[Overview](#)

Repositories 85

Projects 0

Stars 21

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[chili-epfl/nao_writing](#)

A set of ROS nodes which allow a robot to perform simulated handwriting through motions which are synchronised with an android tablet's display.

Python ★ 8 3

[pullrequest-visualiser](#)

Bookmarklet for graphing pull requests of a github repository over time

JavaScript ★ 4 1

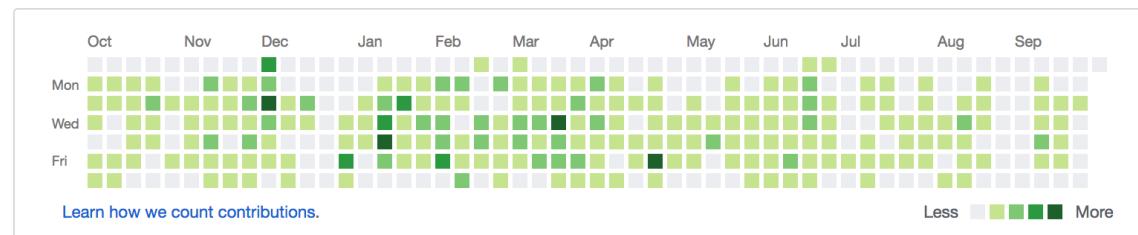
dhood

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Organizations



1,226 contributions in 2018



2019

2018

2017

2016

2015

2014

2013

@ros

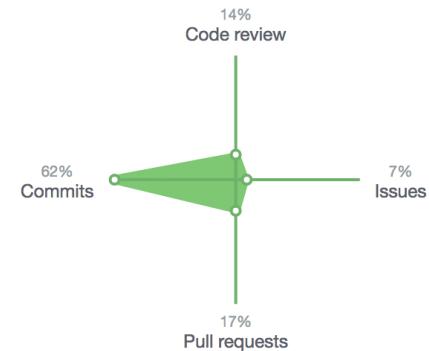
@ADLINK-IST

@ros-visualization

More

Activity overview

Contributed to [dhood/ariac](#), [ros2/rclcpp](#), [ros2/demos](#) and 5 other repositories



Contribution activity

2019

dhood has no activity yet for this period.

October - December 2018

dhood had no activity during this period.

September 2018

Created 13 commits in 5 repositories



Created a pull request in ros2/rcl that received 10 comments

Sep 15

🔧 [yaml parser] Fix FQN=/node_name when ns is /

Consider the parameters file: /: talker: ros__parameters: some_int: 42 Without this PR, the parameters are stored under the FQN of //talker, so pa...

+40 -1 40 green squares • 10 comments

Opened 9 other pull requests in 5 repositories



ros2/launch

4 merged

ros2/rclcpp

2 merged

ros2/design

1 closed

ros2/rclpy

1 merged

ros-simulation/gazebo_ros_pkgs

1 merged

Reviewed 5 pull requests in 4 repositories



Created an issue in ros2/rcl that received 5 comments

Sep 12

❗ Name remapping specific to a fully-qualified node's name

Remapping can be passed to a specific node with e.g. talker:chatter:=my_chatter. Suppose I have multiple nodes named talker in a process, but in di...

5 comments

Opened 2 other issues in 2 repositories



August 2018

Created 20 commits in 7 repositories



Created 1 repository

dhood/homebrew-simulation Ruby

Aug 1

Created a pull request in ros2/design that received 7 comments

Aug 11

Clarify ROS default values will be used in default constructor

@mikaelarguedas explained this to me in ros-simulation/gazebo_ros_pkgs#793 (comment)

+2 -2 7 comments

Opened 11 other pull requests in 8 repositories



ros-simulation/gazebo_ros_pkgs

3 merged 1 closed

ros2/rclpy

1 merged

github-workshops/github-workshop-2018-08-15

1 open

ros2/rclcpp

1 merged

ros-infrastructure/rosindex

1 merged

rosindex/rosindex

1 open

ros2/rosdistro

1 merged

ros2/rcl

1 merged

Reviewed 7 pull requests in 5 repositories



Created an issue in ros-simulation/gazebo_ros_pkgs that received 6 comments

Aug 10

[ros2] Plugins not creating their own node

There is overhead associated with having multiple nodes, e.g. services for parameters. This is especially true at the moment because ROS 2 nodes ea...

6 comments

① Opened 4 other issues in 3 repositories

2

July 2018

 Created 11 commits in 8 repositories

2

 Created a pull request in osrf/homebrew-simulation that received 8 comments

Aug 7

🔗 ignition-cmake1: use newer commit

I'm looking for an updated version of ignition cmake for ignition rendering (see [#457](#)). This converts it from using a released version to a particu...

+4 -4     • 8 comments

 Opened 11 other pull requests in 8 repositories

1

ros2/rclpy

2 merged

ros2/ci

2 merged

ros2/launch

2 merged

osrf/homebrew-simulation

1 merged

ros2/rcl

1 merged

ros2/rclcpp

1 merged

ros2/design

1 merged

 Reviewed 5 pull requests in 5 repositories

三

 Created an issue in ros/urdfdom_headers that received 40 comments

111

④ Release for bionic doesn't include #42

This PR doesn't seem to have made it into the packaged urdfdom_headers in bionic. The 1.0.0 tag on this repo doesn't seem to include this PR, and t...

40 comments

① Opened 5 other issues in 2 repositories



ros2/rclcpp

1 open 3 closed

ros/urdfdom_headers

1 closed

June 2018

④ Created 42 commits in 17 repositories



🔥 Created a pull request in ros2/rcl that received 14 comments

Jun 20

↗ Add regression test for node:__ns remapping

Regression test for #262 to check it's not just my machine Linux Linux-aarch64 macOS Windows

+17 -1 4 green 1 grey • 14 comments

⑩ Opened 30 other pull requests in 13 repositories



ros2/ci

4 merged 1 closed

ros2/rmw_opensplice

4 merged

ros2/demos

4 merged

ros2/rcl

3 merged 1 closed

ros2/ros_core_documentation

2 merged

ros2/launch

2 merged

ros2/ros2cli

1 closed 1 merged

ros2/rcutils

2 merged

ros2/rosidl

1 closed

ros2/rclpy

1 merged

ros2/sros2

1 merged

ros2/rmw_connect

1 merged

ros2/libyaml_vendor

1 merged

⌚ Reviewed 47 pull requests in 19 repositories



🔥 Created an issue in colcon/colcon-core that received 15 comments

Jun 21

⌚ Dependencies of package in overlay workspace required to be in the overlay

I am trying to build a single package in an overlay workspace. colcon seems to be looking for the dependencies of that package to be in the overlay...

15 comments

⌚ Opened 15 other issues in 8 repositories



May 2018

⌚ Created 29 commits in 9 repositories



🔥 Created a pull request in ros2/ci that received 4 comments

Jun 1

👾 Add nightly xenial jobs

This PR targets #148 This creates nightlies using xenial, testing the ros2 "core" (linux x86 and ARM) It does not build/test the turtlebot demo bec...

+69 -21  4 comments

⌚ Opened 6 other pull requests in 5 repositories



ros2/rclcpp

2 merged

colcon/colcon.readthedocs.org

1 merged

ros-infrastructure/roswiki

1 merged

c11z/git-tableflip

1 open

ros/rosdistro

1 merged

Reviewed 12 pull requests in 7 repositories



Created an issue in ros2/ros2 that received 12 comments

May 3

ⓘ Update get_node_names to never return empty values

Each supported RMW implementation (e.g. rmw_connext_cpp, rmw_fastrtps_cpp, rmw_opensplice_cpp) has its own vendor-specific implementation of rmw_ge...

0 of 5 • 12 comments

ⓘ Opened 3 other issues in 3 repositories



April 2018

Created 71 commits in 11 repositories



Created a pull request in ros-visualization/rviz that received 5 comments

Apr 13

ⓘ allow classes inheriting from image display access to more state

replacement of #1161

+6 -5 ●●●●● • 5 comments

ⓘ Opened 18 other pull requests in 7 repositories



ros-visualization/rviz

6 merged 1 closed

ros/rosdistro

3 merged

ros2/ci

3 merged

ros2/ros2cli

2 merged

osrf/ariac-docker

1 merged

ros2/ros1_bridge

1 merged

ros2/demos

1 merged

ⓘ Reviewed 13 pull requests in 4 repositories



ros-visualization/rviz	6 pull requests
ros2/ci	4 pull requests
ros2/rclcpp	2 pull requests
ros2/rmw_opensplice	1 pull request

🔥 Created an issue in ros2/build_cop that received 20 comments Apr 3

⌚ building the bridge requires a lot of memory

e.g. https://ci.ros2.org/job/ci_linux/4166/ Step 31/43 : RUN echo "2018-04-02" ---> Running in
a71b44327fca connection error: desc = "transport: di..."

20 comments

⌚ Opened 14 other issues in 7 repositories ⚡

March 2018

💻 Created 173 commits in 11 repositories ⚡

🔥 Created a pull request in ros2/ci that received 6 comments Mar 22

👾 Use --rm on docker run invocation

To prevent having to remove old containers manually. Our linux nodes run out of disk space regularly because of a build up of containers. Will give...

+2 -2 🟢🟡🔴 ● 6 comments

🍴 Opened 8 other pull requests in 4 repositories ⚡

ros2/ci 4 merged

osrf/ariac-docker 2 merged

ament/ament_lint 1 merged

ros2/system_tests 1 merged

Reviewed 15 pull requests in 9 repositories



Created an issue in ros2/rclcpp that received 8 comments

Mar 30

⌚ Test of node->now() flaky on OS X

This test is flaky: TEST_F(TestNode, now) { auto node = std::make_shared<rclcpp::Node>("my_node", "/ns");
auto clock = node->get_clock(); auto now_...

8 comments

⌚ Opened 12 other issues in 5 repositories



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