

Sistema de control de acceso vehicular con PLC

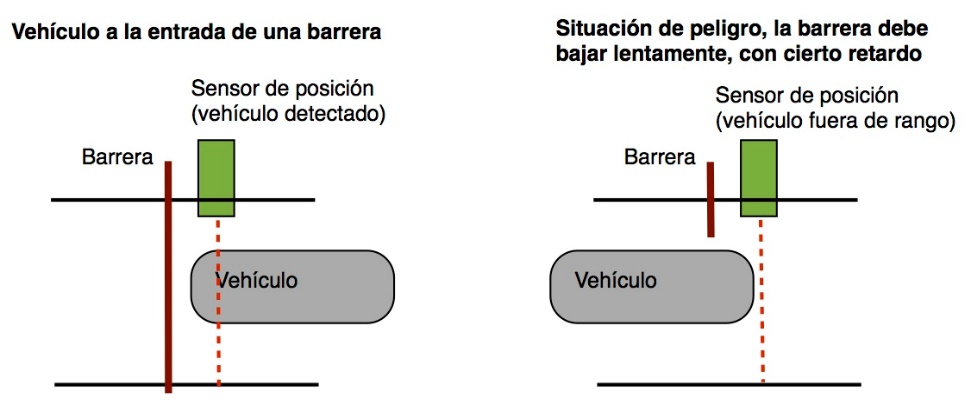
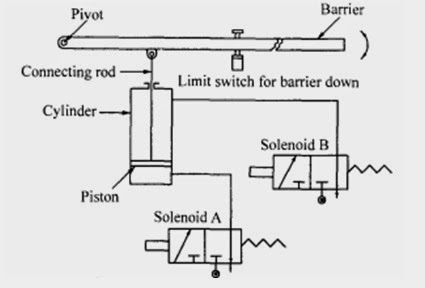
Felipe Alvarado Galicia Víctor Fabián Hernández Vidrio



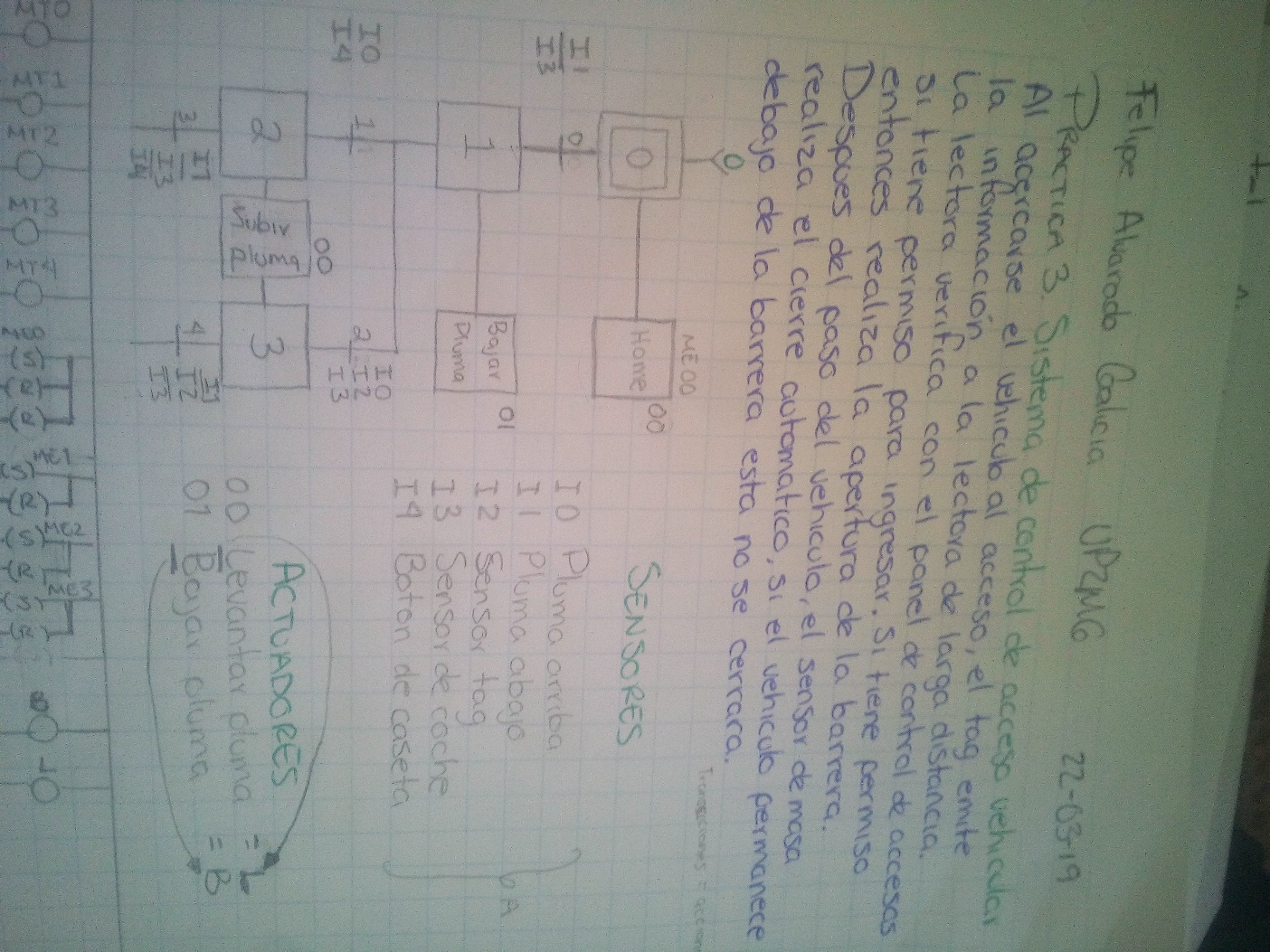
upzmg



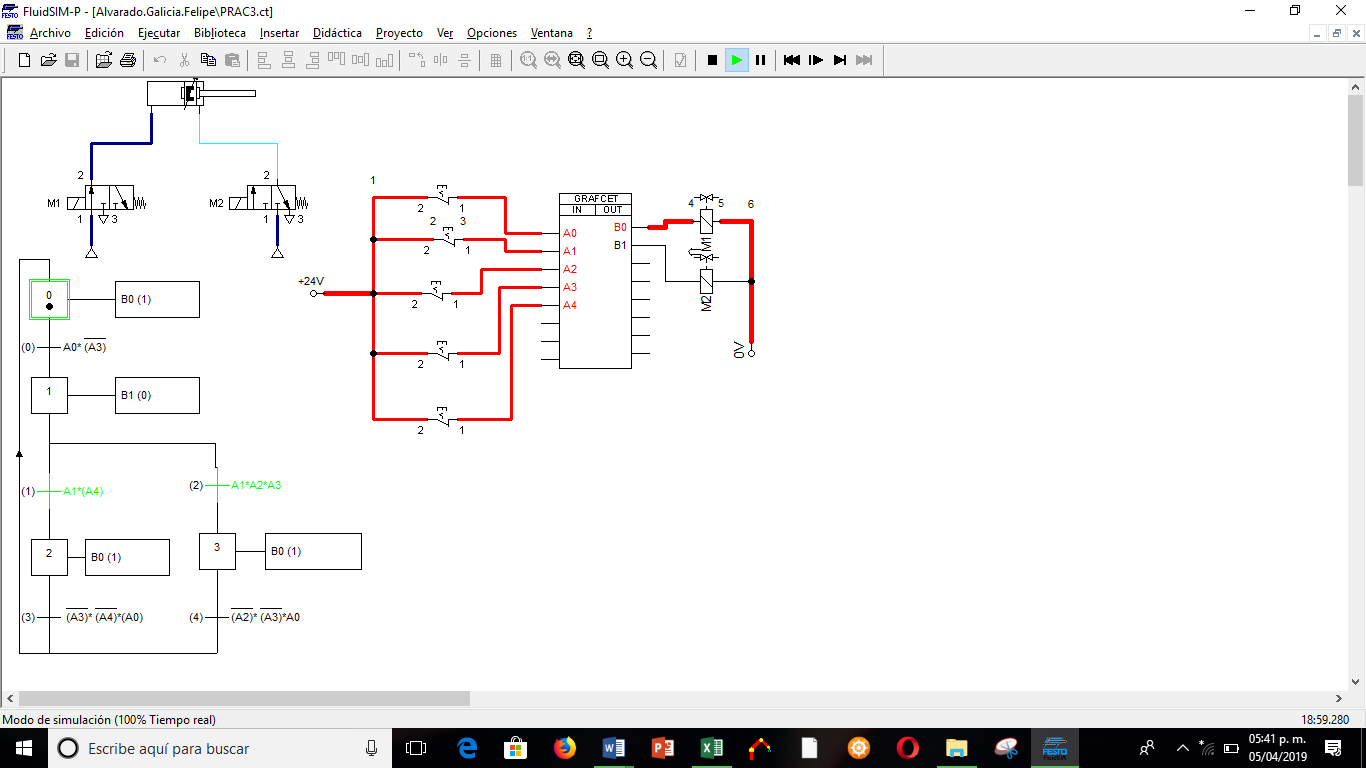
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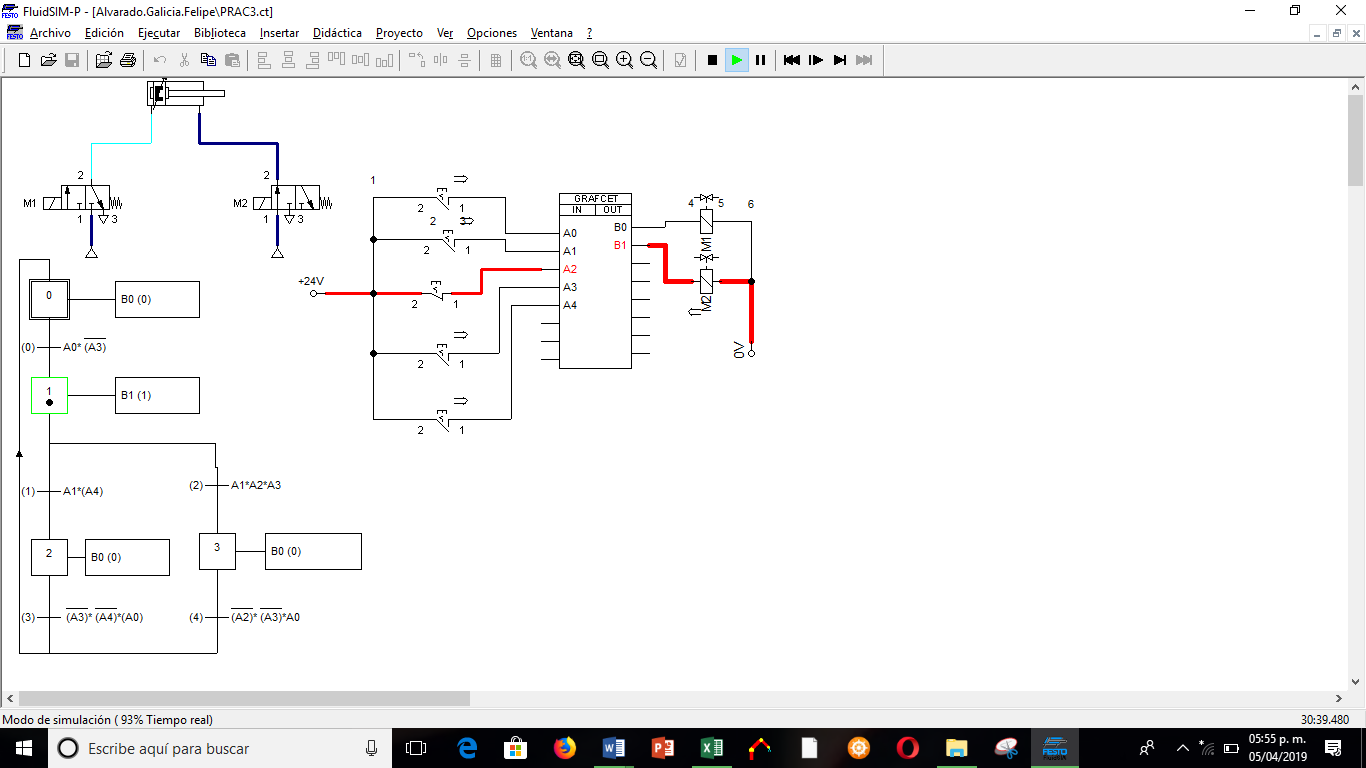
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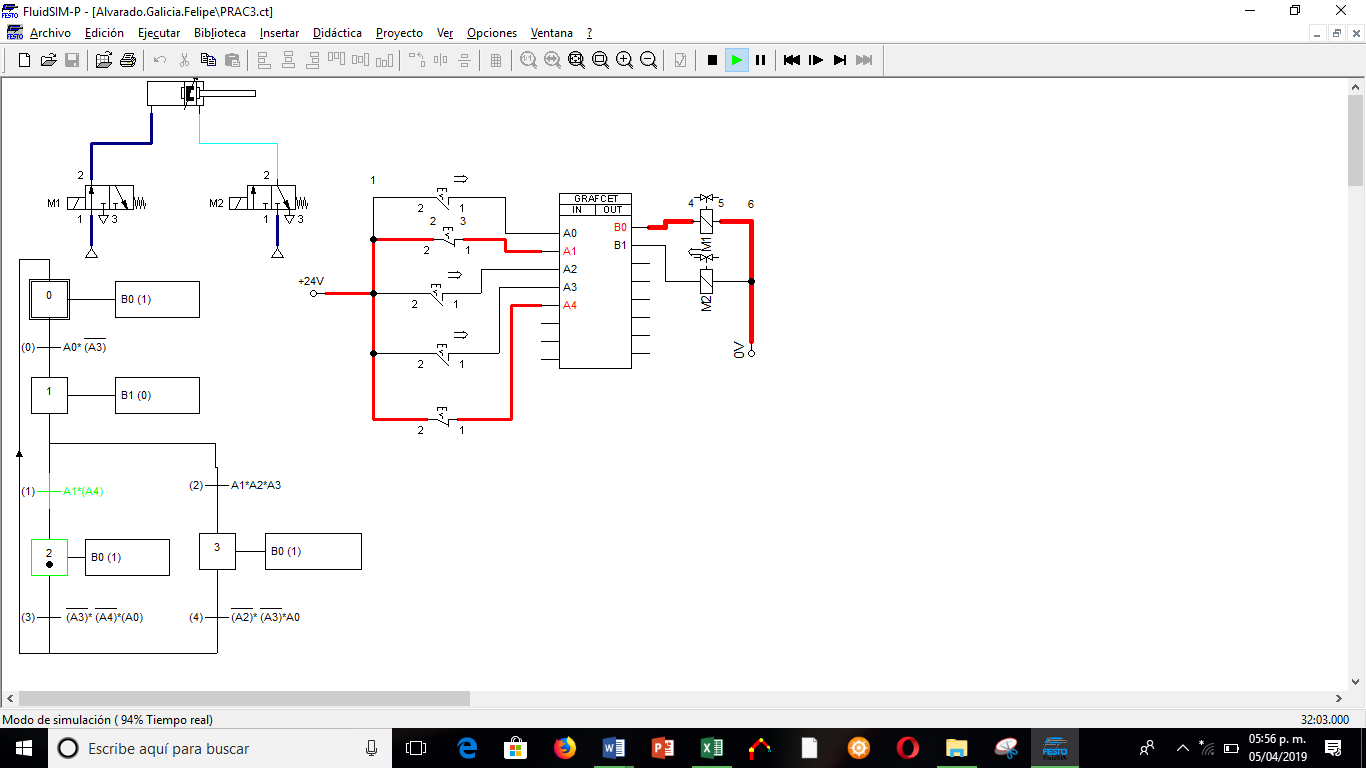
Primero declaramos las variables y despues hicimos el grafcet en papel

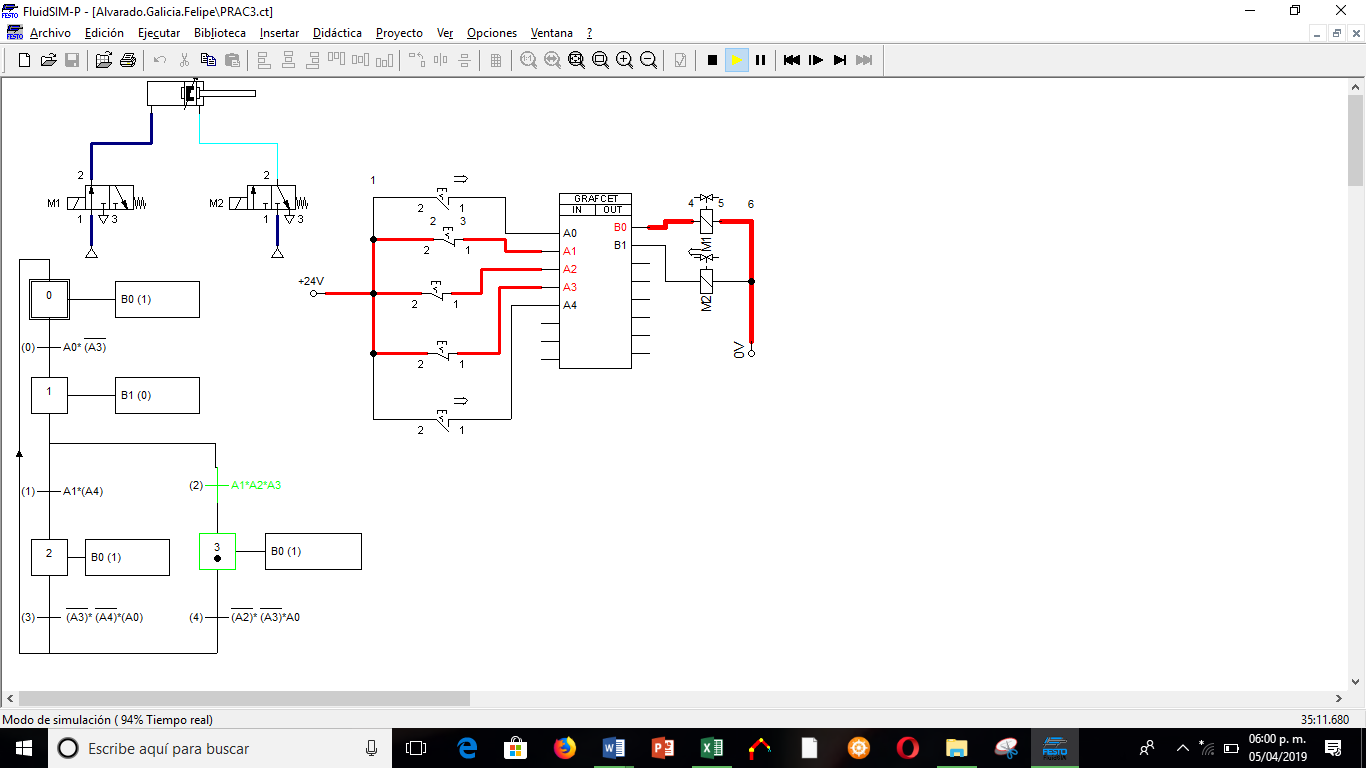
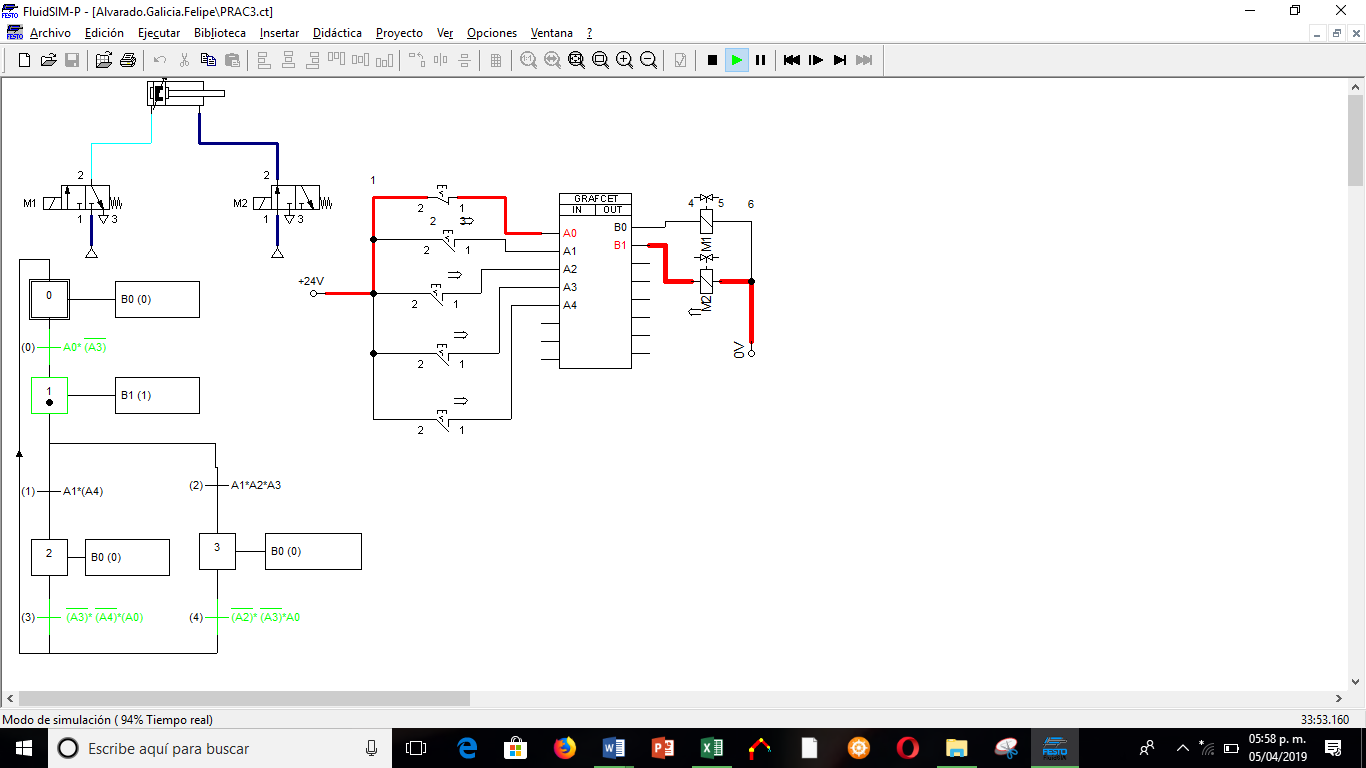


Y en seguida lo pasamos en fluidsim y en logiblab



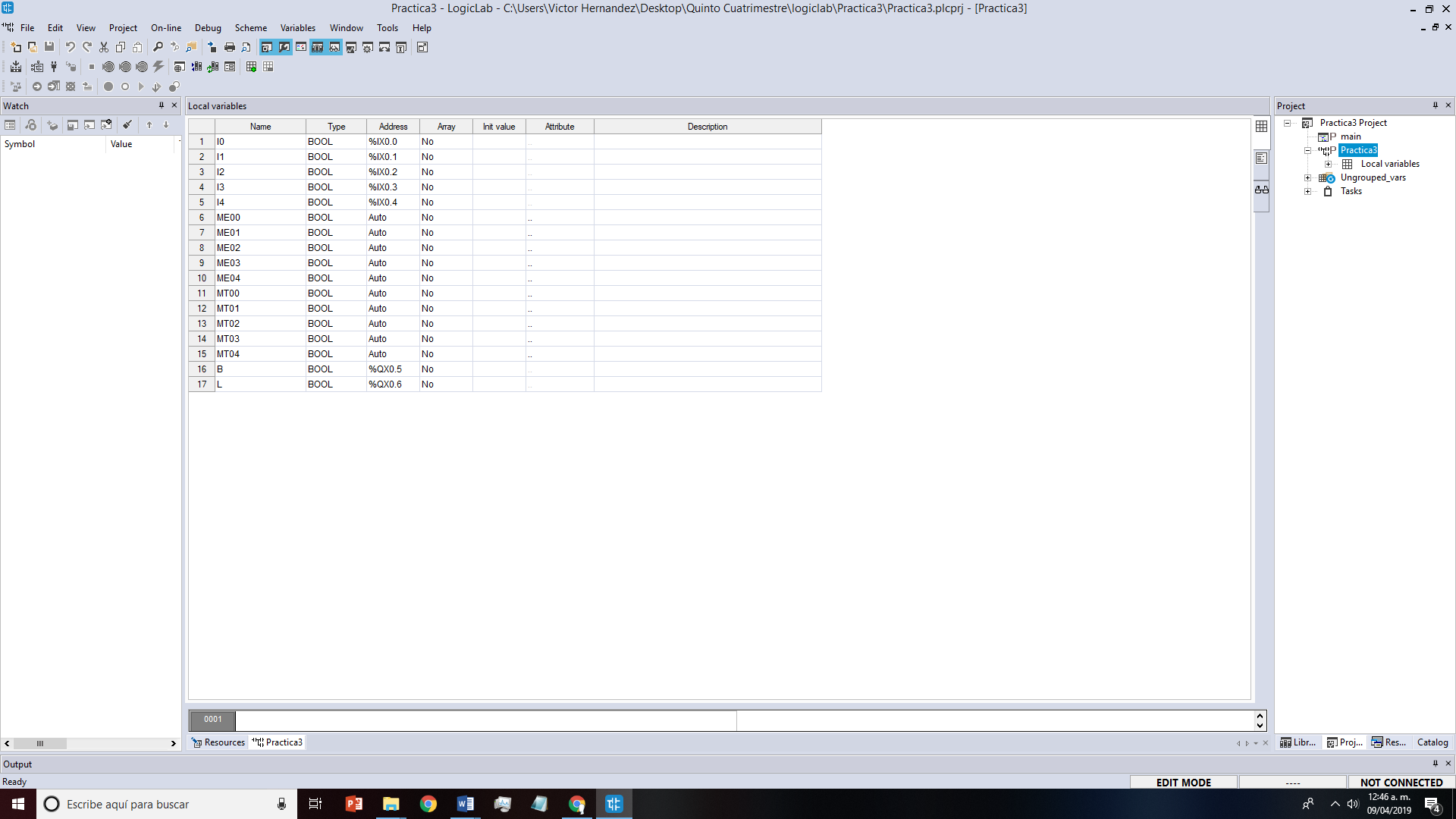






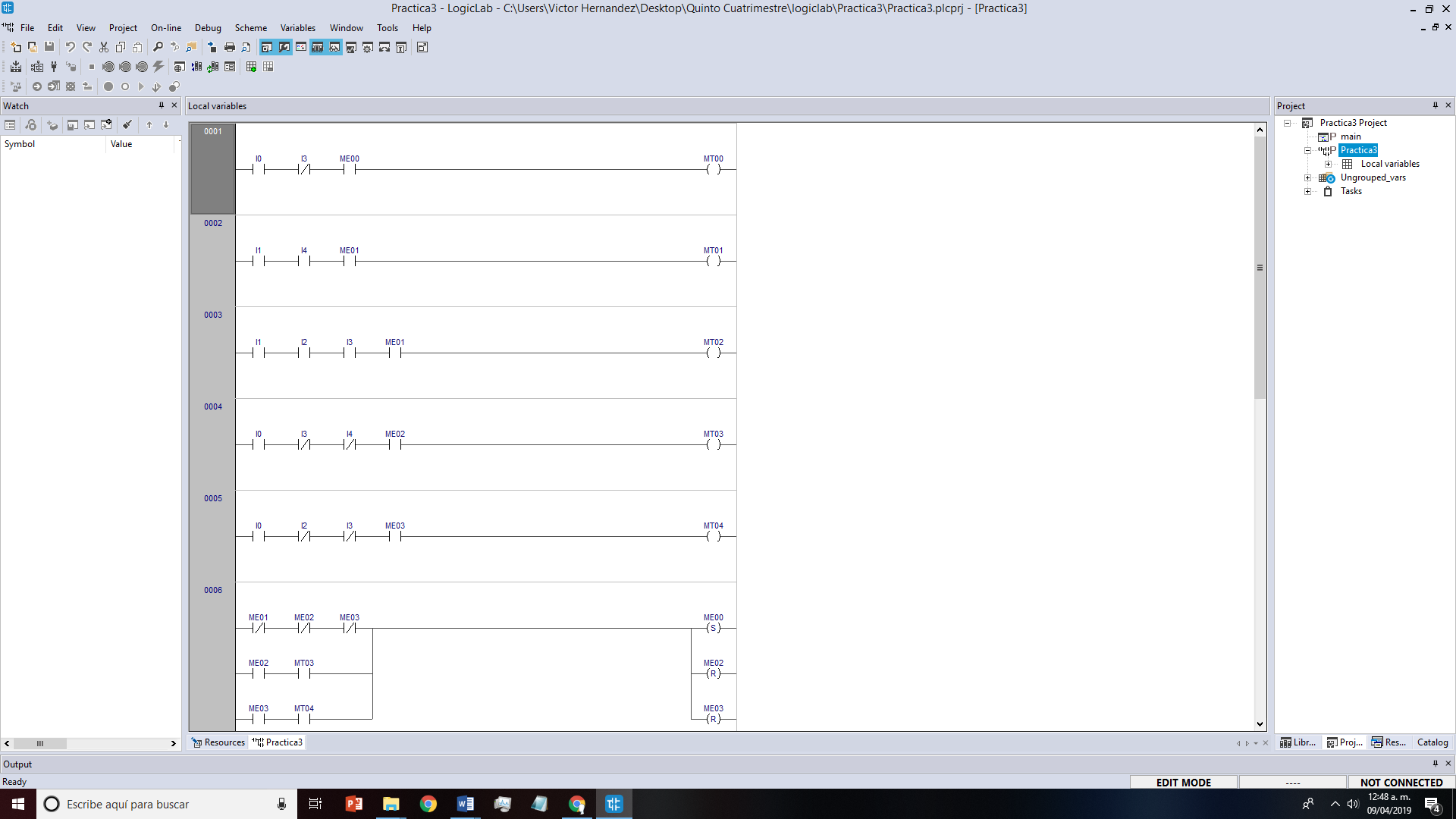
# Local Variables

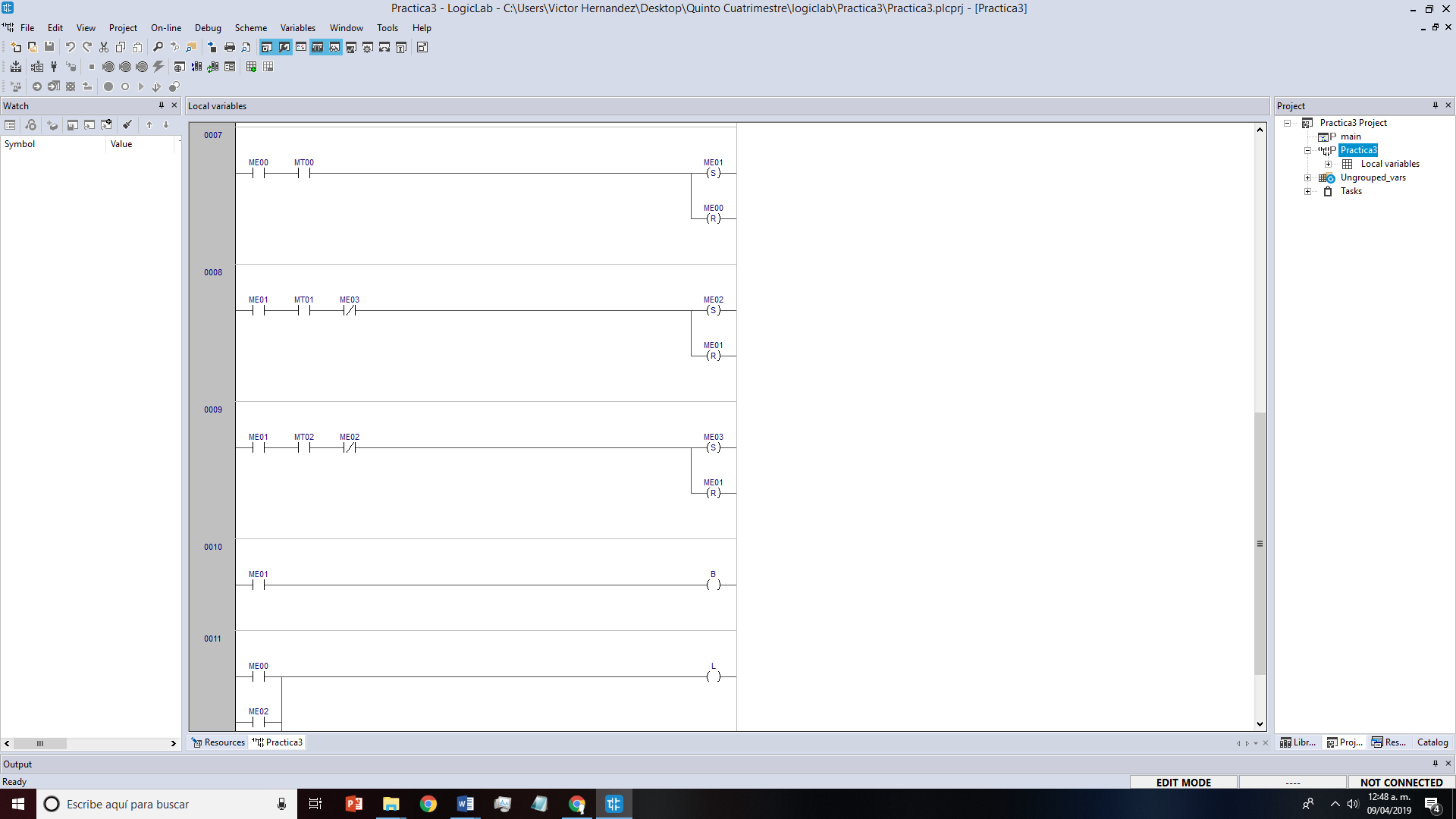
Se ingresa el nombre de la variable en el área Name.

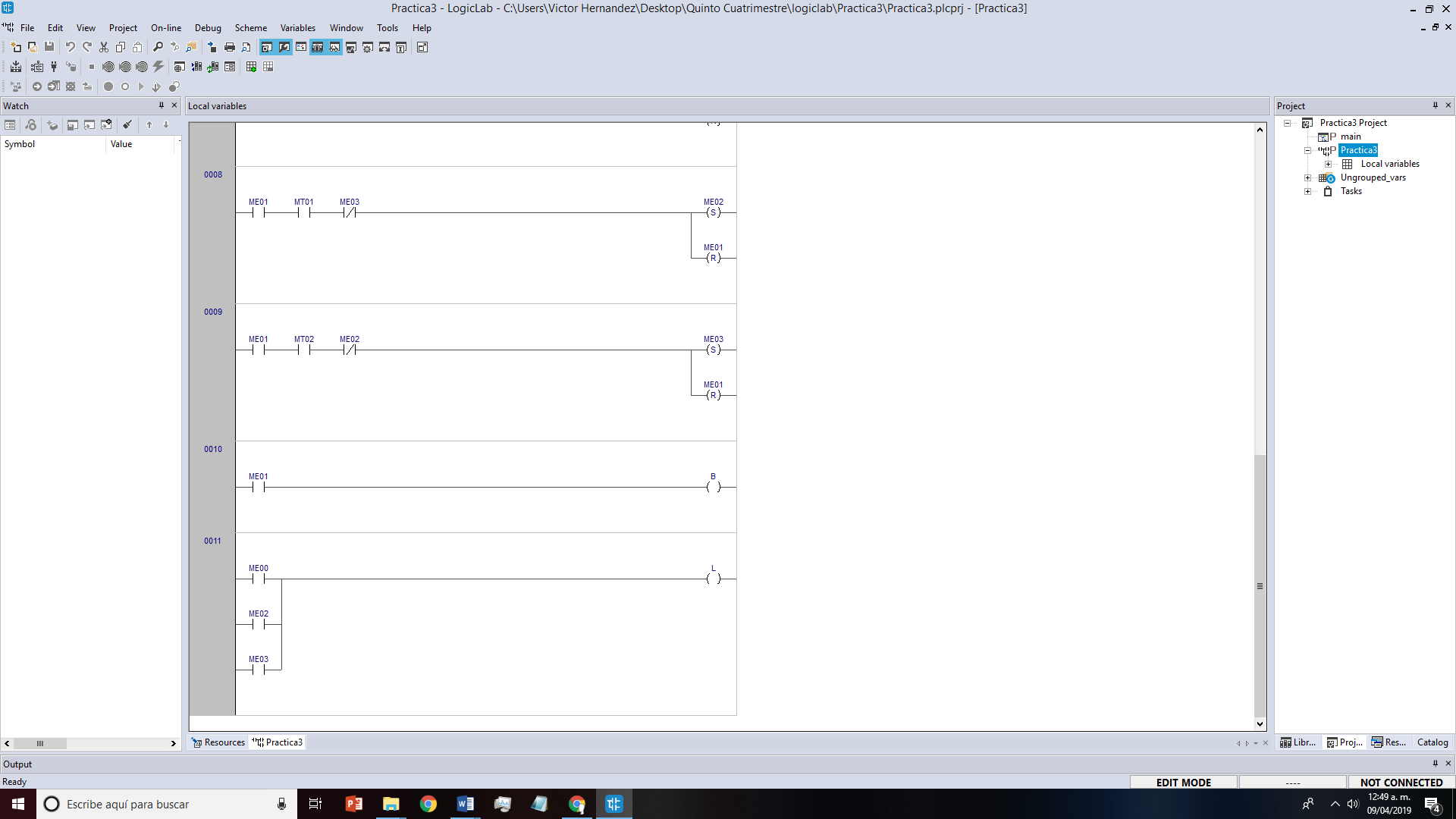


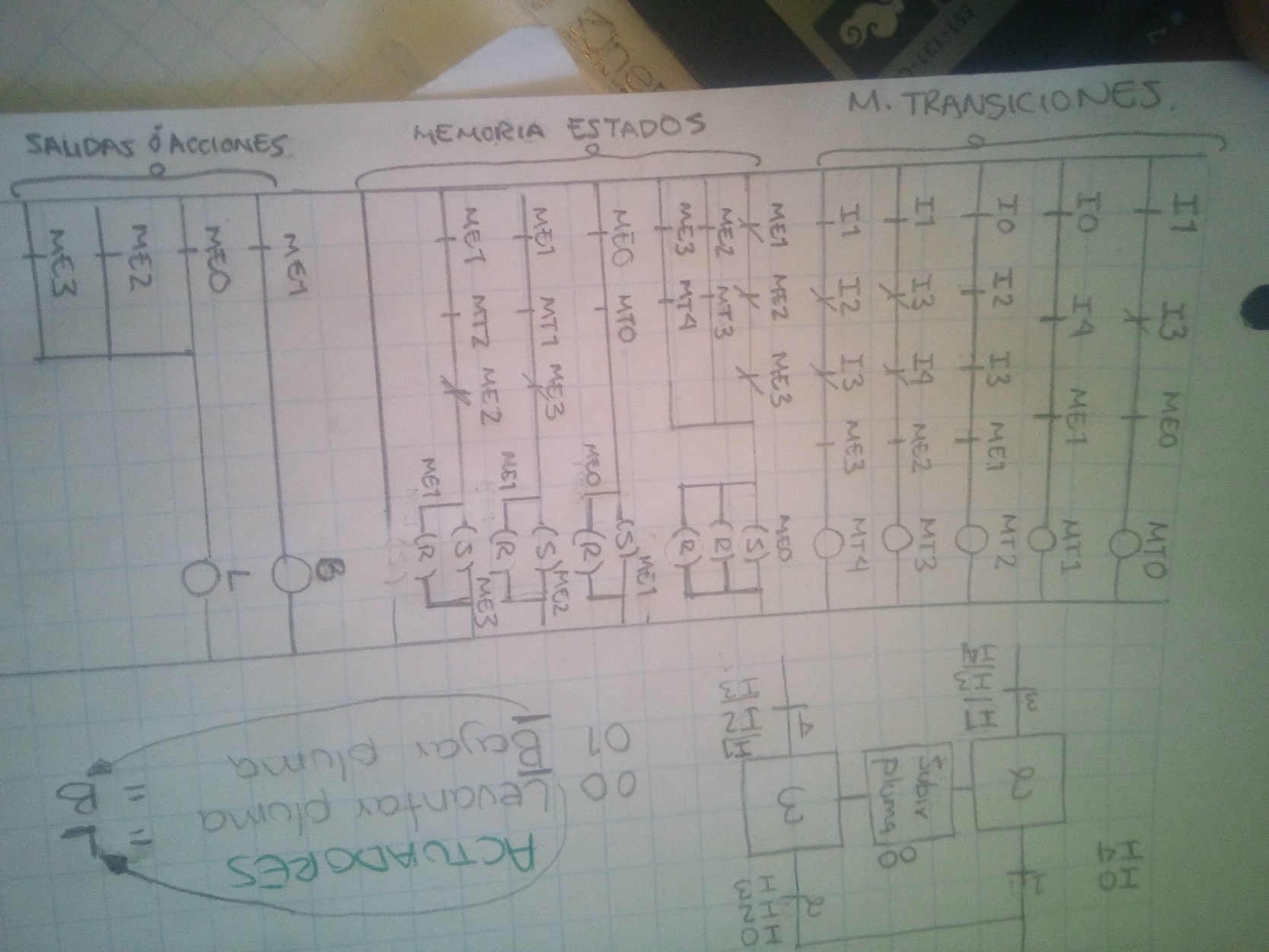
# Diagrama de Escalera

Se realiza el diagrama de escalera dependiendo de lo que se quiera realizar.



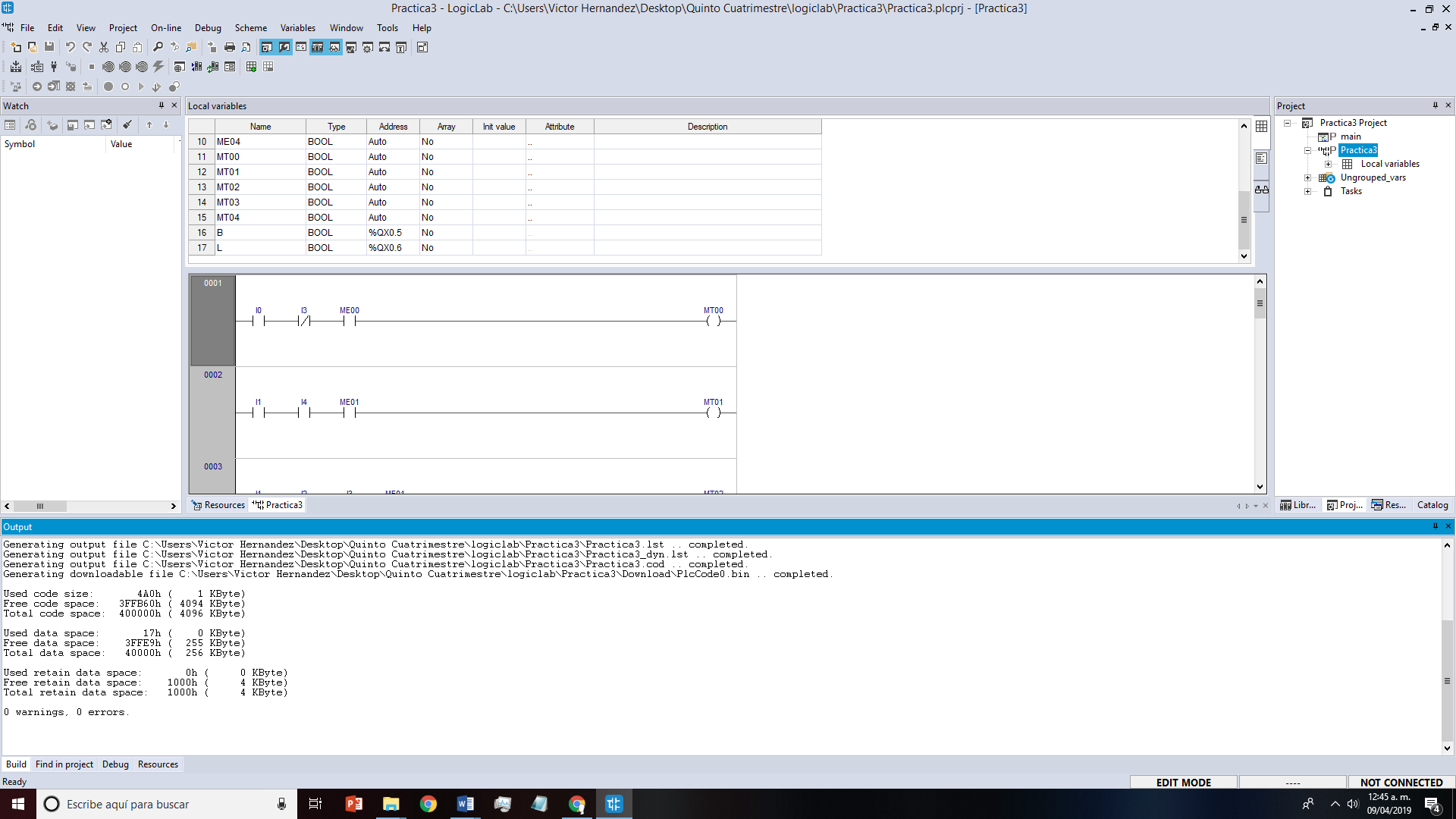






# Compilación

No se detectan errores en compilación.

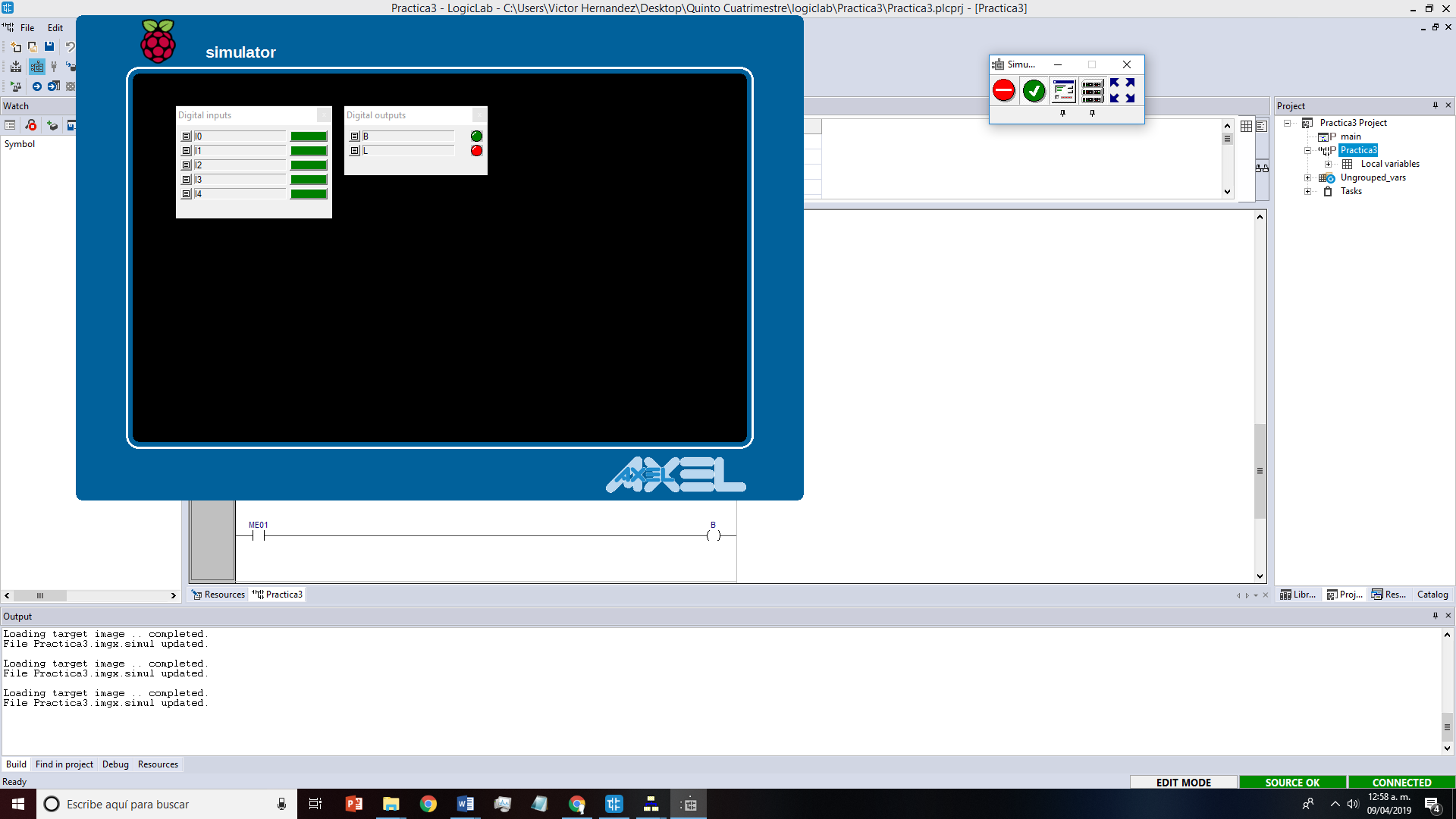


# Simulación

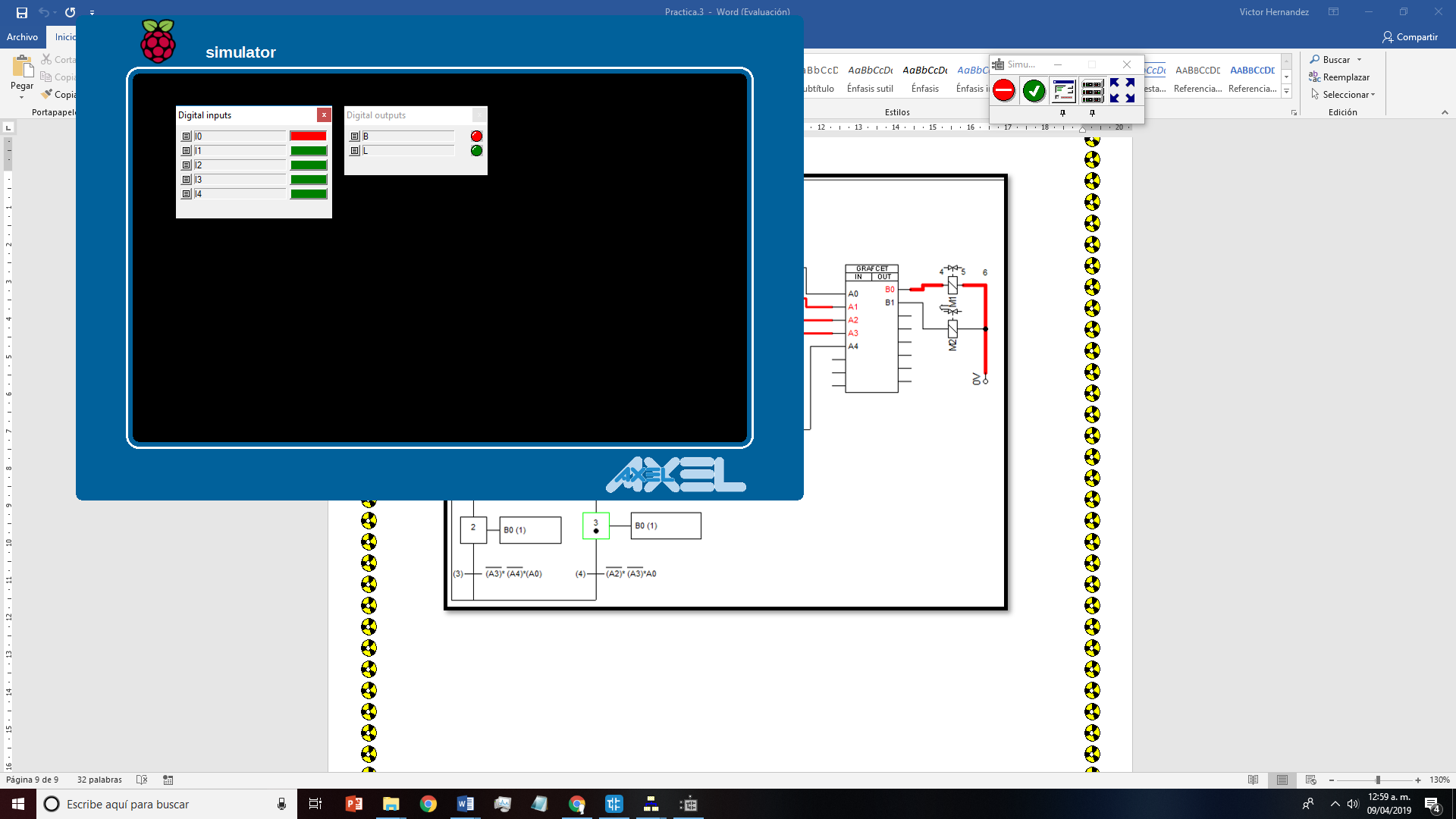
Home

L= Levantar pluma.

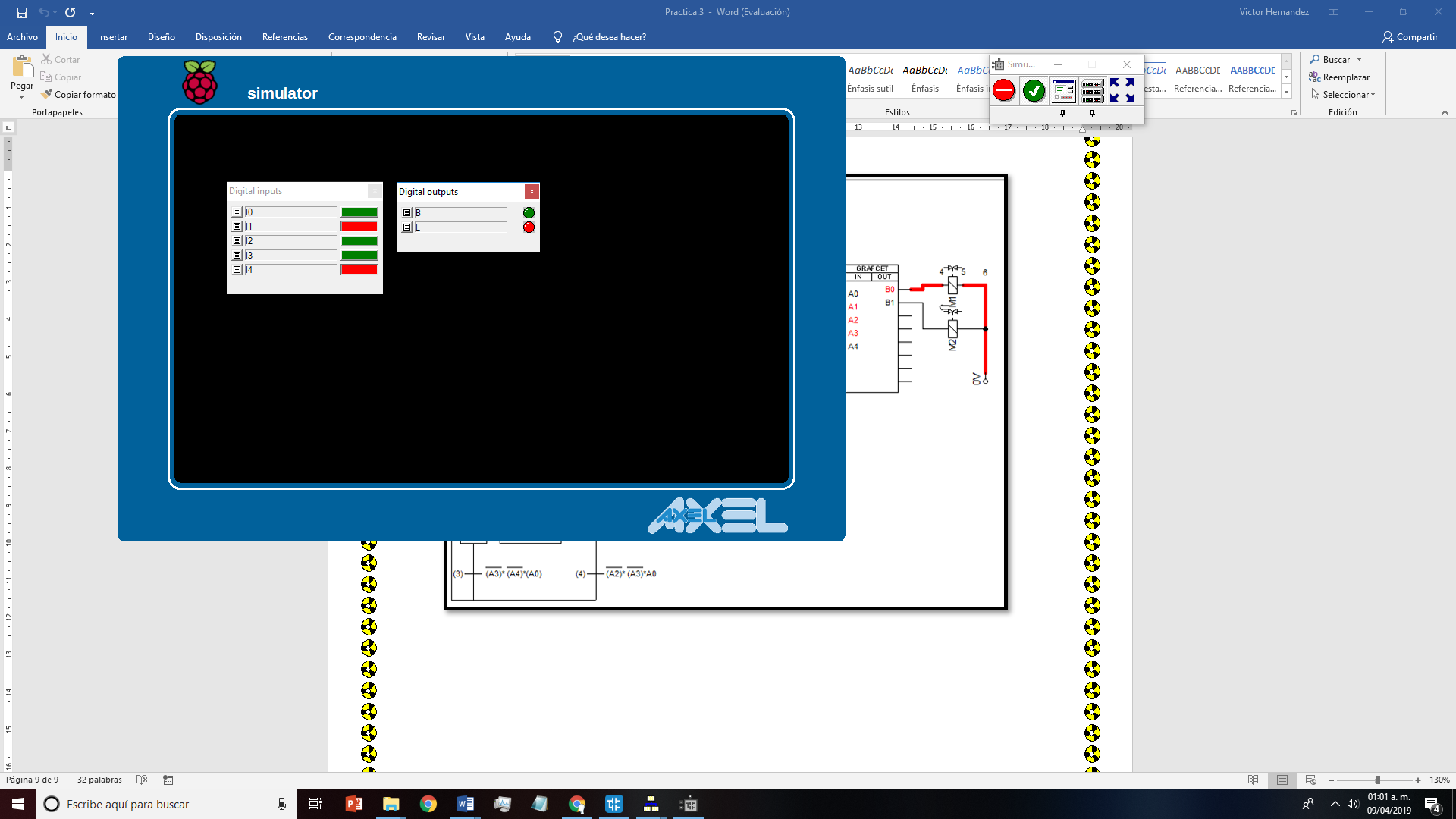
B= Bajar pluma.



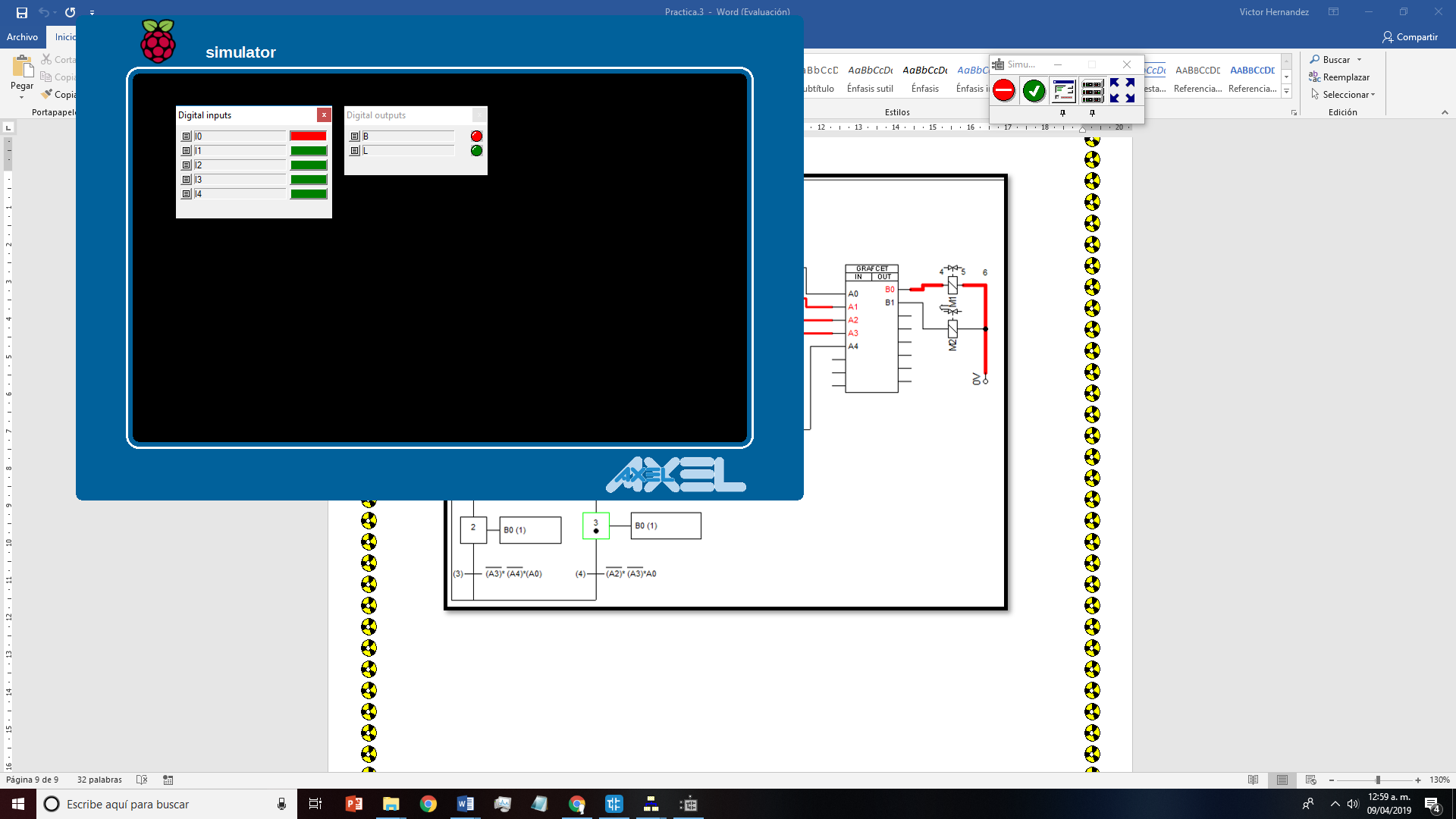
I0=Bajar Pluma.



I1+14=Levantar Pluma.



I0=Bajar Pluma.



I1+I2+I3= Levantar Pluma.

