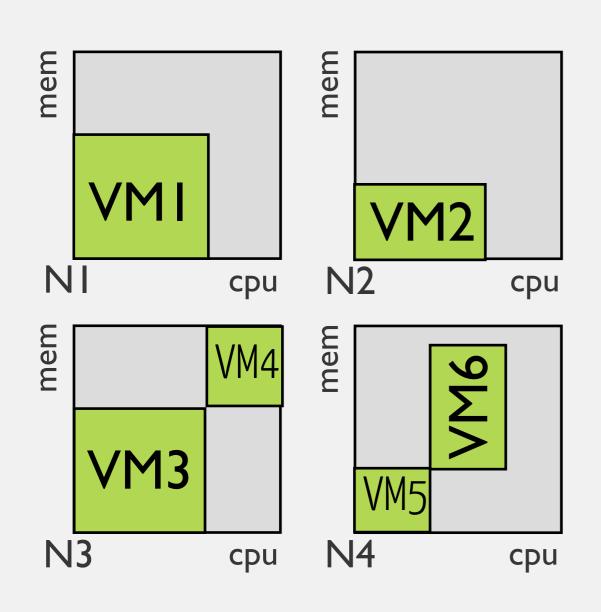


n-phases vector packing

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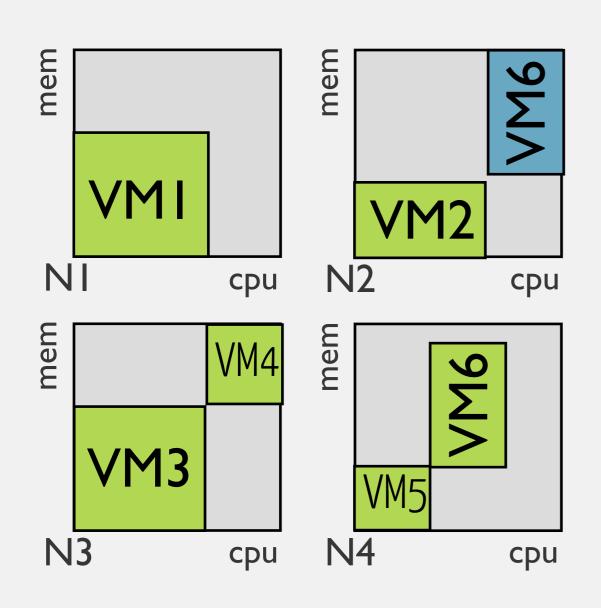


n-phases vector packing

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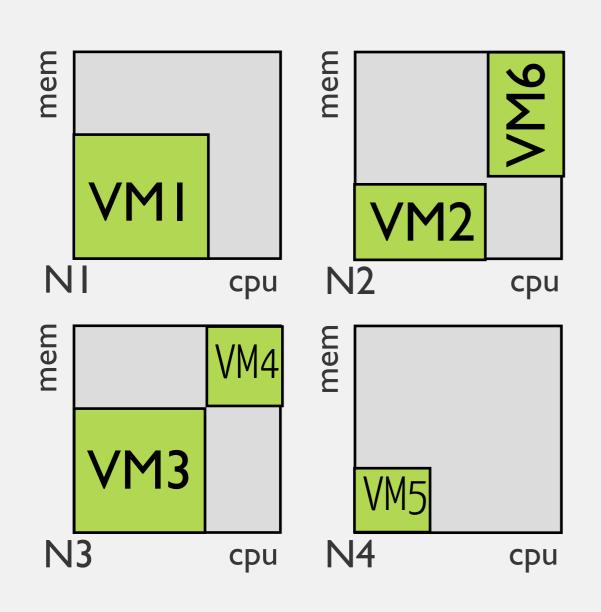


n-phases vector packing

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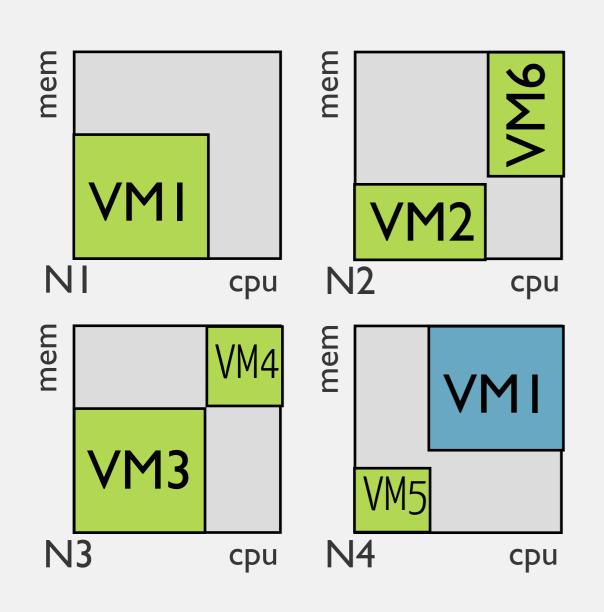


n-phases vector packing

VM duplication between 2 phases to simulate the migration

easy to implement

a simple way

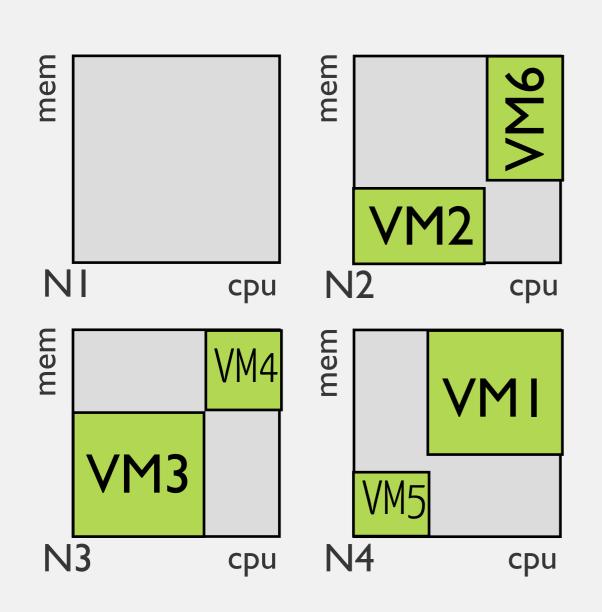


n-phases vector packing

VM duplication between 2 phases to simulate the migration

easy to implement

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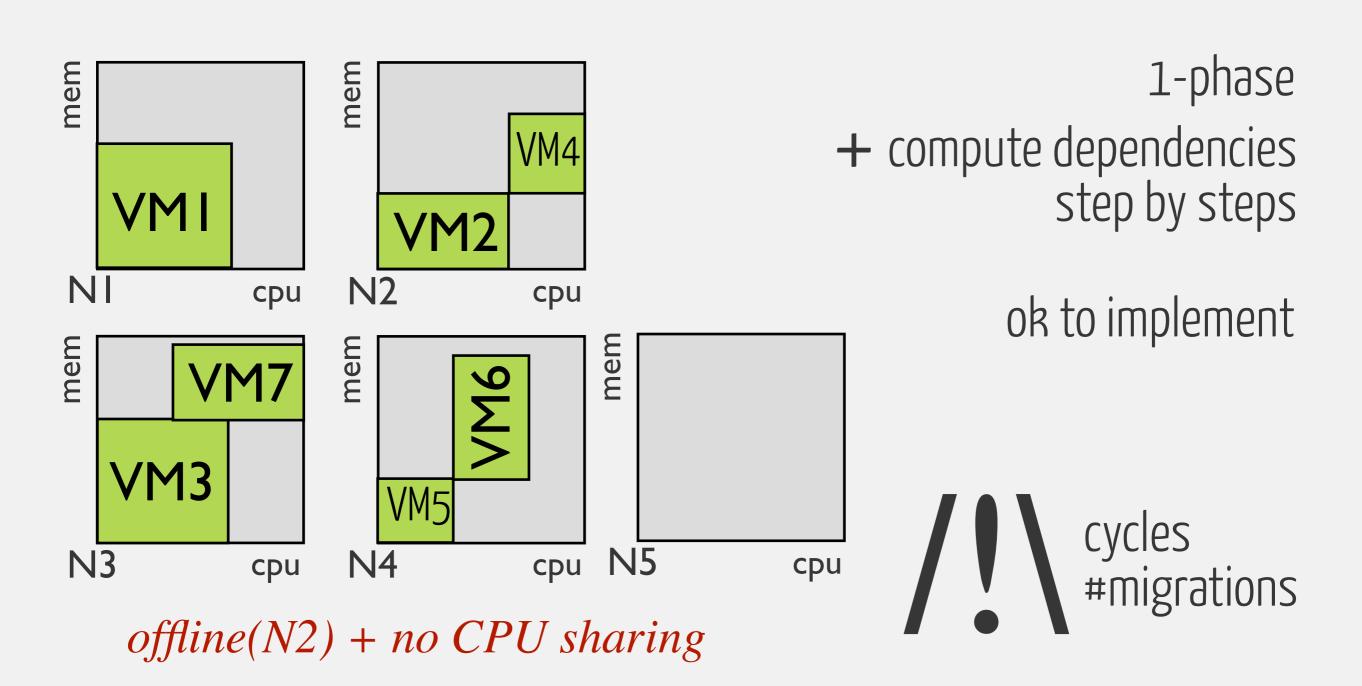


n-phases vector packing

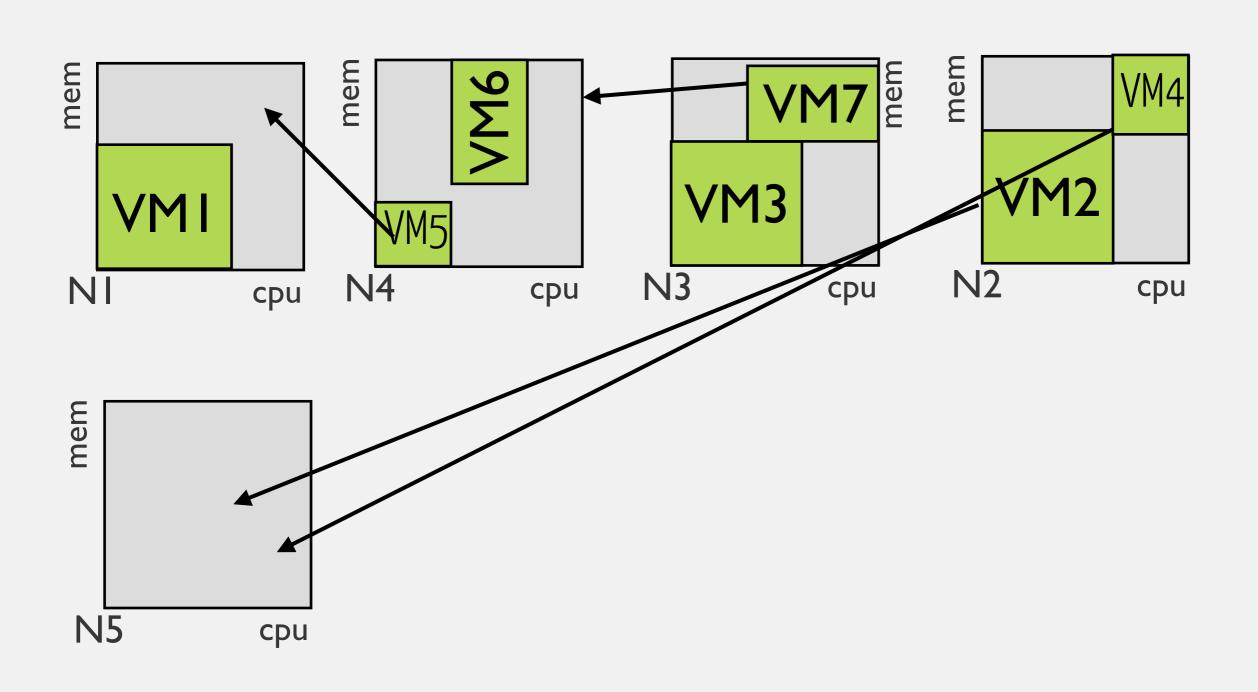
VM duplication between 2 phases to simulate the migration

easy to implement

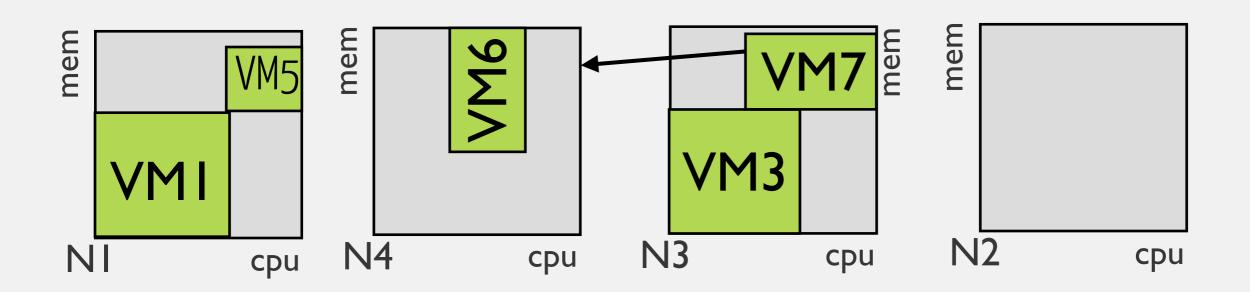
the alternative way

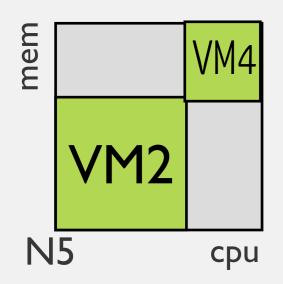


the alternative way



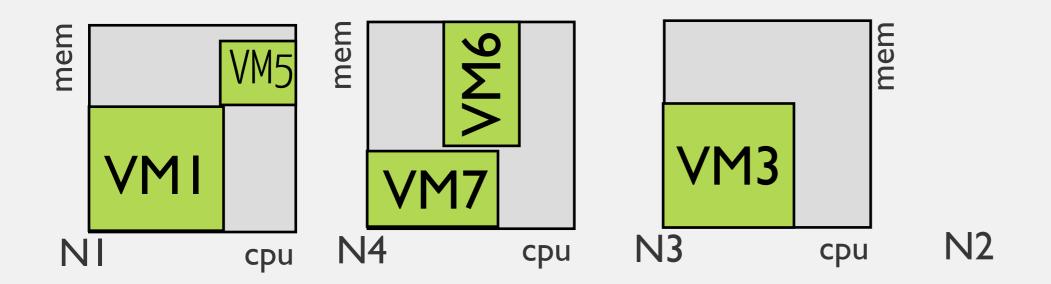
the alternative way

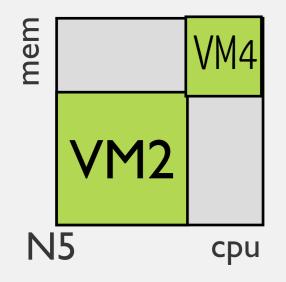




1) migrate VM2, migrate VM4, migrate VM5

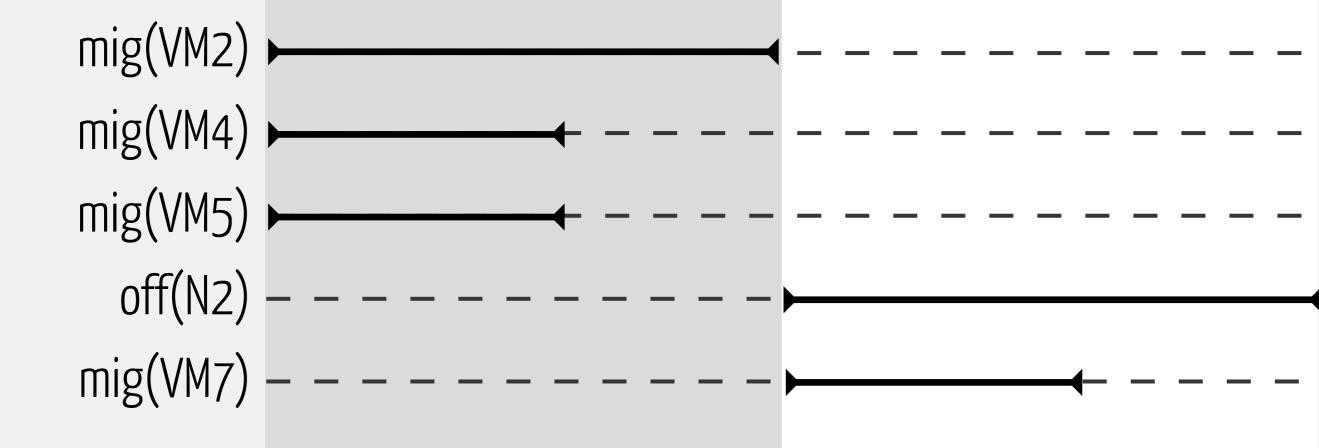
the alternative way





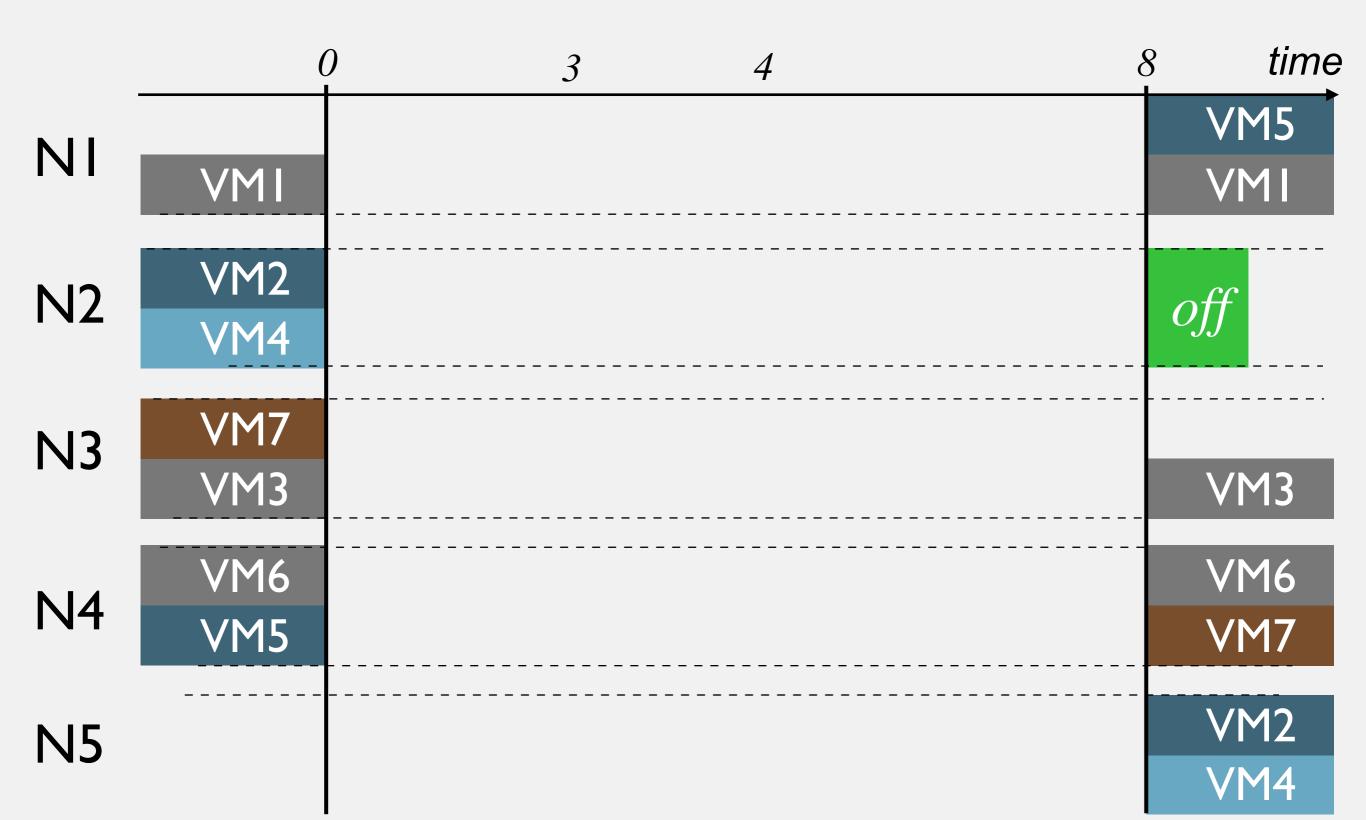
- 1) migrate VM2, migrate VM4, migrate VM5
- 2) shutdown(N2), migrate VM7

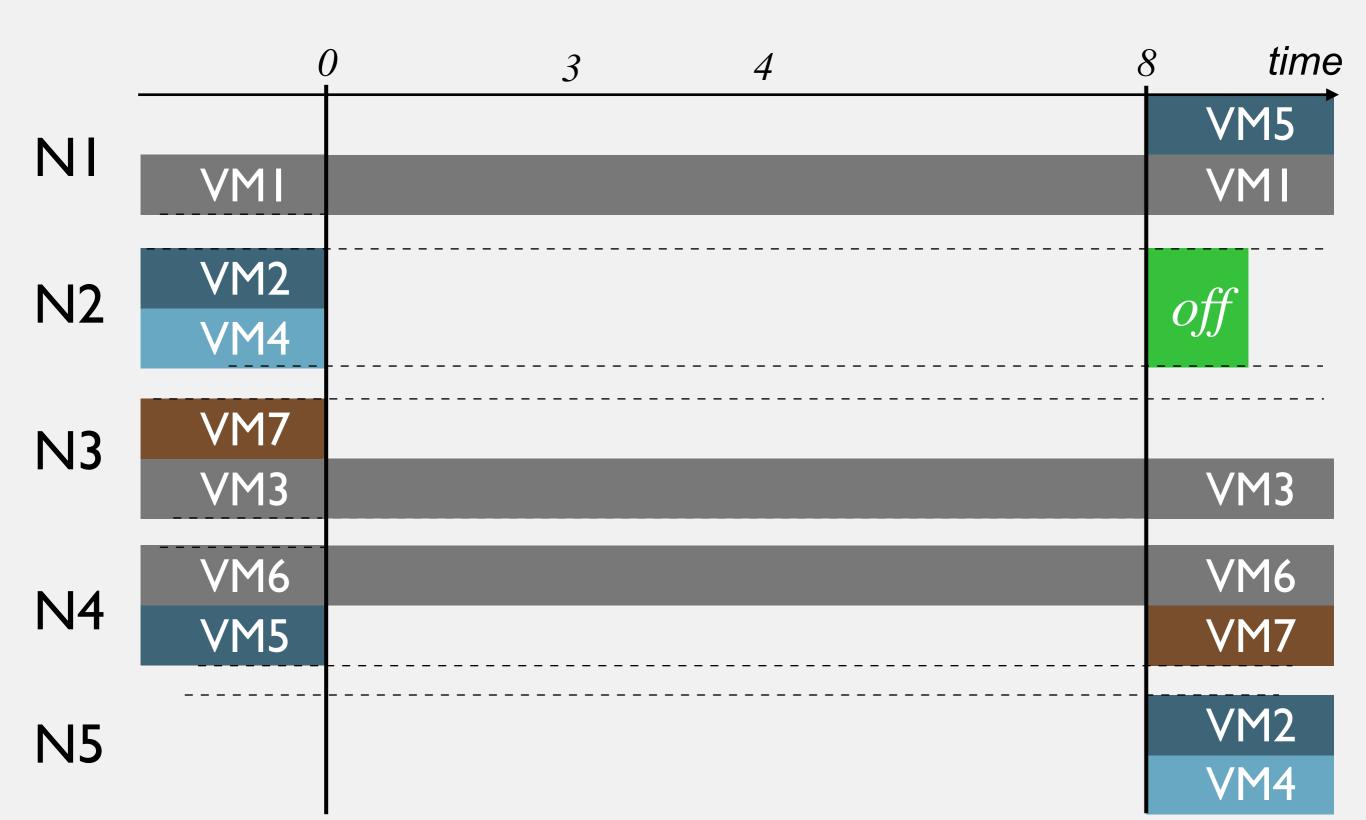
### coarse grain staging delay actions

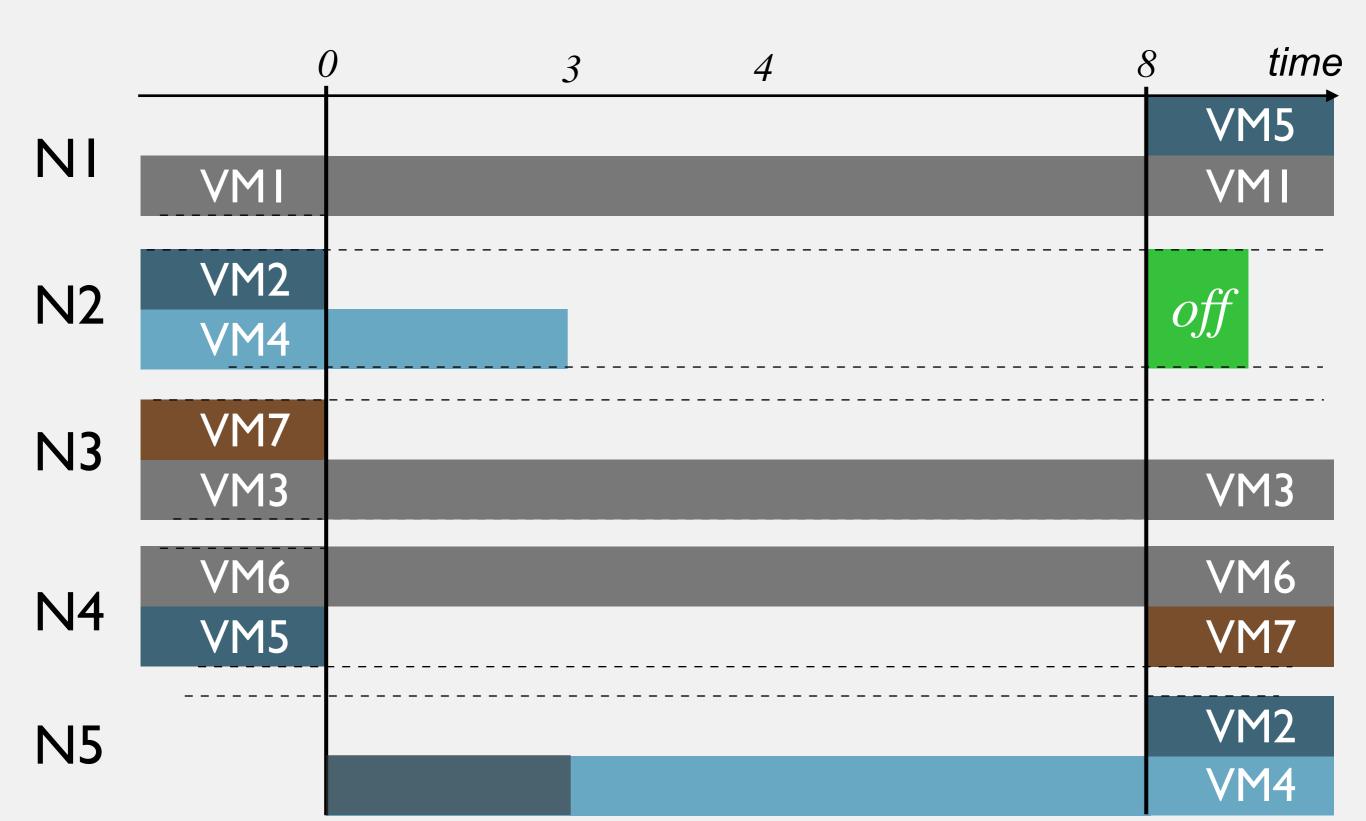


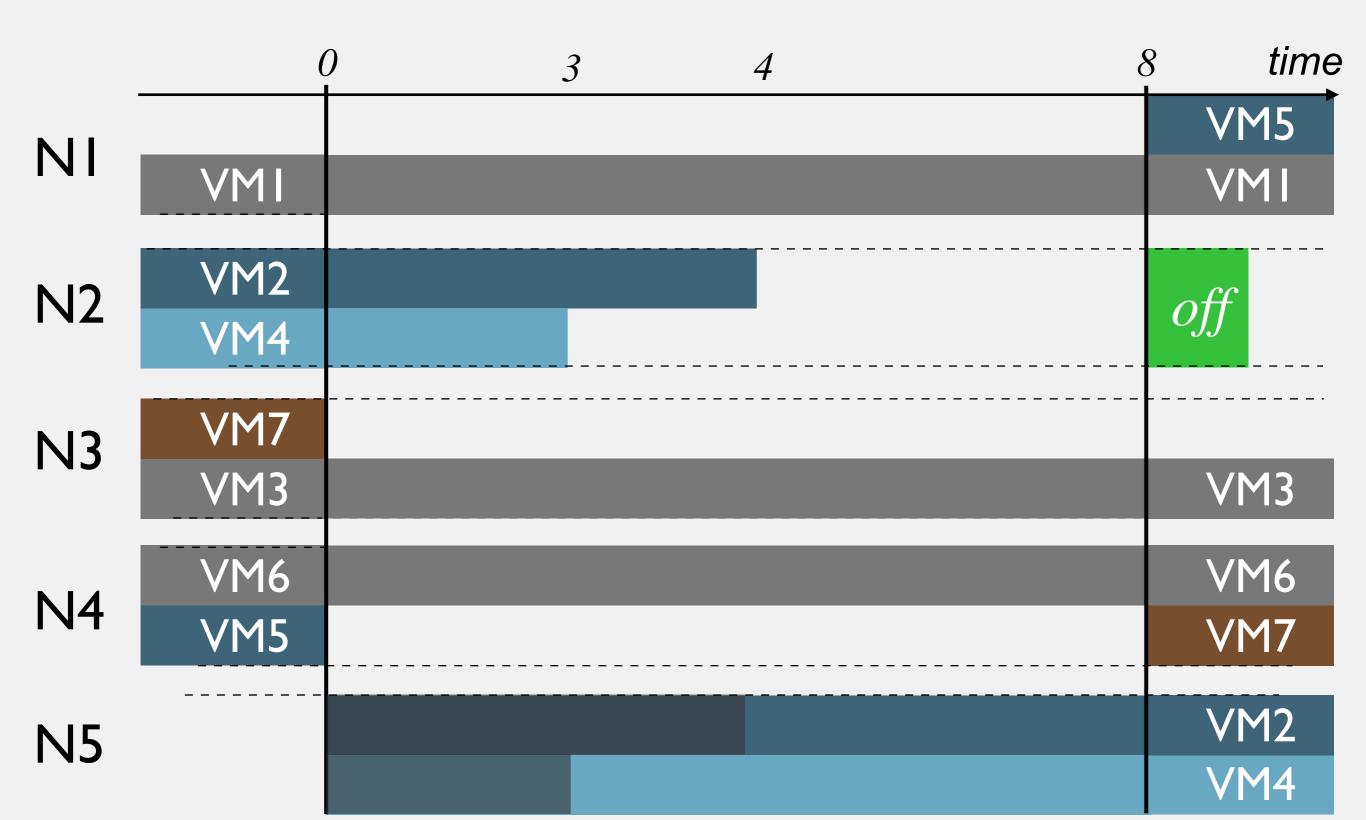
stage 1

stage2 timé

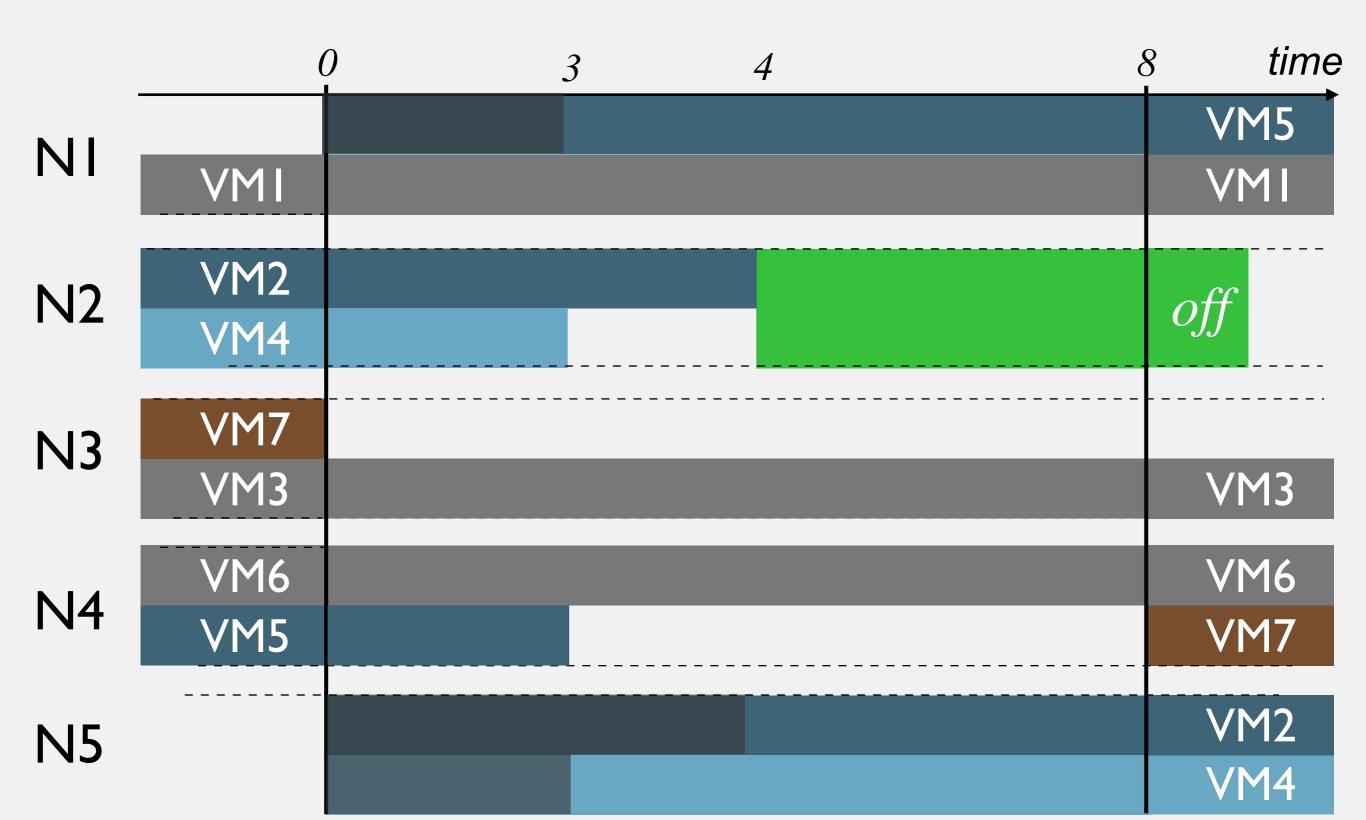




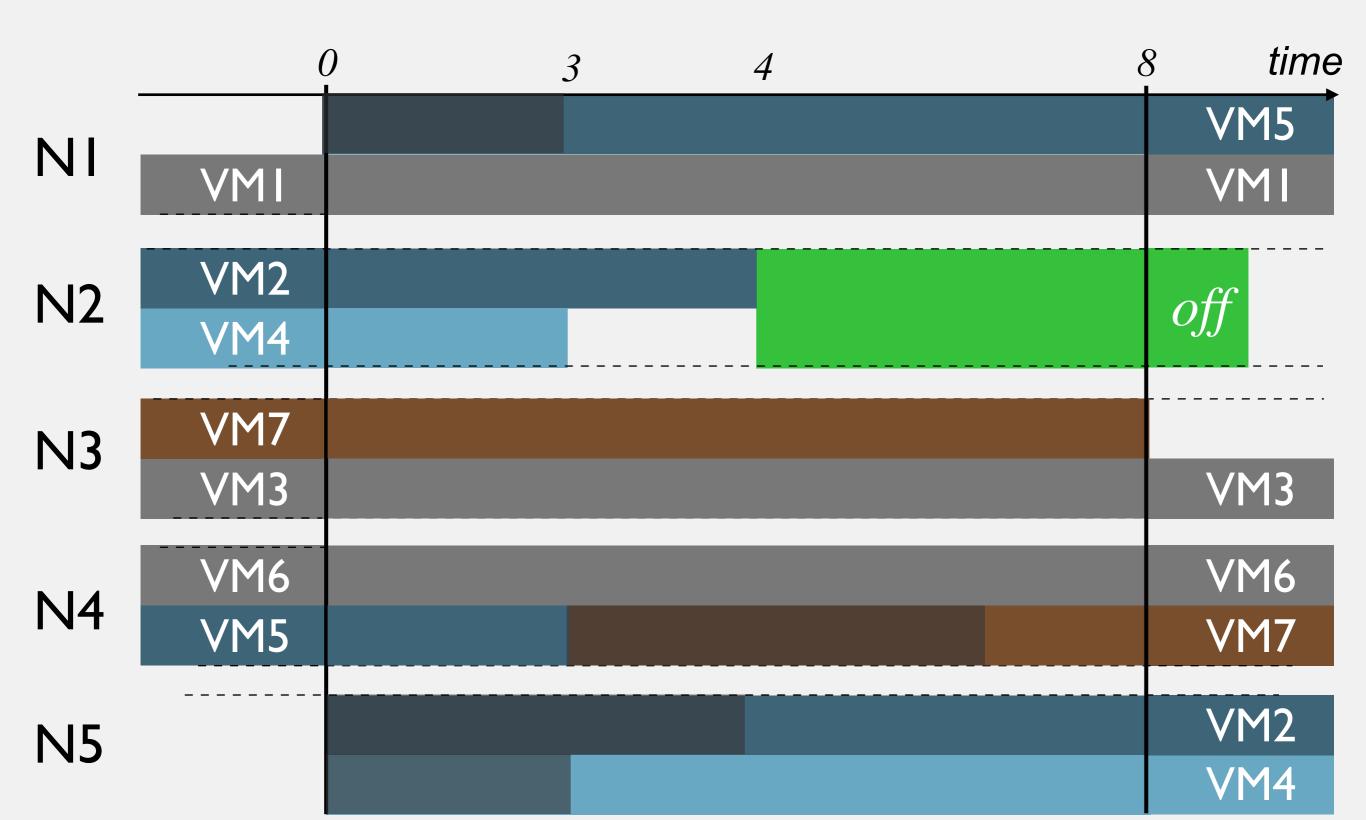




## Resource-Constrained Project Scheduling Problem the clean way to model space and time



## Resource-Constrained Project Scheduling Problem the clean way to model space and time



## Resource-Constrained Project Scheduling Problem the pure way to support migrations

1 resource per (node x dimension), bounded capacity

tasks to model the VM lifecycle. height to model a consumption width to model a duration

at any moment, the cumulative task consumption on a resource cannot exceed its capacity

comfortable to express continuous optimisation

very hard to implement (properly)

#### From a theoretical schedule to a practical one

duration may be longer convert to an event based schedule

0:3 - migrate VM4

0:3 - migrate VM5

0:4 - migrate VM2

3:8 - migrate VM7

4:8 - shutdown(N2)

-: migrate VM4

-: migrate VM5

-: migrate VM2

!migrate(VM2) & !migrate(VM4): shutdown(N2) !migrate(VM5): migrate VM7

# Back to vector packing based approaches

basic VM scheduling

```
sort VMs in desc order
for each VM
  pick the first suitable node
```

basic VM scheduling

```
sort VMs in desc order
for each VM
  pick the first suitable node
```

difficult VMs first!

basic VM scheduling

```
sort VMs in desc order
for each VM
   pick the first suitable node
```

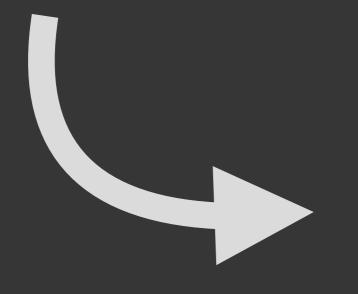
difficult VMs first!

enough free resources





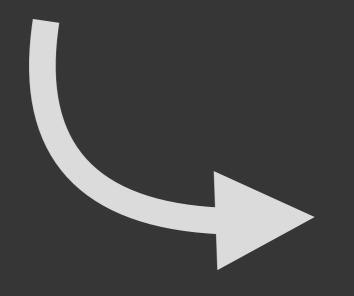


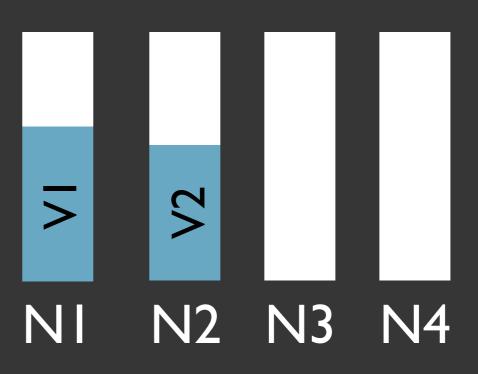




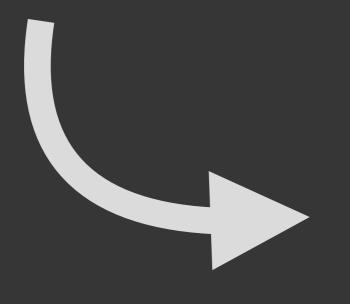


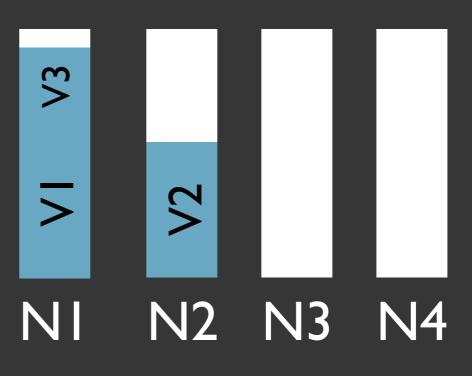


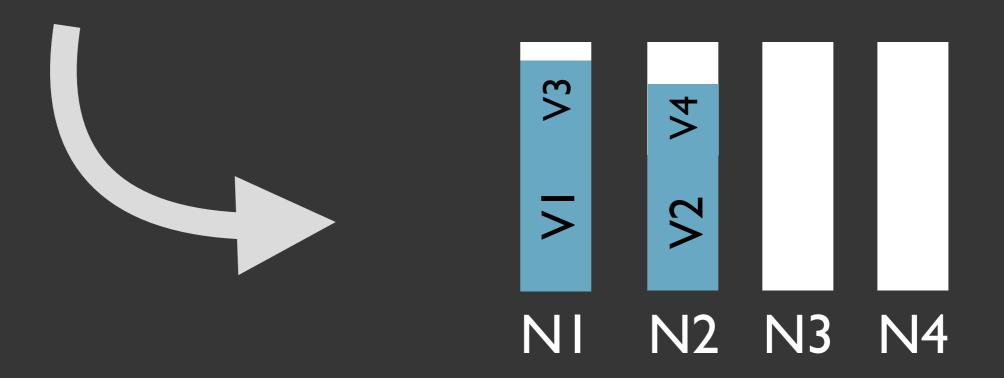




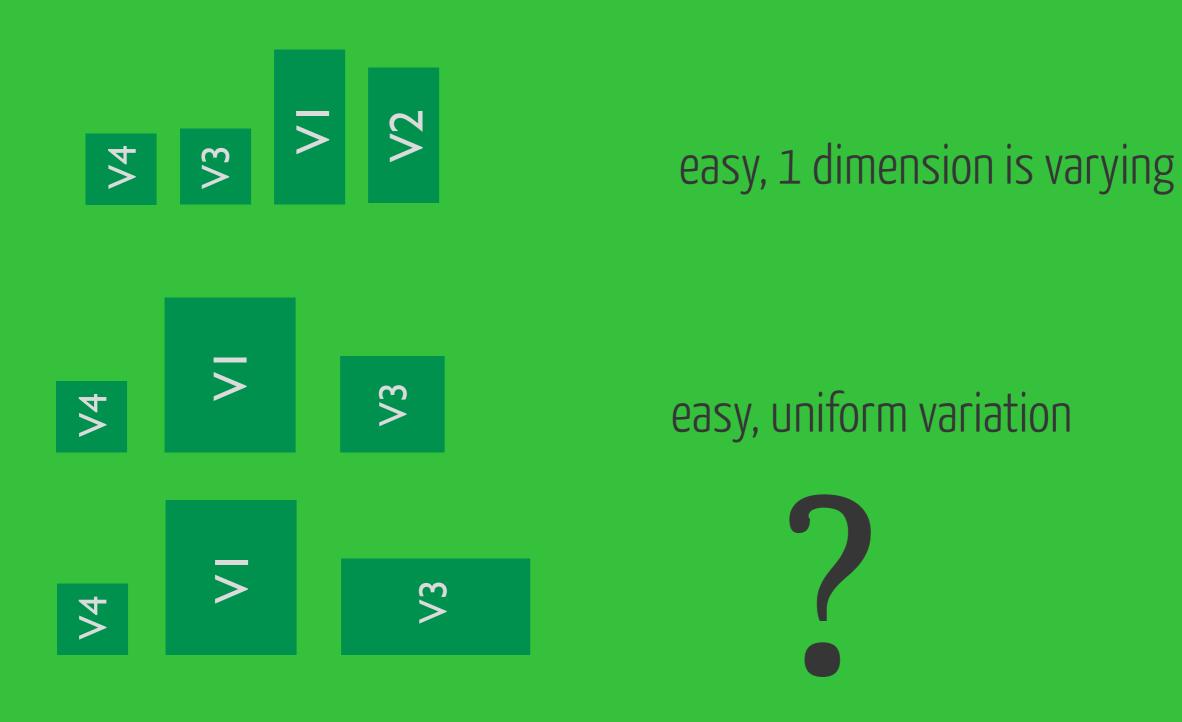




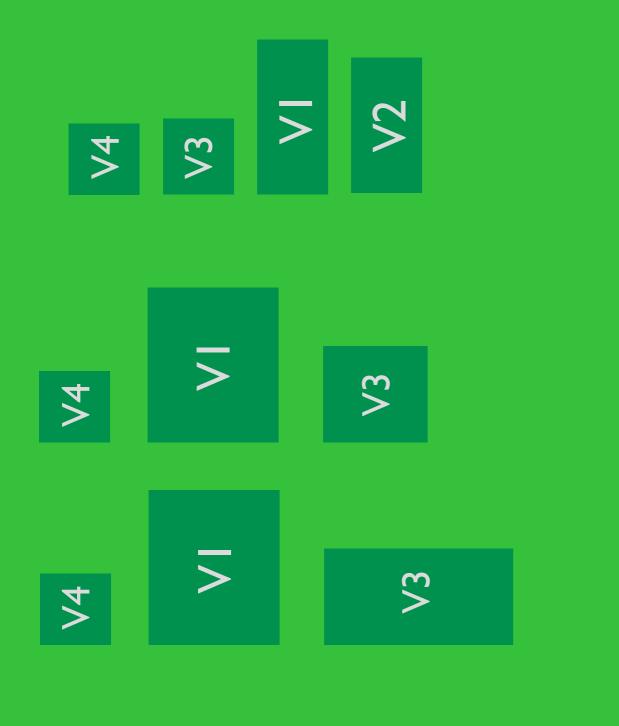




#### multi-dimension sorting?



#### multi-dimension sorting?



easy, 1 dimension is varying

easy, uniform variation

sort by dimension aggregate dimensions find the most critical one

• • •

## Balancing VMs





# 

to reduce loss in terms of failures to reduce hotspots to absorb load spikes

# balancing in theory

```
min(stddev([load(n_1), ..., load(n_i)]))
                     OR
min(
 max([load(n_1), ..., load(n_i)]),
 min([load(n_1), \ldots, load(n_i)]),
```

### Worst Fit Decrease (WFD)

balancing, a practice

```
for each VMs

for each VM

pick the suitable node

with the highest remaining

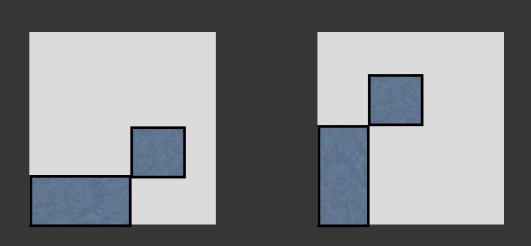
space
```



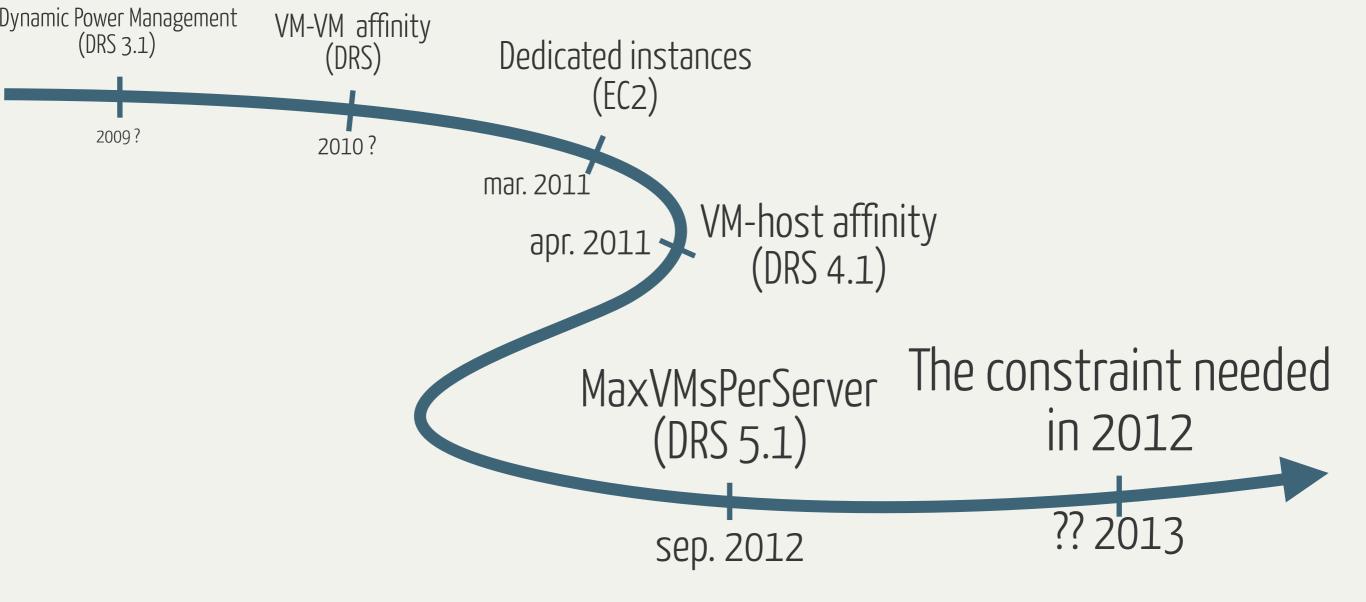
balancing over multiple dimensions

# balancing over — multiple dimensions

dimension normalisation worst dimension dimension aggregation current state vs. next state



#### What about the SLOs?



#### SLOs inject additional rules

placement constraint (anti)affinity rules

(anti)affinity rules fault tolerance, hw. compatibility, security VM-VM, VM-PM, relative, absolute

temporal constraint

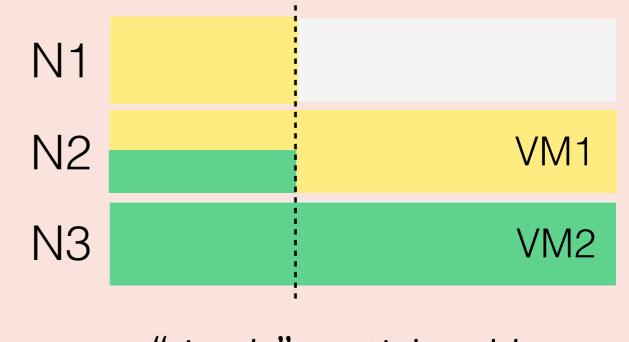
precedences, parralelism, sequence control, performance control between actions

counting constraint

precedences, parralelism, sequence performance, licensing restriction per node, group of nodes, resource

## discrete constraints

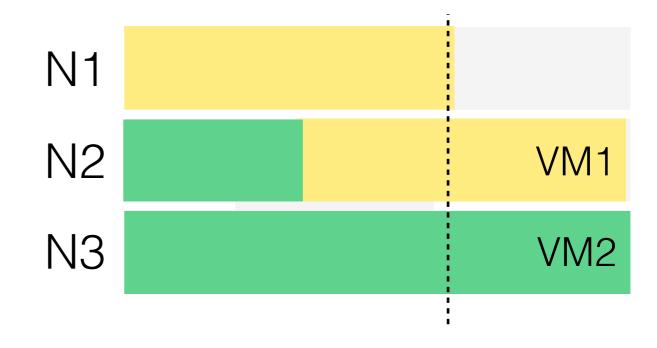
```
>>spread(VM[1,2])
ban(VM1, N1)
ban(VM2, N2)
```



#### "simple" spatial problem

## continuous constraints

spread(VM[1,2])
ban(VM1, N1)
ban(VM2, N2)



harder scheduling problem (think about actions interleaving)

#### hard constraints

spread(VM[1..50])

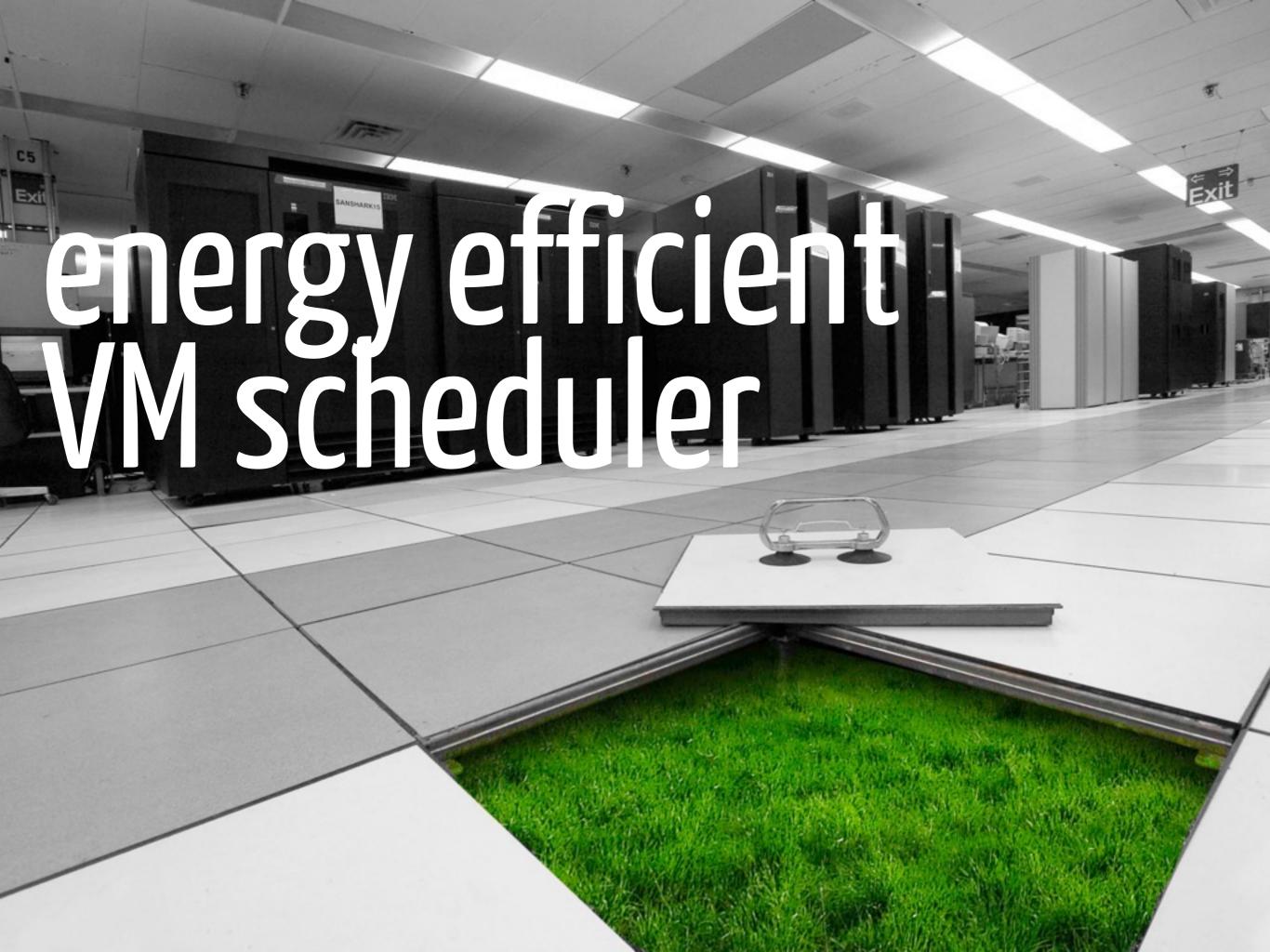
must be satisfied all or nothing approach not always meaningful

mostlySpread(VM[1..50], 4, 6)

soft constraints

satisfiable or not internal or external penalty model

harder to implement/scale hard to standardise?





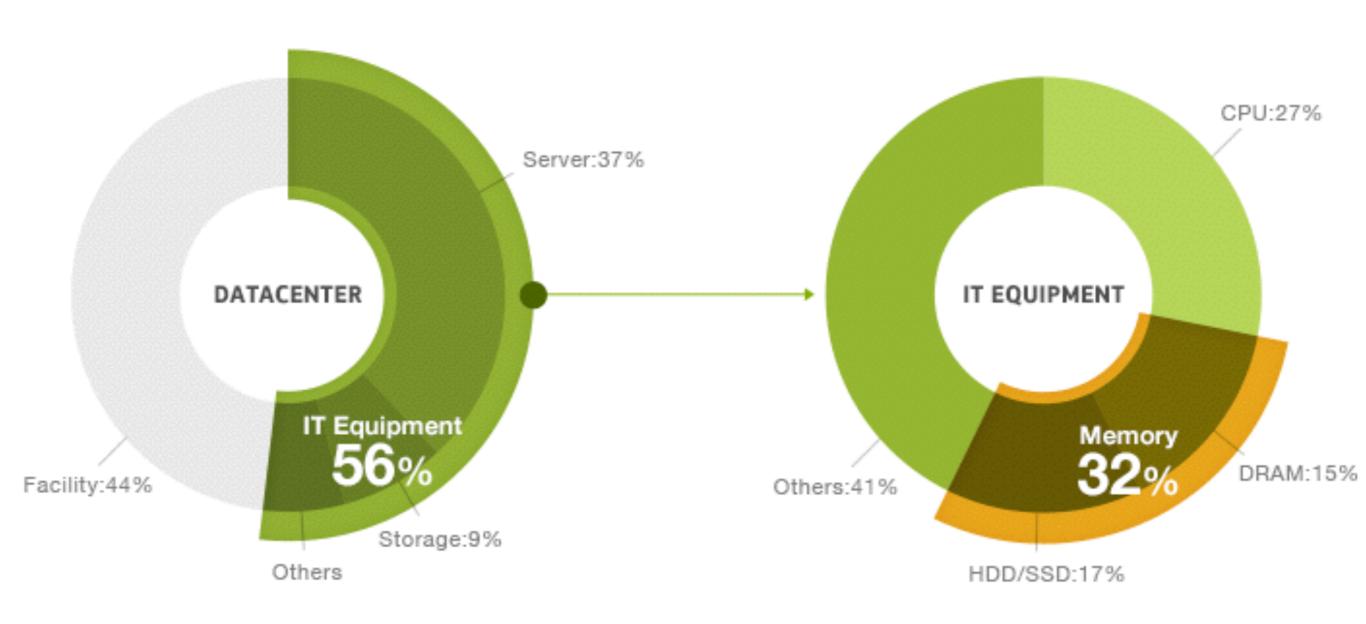
1.5%

of the 2005 budget

3 % in 2010?



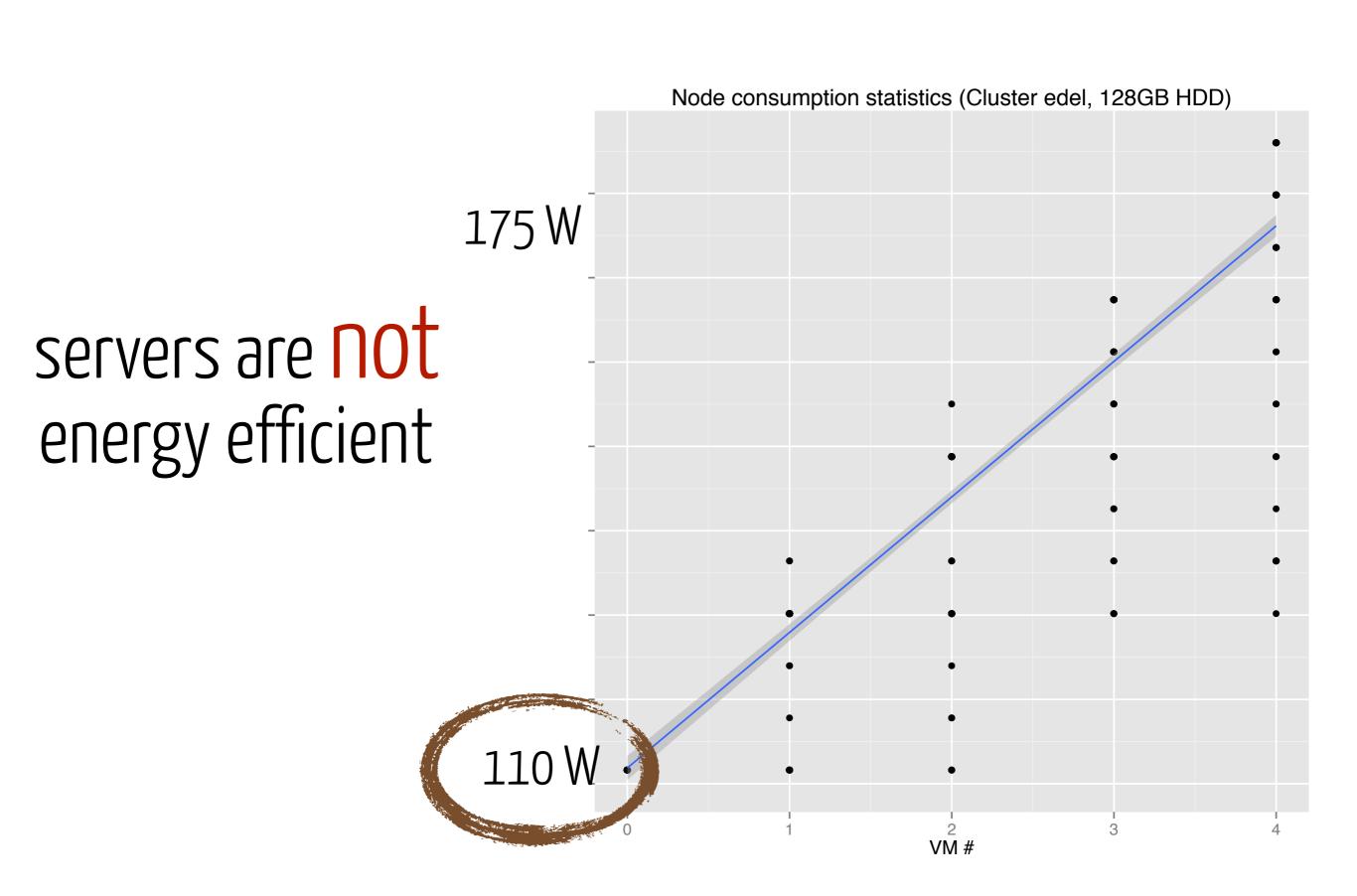
#### IT EQUIPMENT POWER DRAW



Source: Uptime Institute's 2012 Data Center Survey J. Koomey's Report, Aug 2011 Source: Samsung, IDC, EMC

# Consume less

2003



# how to reduce consumption with identical nodes



## The principles

place VMs on the minimum number of nodes

turn off idle nodes

rince/repeat for the dynamic version

## Best Fit Decrease (BFD)

a simple heuristic to pack VMs

```
for each VM

pick the suitable node

with the least remaining

space
```

efficiency decreases when nb. of dimensions increase

#### 2-pass dynamic VM packing

to manage the running VMs

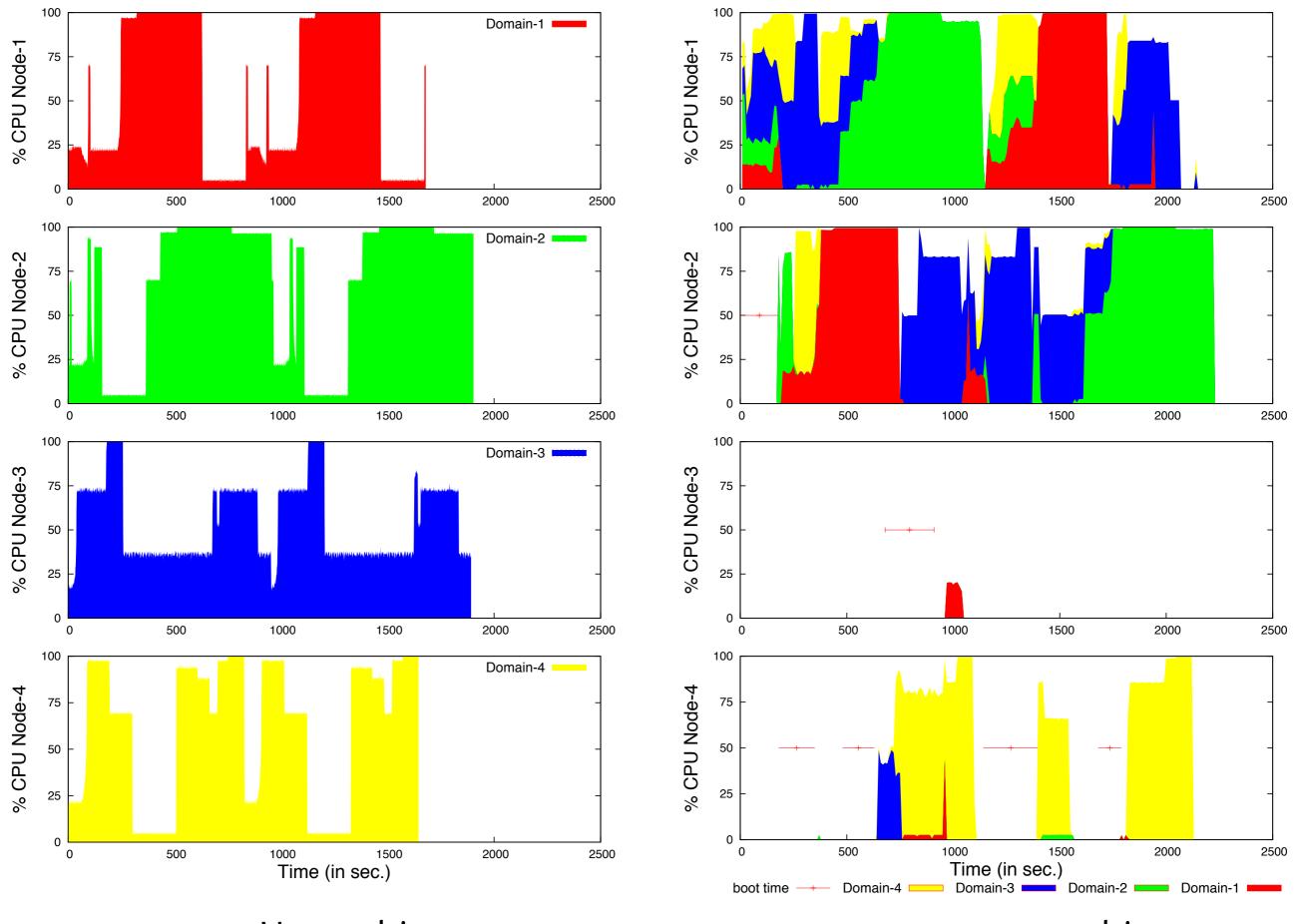
address performance issues

on saturated nodes, BFD to move away VMs on non-saturated nodes

2) address energy efficiency issues

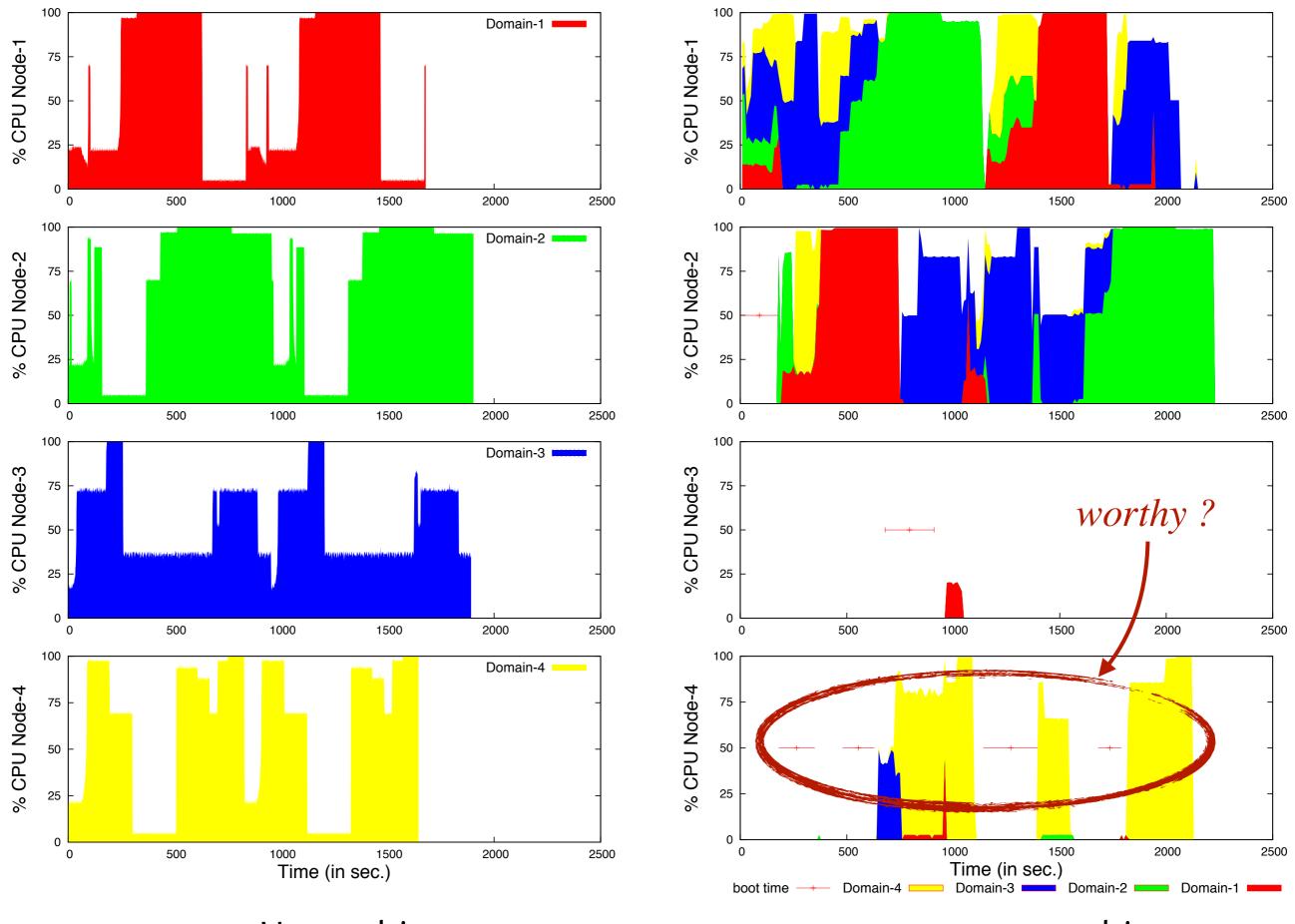
on low-loaded nodes, BFD to move away VMs on heavily loaded nodes

many variations using threshold based systems, load predictions ...



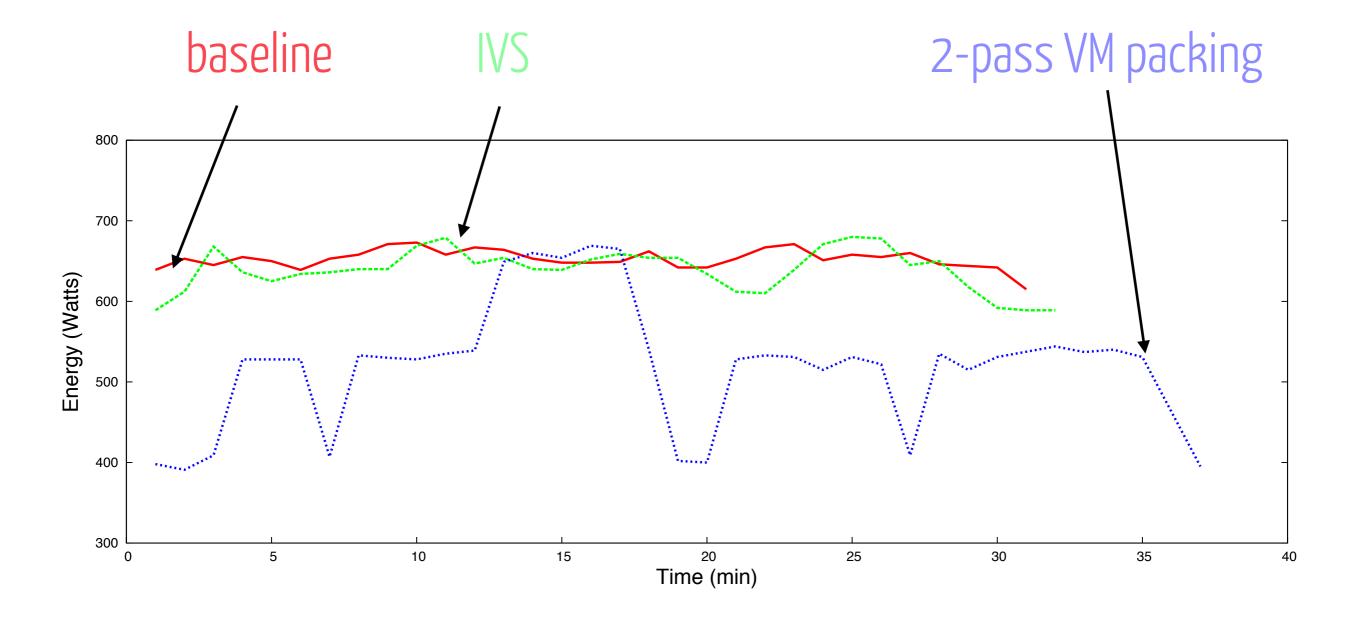
No packing

2-passes packing



No packing

2-passes packing



interesting gains, the node boot time was the bottleneck simplistic model (identical nodes)

## Consequences of having heterogeneous nodes?

# Consequences of having heterogeneous nodes?

different performance different Power Usage Effectiveness

••

how to estimate the benefits of a migration?

- vector packing problem
  - +performance model
  - +power model
  - +cost model
  - 十...

### a specialised model

### power models estimate the energy consumption

model the static and the dynamic energy profile of the components

usually linear equations Wh(node) =  $\alpha$  Hw +  $\beta$ 

### VM performance models

a neutral performance unit mips, ECU, GCU, ...

a model to map VM performance with their host  $perf(VM, N) = \alpha_{\Pi}\%cpu + \beta$ 

#### hw. particularities

multi-core CPUs, DDR3 memory, spinning HD, PUE / CUE, boot/shutdown time



#### workload particularities

VM template migration duration migration payback time

### a fine-grain power model







coarse to fine grain optimisation

# Consume better

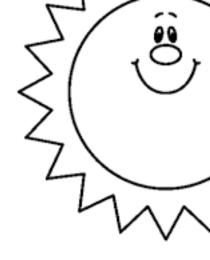
2012

from a spatial to a temporal point of view

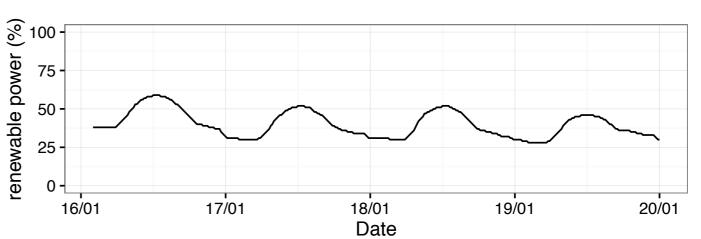


2013 - 2016

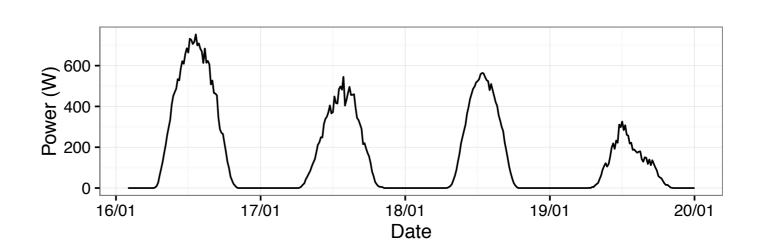
let existing and new data centres become energy adaptive



grid renewable part



sunroof PV production



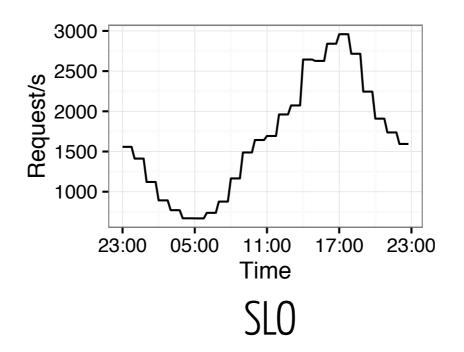
renewable energies are intermittent

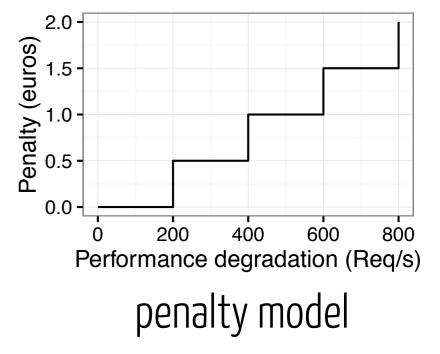


#### so are elastic and batch-oriented applications



6 to 20 moonshot cartridges

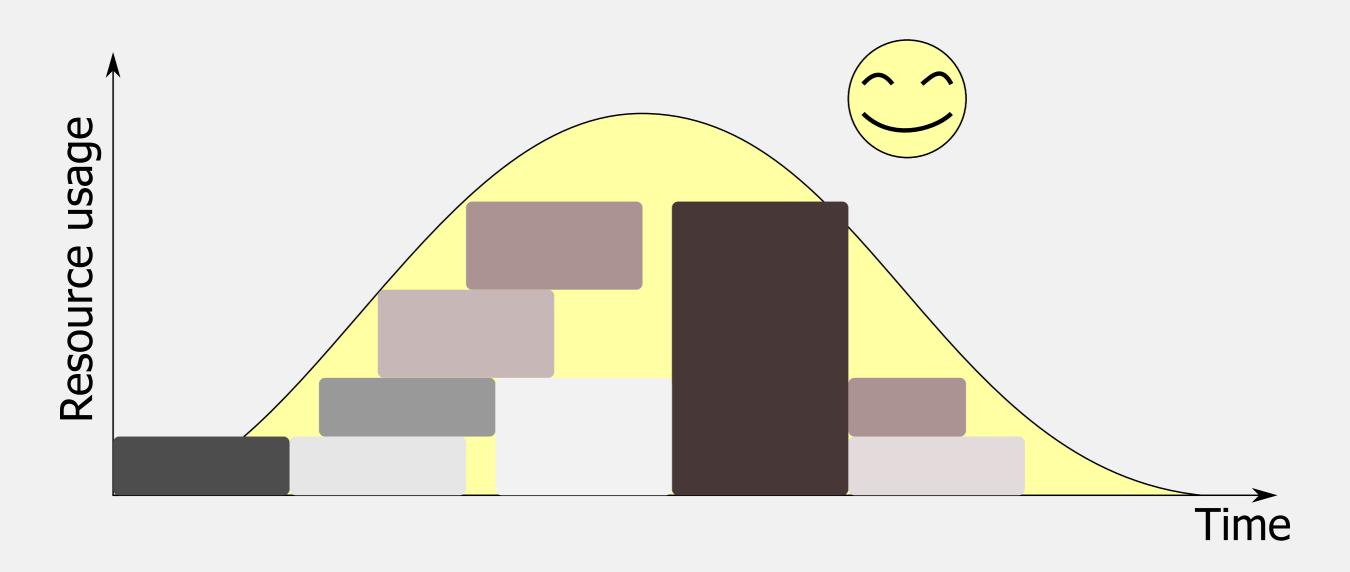




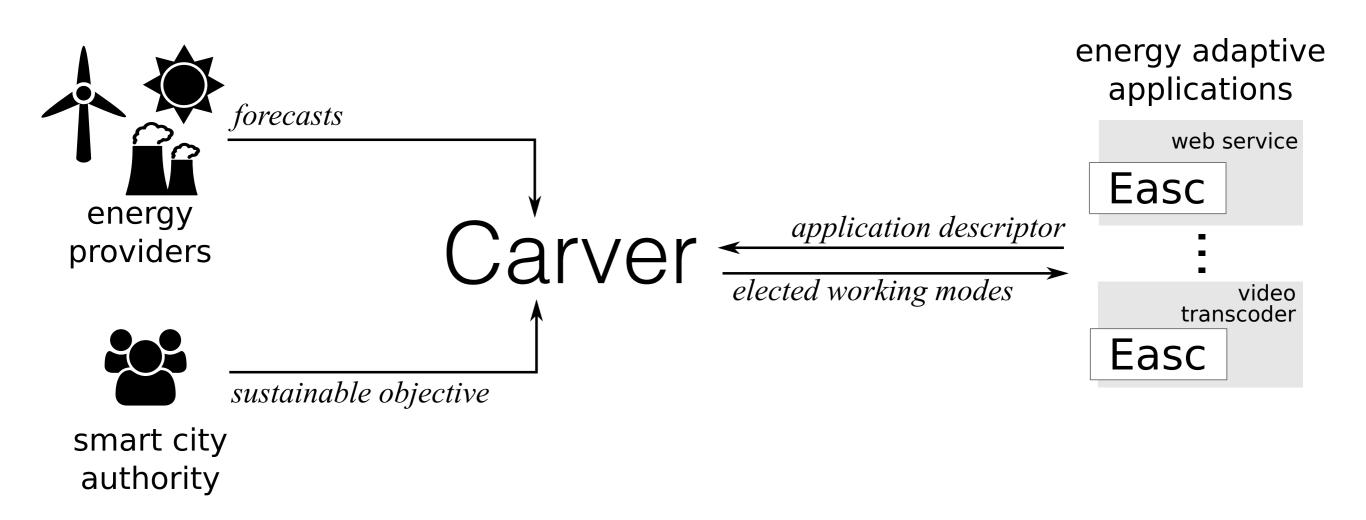
| Application | Performance                | Power (W) |
|-------------|----------------------------|-----------|
| Website     | $1050-3250~\mathrm{Req/s}$ | 360 - 550 |
| G-indexing  | 0-565  kPages/h            | 6-33      |
| E-indexing  | 0-60  kPages/h             | 6-33      |

### align workload to renewable energies availability





#### shape EASCs for sustainable profitability



pick WMs such as min(penalty(SLO) + penalty(SMA) + price(E))

#### Energy Adaptive Software Components

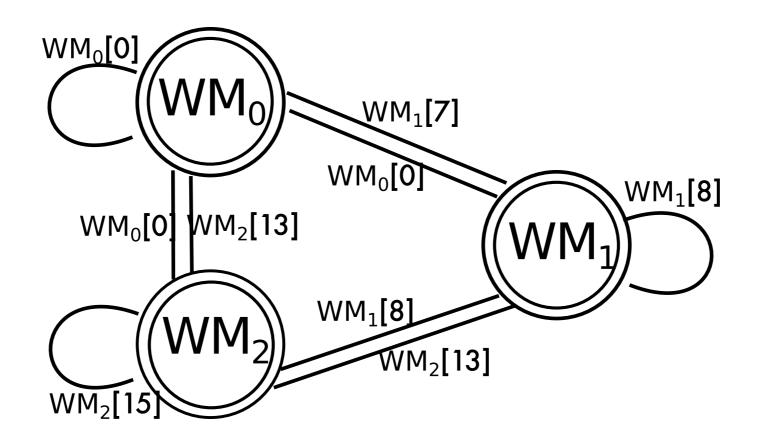
attached to an application

#### exhibit

- working modes
- SLO (cumulative or instant)
- actuators

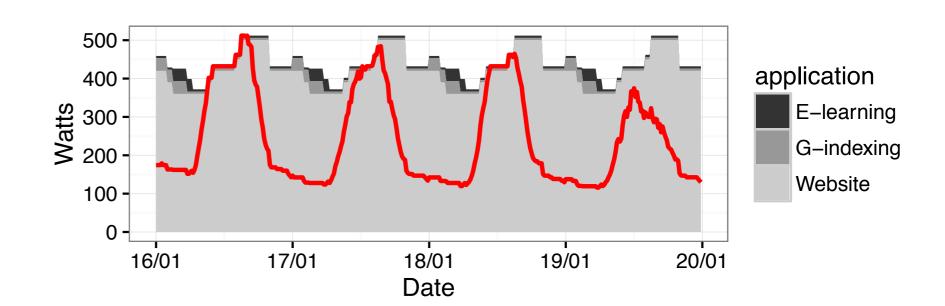
```
name: pageIndexing
 businessUnit: kPage
 SL0:
 - timeFrom: 00:00:00
    timeTo: 24:00:00
    cumulativeObjective: !amount '200 kPage'
    basePrice: !amount '100 EUR'
    priceModifiers:
    - threshold: !amount '200 kPage'
      penalty: !amount '0 EUR/kPage'
    - threshold: !amount '100 kPage'
      penalty: !amount '-1 EUR/kPage'
    - threshold: !amount '0 kPage'
      penalty: !amount '-100 EUR'
 workingModes:
  - name: WM0
    actuator: bin/run.sh WM0
    performance: !amount '0 kPage/h'
    power: !amount '6 W'
    transitions:
      - target: WM1
        performanceCost: !amount '1 kPage'
      - target: WM2
        performanceCost: !amount '2 kPage'
  - name: WM1
    actuator: bin/run.sh WM1
    performance: !amount '32 kPage/h'
    power: !amount '27 W'
    transitions:
      - target: WM2
        performanceCost: !amount '2 kPage'
  - name: WM2
    actuator: bin/run.sh WM2
    performance: !amount '60 kPage/h'
    power: !amount '33 W'
```

#### An automaton for each EASC model the behavior,

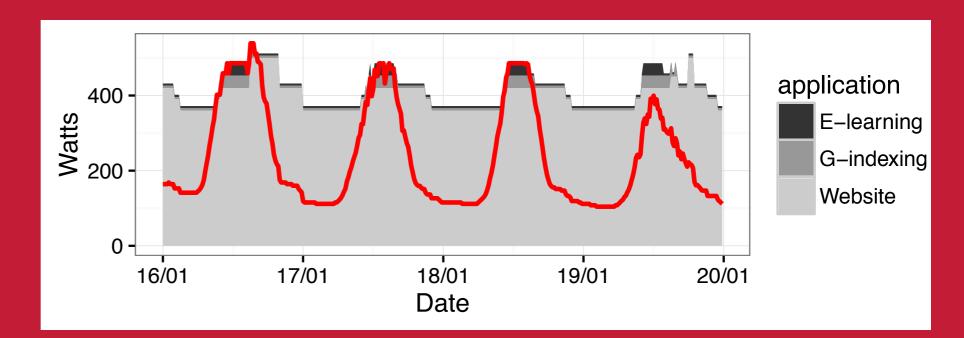


+ penalty functions for the SMA, the SLA

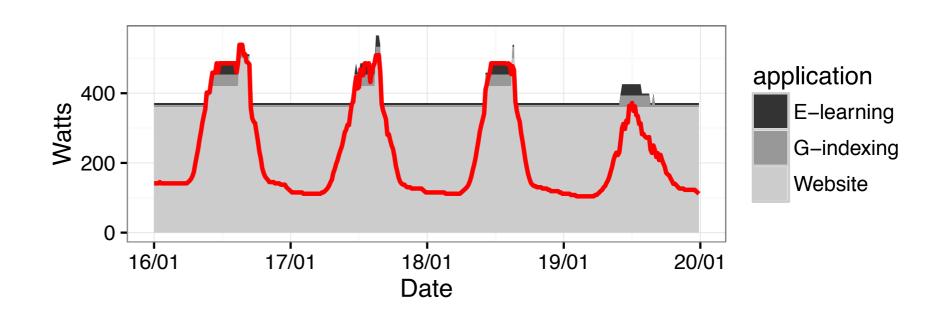
baseline (satisfy perf)



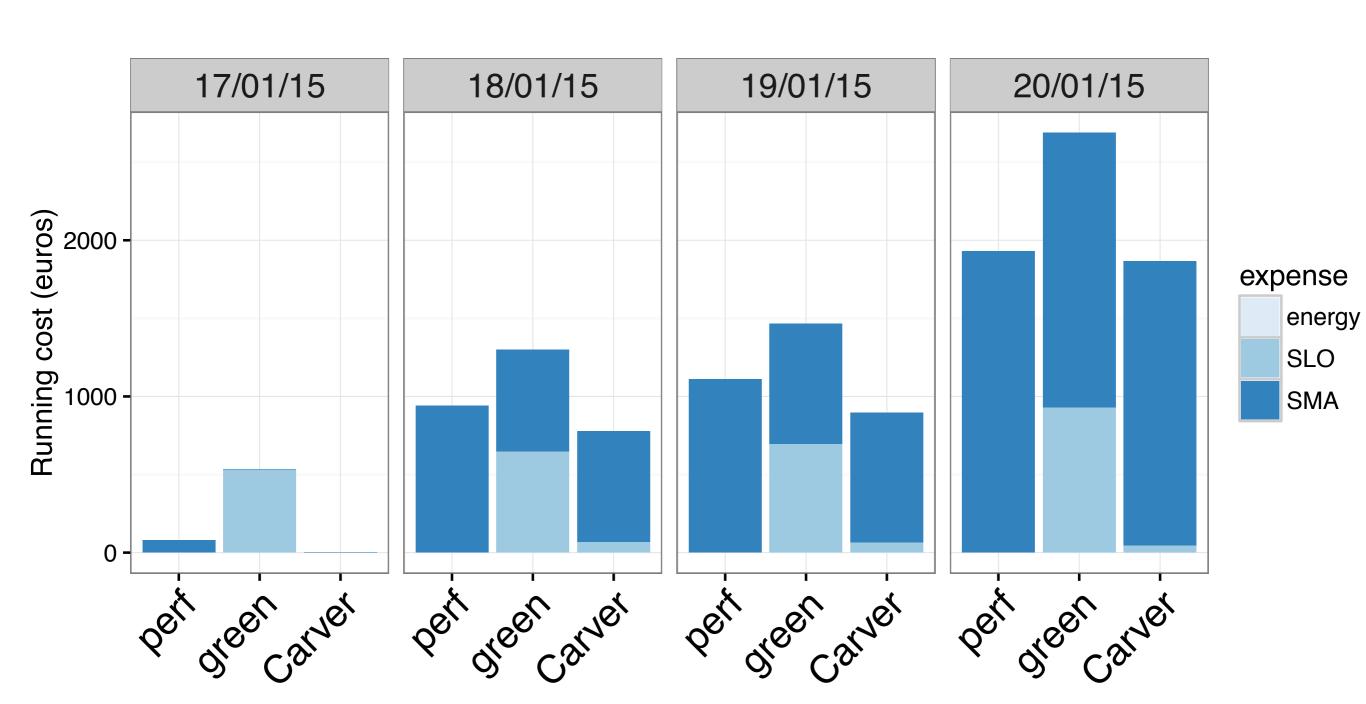
#### carver



"green" (max renewable)



### Resulting running costs



# 

### no holy grail

# master the problem