Input: a differentiable action-value function parameterization $\hat{q}: \mathbb{S} \times \mathcal{A} \times \mathbb{R}^d \to \mathbb{R}$ Algorithm parameters: step size $\alpha > 0$, small $\varepsilon > 0$

Initialize value-function weights $\mathbf{w} \in \mathbb{R}^d$ arbitrarily (e.g., $\mathbf{w} = \mathbf{0}$)

Loop for each episode:
$$S, A \leftarrow \text{initial state}$$
 and action of episode (e.g., ε -greedy)

Episodic Semi-gradient Sarsa for Estimating $\hat{q} \approx q_*$

Loop for each step of episode:

Take action
$$A$$
, observe R, S'
If S' is terminal:

 $\mathbf{w} \leftarrow \mathbf{w} + \alpha [R - \hat{q}(S, A, \mathbf{w})] \nabla \hat{q}(S, A, \mathbf{w})$

 $A \leftarrow A'$

Go to next episode Choose A' as a function of $\hat{q}(S', \cdot, \mathbf{w})$ (e.g., ε -greedy) $\mathbf{w} \leftarrow \mathbf{w} + \alpha [R + \gamma \hat{q}(S', A', \mathbf{w}) - \hat{q}(S, A, \mathbf{w})] \nabla \hat{q}(S, A, \mathbf{w})$