KTH Mechatronics Advanced Course

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FINAL REPORT

ESS-NW/ESS-CAR

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Abstract

Abstract starts here, what should be included:
The problem issue subject being addressed
How the problem is tackled
Overview of the results, and indication as to what level they solve the problem.
Implications of the results

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This report presents the process and results of two projects "Embedded Service for Self-adaptive Network" (ESS-NW) and "Embedded Service for Self-adaptive Car" (ESS-CAR).

1.1 Background

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1.4 Readers guide / Report disposition

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3 Methodology

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4 Implementation

4.1 System overview

maybe put communication diagram here

4.2 Communication between Beaglebones

4.3 Communication between Beaglebone and Arduino

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