KTH Mechatronics Advanced Course

MF2063, HT 2018

FINAL REPORT

ESS-NW/ESS-CAR

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Abstract   1

Abstract starts here, what should be included:

    The problem issue subject being addressed

    How the problem is tackled

    Overview of the results, and indication as to what level they solve the problem.

    Implications of the results

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1 Introduction

This report presents the process and results of two projects "Embedded Service for Self-adaptive Network" (ESS-NW) and "Embedded Service for Self-adaptive Car" (ESS-CAR).

1.1 Background

1.1.1 Background subsection blabla

1.2 Project Description

1.2.1 Project Description sub blabla

1.3 Delimitations

1.4 Readers guide / Report disposition

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2   Literature Review and State of the Art

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3   Methodology   7

3.1   Engineering approaches ?

3.2   Tool-chains ?

3.3   Project management

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4   Implementation   8

4.1   System overview

maybe put communication diagram here

4.2   Communication between Beaglebones

4.3   Communication between Beaglebone and Arduino

4.4   Implementing the OS

4.5   Sensors

4.5.1   Ultrasonic sensor

4.5.2   Reflective object sensor

4.5.3   Camera

4.6   Controlling actuators

4.6.1   Steering servo

4.6.2   Motor ESC

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5   Verification and Validation

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6 Results

7 Discussion and Conclusion

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8 Future Work