



JÖNKÖPING UNIVERSITY

School of Engineering

ANDROID SENSORS

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SENSORS

Sensor = object collecting data from its surroundings.

- Android supports many different type of sensor.
 - Temperature - The ambient room temperature.
 - Light - The ambient light level.
 - Pressure - The ambient air pressure.
 - Humidity - The ambient humidity.

SENSORS

Sensor = object collecting data from its surroundings.

- Android supports many different type of sensor.
 - Accelerometer - Acceleration force (including gravity) in 3 directions.
 - Gravity - Gravitational force in 3 directions.
 - Linear Acceleration - Acceleration force (excluding gravity) in 3 directions.
 - Gyroscope - Rotational speed around 3 axes.
- Sensors can be implemented either as hardware or software.
- All Android devices do not support all sensors.

SENSOR SUPPORT TABLE

Sensor	Android 4.0	Android 2.3	Android 2.2	Android 1.5
TYPE_ACCELEROMETER	Yes	Yes	Yes	Yes
TYPE_AMBIENT_TEMPERATURE	Yes	n/a	n/a	n/a
TYPE_GRAVITY	Yes	Yes	n/a	n/a
TYPE_GYROSCOPE	Yes	Yes	n/a	n/a
TYPE_LIGHT	Yes	Yes	Yes	Yes
TYPE_LINEAR_ACCELERATION	Yes	Yes	n/a	n/a
TYPE_MAGNETIC_FIELD	Yes	Yes	Yes	Yes
TYPE_ORIENTATION	Deprecated	Deprecated	Deprecated	Yes
TYPE_PRESSURE	Yes	Yes	n/a	n/a
TYPE_PROXIMITY	Yes	Yes	Yes	Yes
TYPE_RELATIVE_HUMIDITY	Yes	n/a	n/a	n/a
TYPE_ROTATION_VECTOR	Yes	Yes	n/a	n/a
TYPE_TEMPERATURE	Deprecated	Yes	Yes	Yes

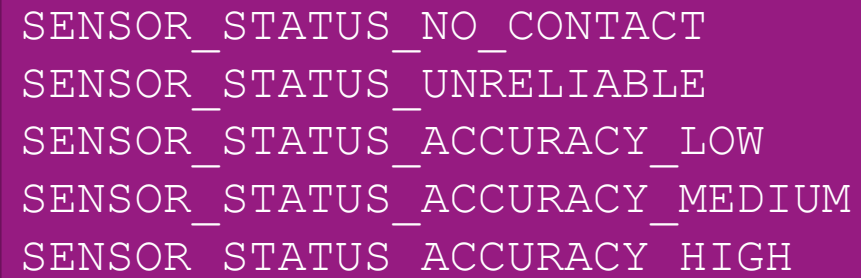
USING SENSORS

```
SensorManager sensorManager = (SensorManager)
    aContext.getSystemService(Context.SENSOR_SERVICE);

Sensor sensor = sensorManager.
    getDefaultSensor(Sensor.TYPE_XXX);

SensorEventListener listener = new SensorEventListener() {
    @Override
    public void onSensorChanged(SensorEvent event) {
    }

    @Override
    public void onAccuracyChanged(Sensor sensor, int accuracy) {
    }
};
```



```
SENSOR_STATUS_NO_CONTACT
SENSOR_STATUS_UNRELIABLE
SENSOR_STATUS_ACCURACY_LOW
SENSOR_STATUS_ACCURACY_MEDIUM
SENSOR_STATUS_ACCURACY_HIGH
```

USING SENSORS

```
SensorEventListener listener = new SensorEventListener() {  
    protected float[] myValues = new float[3];  
    @Override  
    public void onSensorChanged(SensorEvent event) {  
        Sensor sensor = event.sensor;  
        float[] values = event.values;  
        System.arraycopy(event.values, 0,  
                           myValues, 0,  
                           event.values.length);  
    }  
};
```

USING SENSORS

To start listen for events:

```
sensorManager.registerListener(  
    listener,  
    sensor,  
    SensorManager.SENSOR_DELAY_XXX  
);
```



SENSOR_DELAY_FASTEST
SENSOR_DELAY_GAME
SENSOR_DELAY_NORMAL
SENSOR_DELAY_UI

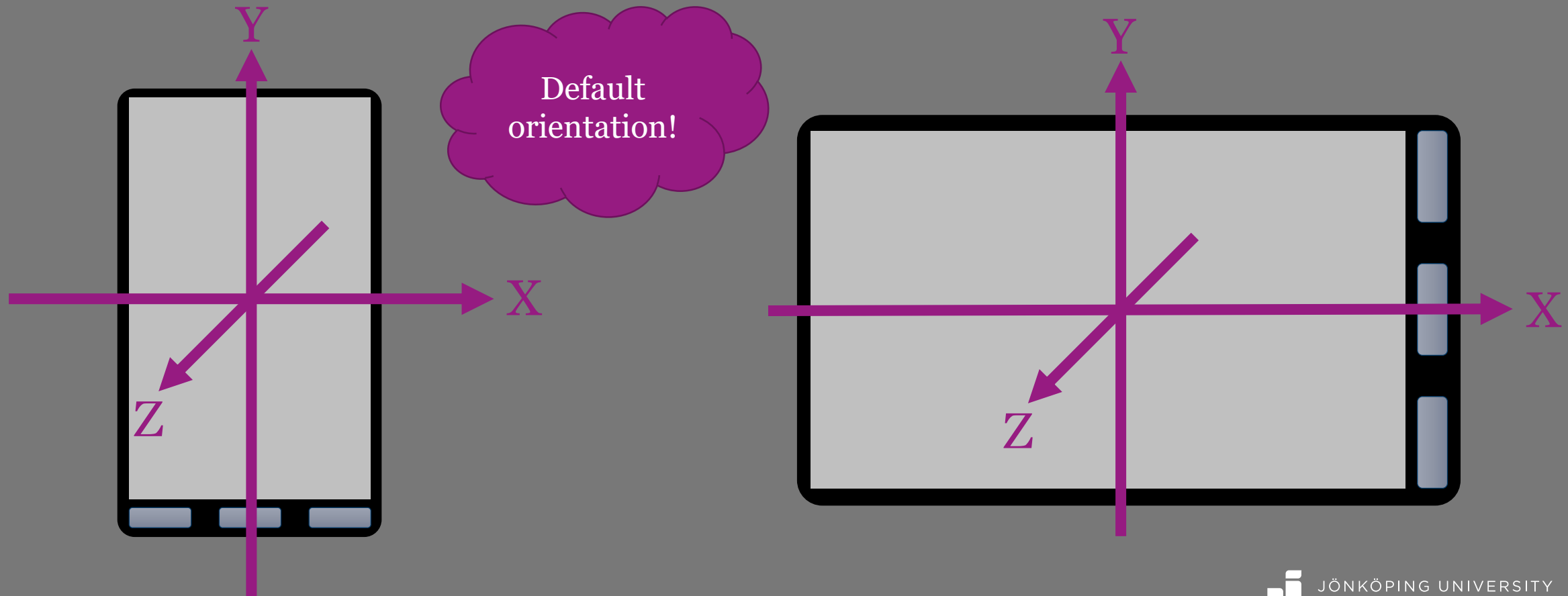
To stop listen for events:

```
sensorManager.unregisterListener(listener);
```

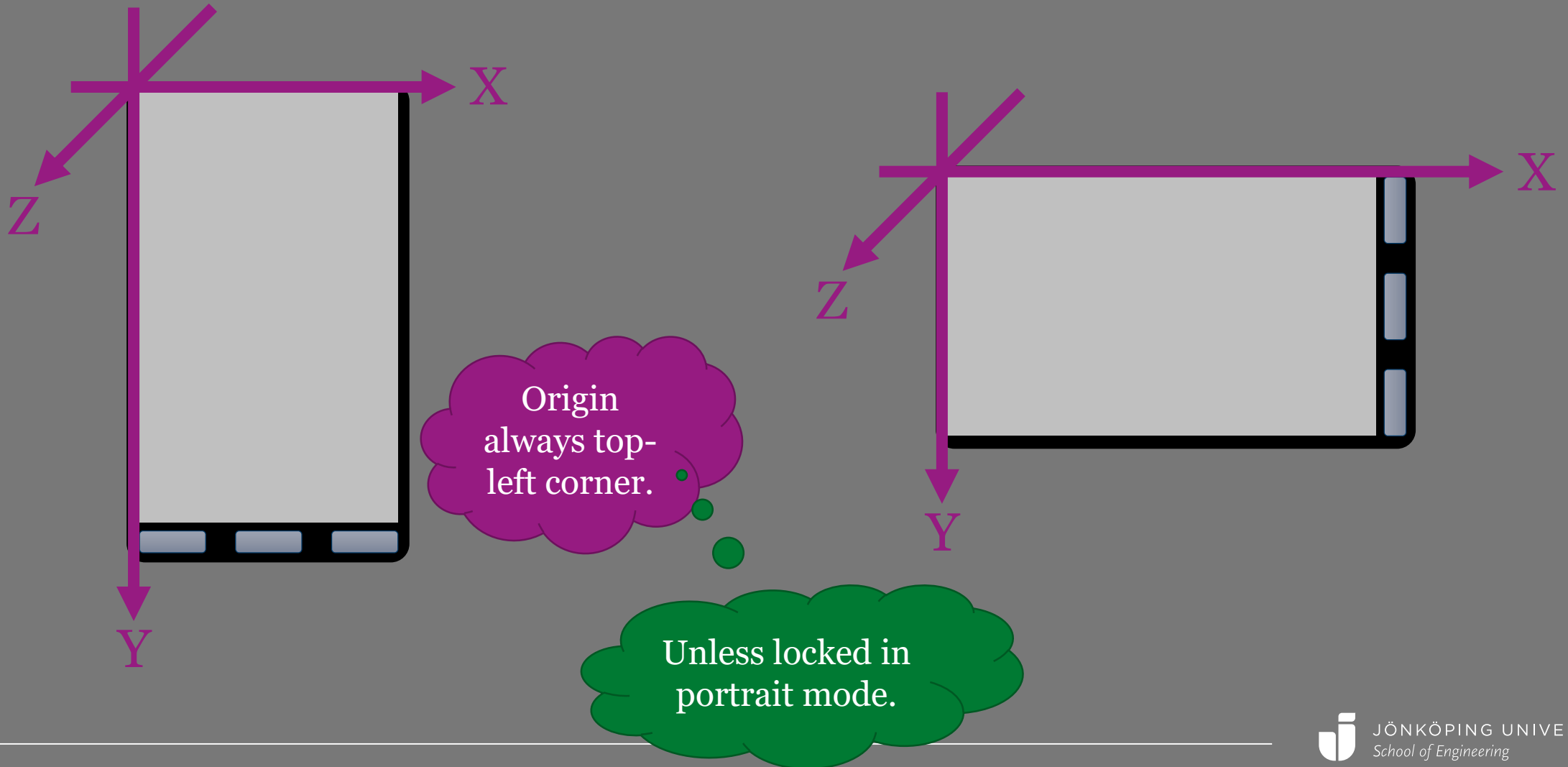
Documentation: *"Note that the system will not disable sensors automatically when the screen turns off"*

COORDINATE SYSTEM FOR MOTION

The device's frame of reference.



COORDINATE SYSTEM FOR UI



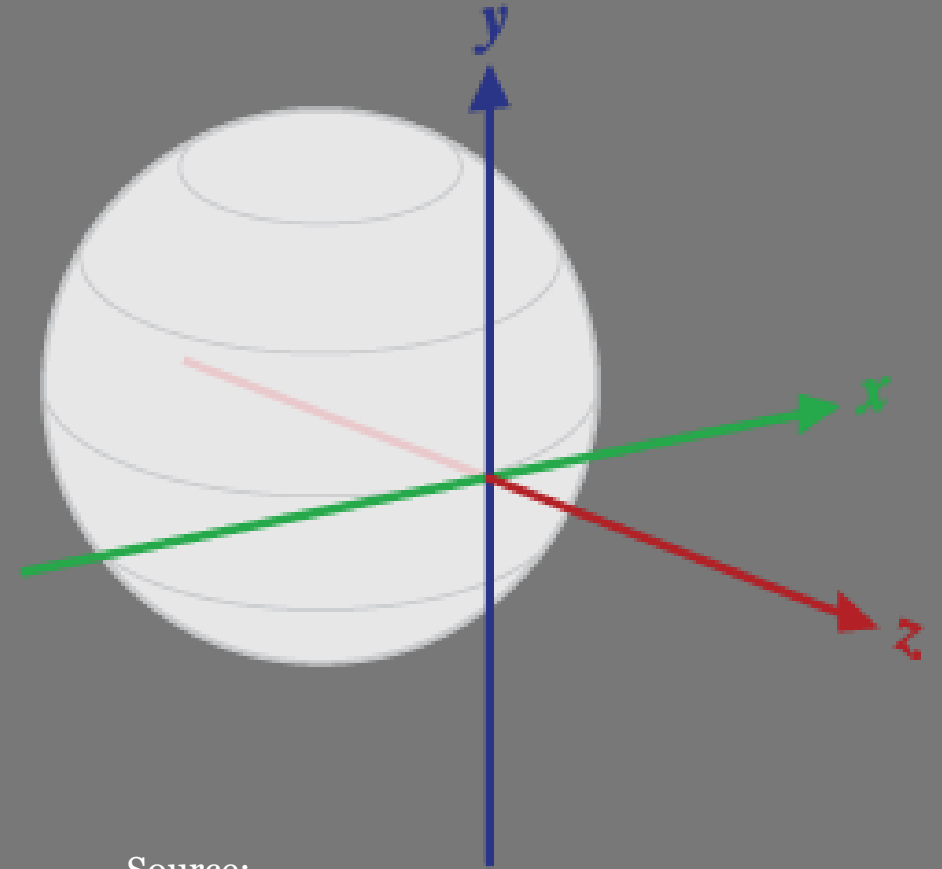
FINDING CURRENT ORIENTATION

```
int rotation = anActivity.getWindowManager().  
                getDefaultDisplay().getRotation();  
  
switch(rotation) {  
    case Surface.ROTATION_0:  
        // Default orientation is used.  
        break;  
    case Surface.ROTATION_90:  
        // Default orientation + 90 degrees.  
        break;  
    // ...  
}
```

COORDINATE SYSTEM FOR EARTH

The world's frame of reference.

- Z points towards the sky.
- Y points towards the magnetic North Pole.
- X points towards the East(-ish).



Source:

<https://developer.android.com/reference/android/hardware/SensorManager.html>

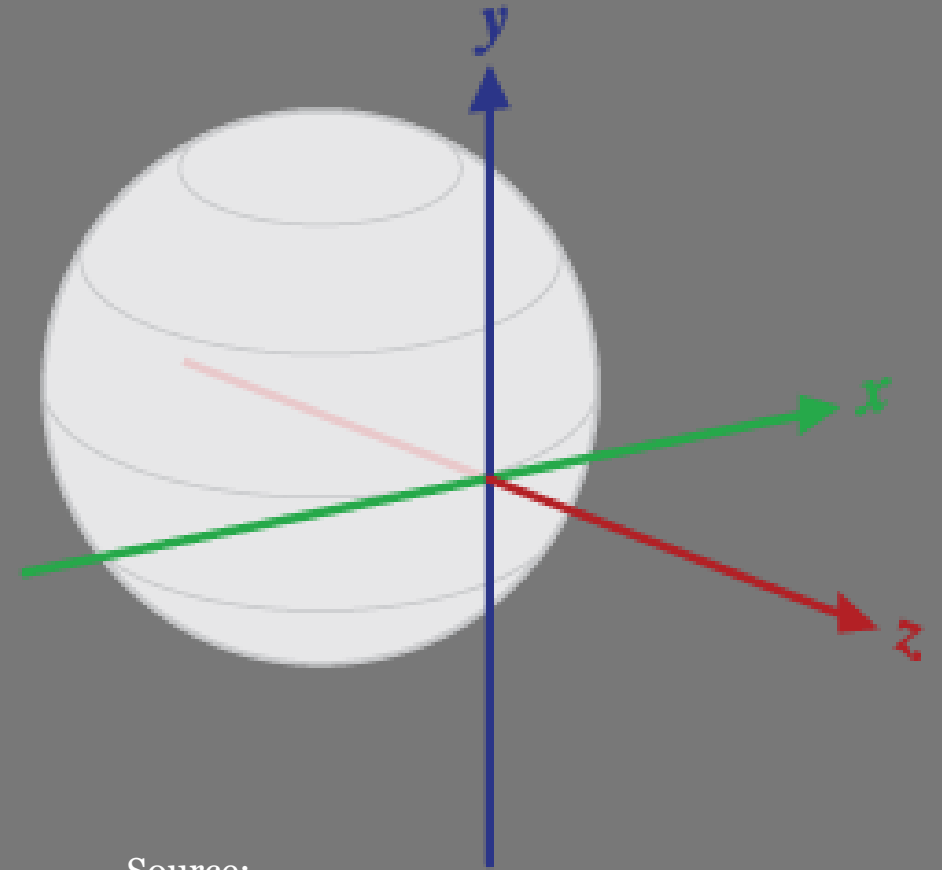


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COORDINATE SYSTEM FOR EARTH

```
SensorManager.getRotationMatrix(  
    float[9] R,  
    float[9] I,  
    accelerometerValues,  
    geomagneticValues  
);
```

Computes the inclination matrix **I** as well as the rotation matrix **R** transforming a vector from the device coordinate system to the world's coordinate system.



Source:
<https://developer.android.com/reference/android/hardware/SensorManager.html>

GETTING THE ORIENTATION

```
SensorManager.getOrientation(  
    R,  
    float[3] rotations  
);
```

Computes the device's orientation based on the rotation matrix.

- `rotations[0]` - Rotation around the Z axis.
- `rotations[1]` - Rotation around the X axis.
- `rotations[2]` - Rotation around the Y axis.

REMAPPING SENSOR DATA

```
SensorManager.remapCoordinateSystem(  
    oldR, SensorManager.AXIS_Y, SensorManager.AXIS_Z,  
    float[9] newR  
);
```

- The third axis?
 - The system figures it out (orthonormal system).



The new
X axis.



The new
Y axis.