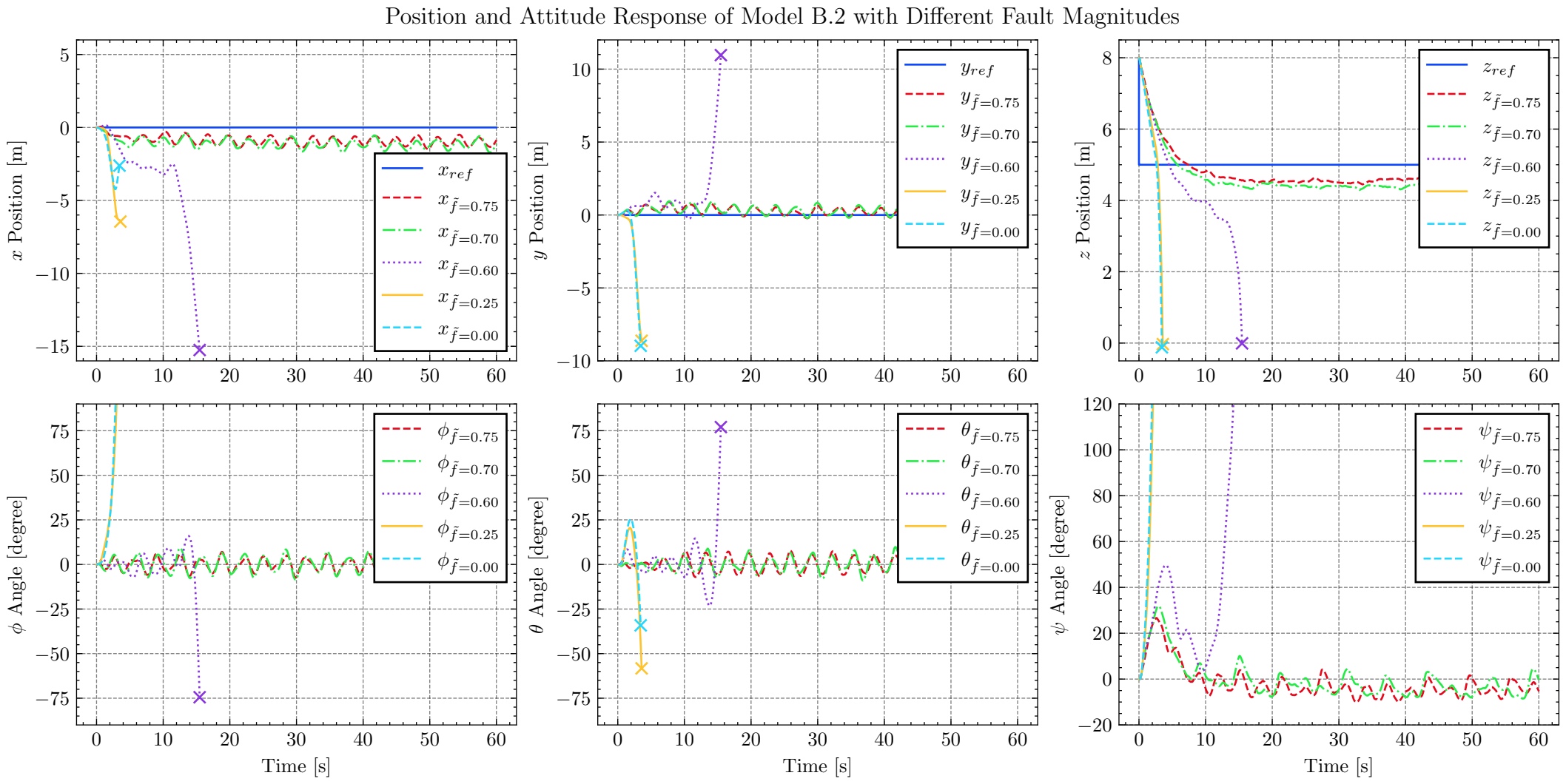
Position and Attitude Response of Model B.2 with Different Fault Magnitudes
x Position [m]
y Position [m]
z Position [m]
ϕ Angle [degree]
θ Angle [degree]
ψ Angle [degree]
Time [s]
Time [s]
Time [s]
x_{ref}
$x_{\tilde{f}=0.75}$
$x_{\tilde{f}=0.70}$
$x_{\tilde{f}=0.60}$
$x_{\tilde{f}=0.25}$
$x_{\tilde{f}=0.00}$
y_{ref}
$y_{\tilde{f}=0.75}$
$y_{\tilde{f}=0.70}$
$y_{\tilde{f}=0.60}$
$y_{\tilde{f}=0.25}$
$y_{\tilde{f}=0.00}$
z_{ref}
$z_{\tilde{f}=0.75}$
$z_{\tilde{f}=0.70}$
$z_{\tilde{f}=0.60}$
$z_{\tilde{f}=0.25}$
$z_{\tilde{f}=0.00}$
$\phi_{\tilde{f}=0.75}$
$\phi_{\tilde{f}=0.70}$
$\phi_{\tilde{f}=0.60}$
$\phi_{\tilde{f}=0.25}$
$\phi_{\tilde{f}=0.00}$
$\theta_{\tilde{f}=0.75}$
$\theta_{\tilde{f}=0.70}$
$\theta_{\tilde{f}=0.60}$
$\theta_{\tilde{f}=0.25}$
$\theta_{\tilde{f}=0.00}$
$\psi_{\tilde{f}=0.75}$
$\psi_{\tilde{f}=0.70}$
$\psi_{\tilde{f}=0.60}$
$\psi_{\tilde{f}=0.25}$
$\psi_{\tilde{f}=0.00}$