

# EH2760 MANAGEMENT OF PROJECTS

ESS-CAR/ESS-NW

STOCKHOLM, SWEDEN

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## Project Plan

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JONAS EKMAN  
YINI GAO  
JACOB KIMBLAD

LEON FERNANDEZ  
FREDRIK HYYRYNEN  
YIFAN RUAN

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## Background

Advanced Driver Assistance Systems (ADAS) is one of the hottest research areas in the automotive industry. ADAS should be capable of sensing the vehicle's surroundings, as well as vehicle's own status. To achieve those abilities, multiple sensors and Embedded Control Units (ECUs) are used in the ADAS and a network inside the vehicle is established to combine the data gathered from different nodes.

The two projects "ESS-Car Embedded Services for a Self-Adaptive Car" and "ESS-Network Embedded services for Self-Adaptive Networking" were provided by professor De-Jiu Chen at KTH Royal Institute of Technology. The idea of our projects are from Viktor Karlquist's Master's thesis [1]. He presented a design and implementation of an automotive experimental platform for ADAS, and the "ESS-Car" team from last year's MF2063 course round has already built a autonomous vehicle prototype based on the thesis [2]. Our projects will be focused on the development and extension of the prototype. Instead of traditional IP networks, software defined networking, which centralizes the control plane in the network and allows for a better granular and agile network management, will be implemented by "ESS-NW" team. "ESS-Car" team will implement error injectors on the new prototype which makes the car more autonomous.

## Reference Documents

- EH2760 course-pm [3]
- ESS-CAR and ESS-NW entries in the MF2063 project catalog [4]

## 1 Goals

## 2 Organization

The requirements of the project were divided into a number of topics, with each team member being focused on two topics. Additionally, Leon and Fredrik have been appointed roles of Project Manager and Secretary, respectively.

### 2.1 People

#### 2.1.1 Project Members

- Fredrik Hyyrynen, fhyy@kth.se, Software and Computer Vision, Secretary
- Jacob Kimblad, jacobki@kth.se, Software and Control
- Jonas Ekman, jonekm@kth.se, Network and Electronics
- Leon Fernandez, leonfe@kth.se, Network and Software, Project Manager
- Yifan Ruan, yifanr@kth.se, Control and Electronics
- Yini Gao, yini@kth.se, Computer Vision and Software

#### 2.1.2 Stakeholders

- Dejiu Chen, chen@md.kth.se, Stakeholder, Supervisor
- Matthias Becker, mabecker@kth.se, Stakeholder, Supervisor

## 2.2 Topics and Roles Elaboration

Software - Consists of scheduling the tasks running at the different nodes in the system, managing the bootstrapping of the system upon startup and lastly, writing code for the arduino nodes

Computer Vision - Consists of setting up the Raspberry Pi + Camera subsystem and implementing the computer vision algorithm

Control - Consists of devising and implementing the main control algorithm that will run on one of the nodes

Network - Consists of configuring the SDN switches and SDN controller as well as writing the application-layer programs that the nodes use to communicate

Electronics - Consists of doing the PCB design for the "motherboard" in the car as well as mounting the sensors and wiring in the car

Project Manager - Consists of communicating with stakeholders, schedule and lead meetings and handling parts orders

Secretary - Consists of taking notes during meetings and being a temporary manager in the absence of the project manager

## 3 Project Model

### 4 Commentary: Time Plan

### 5 Commentary: Resource Plan

### 6 Risk Analysis

### 7 Communication

### 8 Documentation

## References

- [1] Karlquist, “Design and implementation of an automotive experimental platform for ADAS,” KTH, Skolan för informations- och kommunikationsteknik (ICT), 2017.
- [2] Bark *et al.*, “Embedded service for self-adaptive cars,” KTH, Institutionen för Maskinkonstruktion, 2017. [Online]. Available: <https://kth.box.com/s/iaabvkok3fsqgpbgaq10ymgqnnf3a135>
- [3] Lilliesköld, Gingnell, Petterson, and Varawala, “Management of projects eh2760,” KTH, Management of Technology Research Group, 2018.
- [4] Chen and Derbyshire, “The embedded systems HK 2018 project descriptions,” KTH, Institutionen för Maskinkonstruktion, 2018.

- A Time Plan
- B Resource Plan
- C Work Breakdown Structure