

ADS1256EVM Evaluation Module

This user's guide describes the characteristics, operation, and use of the ADS1256EVM. This EVM is an evaluation fixture for the ADS1256 24-bit delta-sigma ($\Delta\Sigma$) analog-to-digital converter (ADC). The ADS1256EVM is designed for prototyping and evaluation. It also serves as an evaluation platform for the ADS1255, which is a proper subset of the ADS1256. A complete circuit description, schematic diagram, and bill of materials are included. Throughout this document, the abbreviation *EVM* and the term *evaluation module* are synonymous with the ADS1256EVM.

The following related documents are available through the Texas Instruments web site at www.ti.com.

Device	Literature Number
ADS1256	SBAS288
REF1004	SBVS002
OPA335	SBOS245

Contents

1	ADS1256EVM Overview
2	Circuit Description
3	Usage
4	Schematic and Layout
	List of Figures
1	Connectors and Jumpers
2	Analog Connector Pinout
3	Serial Connector Pinout
4	GPIO Header Pinout
5	Power Connector Pinout
6	Jumper Block
7	Switches
8	ADS1256EVM Schematic
9	Top Side Layout
10	Bottom Side Layout
	List of Tables
1	Analog Connector Pin Descriptions
2	Serial Connector Pin Descriptions
3	GPIO Pin Descriptions
4	Power Connector Pin Descriptions
5	AIN0-1 Input Select Switch
6	AIN2-3 Input Select Switch
7	Reference Input Select Switch
8	System Clock Select Switch
9	ADS1256EVM Bill of Materials

All trademarks are the property of their respective owners.



1 ADS1256EVM Overview

The ADS1256EVM is an evaluation fixture for the ADS1256 24-bit delta-sigma ADC.

1.1 Introduction

Many data-converter evaluation fixtures contain a computer interface or a microcontroller, but the ADS1256EVM contains only the ADS1256 device and a few support components. All ADS1256 pins are accessible through various pins on the ADS1256EVM analog and digital connectors.

The ADS1256EVM is designed using a simple card format developed by TI. This simple, consistent design makes the ADS1256EVM very easy to connect to your own prototype system. You can even think of the ADS1256EVM as an alternate package for the ADS1256—one much larger than the device itself, but also much easier to wire up by hand on your test bench.

The ADS1256EVM can be plugged directly into suitable motherboards, such as the HPA449 MSP430 microcontroller development system from Soft-Baugh, Inc. (http://www.softbaugh.com/). See TI's web site for example code using the ADS1256EVM with the HPA449.

The ADS1256EVM, together with a motherboard and appropriate software, also forms a complete evaluation system for verifying the performance of the ADS1256; see the <u>ADS1256 product information</u> folder on the Texas Instruments web site for more information.

If you intend to use the ADS1255 in your application, use the ADS1256EVM for evaluation and test purposes. The ADS1255 is in a smaller package, and lacks inputs AIN2 through AIN7; otherwise, it is identical to the ADS1256.

1.2 Built-In Accessories

The ADS1256EVM includes a system clock crystal and a low-noise voltage reference. Both are optional; you can select an external system clock and an external reference using slide switches.

The +2.5V reference circuit is based on a REF1004-2.5 buffered by an OPA335 and filtered by a large tantalum electrolytic capacitor. While its noise performance is not sufficiently low to allow the ADS1256 to perform at its lowest noise level at all data rates, it can closely approach the limit, and is representative of the kind of reference circuit used in many applications.

1.3 Connectors

The ADS1256 device on the ADS1256EVM is connected through four headers: the analog connector, the serial connector, the power connector, and the GPIO header. Pinouts and locations for the connectors are given in the following section

The **analog connector** (J1) carries analog I/O. The ADS1256 has a nine-input multiplexer connected through pins 1 through 8 and 10. An optional external differential reference can be connected to pins 18 and 20.

The **serial connector** (J2) carries the ADS1256 serial digital interface, an optional external system clock signal, and an I2C connection to the onboard serial EEPROM.

The **power connector** (J3) carries the power supplies. The ADS1256EVM requires a +5V analog supply and a +1.8V to +3.3V digital supply. The board is designed using a single ground net connected to DGND. An AGND pin is also provided; it can be connected to DGND using jumper J4.

The GPIO header (J5) provides a connection to the four GPIO pins on the EVM.

The ADS1256 uses separate supplies for its analog and digital sections. A jumper is inserted in each supply line. These jumpers allow the current of each supply to be measured independently.



1.4 Controls

The ADS1256EVM is configured using five slide switches and a jumper.

Switches S1 and S2 select the input signal provided to the first four multiplexer inputs on the ADS1256. Normally you will use the external input, but you can also use the switches to short the inputs together and to connect the reference voltage to the inputs. Additionally, the latter two positions are useful for conducting noise and functional tests.

Switch S3 selects the reference input. One position selects the external reference input pins on the analog connector (J1). The other two positions connect the onboard +2.5V reference in one of two ways: between ground and the reference, or between the reference and the analog supply.

Switch S5 selects the system clock source for the ADS1256. You can select between the onboard 7.68MHz crystal or an external clock.

1.5 Setting Up

The ADS1256EVM is configured according to its use. Thus, there is no single correct procedure to configure the test fixture.

Nevertheless, it is useful to remember the following things when you are setting up the board:

- q If you are not measuring the ADS1256 supply current, remember to place shorting blocks in the appropriate positions on jumper block J4. Without these shorting blocks, the ADS1256 will not be powered on, and will not work properly.
- q Unless you are using two entirely separate power supplies for analog and digital, place a shorting block on the analog-digital ground jumper. This connects the analog and digital grounds together, which is the normal way to operate the ADS1256EVM.
- q Check the system clock switch. If it is set to *EXT* and you have not connected a clock signal to the external clock input pin on J2, the ADS1256 will not operate.
- q The RESET and SYNC/PDWN pins (J2 pins 14 and 19) do not have pull-up or pull-down resistors connected to them. For normal operation, tie these pins high. If they are left floating, the ADS1256 may not operate properly. See the ADS1256 data sheet for further information about these pins.



2 Circuit Description

This section describes the connectors, controls, and circuit design of the ADS1256EVM in detail.

2.1 I/O Connectors and Testpoints

The positions and functions of the connectors and testpoints are shown in Figure 1.

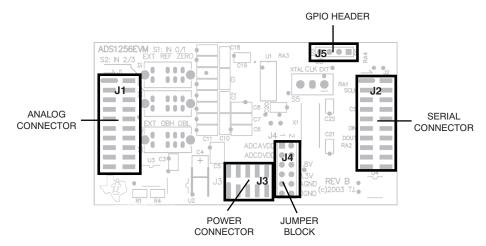


Figure 1. Connectors and Jumpers

Many of the pins on the connectors are not used. On the pinout diagrams, unused pins are not marked. In the pin description tables, unused pins are not listed, and ground pins are listed together, with the exception of the power connector.

J1, J2, and J3, although each treated as a single connector, are actually mounted as connector pairs in a pass-through configuration. Each pair has a surface-mount header on the top (component) side of the board, and a corresponding surface-mount socket on the bottom (solder) side of the board. The headers, mounted on top, are suffixed **A**; the sockets, mounted on bottom, are suffixed **B**.

In the schematic, the connector pairs are shown as one symbol. For J1, J2, and J3, all bottom-side pins are connected to the corresponding top-side pins; for example, J1B pin 1 connects to J1A pin 1, J1B pin 2 connects to J1A pin 2, etc. This convention holds true for every pin on connectors J1, J2, and J3.

In the following descriptions, the connector pairs will be referred to as a single connector.



2.1.1 J1: Analog Connector

The analog connector pinout is shown in Figure 2 and described in Table 1.

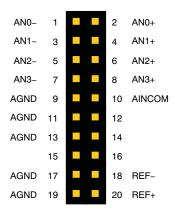


Figure 2. Analog Connector Pinout

CAUTION

Although certain pins are described as *negative*, never apply voltages less than -0.3V to these pins. The ADS1256 is not a bipolar-input device, and it cannot accept negative voltages below -0.3V without damaging the functional operation of the unit.

The negative input pins are so named because the voltage on such a pin is subtracted from a positive input pin during a reading.

Pin Number	Pin Name	Standard Name	Direction	Function
1	AIN0	AN0-	Input	Analog input 0 (switched by S1)
2	AIN1	AN0+	Input	Analog input 1 (switched by S1)
3	AIN2	AN1-	Input	Analog input 2 (switched by S2)
4	AIN3	AN1+	Input	Analog input 3 (switched by S2)
5	AIN4	AN2-	Input	Analog input 4
6	AIN5	AN2+	Input	Analog input 5
7	AIN6	AN3-	Input	Analog input 6
8	AIN7	AN3+	Input	Analog input 7
10	AINCOM	AN4+	Input	Analog input common
18	SYSREFN	REF-	Input	Inverting external reference input
20	SYSREFP	REF+	Input	Noninverting external reference input
9, 11, 13, 17, 19	GND	AGND	Power	Signal ground

Table 1. Analog Connector Pin Descriptions



2.1.2 J2: Serial Connector

The serial connector pinout diagram is shown in Figure 3 and described in Table 2.

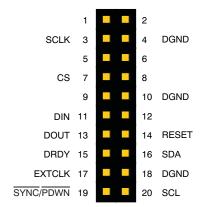


Figure 3. Serial Connector Pinout

Table 2. Serial Connector Pin Descriptions

Standard Name Direction Function

Pin Number	Pin Name	Standard Name	Direction	Function
3	SCLK	CLKX	Input	Serial clock input
7	CS	FSX	Input	Chip-select
11	DIN	DX	Input	Serial clock input
13	DOUT	DR	Output	Serial data output
14	RESET	GPIO4	Input	Reset input
15	DRDY	INT	Output	Data ready signal
16	SCL	SCL	I/O	I ² C clock line
17	EXTCLK	TOUT	Input	External system clock input
19	SYNC/PDWN	GPIO5	Input	Synchronization and power down control pin
20	SDA	SDA	I/O	I ² C data line
4, 10, 18	GND	DGND	Power	Signal ground

2.1.3 J5: GPIO Header

The ADS1256 has four general-purpose I/O (GPIO) pins. One of these pins can also be configured as a buffered system clock output. This output is typically used to clock additional ADS1255/ADS1256 devices, but can be used for other purposes.

Each pin is connected to the GPIO header through a 100Ω resistor. $100k\Omega$ pull-downs on each pin protect the GPIOs when they are configured as inputs, which is the default setting.



The GPIO header pinout diagram is shown in Figure 4 and described in Table 3.

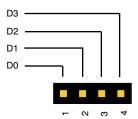


Figure 4. GPIO Header Pinout

Table 3. GPIO Pin Descriptions

Pin Number	Pin Name	Function
1	D0	GPIO or Buffered system clock output
2	D1	GPIO
3	D2	GPIO
4	D3	GPIO

2.1.4 J3: Power Connector

The power connector pinout diagram is shown in Figure 5 and described in Table 4.

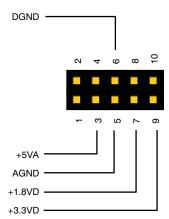


Figure 5. Power Connector Pinout

Table 4. Power Connector Pin Descriptions

Pin Number	Pin Name	Function	Use on ADS1256EVM
1	+VA	Positive Analog Supply, +5V to +18V	Not used
2	-VA	Negative Analog Supply, -5V to -18V	Not used
3	+5VA	Positive Analog Supply, +5V	Analog supply
4	-5VA	Negative Analog Supply, -5V	Not used
5	AGND	Analog Ground	Optional connection to DGND through J4
6	DGND	Digital Ground	Ground
7	+1.8VD	Positive Digital Supply, +1.8V	Digital supply; select using J4
8	VD1	Positive Digital Supply	Not used
9	+3.3VD	Positive Digital Supply, +3.3V	Digital supply; select using J4
10	+5VD	Positive Digital Supply, +5V	Not used



The ADS1256 uses an analog supply of +5V and a digital supply of +1.8V to +3.3V. Both +1.8V and +3.3V are available as standard supply voltages over the power connector, and the ADS1256EVM allows you to switch between them using J4.

2.2 Jumpers

There are six jumpers on the ADS1256EVM, arranged in a single jumper block. The pinout of this jumper block is shown in Figure 6.

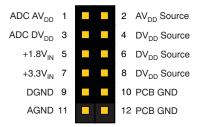


Figure 6. Jumper Block

2.2.1 J4 Pins 1–2: ADS1256 Analog Power Supply

This jumper can be used to measure the current of the ADS1256 analog power supply.

For normal operation, this jumper should be shorted.

2.2.2 J4 Pins 3-4: ADS1256 Digital Power Supply

This jumper can be used to measure the current of the ADS1256 digital power supply.

For normal operation, this jumper should be shorted. The voltage of the digital supply is chosen by the jumper on pins 5–6 (1.8V) or 7–8 (3.3V).

2.2.3 J4 Pins 5–6: Select 1.8V Digital Supply Voltage

These pins select 1.8V for the digital supply voltage.

2.2.4 J4 Pins 7–8: Select 3.3V Digital Supply Voltage

These pins select 3.3V for the digital supply voltage.

2.2.5 J4 Pins 9-10: DGND Select

Shorting this jumper connects the ADS1256EVM ground net to DGND.

2.2.6 J4 Pins 11-12: AGND Select

Shorting this jumper connects the ADS1256EVM ground net to AGND.



2.3 Switches

The positions and functions of the EVM switches are shown in Figure 7.

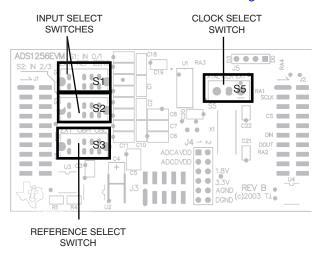


Figure 7. Switches

2.3.1 S1: AIN0-1 Input Select

These switches control which lines are routed to the ADS1256 AIN0–AIN1 inputs. The positions of the switches are described in Table 5.

		-		
Board Marking	Switch Position	Input Source	AIN0 Connection	AIN1 Connection
EXT	Left	External (J1, pins 1 and 2)	J1 pin 2	J1 pin 1
REF	Middle	Reference voltage	+2.5V	Ground
ZERO	Right	Zero (shorted to reference)	+2.5V	+2.5V

Table 5. AIN0-1 Input Select Switch

In the EXT position, J1 pins 1 and 2 are connected to the ADS1256 AIN1 and AIN0 pins, respectively.

In the REF position, the reference is connected across the ADS1256 AIN0 and AIN1 pins.

In the ZERO position, both AIN0 and AIN1 are connected to the reference. This gives a zero-scale reading across AIN0 and AIN1.

The REF and ZERO positions are useful for noise tests.



2.3.2 S2: AIN2-3 Input Select

These switches control which lines are routed to the ADS1256 AIN2 through AIN3 inputs. The positions of the switches are described in Table 6.

Board Switch Input AIN2 **Position** Source Connection Connection Marking J1 pin 3 **EXT** Left External J1 pin 4 (J1, pins 3 and 4) **REF** Middle Reference +2.5V Ground voltage **ZERO** Right Zero +2.5V +2.5V (shorted to reference)

Table 6. AIN2-3 Input Select Switch

In the EXT position, J1 pins 3 and 4 are connected to the ADS1256 AIN3 and AIN2 pins, respectively.

In the REF position, the reference is connected across the ADS1256 AIN2 and AIN3 pins.

In the ZERO position, both AIN2 and AIN3 are connected to the reference. This gives a zero-scale reading across AIN2 and AIN3.

The REF and ZERO positions are useful for noise tests.

2.3.3 S3: Reference Input Select

This switch controls which signals are connected to the differential reference input on the ADS1256. The positions of the switch are described in Table 7.

Board Marking	Switch Position	Input Source	VRP Connection	VRN Connection
EXT	Left	External (J1, pins 18 and 20)	J1 pin 20	J1 pin 18
ОВН	Middle	Onboard, high common- mode	+AVDD	+2.5V
OBL	Right	Onboard, low common- mode	+2.5V	AGND

Table 7. Reference Input Select Switch

In the EXT position, J1 pins 18 and 20 are connected to the ADS1256 reference input.

In the OBH position, the analog power supply is connected to the positive reference input, and the negative reference input is connected to the output of the onboard reference.

In the OBL position, the onboard reference output is connected to the ADS1256 positive reference input pin, and the negative reference input pin is grounded.

Both OBH and OBL provide a +2.5V reference to the ADS1256. The OBL position corresponds to the usual way to connect a reference to the ADS1256, and should be used for most measurements. The OBH position is useful for testing the reference input common-mode sensitivity, which can be important for ratiometric connections.



2.3.4 S5: System Clock Select

This switch selects which of the two available clock sources on the ADS1256EVM will be provided to the ADS1256. The positions of the switch are described in Table 8.

Table 8. System Clock Select Switch

Board Marking	Switch Position	Digital Power Supply Source
XTAL	Left	Onboard 7.68MHz Crystal
EXT	Right	External (J2 pin 17)

3 Usage

This section provides guidelines on using the ADS1256EVM and connecting other systems to it.

3.1 Input Filtering Capacitors

The ADS1256EVM has pads for filtering capacitors on every input pair and for the reference input. Each input pair has pads for two common-mode capacitors and one differential capacitor.

The ADS1256 has a flexible input multiplexer, so these capacitors do not always function as common-mode and differential signal filters. For example, when measuring a single-ended input, the common-mode capacitors act to filter the signal.

The ADS1256EVM is shipped with only a few of the capacitor pads populated. This allows the board to be immediately used to measure both differential and single-ended inputs. As shipped, inputs AIN0 through AIN7 have 100pF differential mode capacitors installed. A differential 1μ F capacitor is connected to the reference near the reference pins.

The input filtering capacitors are in relatively large 1210-size packages, in contrast to most of the other passives on the board. These capacitors were designed to be large so that you can easily remove them or replace them with other values. By exercising appropriate care, you can even solder leaded devices to these large pads.

3.2 Serial Interface

The ADS1256 serial interface is connected through 100Ω resistors to the ADS1256EVM serial connector. The resistors help terminate the lines and slow down fast edges that can couple into the part and reduce performance.

The way you connect the ADS1256EVM in a prototype situation will normally be the same as the way you connect it in your final product. See the <u>product datasheet</u> for information on the serial interface of the ADS1256.

3.3 Serial EEPROM

The serial EEPROM is a Microchip 24LC256 32kB type. You can use it for anything you like; the chip is not programmed during manufacturing. Some possible uses include calibration data or board ID information.

Information on communicating with the EEPROM is available from Microchip Technology, Inc.



3.4 Single-Ended vs Differential Signals

The ADS1256 is a differential-input ADC with a flexible multiplexer. The ADS1256 has nine input pins. Without restriction, any of them can be the converter's positive input, and any can function as the converter's negative input. This flexibility allows the ADS1256 to measure any combination of differential and single-ended signals.

Since the ADS1256 is a differential-input converter and always records its inputs in a bipolar range, the proper way to measure single-ended signals may not be obvious. Here is one method for measuring a 0V to 5V single-ended signal:

- 1. Connect the signal to one of the ADS1256 input pins.
- 2. Connect the reference to another of the ADS1256 input pins. The ninth input, AINCOM, is provided for this purpose, but any other input can be used.
- 3. Set the ADS1256 device gain to 2.
- 4. Measure between the first input pin and the second input pin. The result will vary from negative full-scale to positive full-scale.

The ADS1256EVM is preconfigured to accept differential signals on input pairs AIN0/1 and AIN2/3; 100pF common-mode filtering capacitors are provided on these channels.

On the ADS1256EVM, the onboard reference is not accessible externally. To connect the reference to an input pin, switch either SW1 or SW2 to the REF position. This connects the reference to AINO and AIN2 respectively. You can then measure a single-ended signal on inputs AIN4 to AIN7 or AINCOM as described earlier. (Since AIN1 and AIN3 are grounded in the REF position, these cannot be used as signal inputs.)

3.5 Notes on Optimizing Performance

In our tests, we found that the ADS1256EVM alone—that is, using the onboard reference circuit—is capable of closely approaching, though not matching, the highest possible performance of the ADS1256. This section describes the issues that limit EVM performance, and suggests several ways to increase its performance.

The ADS1256 is unusual among high-resolution delta-sigma ADCs because of the wide range of data rates it offers. A single register setting changes it from a very low-speed, low-noise converter to a relatively high-speed converter. These uses have different circuit requirements.

When low noise is the primary goal, the ADS1256 can be operated in a very low data-rate mode—nominally 2.5 samples per second. The low noise observed in this mode results from the modulator design, the chopper front-end, and averaging together a large number of samples. In this mode, much of the noise is averaged out of the data, and issues such as reference noise become less important. The primary concern at low data rates is then drift and 1/f noise. The onboard reference, based on a REF1004, has a maximum temperature drift of 20ppm/°C. In many applications, this drift will adversely affect performance, and an external low-drift reference should be used.

At higher data rates, higher-frequency noise sources are no longer averaged out and begin to be troublesome. These noise sources include the noise inherent in the ADS1256 device itself, which is not reducible, and the reference noise, which may be reduced. Lowering the reference noise is easily done by filtering with large capacitors (as on the ADS1256EVM reference), but this offers diminishing returns, as the ESR of the capacitor limits its effectiveness as a low-pass filter. Beginning with an inherently low-noise reference circuit can be of great benefit here.

Note that large capacitors have increased turn-on settling time, which may be detrimental in some applications. Note also that higher data rate applications are often less affected by drift and 1/f noise. (1)

The ADS1256 is a highly precise converter. Its measurement performance can be degraded by a large number of factors. For example, on the HPA449 mini-EVM motherboard, we noted wide variation in ENOB at certain data rates, sometimes depending on the particular computer that is connected to the fixture. A lower-than-expected ENOB is typically not a fault in the EVM construction, but in numerous possible external factors.

⁽¹⁾ An early test board for the ADS1256 employed a 10-farad ultracapacitor to filter the reference noise. Although it filtered the noise very thoroughly, it took over three days following power-up for this capacitor to settle to the proper voltage.



4 Schematic and Layout

This section contains the complete bill of materials, schematic diagram, and printed circuit board (PCB) layout for the ADS1256EVM.

Note:

Board layouts are not to scale. These are intended to show how the board is laid out; they are not intended to be used for manufacturing ADS1256EVM PCBs.

4.1 Schematic

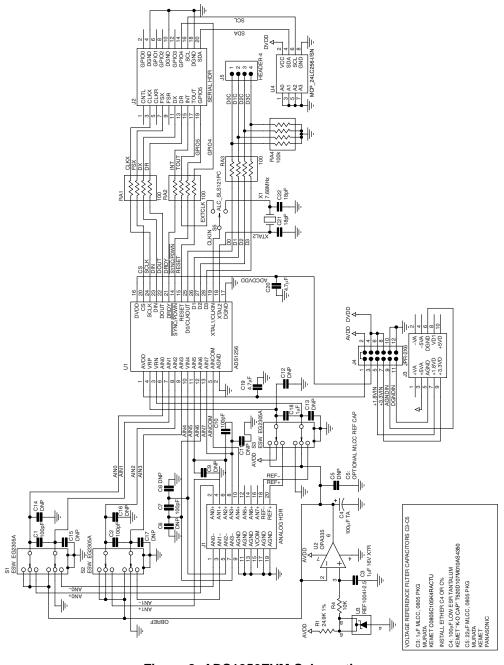


Figure 8. ADS1256EVM Schematic



4.2 Printed Circuit Board Layout

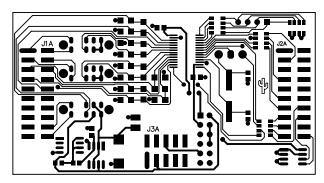


Figure 9. Top Side Layout

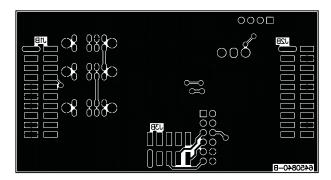


Figure 10. Bottom Side Layout



4.3 Bill of Materials

Table 9. ADS1256EVM Bill of Materials

Reference Designator	Description	Vendor	Part Number
R4	1/10W 5% 10kΩ chip resistor	Panasonic	ERJ-3GEYJ103V
R1	1/16W 1% 24.9kΩ chip resistor	Panasonic	ERJ-3EKF2492V
RA1, RA2, RA3	100Ω 4-position resistor array	CTS	744C083101JTR
RA4	100kΩ 4-position resistor array	CTS	744C083104JTR
C21, C22	18pF ceramic chip capacitor, ±5%, NPO, 0603, 50V	Panasonic	ECJ-1VC1H180J
C3	1μF ceramic chip capacitor, ±10%, X7R, 0603, 16V	Kemet	C0805C105K4RACTU
C18	1μF ceramic chip capacitor, ±10%, X7R, 1206, 25V	TDK	C3216X7R1C105K/0.85
C19, C20	4.7μF ceramic chip capacitor, ±20%, X5R, 0805, 6.3V	TDK	C2012X5R0J475K
C4	100μF tantalum electrolytic capacitor, low ESR type, ±20%, 10V	Kemet	T520D107M010ASE055
C1, C2, C7, C10	100pF ceramic chip capacitor, ±5%, NP, 1206, 50V	Kemet	C1206C101J5GACTU
C5, C6, C8, C9, C11–C17	Not installed	_	-
D1, D2	30V 1.5A Schottky barrier diode	Panasonic	MA2Q70500L
X1	Crystal, 7.68MHz	Citizen	HCM49-7.680MABJT
U1	Analog-to-digital converter	Texas Instruments	ADS1256IDB
U2	Operational amplifier	Texas Instruments	OPA335UA
U3	Voltage reference, 2.5V	Texas Instruments	REF1004I-2.5
U4	EEPROM, I ² C, 256K bits	Microchip	24LC256-I/SN
J1A, J2A	SMT header, 20-pin, dual-row	Samtec	TSM-110-01-L-DV-P
J1B, J2B	SMT socket, 20-pin, dual-row	Samtec	SSW-110-22-F-D-VS-K
J3A	SMT header, 10-pin, dual-row	Samtec	TSM-105-01-L-DV-P
J3B	SMT socket, 10-pin, dual-row	Samtec	SSW-105-22-F-D-VS-K
J5	Header, 4-pin	Samtec	TSW-104-07-L-S
J4	Header, 10-pin, dual-row	Samtec	TSM-105-07-L-S
S5	SPDT slide switch	Tyco-Alcoswitch	SLS121PC
S1, S2, S3	DP3T slide switch	E-Switch	EG2305A

FCC Warning

This evaluation board/kit is intended for use for **ENGINEERING DEVELOPMENT**, **DEMONSTRATION**, **OR EVALUATION PURPOSES ONLY** and is not considered by TI to be a finished end-product fit for general consumer use. It generates, uses, and can radiate radio frequency energy and has not been tested for compliance with the limits of computing devices pursuant to part 15 of FCC rules, which are designed to provide reasonable protection against radio frequency interference. Operation of this equipment in other environments may cause interference with radio communications, in which case the user at his own expense will be required to take whatever measures may be required to correct this interference.

EVALUATION BOARD/KIT IMPORTANT NOTICE

Texas Instruments (TI) provides the enclosed product(s) under the following conditions:

This evaluation board/kit is intended for use for **ENGINEERING DEVELOPMENT**, **DEMONSTRATION**, **OR EVALUATION PURPOSES ONLY** and is not considered by TI to be a finished end-product fit for general consumer use. Persons handling the product(s) must have electronics training and observe good engineering practice standards. As such, the goods being provided are not intended to be complete in terms of required design-, marketing-, and/or manufacturing-related protective considerations, including product safety and environmental measures typically found in end products that incorporate such semiconductor components or circuit boards. This evaluation board/kit does not fall within the scope of the European Union directives regarding electromagnetic compatibility, restricted substances (RoHS), recycling (WEEE), FCC, CE or UL, and therefore may not meet the technical requirements of these directives or other related directives.

Should this evaluation board/kit not meet the specifications indicated in the User's Guide, the board/kit may be returned within 30 days from the date of delivery for a full refund. THE FOREGOING WARRANTY IS THE EXCLUSIVE WARRANTY MADE BY SELLER TO BUYER AND IS IN LIEU OF ALL OTHER WARRANTIES, EXPRESSED, IMPLIED, OR STATUTORY, INCLUDING ANY WARRANTY OF MERCHANTABILITY OR FITNESS FOR ANY PARTICULAR PURPOSE.

The user assumes all responsibility and liability for proper and safe handling of the goods. Further, the user indemnifies TI from all claims arising from the handling or use of the goods. Due to the open construction of the product, it is the user's responsibility to take any and all appropriate precautions with regard to electrostatic discharge.

EXCEPT TO THE EXTENT OF THE INDEMNITY SET FORTH ABOVE, NEITHER PARTY SHALL BE LIABLE TO THE OTHER FOR ANY INDIRECT, SPECIAL, INCIDENTAL, OR CONSEQUENTIAL DAMAGES.

TI currently deals with a variety of customers for products, and therefore our arrangement with the user is not exclusive.

TI assumes no liability for applications assistance, customer product design, software performance, or infringement of patents or services described herein.

Please read the User's Guide and, specifically, the Warnings and Restrictions notice in the User's Guide prior to handling the product. This notice contains important safety information about temperatures and voltages. For additional information on TI's environmental and/or safety programs, please contact the TI application engineer or visit www.ti.com/esh.

No license is granted under any patent right or other intellectual property right of TI covering or relating to any machine, process, or combination in which such TI products or services might be or are used.

EVM WARNINGS AND RESTRICTIONS

It is important to operate this EVM within the analog input voltage range of 0V to 5V and the output voltage range of 0V to DV_{DD}.

Exceeding the specified input range may cause unexpected operation and/or irreversible damage to the EVM. If there are questions concerning the input range, please contact a TI field representative prior to connecting the input power.

Applying loads outside of the specified output range may result in unintended operation and/or possible permanent damage to the EVM. Please consult the EVM User's Guide prior to connecting any load to the EVM output. If there is uncertainty as to the load specification, please contact a TI field representative.

During normal operation, some circuit components may have case temperatures greater than 60°C. The EVM is designed to operate properly with certain components above 60°C as long as the input and output ranges are maintained. These components include but are not limited to linear regulators, switching transistors, pass transistors, and current sense resistors. These types of devices can be identified using the EVM schematic located in the EVM User's Guide. When placing measurement probes near these devices during operation, please be aware that these devices may be very warm to the touch.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2006, Texas Instruments Incorporated

IMPORTANT NOTICE

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, modifications, enhancements, improvements, and other changes to its products and services at any time and to discontinue any product or service without notice. Customers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All products are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its hardware products to the specifications applicable at the time of sale in accordance with TI's standard warranty. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by government requirements, testing of all parameters of each product is not necessarily performed.

TI assumes no liability for applications assistance or customer product design. Customers are responsible for their products and applications using TI components. To minimize the risks associated with customer products and applications, customers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any TI patent right, copyright, mask work right, or other TI intellectual property right relating to any combination, machine, or process in which TI products or services are used. Information published by TI regarding third-party products or services does not constitute a license from TI to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. Reproduction of this information with alteration is an unfair and deceptive business practice. TI is not responsible or liable for such altered documentation.

Resale of TI products or services with statements different from or beyond the parameters stated by TI for that product or service voids all express and any implied warranties for the associated TI product or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

TI products are not authorized for use in safety-critical applications (such as life support) where a failure of the TI product would reasonably be expected to cause severe personal injury or death, unless officers of the parties have executed an agreement specifically governing such use. Buyers represent that they have all necessary expertise in the safety and regulatory ramifications of their applications, and acknowledge and agree that they are solely responsible for all legal, regulatory and safety-related requirements concerning their products and any use of TI products in such safety-critical applications, notwithstanding any applications-related information or support that may be provided by TI. Further, Buyers must fully indemnify TI and its representatives against any damages arising out of the use of TI products in such safety-critical applications.

TI products are neither designed nor intended for use in military/aerospace applications or environments unless the TI products are specifically designated by TI as military-grade or "enhanced plastic." Only products designated by TI as military-grade meet military specifications. Buyers acknowledge and agree that any such use of TI products which TI has not designated as military-grade is solely at the Buyer's risk, and that they are solely responsible for compliance with all legal and regulatory requirements in connection with such use.

TI products are neither designed nor intended for use in automotive applications or environments unless the specific TI products are designated by TI as compliant with ISO/TS 16949 requirements. Buyers acknowledge and agree that, if they use any non-designated products in automotive applications, TI will not be responsible for any failure to meet such requirements.

Following are URLs where you can obtain information on other Texas Instruments products and application solutions:

Products		Applications	
Amplifiers	amplifier.ti.com	Audio	www.ti.com/audio
Data Converters	dataconverter.ti.com	Automotive	www.ti.com/automotive
DSP	dsp.ti.com	Broadband	www.ti.com/broadband
Interface	interface.ti.com	Digital Control	www.ti.com/digitalcontrol
Logic	logic.ti.com	Military	www.ti.com/military
Power Mgmt	power.ti.com	Optical Networking	www.ti.com/opticalnetwork
Microcontrollers	microcontroller.ti.com	Security	www.ti.com/security
RFID	www.ti-rfid.com	Telephony	www.ti.com/telephony
Low Power Wireless	www.ti.com/lpw	Video & Imaging	www.ti.com/video
		Wireless	www.ti.com/wireless

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2007, Texas Instruments Incorporated