

# Fidel Echevarría

*Aerospace Engineer*

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<https://fidelechevarria.github.io/>  
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Proactive aerospace engineer. Creative and agile problem solver, strongly motivated to teamwork. In continuous search of learning. Really interested in autonomous driving, computer vision, artificial intelligence, renewable energies and urban sustainability.

## Experience

since jun16 **Flight Control Engineer - Sensor Fusion, UAV Navigation, Madrid.**

Responsible for software development of perception solutions. Also leading research and development project in the area of computer vision. Areas of work:

- Sensor fusion techniques for aircraft dynamic estimation (GNSS, ADU, IMU, MAG).
- Sensor calibration techniques.
- Computer vision systems for autonomous aircraft navigation.
- Simulation. Dynamics, kinematics, atmospheric perturbances.
- Flight control algorithms and logics.
- Preparation, revision and maintenance of test cases, requirements and technical documentation.
- Technical support for international clients and internal departments.
- Internship mentor for flight dynamics department.

sep15-jun16 **Flight Control Engineering Intern, UAV Navigation, Madrid.**

Involved in the development and validation process of several aircraft simulators and control systems.

## Education

sep19-sep20 **M.Sc. Research in Artificial Intelligence, Universidad Nacional de Educación a Distancia (UNED).**

Key subjects: Bio-inspired neural methods, evolutionary computation, computer vision, perceptual and autonomous robotics, machine learning methods, research methodology for intelligent systems.

Thesis: *Identification of Aircraft Dynamics Using Neural Networks.*

oct18-jun19 **Self-Driving Car Engineering Nanodegree, Udacity.**

Key subjects: Deep learning, computer vision, sensor fusion, localization, model predictive control, optimal path algorithms, system integration (ROS).

sep10-sep16 **B.Sc. Aerospace Engineering, Universidad Politécnica de Madrid (UPM).**

Key subjects: Mechanical design, flight mechanics, aerodynamics, fluid mechanics, thermodynamics, aerospace materials, structures, electronics, project management, aerospace propulsion.

Thesis: *Design of a Flight Control System Optimization Tool for Aerial Vehicles.*

Link: <https://fidelechevarria.github.io/BSc-Thesis.pdf>

## Languages

**Spanish** Fluent. Mother tongue.

**English** Fluent. CEFR Level C1 (2014).

**French** Basic skills. CEFR Level A2 (2007).

## Skills

**Experience fields.** Artificial intelligence, computer vision, numerical optimization, sensor fusion, automation and control, dynamic system simulation, data analysis, embedded software development, user interface design, graphical design, version control.

**Tools and technologies.** C/C++, Python, R, Fortran, MATLAB, Simulink, Tensorflow, Keras, OpenCV, Qt, Latex, MS Office, Git, SVN, Linux, Bash, CATIA, SketchUp.

## Projects

feb18-sep18 **Aircraft Trajectory Optimization.** Development of an analysis tool for estimation of optimal aircraft trajectories in air races. The tool is designed for use in Red Bull Air Race, and released as open-source software.

Link: <https://fidelechevarria.github.io/aircraft-trajectory-optimization>

## Publications

1. F. Echevarría Corrales, J. M. Pulido Fernández and M. A. de Frutos Carro, "Efficient visual navigation applied to unmanned aerial systems in GNSS-denied environments," presented at the 8th Annu. National R&D Security and Defence Conf. (DESEi+d), León, Spain, 2020.

## Additional Training

- 2018 **Python Courses**, *Packt Publishing*.
- 2017 **RPAS Pilot Certification**, *ATO 238*, Madrid.
- 2015 **Advanced CATIA V5 Certification**, *ETSIAE (UPM)*, Madrid.
- 2014 **MATLAB Course**, *ETSIAE (UPM)*, Madrid.