

Algoritmos e Estruturas de Dados II

Caminhos mínimos em grafos

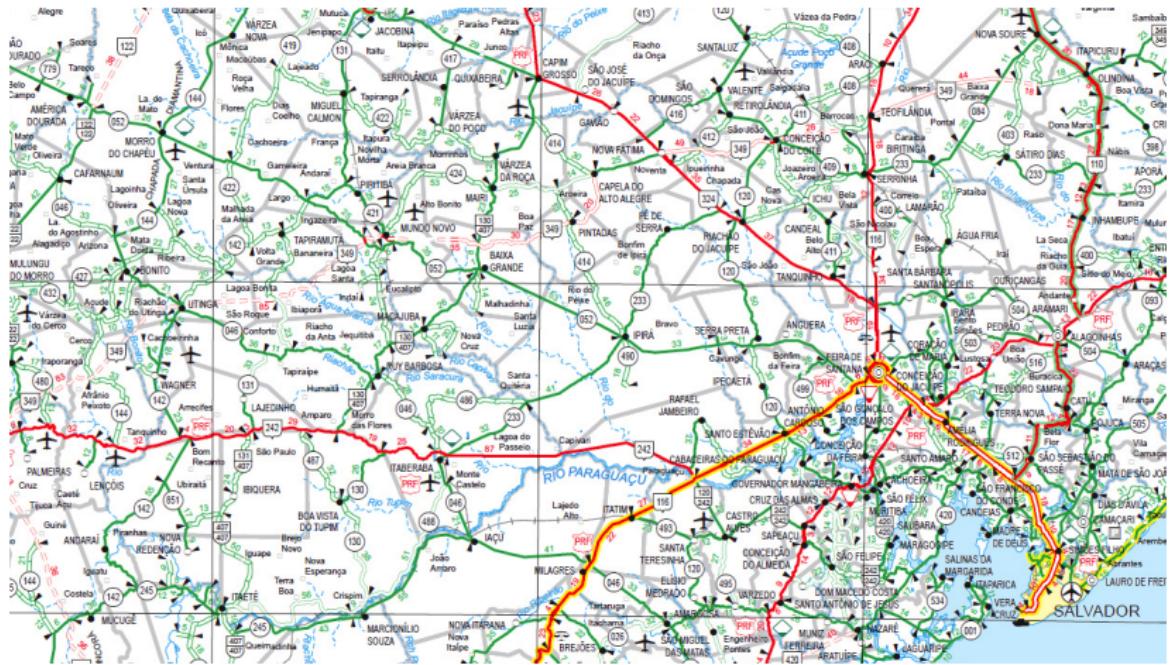
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Objetivos

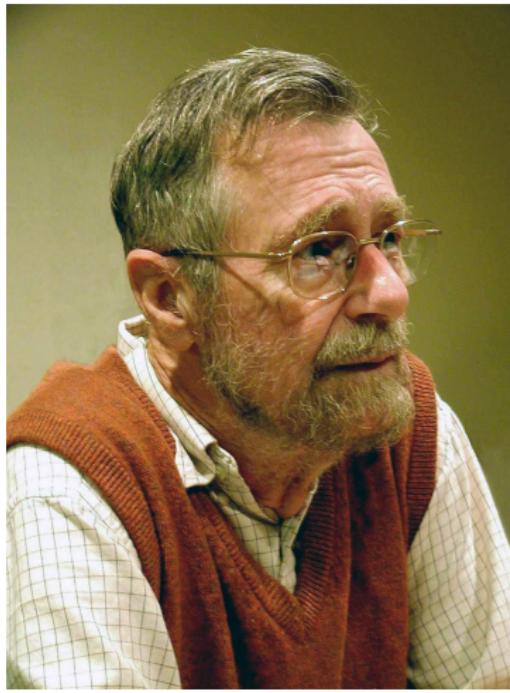
Entender o algoritmo de **Dijkstra** para caminhos mínimos em grafos.

E se o grafo for ponderado?



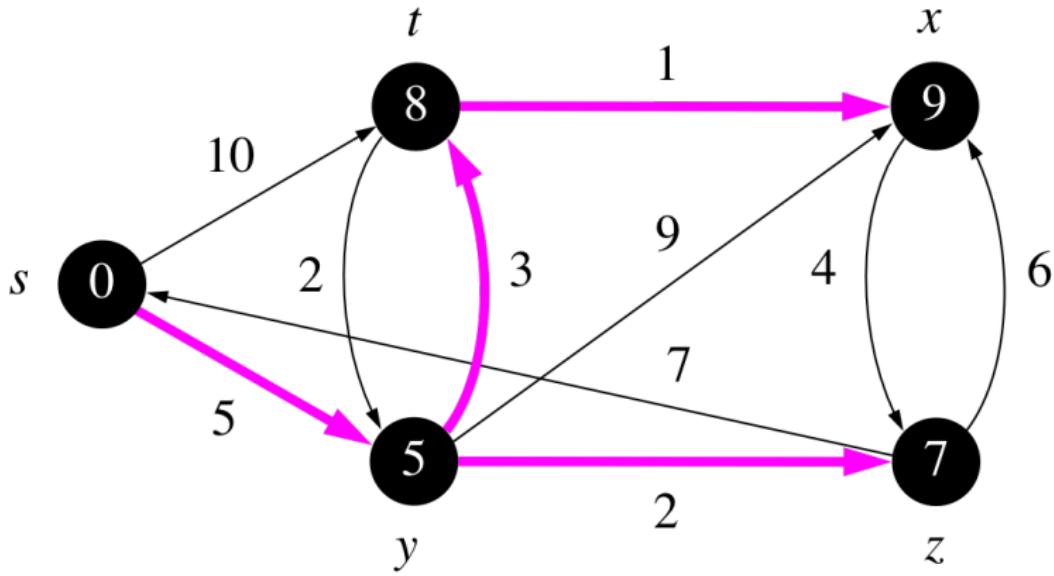
E se o grafo for ponderado?





Cientista da Computação holandês, **Edsger W. Dijkstra** (1930-2002). Prêmio Turing (1972).

O **algoritmo de Dijkstra** descobre todos os **caminhos mínimos** em um grafo ponderado (com pesos positivos) a partir de uma origem.



Elementos do algoritmo

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- ▶ s é o vértice-origem.

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- ▶ Uma **fila de prioridades mínimas** Q mantém os vértices ainda não processados.
- ▶ Para cada vértice v em Q , a chave $v.d$ guarda a distância estimada (soma dos pesos) da origem s até v .

INICIALIZA(G, s)

- 1 **para cada** $v \in G.V$
- 2 $v.d = \infty$
- 3 $v.\pi = \text{NIL}$
- 4 $s.d = 0$

RELAXA(u, v, w)

1 **se** $v.d > u.d + w(u, v)$

2 $v.d = u.d + w(u, v)$

3 $v.\pi = u$

DIJKSTRA(G, w, s)

1 INICIALIZA(G, s)

2 $S = \emptyset$

3 $Q = G.V$

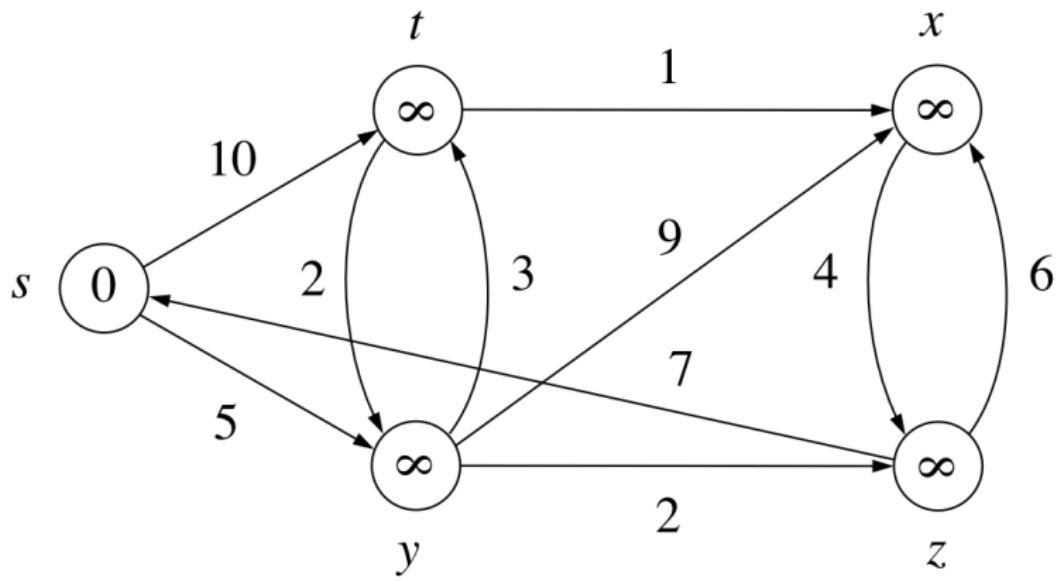
4 **enquanto** $Q \neq \emptyset$

5 $u = \text{EXTRACT-MIN}(Q)$

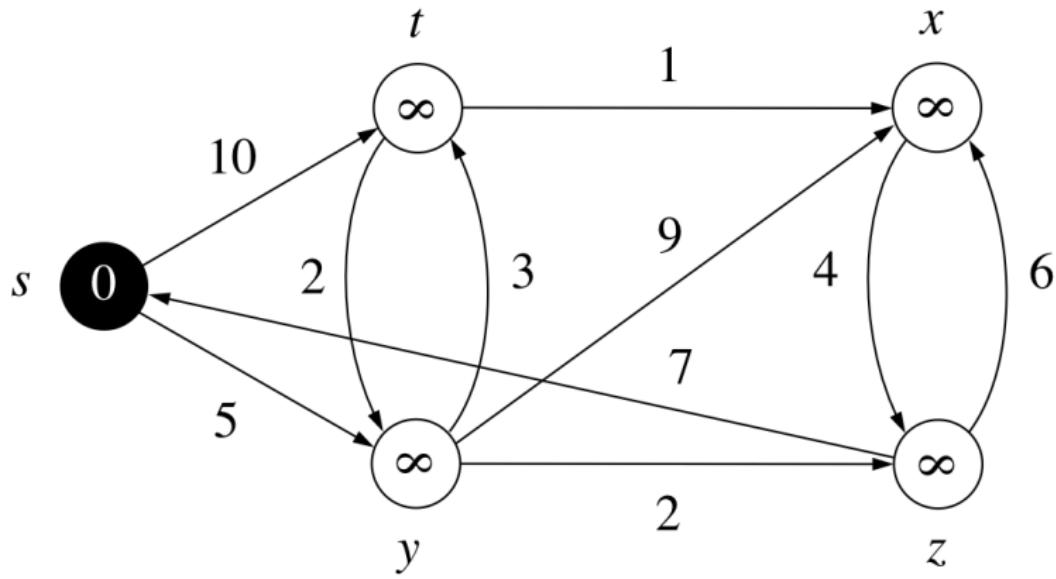
6 $S = S \cup \{u\}$

7 **para cada** $v \in G.Adj[u]$

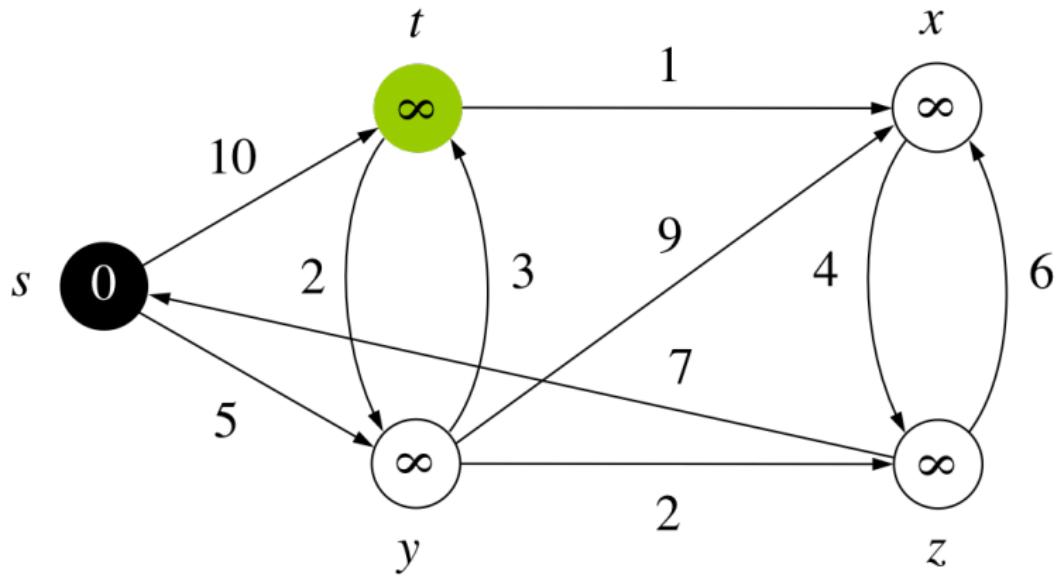
8 RELAXA(u, v, w)



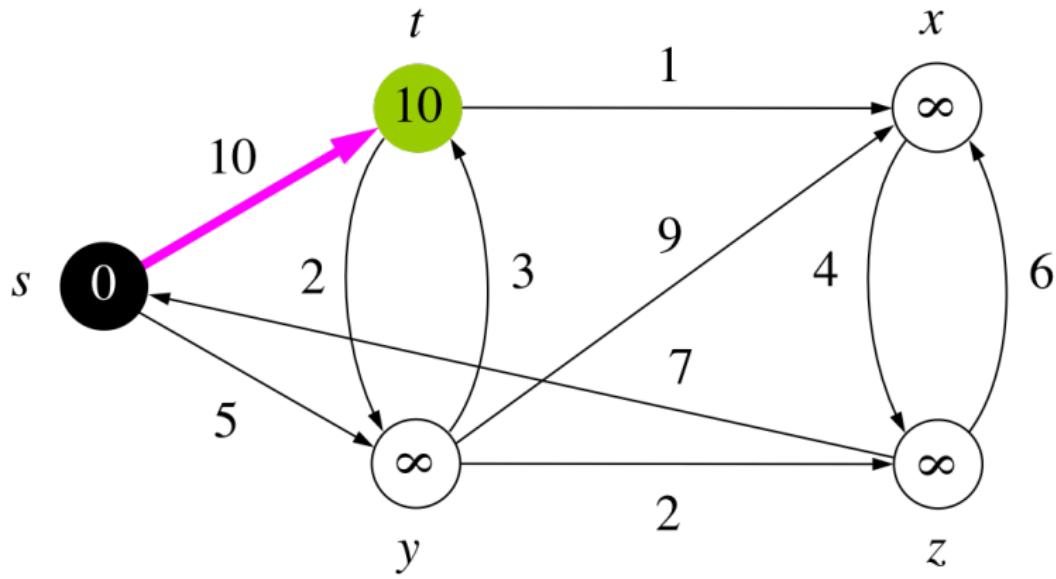
$v.d$ iniciados com ∞ , exceto o vértice-origem
 $s.d = 0$.



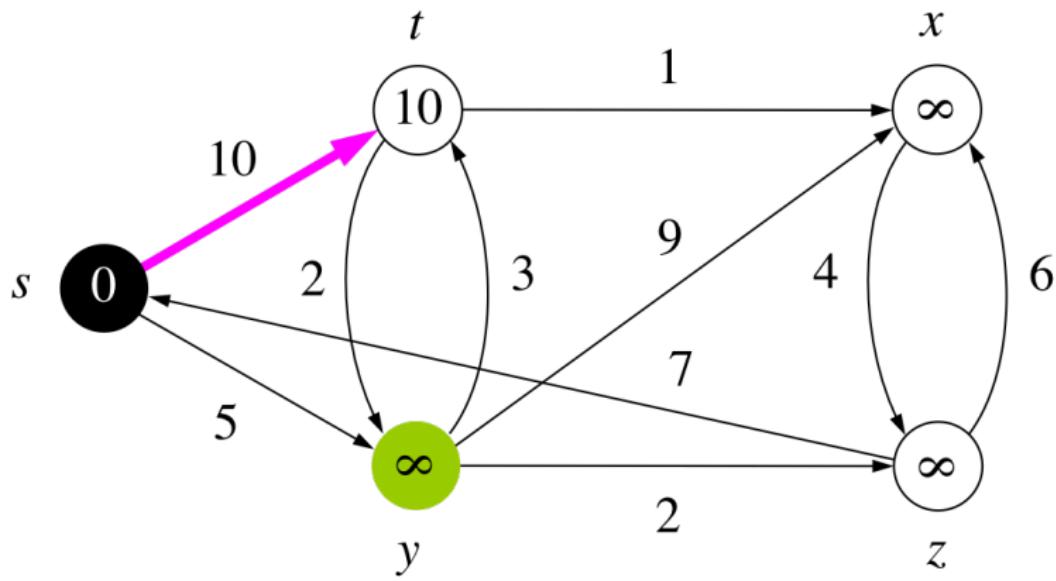
Origem s sai da fila.



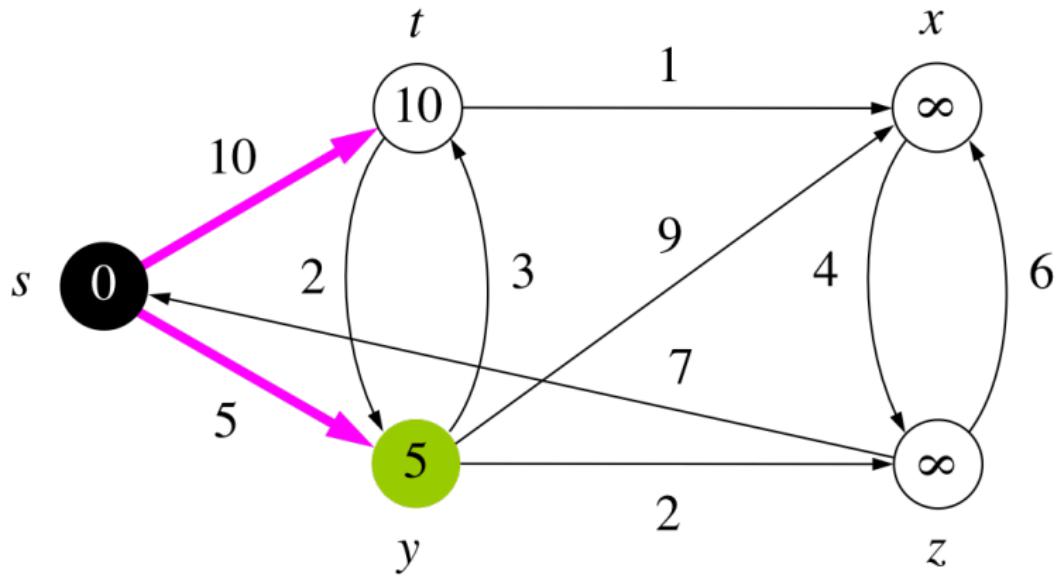
Adjacentes de s são relaxados.



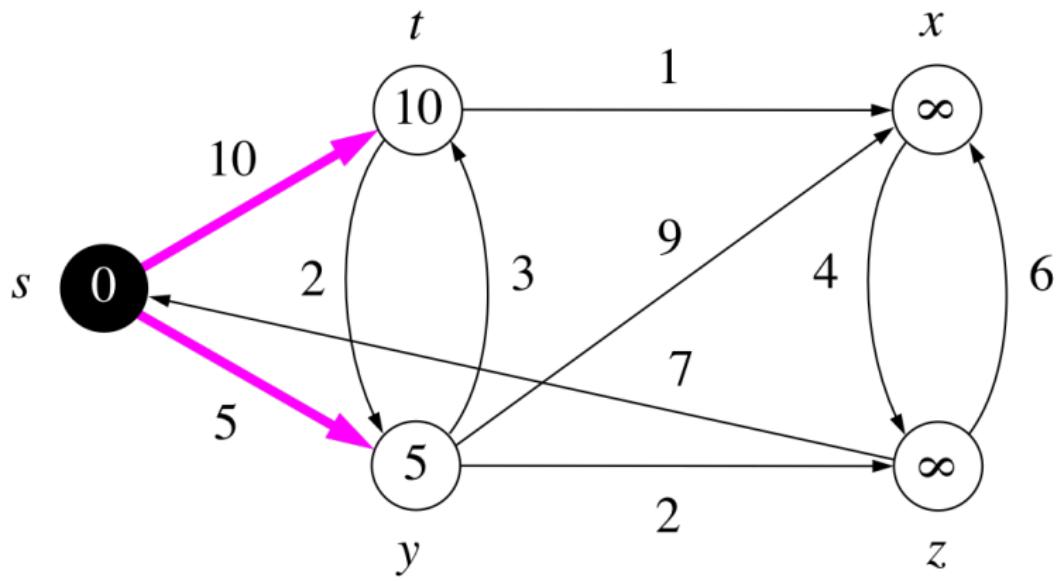
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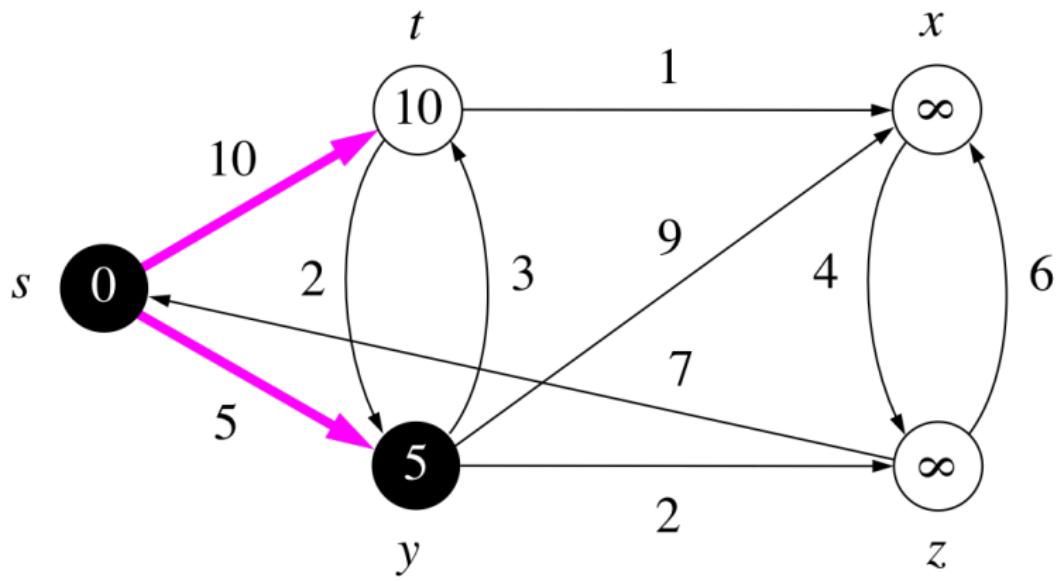
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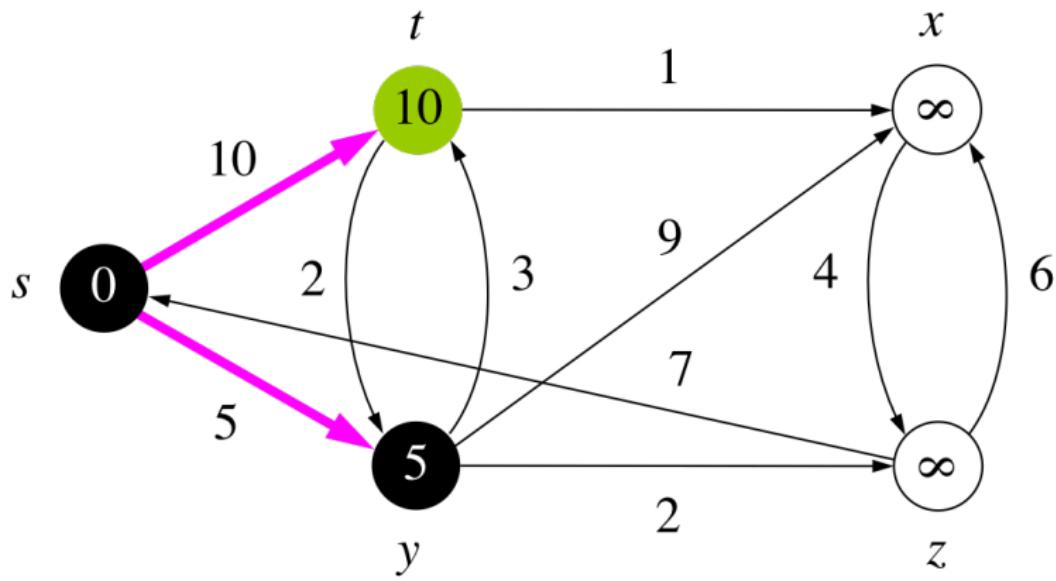
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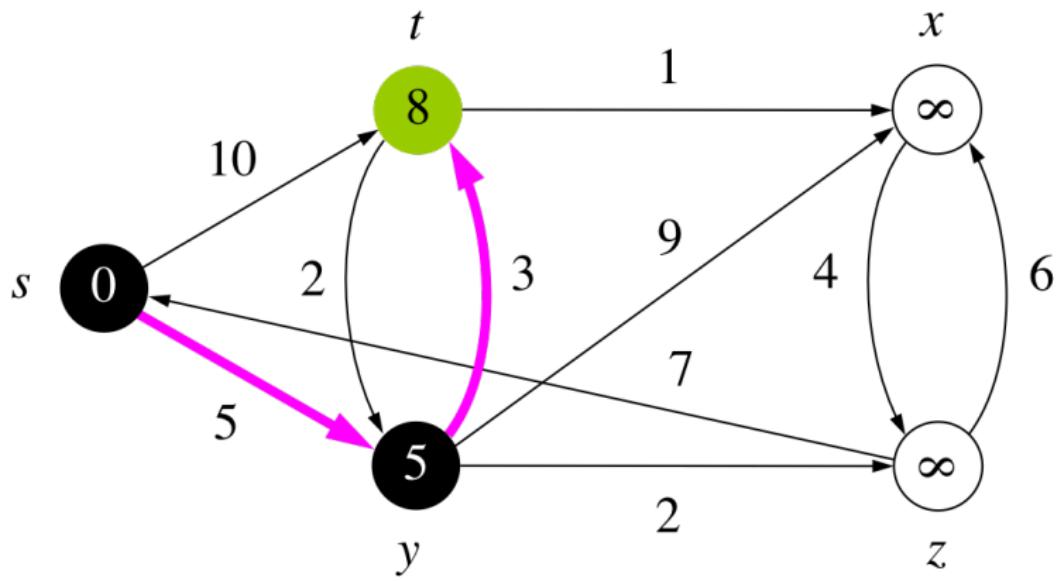
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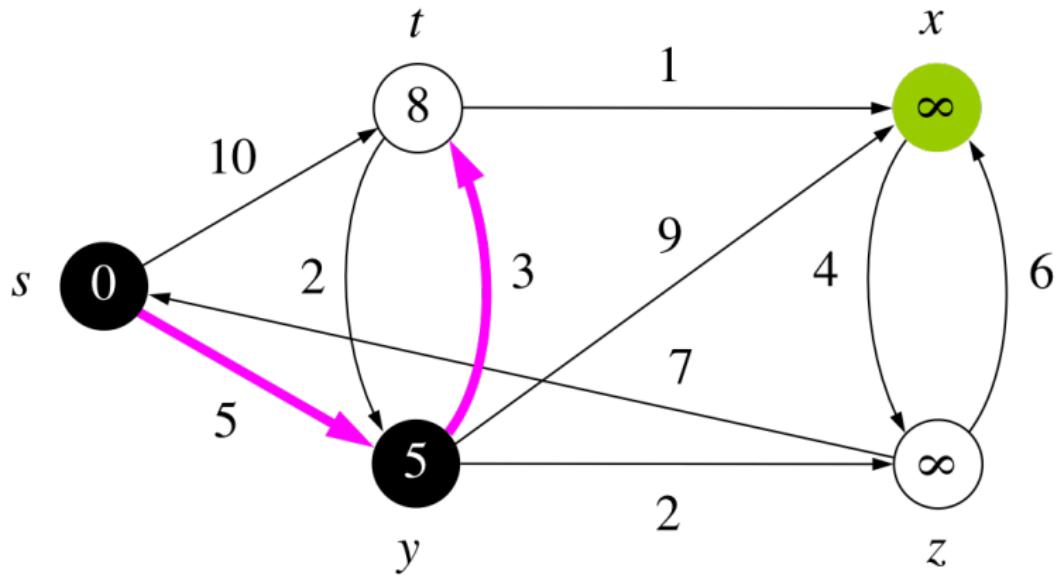
Vértice y sai da fila.



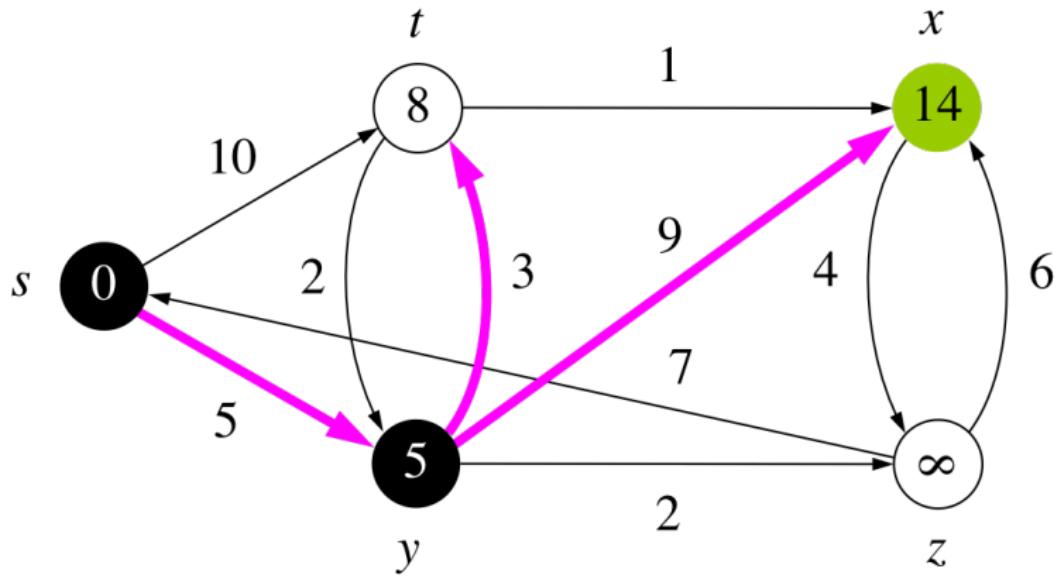
Adjacentes de y são relaxados.



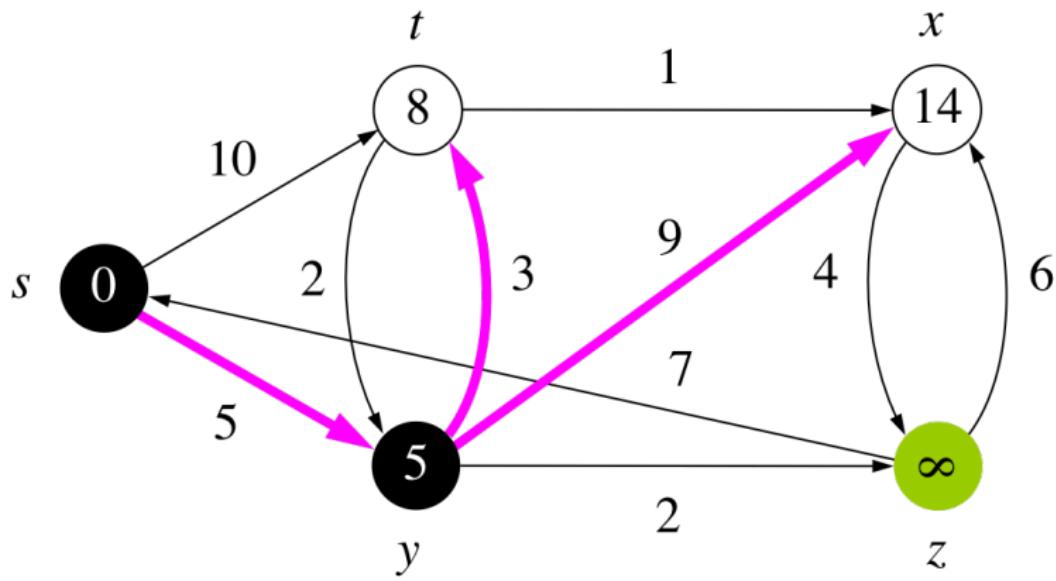
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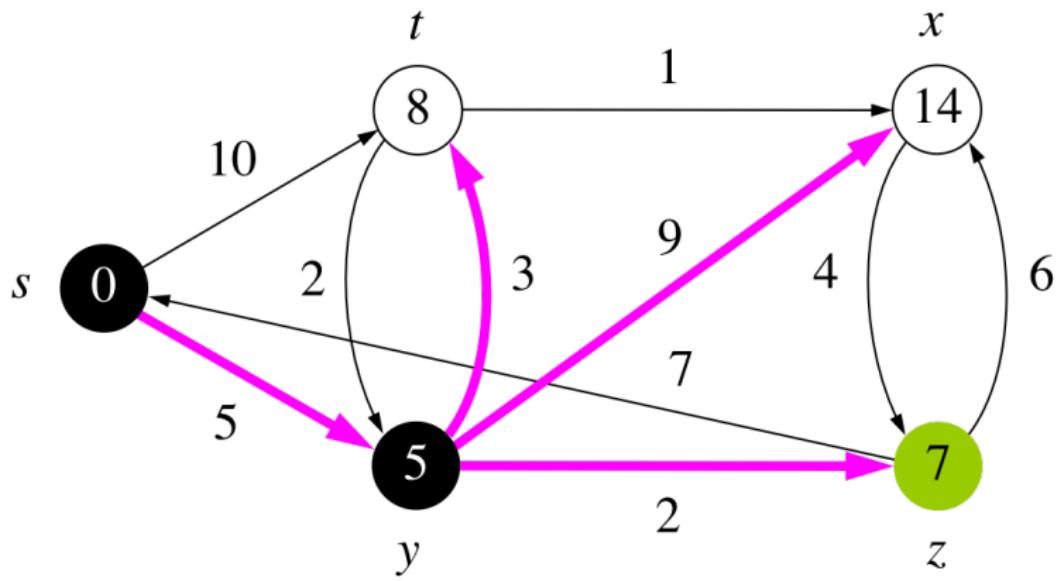
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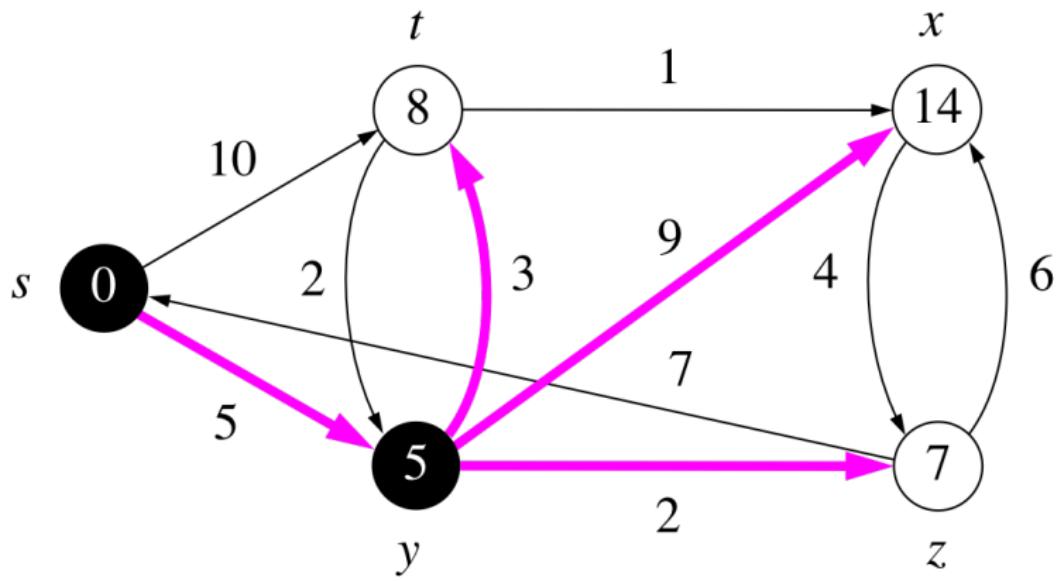
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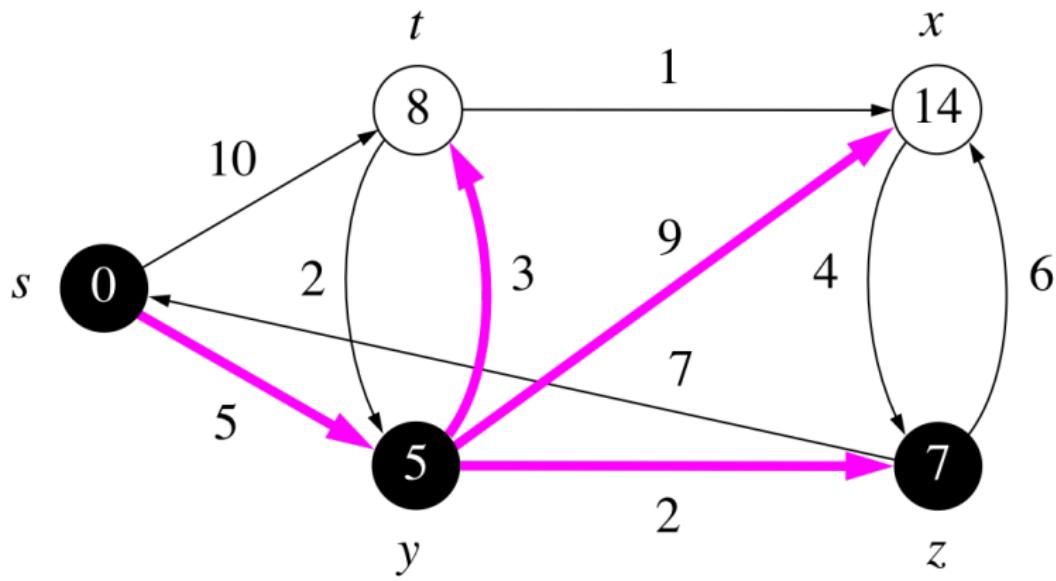
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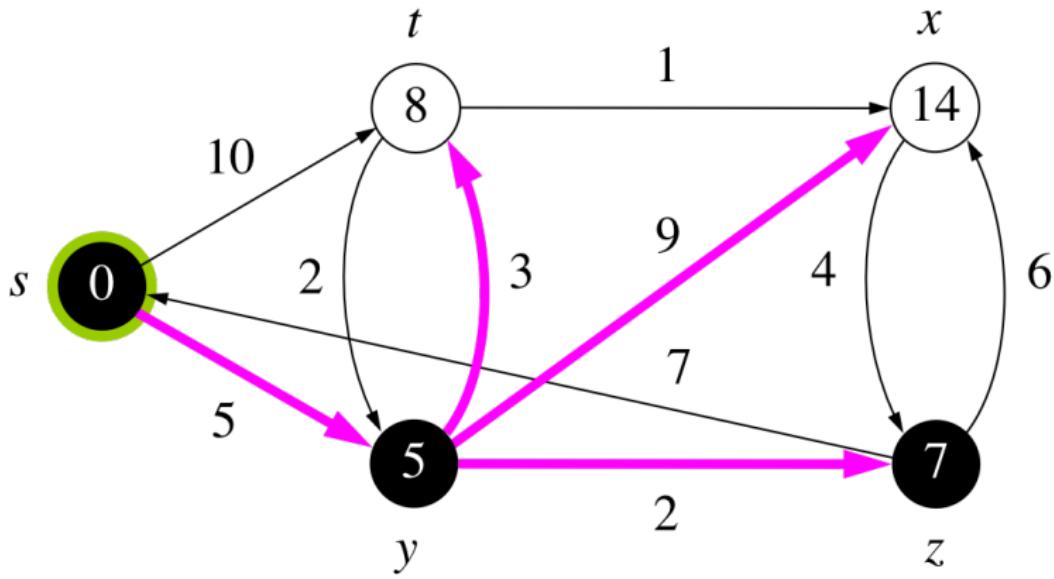
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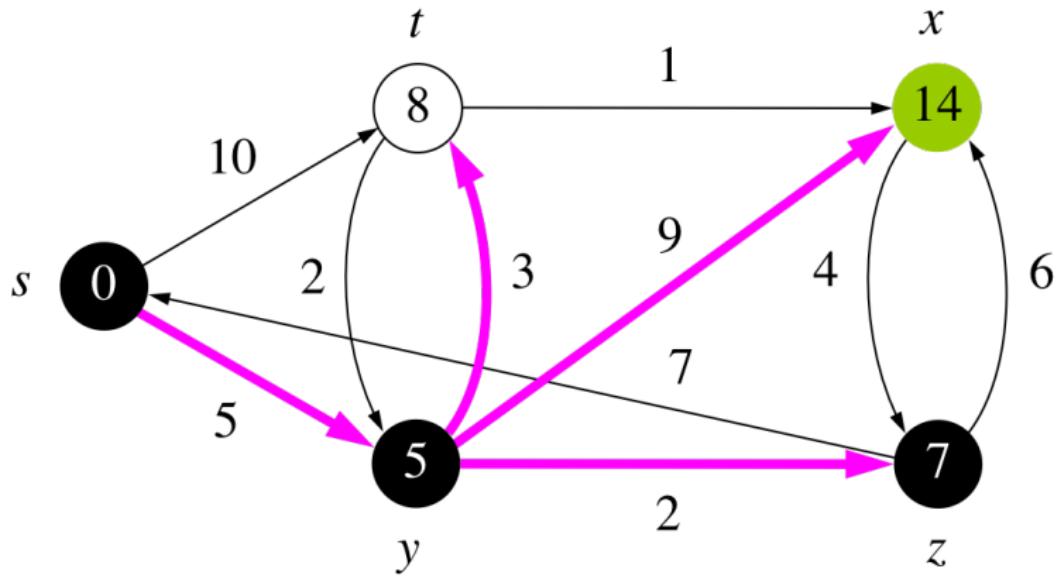
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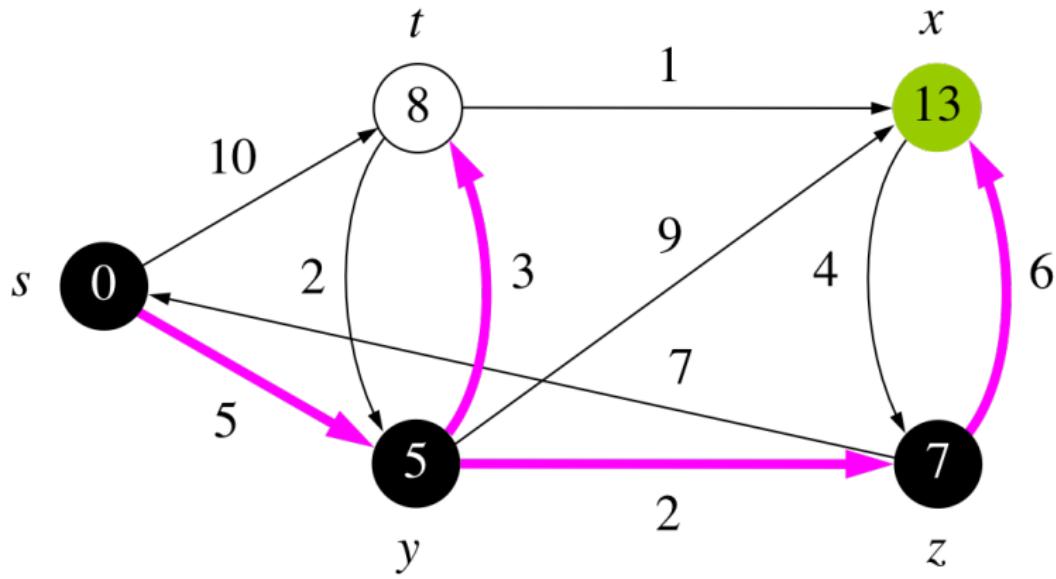
Vértice z sai da fila.



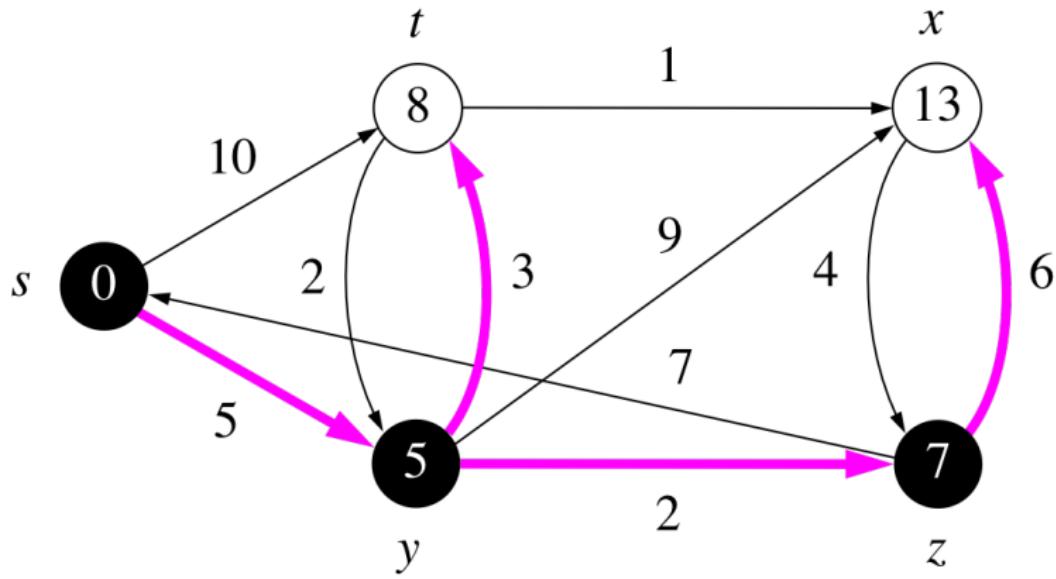
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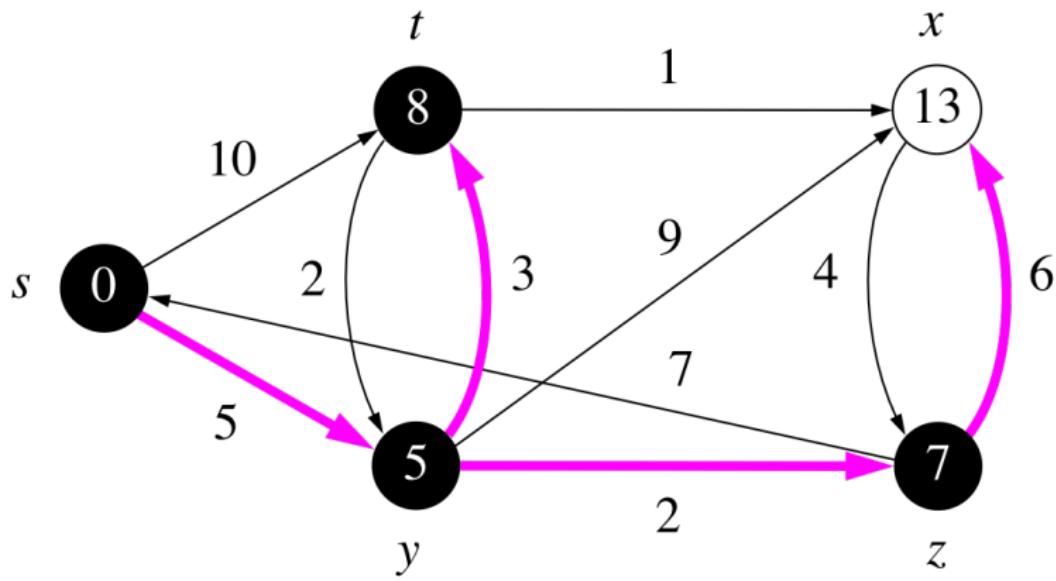
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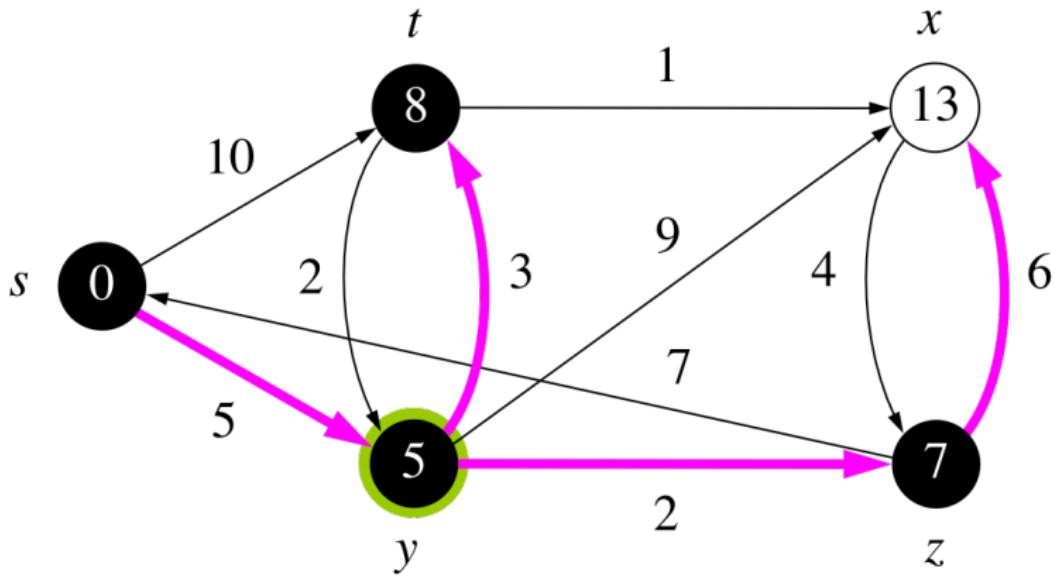
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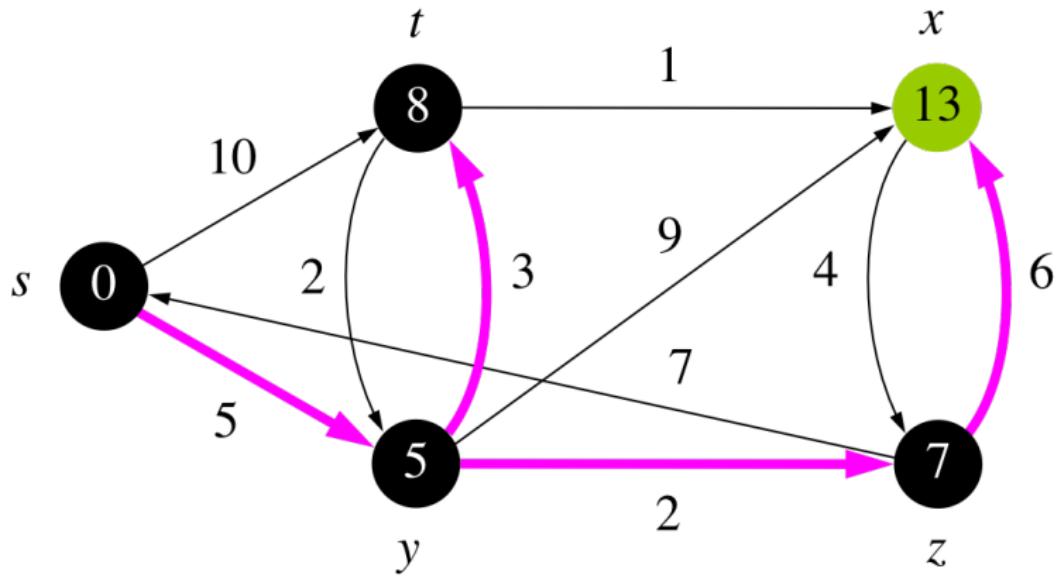
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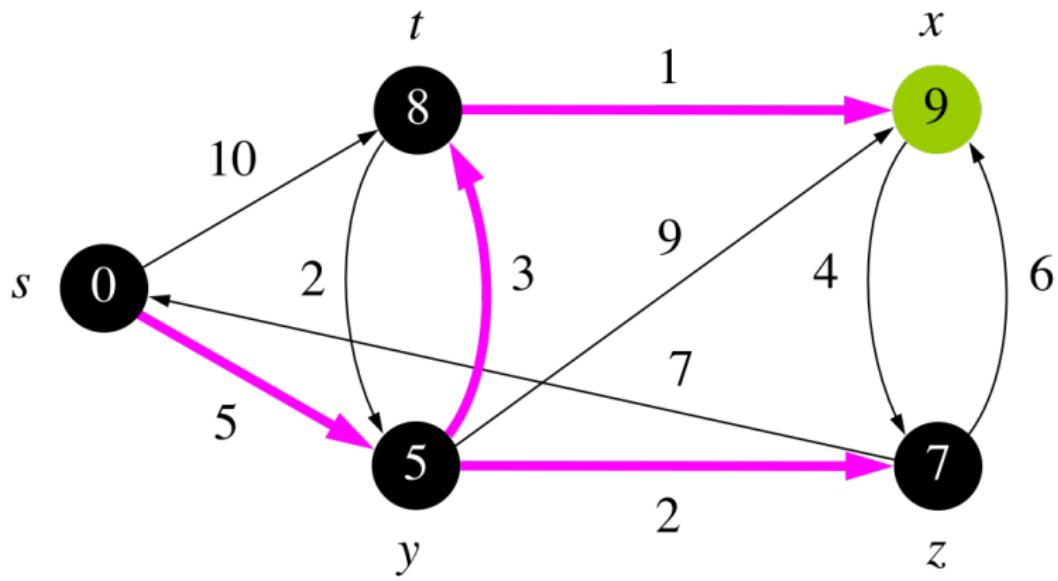
Vértice t sai da fila.



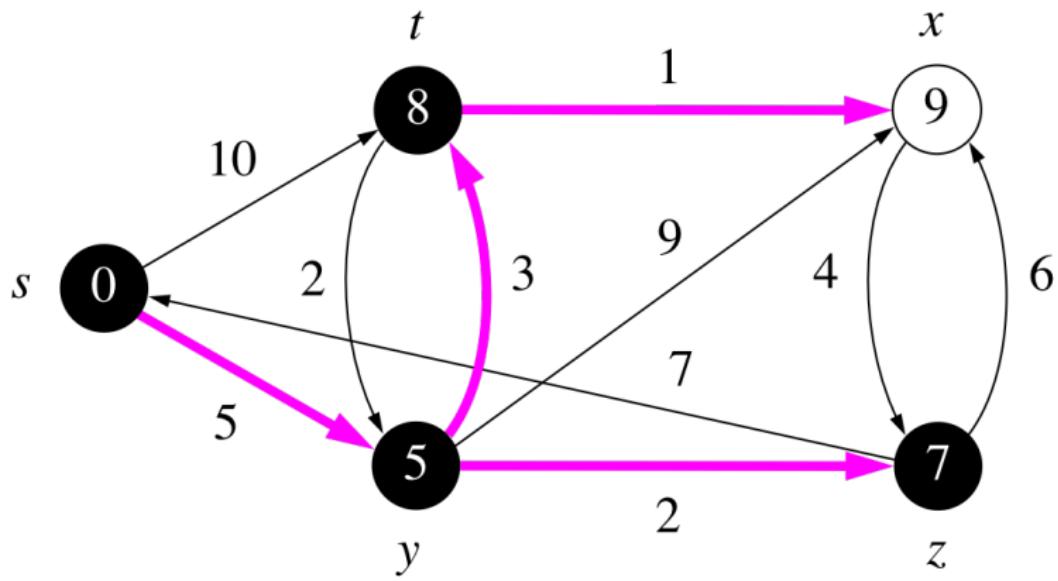
Adjacentes de t são relaxados.



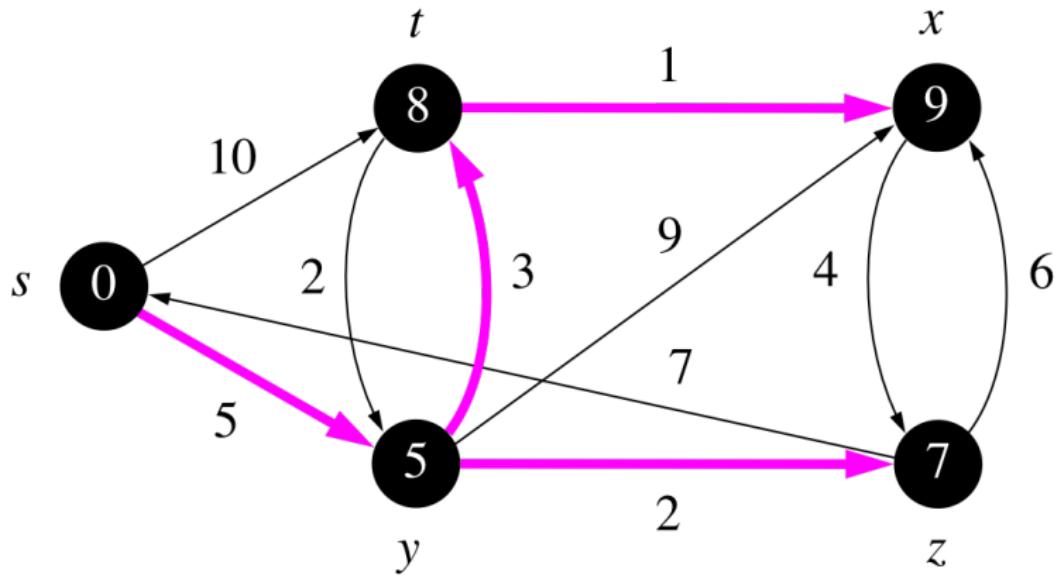
Adjacentes de t são relaxados.



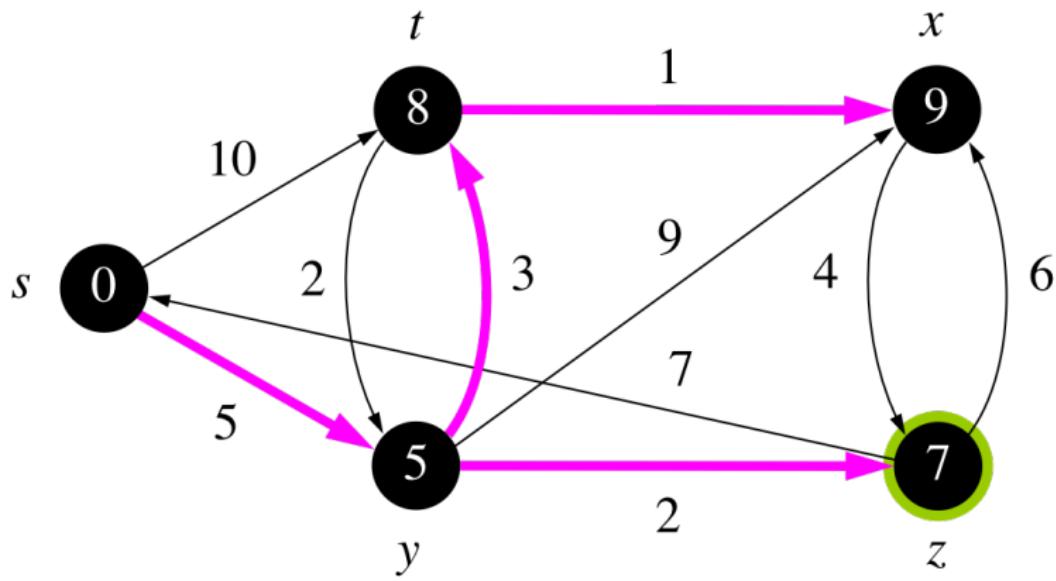
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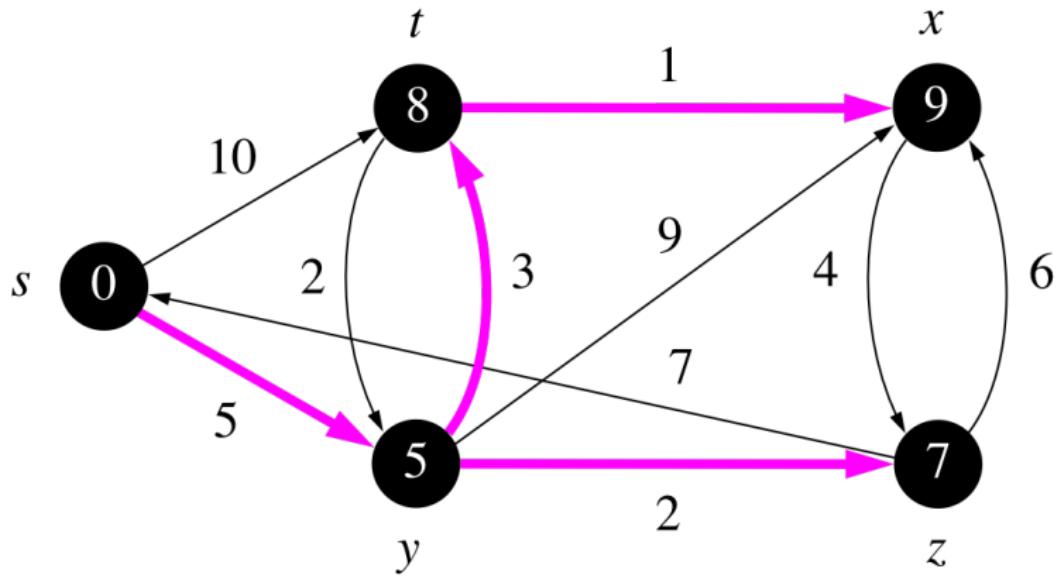
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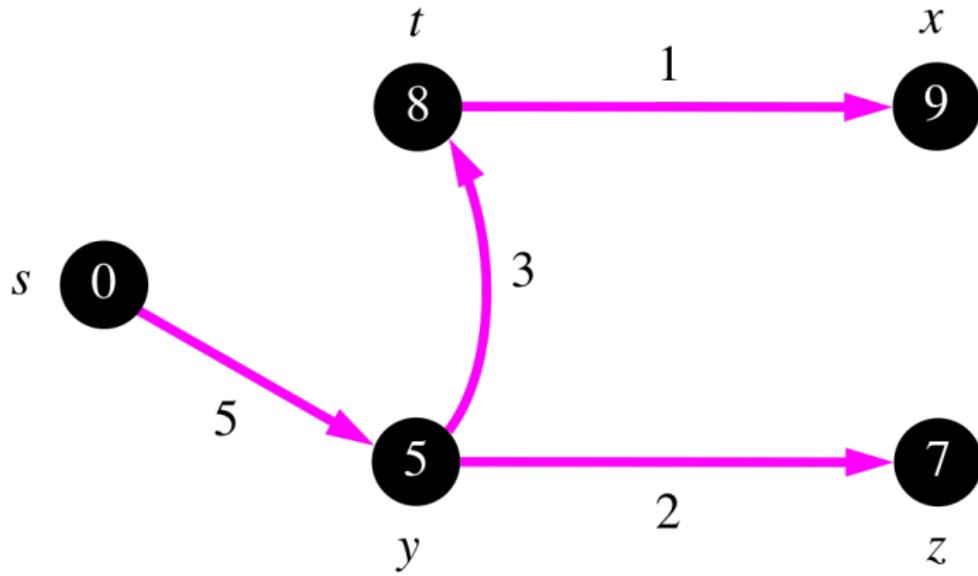
Vértice x sai da fila (Q vazia).



Adjacentes de x são relaxados.



Adjacentes de x são relaxados.



Árvore geradora com **caminhos de custo mínimo** a partir da origem.

Complexidade de tempo de Dijkstra

- ▶ Q usando vetor simples: $O(V^2)$.
- ▶ Q usando heap binário: $O(E \lg V)$.
- ▶ Q usando heap de Fibonacci:
 $O(V \lg V + E)$.

Referências

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Onde obter este material:

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