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# Introduction to Gaussian Processes

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The **Gaussian Processes** are the widely used stochastic processes for modeling dependent data observed over time, space or even time and space. Here, we'll initiate our study with a **Probability and Random Process Theory Review** taking some point to base our journey, going through **Linear Regression** and finally the **Gaussian Processes**.

The material here presented isn't sufficient to guide you over basic probability, so it's recommended to have some knowledge, once we'll just take a simple review.

## 1 Probability and Random Process Theory Review

- 1.1 Basic Concepts of Probability Theory
- 1.2 The Gaussian distribution
- 1.3 Independency of two random variables

## 2 Linear Regression

- 2.1 Basic Concepts of Curve Fitting
- 2.2 Bayesian Curve Fitting

# Probability and Random Process Theory Review

Let's start with the sentence

## Sentence

*A random experiment is specified by stating an **experimental procedure** and a **set** of one or more measurements or observations.*

The **Gaussian distribution** is defined as

$$\mathcal{N}(x|\mu, \sigma^2) = \frac{1}{(2\pi\sigma^2)^{1/2}} \exp \left\{ -\frac{1}{2\sigma^2} (x - \mu)^2 \right\} \quad (1)$$

# Independency of two random variables

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that means in other words that *if X and Y are independent discrete random variables, then the **joint probability mass function (pmf)** is equal to the product of the marginal pmf's.*

# Linear Regression

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*If we could update the **regression weights** as we acquire some new values of the experiment?*

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$$p(\mathbf{w}|\mathcal{D}) = \frac{\overbrace{p(\mathcal{D}|\mathbf{w})}^{\text{the weights probability}} \overbrace{p(\mathbf{w})}^{\text{the data probability}}}{\underbrace{p(\mathcal{D})}_{\text{the data probability}}} \quad (3)$$



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So, if **we have the probability** of the data, we'll could estimate the **future weights**.

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**But, how?**

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A good idea is to express our target values  $\mathbf{t}$  in terms of **gaussians distributions** with the mean equals to  $y(x, \mathbf{w})$ .

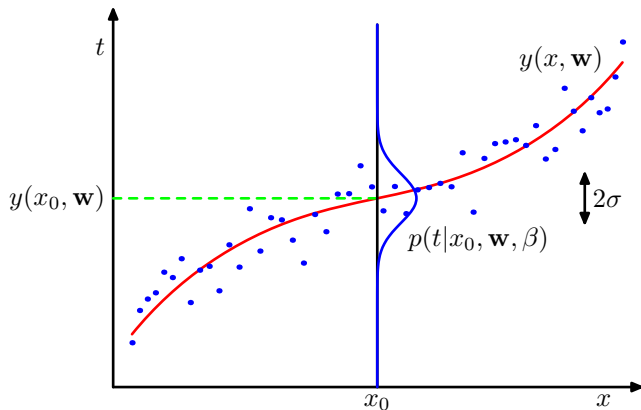


Figure: Schematic of the polynomial function  $y(x, \mathbf{w})$  and the gaussian distribution  $p$ .

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and then, assume that the training data  $\{\mathbf{x}, \mathbf{t}\}$  is independent and identically distributed (i.i.d.) and put on **product form**, i.e. the joint probability is

$$p(\mathbf{t}|\mathbf{x}, \mathbf{w}, \beta) = \mathcal{N}(t_0|y(x_1, \mathbf{w}), \beta^{-1}) \cap \mathcal{N}(t_n|y(x_0, \mathbf{w}), \beta^{-1}) \dots \cap \mathcal{N}(t_n|y(x_0, \mathbf{w}), \beta^{-1}) \quad (5)$$

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$$= \prod_{n=1}^N \mathcal{N}(t_n|y(x_n, \mathbf{w}), \beta^{-1}) \quad (6)$$

regarding that  $\beta^{-1} = \sigma^2$ .

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Applying the **Gaussian distribution** (see 1) will result

$$\ln(p(\mathbf{t}|\mathbf{x}, \mathbf{w}, \beta)) = -\frac{\beta}{2} \sum_{n=1}^N \{y(x_n, \mathbf{w}) - t_n\}^2 + \frac{N}{2} \ln(\beta) - \frac{N}{2} \ln(2\pi) \quad (8)$$

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$$\frac{1}{N} \sum_{n=1}^N \{y(x_n, \mathbf{w} - t_n)\}^2 = \frac{1}{\beta_{ML}} \quad (11)$$

Where  $\beta_{ML}$  is the maximum likelihood.