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# Introduction to Gaussian Processes

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The Gaussian Processes are the widely used stochastic processes for modeling dependent data observed over time, space or even time and space. Here, we'll iniciate our study with a Probability and Random Process Theory Review taking some point to base our journey, going through Linear Regression and finally the Gaussian Processes.

The material here presented isn't sufficient to guide you over basic probability, so it's recommended to have some knowledge, once we'll just take a simple review.

## Outline

- Probability and Random Process Theory Review
- 1.1 Basic Concepts of Probability Theory

- ② Linear Regression
- 2.1 Basic Concepts of Curve Fitting
- 2.2 Bayesian Curve Fitting

## Theory Review

**Probability and Random Process** 



#### Specifying Random Experiments

Let's start with the sentence

#### Sentence

A random experiment is specified by stating an experimental procedure and a set of one or more measurements or observations.



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# Linear Regression



So, we'll start to look the regression with a statistical approach. To encourage you, let's take the sentence.



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#### Sentence

If we could update the **regression weights** as we acquire some new values of the experiment?



Let's take a look again at the Bayes Theorem



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#### **Bayes Theorem**

$$p(\mathbf{w}|\mathcal{D}) = \underbrace{\frac{p(\mathcal{D}|\mathbf{w}) \, p(\mathbf{w})}{p(\mathcal{D})}}_{\text{the } a \, priori \, \text{probability}} \tag{1}$$



Let's take a look again at the Bayes Theorem

#### **Bayes Theorem**

the a priori probability
$$p(\mathbf{w}|\mathcal{D}) = \underbrace{\frac{p(\mathcal{D}|\mathbf{w})}{p(\mathbf{w})}}_{\text{the a priori probability}}$$
the a priori probability (1)

So, if we have the probability of the data, we'll could estimate the future weights.



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So, if we have the probability of the data, we'll could estimate the future weights. But, how?



Taking some steps back, let's re-visit the **Curve Fitting**. There, the strategy was minimize the error function.



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A good ideia is to express our target values t in terms of **gaussians distributions** with the mean equals to  $y(x, \mathbf{w})$ .



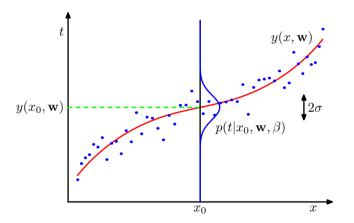


Figure: Schematic of the polynomial function  $y(x, \mathbf{w})$  and the gaussian distribution p.



#### Title

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blah = result