KTH Mechatronics Advanced Course

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FINAL REPORT

ESS-NW/ESS-CAR

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Abstract

Abstract starts here, what should be included:
The problem issue subject being addressed
How the problem is tackled
Overview of the results, and indication as to what level they solve the problem.
Implications of the results

Contents

List of Figures

List of Tables

1 Introduction

This report presents the process and results of two projects "Embedded Service for Self-adaptive Network" (ESS-NW) and "Embedded Service for Self-adaptive Car" (ESS-CAR). This chapter will start by describing the background of the two projects. The next thing to be described is formulation, goals and motivation of the two projects. Following this will be a short discussion on the delimitations for our team. The last part of this chapter will present an explicit report disposition which helps readers to get a sense of the overall report.

1.1 Background

1.1.1 Background subsection blabla

1.2 Project Description

1.2.1 Project Description sub blabla

1.3 Delimitations

1.4 Report disposition

2 Literature Review and State of the Art

3 Methodology

3.1 Engineering approaches ?

3.2 Tool-chains ?

3.3 Project management

Scrum project management is used during the process of our projects.

4 Implementation

4.1 System overview

maybe put communication diagram here

4.2 Implementing SDN network

4.3 Communication between Beaglebone and Arduino ?

4.4 Sensors

Three categories of sensors are implemented in the prototype vehicle to monitor its surrounding environments. Data from distance sensors and speed sensor will be sent to an Arduino initially, then sent to corresponding Beaglebone. Data from Pi Camera will be sent to the Raspberry Pi which is directly connected to the main network.

4.4.1 Ultrasonic sensor

To get data from HC-SR04, 10µs

4.4.2 Reflective object sensor

4.4.3 Camera

4.5 Controlling actuators

4.5.1 Steering servo

4.5.2 Motor ESC

4.6 Assemble the car, power supply, etc

5 Verification and Validation

6 Results

7 Discussion and Conclusion

8 Future Work