view\_frames Result Recorded at time: 1597341213.018 base\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10.204 Hz Most recent transform: 0.000 ( 1597341213.018 sec old) Most recent transform: 1597341212.976 (0.042 sec old) Buffer length: 0.000 sec Buffer length: 4.900 sec shoulder\_link base Broadcaster: /robot\_state\_publisher Average rate: 10.204 Hz Most recent transform: 1597341212.976 ( 0.042 sec old) Buffer length: 4.900 sec upper\_arm\_link Broadcaster: /robot\_state\_publisher Average rate: 10.204 Hz Most recent transform: 1597341212.976 (0.042 sec old) Buffer length: 4.900 sec forearm\_link Broadcaster: /robot\_state\_publisher Average rate: 10.204 Hz Most recent transform: 1597341212.976 ( 0.042 sec old) Buffer length: 4.900 sec wrist\_1\_link Broadcaster: /robot\_state\_publisher Average rate: 10.204 Hz Most recent transform: 1597341212.976 ( 0.042 sec old) Buffer length: 4.900 sec wrist\_2\_link Broadcaster: /robot\_state\_publisher Average rate: 10.204 Hz Most recent transform: 1597341212.976 ( 0.042 sec old) Buffer length: 4.900 sec wrist\_3\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1597341213.018 sec old) Most recent transform: 0.000 ( 1597341213.018 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec tool0 ee\_link Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1597341213.018 sec old) Buffer length: 0.000 sec connector\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1597341213.018 sec old) Most recent transform: 0.000 ( 1597341213.018 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec d435\_link gripper Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1597341213.018 sec old) Most recent transform: 0.000 ( 1597341213.018 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec dumb\_link intel\_cam\_bottom\_screw\_frame Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1597341213.018 sec old) Most recent transform: 0.000 ( 1597341213.018 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec dumb\_link\_2 intel\_cam\_link