Database Management Systems

Lecture 12

Distributed Databases

Researchers(RID: integer, Name: string, ImpactF: integer, Age: real)
AuthorContribution(RID: integer, PID: integer, Year: integer, Coord: string)

- Researchers
 - 1 tuple 50 bytes
 - 1 page 80 tuples
 - 500 pages
- AuthorContribution
 - 1 tuple 40 bytes
 - 1 page 100 tuples
 - 1000 pages

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- * join queries in a distributed DBMS
 - Researchers R New York, AuthorContribution A Lisbon, R join A
- * fetch as needed
- index nested loops join in New York
 - AuthorContribution unclustered hash index on RID
 - 100,000 AuthorContribution tuples, 40,000 Researchers tuples
 - on average, a researcher has 2.5 corresponding tuples in AuthorContribution
 - for each Researchers tuple, retrieve the 2.5 corresponding tuples in AuthorContribution:
 - obtain the index page: 1.2 t_d (on average)

read the matching records in AuthorContribution: 2.5 t_d

- * join queries in a distributed DBMS
 - Researchers R New York, AuthorContribution A Lisbon, R join A

* fetch as needed

- index nested loops join in New York
 - for each Researchers tuple, retrieve the 2.5 corresponding tuples in AuthorContribution:
 - => cost per Researchers tuple: (1.2 + 2.5)t_d
 - the pages containing these 2.5 tuples must also be shipped from Lisbon to New York
 - => total cost: $500t_d + 40.000(3.7t_d + 2.5t_s)$ (there are 40.000 records in Researchers)

- * join queries in a distributed DBMS
 - Researchers R New York, AuthorContribution A Lisbon, R join A

* ship to one site

- ship Researchers to Lisbon, compute the join at Lisbon
 - scan Researchers, ship it to Lisbon, save Researchers at Lisbon:
 - cost: $500(2t_d + t_s)$
 - compute Researchers join AuthorContribution at Lisbon
 - example: use improved version of Sort-Merge Join
 - combine the merging phase of sorting with the merging phase of the join => SMJ cost: 3(number of R pages + number of A pages)SMJ cost: $3(500 + 1000) = 4500t_d$
 - $=> total cost: 500(2t_d+t_s) + 4500t_d$

- * join queries in a distributed DBMS
 - Researchers R New York, AuthorContribution A Lisbon, R join A
- * ship to one site
- ship Researchers to Lisbon, compute the join at Lisbon
 - total cost: 500(2 t_d + t_s) + 4500 t_d
- ship AuthorContribution to New York, compute the join at New York
 - total cost: $1000(2t_d + t_s) + 4500t_d$

- * join queries in a distributed DBMS
 - Researchers R New York, AuthorContribution A Lisbon, R join A

* semijoin

- at New York:
 - project Researchers onto the join columns (RID)
 - ship the projection to Lisbon
- at Lisbon:
 - join the Researchers projection with AuthorContribution
 - => the so-called reduction of AuthorContribution with respect to Researchers
 - ship the reduction of AuthorContribution to New York
- at New York:
 - join Researchers with the reduction of AuthorContribution

- * join queries in a distributed DBMS
 - Researchers R New York, AuthorContribution A Lisbon, R join A

* semijoin

- tradeoff:
 - the cost of computing and shipping the projection
 - the cost of computing and shipping the reduction versus
 - the cost of shipping the entire AuthorContribution relation
- very useful if there is a selection on one of the relations

- * join queries in a distributed DBMS
 - Researchers R New York, AuthorContribution A Lisbon, R join A

* bloomjoin

- at New York:
 - compute a bit-vector of some size k
 - hash Researchers tuples (using the join column RID) into the range 0 to k-1
 - if some tuple hashes to *i*, set bit *i* to 1 (i from 0 to k-1)
 - otherwise (no tuple hashes to i), set bit i to 0
 - ship the bit-vector to Lisbon
- at Lisbon:
 - hash each AuthorContribution tuple (using the join column RID) into the range 0 to k-1, with the same hash function

- * join queries in a distributed DBMS
 - Researchers R New York, AuthorContribution A Lisbon, R join A

* bloomjoin

- at Lisbon:
 - discard tuples with a hash value *i* that corresponds to a 0 bit in the Researchers bit-vector
 - => reduction of AuthorContribution with respect to Researchers
 - ship the reduction to New York
- at New York:
 - join Researchers with the reduction

- keeping track of data distribution across sites
- one should be able to identify each replica of each fragment for a relation that is fragmented and replicated
- local autonomy should not be compromised
 - solution names containing several fields:
 - global relation name:
 - <local-name, birth-site>
 - global replica name:
 - <local-name, birth-site, replica_id>

- centralized system catalog
 - stored at a single site
 - contains data about all the relations, fragments, replicas
 - vulnerable to single-site failures
 - can overload the server

- global system catalog maintained at each site
 - every copy of the catalog describes all the data
 - not vulnerable to single-site failures (the data can be obtained from a different site)
 - local autonomy is compromised:
 - changes to a local catalog must be propagated to all the other sites

- local catalog maintained at each site
 - each site keeps a catalog that describes local data, i.e., copies of data stored at the site
 - the catalog at the birth-site for a relation keeps track of all the fragments / replicas of the relation
 - create a new replica / move a replica to another site:
 - must update the catalog at the birth-site
 - not vulnerable to single-site failures & doesn't compromise local autonomy

- a transaction submitted at a site S could ask for data stored at several other sites
- subtransaction the activity of a transaction at a given site
- context: Strict 2PL with deadlock detection
- problems:
 - distributed concurrency control
 - lock management when objects are stored across several sites
 - deadlock detection
 - distributed recovery
 - transaction atomicity
 - all the effects of a committed transaction (across all the sites it executes at) are permanent
 - none of the actions of an aborted transaction are allowed to persist

- distributed concurrency control
 - lock management
 - techniques synchronous / asynchronous replication
 - which objects will be locked
 - concurrency control protocols
 - when are locks acquired / released
 - lock management
 - centralized
 - primary copy
 - fully distributed

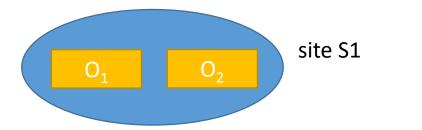
- distributed concurrency control
 - lock management
 - centralized:
 - one site does all the locking for all the objects
 - vulnerable to single-site failures
 - primary copy:
 - object O, primary copy PC of O stored at site S with lock manager
 - all requests to lock / unlock some copy of O are handled by L
 - not vulnerable to single-site failures
 - read some copy C of O stored at site S2:
 - => communicate with both S and S2

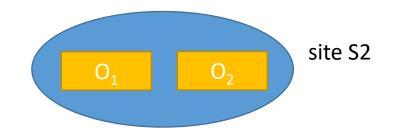
- distributed concurrency control
 - lock management
 - fully distributed:
 - object O, some copy C of O stored at site S with Lock Manager L
 - requests to lock / unlock C are handled by L (the site where the copy is stored)
 - one doesn't need to access 2 sites when reading some copy of

- distributed concurrency control
 - detect and resolve <u>deadlocks</u>
 - each site maintains a local waits-for graph
 - a cycle in such a graph indicates a deadlock
 - but a global deadlock can exist even if none of the local graphs contains a cycle

->

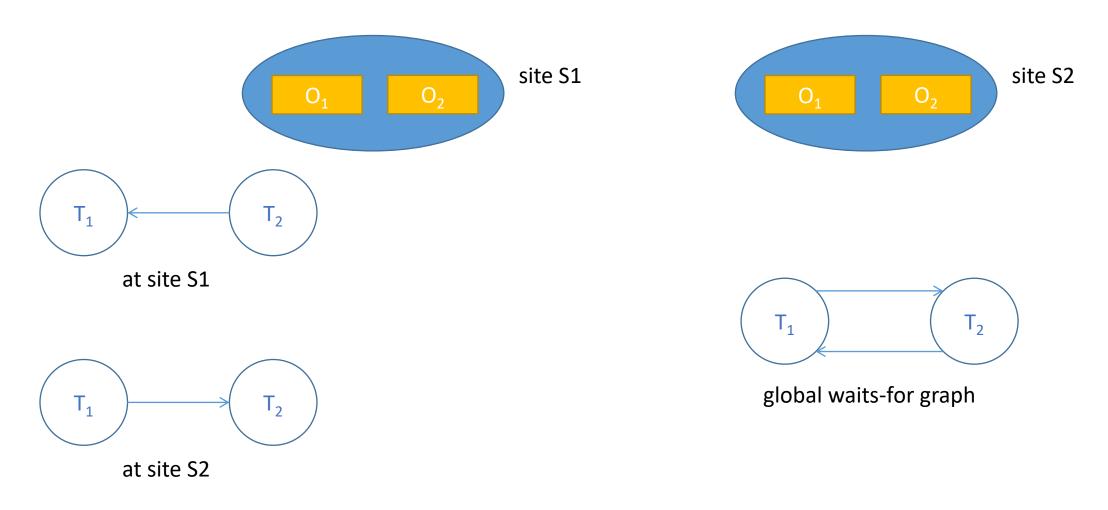
- distributed concurrency control distributed <u>deadlock</u>
 - e.g., using read-any write-all





- T₁ wants to read O₁ and write O₂
- T₂ wants to read O₂ and write O₁
- T₁ acquires a S lock on O₁ and an X lock on O₂ at site S1
- T₂ obtains a S lock on O₂ and an X lock on O₁ at site S2
- T₁ asks for an X lock on O₂ at site S2
- T₂ asks for an X lock on O₁ at site S1

- distributed concurrency control distributed <u>deadlock</u>
 - e.g., using read-any write-all



- distributed concurrency control distributed deadlock
 - distributed <u>deadlock detection algorithms</u>
 - centralized
 - hierarchical
 - based on a timeout mechanism

- distributed concurrency control distributed deadlock
 - distributed <u>deadlock detection algorithms</u>
 - centralized:
 - all the local waits-for graphs are periodically sent to a single site S
 - S responsible for global deadlock detection
 - the global waits-for graph is generated at site S
 - nodes
 - the union of the nodes in the local graphs
 - edges
 - there is an edge from node N1 to node N2 if such an edge exists in one of the local graphs

- distributed concurrency control distributed deadlock
 - distributed <u>deadlock detection algorithms</u>
 - hierarchical:
 - sites are organized into a hierarchy, e.g., grouped by city, county, country, etc
 - each site periodically sends its local waits-for graph to its parent site
 - assumption: more deadlocks are likely across related sites
 - all the deadlocks are detected in the end

- distributed concurrency control distributed deadlock
 - distributed <u>deadlock detection algorithms</u>
 - hierarchical:
 - example:

```
RO (CJ (Cluj-Napoca, Dej, Turda), BN (Bistrita, Beclean))
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Cluj-Napoca: T1 -> T2

Dej: T2 -> T3

Turda: T3 -> T4 <- T7

Bistrita: T5 -> T6

Beclean: T4 -> T7 -> T6 -> T5

CJ: T1 -> T2 -> T3 -> T4 <- T7

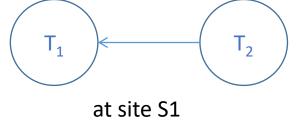
BN: T5 <-> T6 <- T7 <- T4 (*)

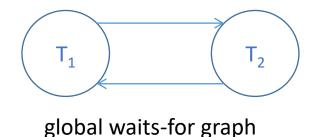
RO: T1 -> T2 -> T3 -> T4 <-> T7 -> T6 <-> T5

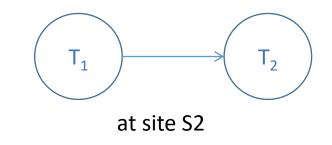
Obs RO: T5 or T6 has been aborted at (*)

- distributed concurrency control distributed deadlock
 - distributed <u>deadlock detection algorithms</u>
 - based on a timeout mechanism:
 - a transaction is aborted if it lasts longer than a specified interval
 - can lead to unnecessary restarts
 - however, the deadlock detection overhead is low
 - could be the only available option in a heterogeneous system (if the participating sites cannot cooperate, i.e., they cannot share their local waits-for graphs)

- distributed concurrency control distributed deadlock
- phantom deadlocks
 - "deadlocks" that don't exist, but are detected due to delays in propagating local information
 - lead to unnecessary aborts
 - example:







- generate local waits-for graphs, send them to the site responsible for global deadlock detection
- T2 aborts (not because of the deadlock) => local waits-for graphs are changed, there is no cycle in the "real" global waits-for graph
- but the built waits-for graph does have a cycle, T1 could be chosen as
 a victim

- distributed recovery
 - more complex than in a centralized DBMS
 - new types of failure
 - network failure
 - site failure
 - commit protocol
 - either all the subtransactions of a transaction commit, or none of them does
 - normal execution
 - ensure all the necessary information is provided to recover from failures
 - a log is maintained at each site; it contains:
 - data logged in a centralized DBMS
 - actions carried out as part of the commit protocol

- distributed recovery
 - transaction T
 - coordinator
 - the Transaction Manager at the site where T originated
 - subordinates
 - the Transaction Managers at the sites where T's subtransactions execute

- distributed recovery
 - two-phase commit protocol (2PC)
 - exchanged messages + records written in the log
 - 2 rounds of messages, both initiated by the coordinator
 - voting phase
 - termination phase
 - any Transaction Manager can abort a transaction
 - however, for a transaction to commit, all Transaction Managers must decide to commit

- distributed recovery
 - two-phase commit protocol
 - the user decides to commit transaction T
 - => the commit command is sent to T's coordinator, initiating 2PC
 - 1. the coordinator sends a *prepare* message to each subordinate
 - 2. upon receiving a *prepare* message, a subordinate decides whether to commit / abort its subtransaction
 - the subordinate force-writes an abort or a prepare* log record
 - then it sends a *no* or *yes* message to the coordinator

* prepare log records are specific to the commit protocol, they are not used in centralized DBMSs

- distributed recovery
 - two-phase commit protocol3.
 - if the coordinator receives *yes* messages from all subordinates:
 - it force-writes a *commit* log record
 - it then sends commit messages to all subordinates
 - otherwise (i.e., if it receives at least one no message or if it doesn't receive any message from a subordinate for a predetermined timeout interval)
 - if force-writes an abort log record
 - it then sends an *abort* message to each subordinate

- distributed recovery
 - two-phase commit protocol4.
 - upon receiving an abort message, a subordinate:
 - force-writes an abort log record
 - sends an ack message to the coordinator
 - aborts the subtransaction
 - upon receiving a commit message, a subordinate:
 - force-writes a commit log record
 - sends an ack message to the coordinator
 - commits the subtransaction

- distributed recovery
 - two-phase commit protocol
 - 5. after it receives *ack* messages from all subordinates, the coordinator writes an *end* log record for the transaction
 - sending a message the sender has made a decision
 - the message is sent only after the corresponding log record has been forced to stable storage (to ensure the corresponding decision can survive a crash)
 - T is a committed transaction if the commit log record of T's coordinator has been forced to stable storage

- distributed recovery
 - two-phase commit protocol
 - log records for the commit protocol
 - record type
 - transaction id
 - coordinator's identity
 - the commit / abort log record for the coordinator also contains the identities of the subordinates

- distributed recovery
 - restart after a failure site S comes back up after a crash
 - if there is a *commit* or an *abort* log record for transaction T:
 - must redo / undo T
 - if S is T's coordinator:
 - periodically send commit / abort messages to subordinates until ack messages are received
 - write an end log record after receiving all ack messages
 - if there is a *prepare* log record for transaction T, but no *commit / abort*, S is one of T's subordinates
 - contact T's coordinator repeatedly until T's status is obtained
 - write a commit / an abort log record
 - redo / undo T

- distributed recovery
 - restart after a failure site S
 - if there are no *commit / abort / prepare* log records for T:
 - abort T, undo T
 - if S is T's coordinator, T's subordinates may subsequently contact S
 - blocking
 - if T's coordinator site fails, T's subordinates who have voted *yes* cannot decide whether to commit or abort T until the coordinator recovers, i.e., T is *blocked*
 - even if all the subordinates know each other (overhead prepare messages), they are still blocked (unless one of them voted no)

- distributed recovery
 - link and remote site failures
 - current site S, remote site R, transaction T
 - if R doesn't respond during the commit protocol for T, either because R failed or the link failed:
 - if S is T's coordinator:
 - S should abort T
 - if S is one of T's subordinates, and has not voted yet:
 - S should abort T
 - if S is one of T's subordinates and has voted yes:
 - S is blocked until T's coordinator responds

- distributed recovery
 - 2PC observations
 - ack messages
 - used to determine when can a coordinator C "forget" about a transaction T
 - C must keep T in the transaction table until it receives all ack messages
 - C fails after sending prepare messages, but before writing a commit / an abort log record
 - when C comes back up it aborts T
 - i.e., absence of information => T is presumed to have aborted
 - if a subtransaction doesn't change any data, its commit / abort status is irrelevant

- distributed recovery
 - 2PC with Presumed Abort
 - coordinator C, transaction T, some subordinate S, some subtransaction t
 - C aborts T
 - T is undone
 - C immediately removes T from the Transaction Table, i.e., it doesn't wait for ack messages
 - subordinates' names need not be recorded in C's abort log record
 - S doesn't send an ack message when it receives an abort message

- distributed recovery
 - 2PC with Presumed Abort
 - coordinator C, transaction T, some subordinate S, some subtransaction t
 - t doesn't change any data
 - t responds to prepare messages with a reader message, instead of yes / no
 - C subsequently ignores readers
 - if all subtransactions are readers, the 2nd phase of the protocol is not needed

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