```
ilename = Magnum Networking Communications Protocol.XLS
7-May-03 Update 10-Oct-03
Jpdate 23-May-05 add 0% charge rate and 250 VAC Dropout for ac disconnect for EMS support
pdate 28 March 2006 for new fault codes and new VAC dropout values
Jpdate Oct 06 for sending VACin and VAC output and new fault codes:
RELAY_FAULT
HARGER_FAULT
Jipdate Nov 06 for new battery sizes and new TCO FAULT

Jpdate Jan 23-07 added EOF (0xFF) value and third party notes.
Jpdate Apr-23-07 added (Ox91) CB3 open fault
Jpdate Aug-13-07 corrected VAC dropout values
pdate Oct-15-09 Added new packet information
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This is a definition of the "TCS" (Temp Comm Sys) for the "Charger" part of the Magnum Energy Inverter/Charger/Remote pair.

TCS-C is the "Charger/Inverter" end.

TCS-R is the "Remote" end.

OVERVIEW:

This implementation works as:

"Charger/Inverter" is the MASTER of communications, and will transmit its data once every 100ms. During this time TCS-C will:

- 1. Enable the RS-485 transmit driver
- 2. (internally) disable the Receiver (RE)
- 3. Reset the RECEIVE DATA POINTER
- 4. Reset the TRANSMIT DATA POINTER, and transmit 16 bytes of data.

- At the "end" of the transmission: 1. Disable the RS-485 transmit driver
 - 2. (internally) ENABLE the Receiver (RE)

On reception of bytes (from the Remote):

- 1. Store data sequentially
- 2. advance the RECEIVE DATA POINTER
- 3. after the 16th byte,

(internally) disable the Receiver (RE).

"Remote" is the SLAVE and responds to messages by transmitting its own message 10ms after the MASTER's message ends.

TCS-R operates in the following manner:
1. Receives bytes of data, storing to ram,

advancing the RAM_POINTER, and RESETTING the Rx_CLOCK (2ms step) to ZERO.

When Rx_CLOCK reaches 5 (10ms) do: 1. (internally) disable Receiver (RE), 2. enable the RS-485 transmit driver

- 3. reset the TRANSMIT DATA POINTER
- 4. reset the RECEIVE DATA POINTER
- 5. trigger the TRANSMITTER
- 6. Every fourth send extends data transmission with AGS or BMK settings

When the transmitter is complete:

- 1. disable Transmitter
- 2. disable the RS-485 transmit driver
- 3. (internally) enable the Receiver (RE)

When AGS clock reaches 10ms, or BMK clock reaches 14ms:

- 1. "Remote" receives bytes of data, storing to ram
- * Note: AGS and BMK do not communicate on every cycle
- * After sending an AGS a hex A0, or hex A1, the AGS will respond in the next cycle. (repeat)

Hardware definition of comm system:

This is a simple communications systems, where the physical

link is RS-485, which is defined as:

true 2 wire only

5V differential, half-duplex,

multi-drop up to 32 connected transceivers.

RJ-11 wiring on inverter is (from top to bottom):

1 = "B" RS485 comm

2 = +14

3= GND

4 = "A" RS485 comm

Comm rate = 19.2K BPS
Each bit time = about 50usec
Each byte = about 500usec
All 16 bytes = about 8 msecs
Time each packet is sent = about every 100 msecs

Communications from inverter and remote:

Every 100 msecs, the inverter sends a packet of data, one right after the other,

whether remote is connected or not.

MS rev 3.9 and earlier / All ME, RD, MM, MMS series Inverter sends 16 bytes of data
MS rev 4.0 and later Inverter sends 21 bytes of data

If remote is connected it will receive the packet and then after a short delay will begin

sending a packet back to the inverter.

ME-RC rev 1.4 and earlier / All MM-R, MM-RC, ME-RB, and ME-MR

ME-RC rev 1.5 and later / All ME-ARC

Remote sends 16 bytes of data

Remote sends 21 bytes of data

The definition of remote byte order:

Scope picture of comm string:



			<u> </u>
Inverter sends			
te order Data name	bits value assignments	Value sent to remote remote (hex)	Comments
0 Inverter status	8 Charger Standby	0x00	AC in, charging disabled
	EQMODE	0x01	// unit is eq'ing with ac
	FLOATMODE	0x02	// unit is float charging w/ac
	ABSORBMODE	0x04	// unit is charging in absorb w/ ac
	BULKMODE	80x0	// unit is charging in bulk mode with ac applied
	BATSAVERMODE	0x09	// unit is charge mode but no charge current since bat is full
	CHARGEMODE	0x10	// unit is in charge mode, no ac applied
	Off	0x20	// inverter off, charger off waiting for user input (no AC pass through)
	INVERTMODE	0x40	// inverter on (charger on or off)
	Inverter Standby	0x50	MS rev 4.0 or later only (PAE)
	SEARCHMODE	0x80	// searching for load (charger on or off)
1 Inverter fault	8 No Fault on inverter	0x00	// not used
	STUCKRELAY	0x01	
	DC_OVERLOAD	0x02	// DC bridge overload fault
	AC_OVERLOAD	0x03	// AC output overload fault
	DEAD BAT	0x04	// charging a dead battery
	BACKFEED	0x05	AC Backfeed
	LOWBAT	80x0	// low bat cutout
	HIGHBAT	0x09	// high bat cutout
	HIGHACVOLTS	0x0A	// high ac output voltage
	BAD_BRIDGE	0x10	// Remote displays = Internal Fault 1 = bad fet bridge
	NTC_FAULT	0x12	// Remote displays = Internal Fault 2 = fets too hot (>20C step)
	FET_OVERLOAD	0x13	// Remote displays = Fet Overload = FETS too hot too fast (6C over 4 sec)
	INTERNAL_FAULT4	0x14	// Not used
	STACKER_MODE_FAL	JLT 0x16	// Stacker fault, both units not in same mode, problem with "other" inverter
	STACKER_CLK_PH_FA	AULT 0x18	// Stacker sync clocks are not in phase
	STACKER_NO_CLK_F/	AULT 0x17	// Stacker does not detect other stackers sync clock
	STACKER_PH_LOSS_I	FAUL10x19	// Stacker AC output voltage is not properly phased
	OVERTEMP	0x20	// overtemp shutdown
	RELAY_FAULT	0x21	// Transfer relay is not closed in chg mode
	CHARGER_FAULT	0x80	// Bridge fault in chg mode = max PWM, no ac amps, Vbat < FloatV
	HIBATEMP	0x81	// high battery temp
	OPEN SELCO TCO	0x90	// open transformer TCO temperature cutout
	CB3 OPEN FAULT	0x91	// open input 30 amp AC Breaker CB3
2.2 DC walks	40* 0.041/		0.04/2 0.0400.01/ and accept/ 0.41/ (real reports 0.400.01/)
2,3 DC volts	16* 0-64K 16* 0-64K		0-64K = 0 - 6400.0V or 1 count/ 0.1V (real range = 0-100.0V) 0-500 amps DC
4,5 DC amps			
6,7 (was) Ac amps NOT IMPLE	N 16* 0-64K 8		NOT Implemented
6 (is) AC volts output			0-150 Volts ac RMS MS Inverter rev 3.0 and later
7 (is) AC volts input	8		0-255 Volts ac peak MS Inverter rev 3.0 and later
8 Inverter LED	8		IF = 0, then INV LED is off else INV Led on remote ON
9 Charger LED	8		IF = 0, then CHG LED is off else CHG Led on remote ON
10 Inverter Revision	8 0 to 256		i.e. 10 = 1.0 Non-zero is mandatory for remote i.e. 11 = 1.1 start up
11 Battery temp	8		0-150 = 0-150 deg C
11 Battery temp 12 Transformer temp	8 8		0-150 = 0-150 deg C 0-150 = 0-150 deg C

14 Inverter Model

Model	Dec	Hex
MM612	6	0x06
MM612-AE	7	0x07
MM1212	8	0x08
MMS1012	9	0x09
MM1012E	10	0x0A
MM1512	11	0x0B
ME1512	15	0x0F
ME2012	20	0x14
ME2512	25	0x19
ME3112	30	0x1E
MS2012	35	0x23
MS2012E	40	0x28
MS2812	45	0x2D
MS2712E	47	0x2F
MM1324E	53	0x35
MM1524	54	0x36
RD1824	55	0x37
RD2624E	59	0x3B
MM1x24E	60	0x3C
RD2824	63	0x3F
RD4024E	69	0x45
RD3924	74	0x4A
MS4124E	90	0x5A
MS2024	91	0x5B
MS4024	105	0x69
MS4024AE	106	0x6A
MS4024PAE	107	0x6B
MS4448AE	111	0x6F
MS3748AEJ	112	0x70
MS4448PAE	115	0x73
MS3748PAEJ	116	0x74

Not a currently release model

15 Not used	0	MS rev 3.9 and earlier / All ME's
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15 Stack mode	8 Standalone unit	0x00	MS rev 4.0 and later
	Parallel stack - master	0x01	
	Parallel stack - slave	0x02	
	Series stack - master	0x04	
	Series stack - slave	80x0	
16 AC Input Amps	8		1 count = 1 Amp AC
17 AC Output Amps	8		1 count = 1 Amp AC
18,19 AC Hz	16*		1 count = 0.1Hz
20 Not used	8	0	

16* = NOTE that for all 16 bit variables, they are sent in two bytes, the high byte sent first. So for DC volts, high byte is sent in third position (byte 2) and low byte is sent in fourth position or byte 3.

Remote sends							
Byte order Data name	bits	value assigr	nments	Value sent to	Comments		
				inverter (decimal)			
0 Inverter ON/OFF	4, low or	der	Bit 0, mome		Toggle inverter on/off		
Charger ON/OFF			Bit 1, mome	entary high	Toggle charger on/off (only	y when AC is in use)	
Future use			Bit 2 = 0		Not used		
EQ Mode				0A), momentary high	Toggle EQ mode (only wh	en AC is in use, only i	n float mode)
Future use	4, high c	order	Bit $4 - 7 = 0$		Not used		
1 Search watts		8 Defeated		0			
		5W	(default)	5			
		5 - 50 Watts	, ,	5 - 50			
2 Battery size		8			1 count = 10Amp hours; Ir	overter accepts increm	nents of 20, from 20-160
,		400Ah	(default)	40	ME-RC		
		200Ah	(default)	20	MM-RC / MM-R 3.6		
3 Battery Type		8 Gel		2			
o Ballery Type		Flooded	(default)	4			
		AGM	(======)	8			
		AGM2		10			
Absorption, if set to 0	Custom	Custom		100+	This becomes Absorption;	144 = 14.4 volts.	Inv rev x.x and later
4 Charger Amps		8 0%	6	0	Must be in steps of 10	0% in Inv rev x.x	and later
0 ,		10%	6	10	·		
		20%	6	20			
		30%	6	30			
		40%	6	40			
		50%	6	50			
		60%	6	60			
		70%	6	70			
		80%	6 (default)	80			
		90%	6	90			
		100%	6	100	Maximum, inverter will def	ault to 80 if any other	value is sent

	5 AC shore amps	8 30A	(default)	30	Range is 5 - 60,	in steps of 1
	6 Remote revision	8	1.0	10	i.e. 10 = 1.0 * MM-R & MM-R ** ME-RB starts	
				*** If using a BMK, the re		ater than 1.8, or the BMK will not communicate
	7 Ambient temp	8		0-150 = 0-150 deg C		
	7 Parallel threshold /	4, low order		BIT 0-3	Parallel threshold	d 1 count = 10% of unit capacity
	Force Charge	4, high order		BIT 4	Disable Refloat	
				BIT 5	Force Silent	
				BIT 6	Force Float	
				BIT 7	Force Bulk	
	8 Auto Genstart	8 Off	(default)	0		
		Enable		1	Allow Auto Gen	Start
		Test		2		
		Enable with	n Quiet Time	4	Don't start during	g quiet time hours
		On		5	Only in AGS rev	v 5.0 and later
	9 Low Battery Cut Out (LBCO)	8 10.0 volts	(default)	100	Range 9.0 to 16.	.0 (90 to 160 sent to Inverter)
	** 24 volt values	20.0 volts	(default)	200	Range 19.0 to 25	5.5 (190 to 255 sent to inverter)
	*** 48 volt values	40.0 volts	(default)	200	Same range as 2	24volt, display shows double the value sent.
	10 VAC cut out voltage	8 60VAC		110	Range is 0 to 25	5, but is not linear
		65V		122	Export models (2	230 VAC/50 Hertz) have the same range, just
		70V		135	double the displa	ayed AC voltage
		75V		145		
		80V	(default)	155		
		85V	, ,	165		
		90V		175		
		95V		182		
		100V		190		
		"EMS over	-ride- open relay"	255	This will cause in	nverter to ignore AC input
	11 Float Volts	8 13.2 volts	(default)	132	Scaled to 12 volt	t numbers; 0.1 = 1
	12 EQ Volts	8 15.6 volts	(default)	12	Range is 0 - 2.0	volts (0 - 20), this is added to Absorption voltage
	13 Absorb Time	8 2.0 hrs	(default)	20	x.x hrs; 0-255, 2	5 would be two and half hours; 0.1 hr = 6 minutes
	14 Hours	8			0 - 23 hours	Remote always sends Hours
	15 Minutes	8			0 - 59 minutes	and minutes, unless otherwise noted
Bytes 1	6-20 were added for AGS	in ME-RC Rev 1.5 and	later.	Works with AGS revisi	on 3.5 and later	
	16 Gen run time	8 2.0 hrs	(default)	20		5 would be two and half hours; 0.1 hr = 6 minutes
1	17 Start Temp	8 Off	(default)	0		Fahrenheit (33 - 104); cooling only
1	40 Ctart VDC	0.0#	(40.44.1)	0		t according to 10-1, cooling only

Bytes 16-20 were added for AGS in	Bytes 16-20 were added for AGS in ME-RC Rev 1.5 and later.			ision 3.5 and later
16 Gen run time	8 2.0 hrs	(default)	20	x.x hrs; 0-255, 25 would be two and half hours; 0.1 hr = 6 minutes
17 Start Temp	8 Off	(default)	0	Range 33 to 104 Fahrenheit (33 - 104); cooling only
18 Start VDC	8 Off		0	Scaled to 12 volt numbers; 0.1 = 1
	11.0 volts	Default	110	Range, 1 to 255
19 Quiet time hours	8 Off	Default	0	
	9pm to 7am		1	** AGS revision 5.0 and later use this byte to enable quiet time
	9pm to 8am		2	
	9pm to 9am		3	
	10pm to 8am		4	
	11pm to 8am		5	
20 Footer	8		0xA0 Hex	Bytes 14 through 19 can be used to communicate to other
				network devices. Byte 20 is used to address the device.

Bytes 14-20 were added for AGS in ME-ARC.		GS revision 5.0 and later		
8 12:00A	Default	0	0 = 12:00 AM one count = 15 minutes	
8 12:00A	Default	0	* If start/stop are set the equal, function is disabled	
8 14.4v	Default	144	Voltage scaled in 12 numbers	
Float		255	Stop on inverter float mode	
8 120 Sec	Default	120	MSB bit controls minute/second selection; Range 0 - 127	
120 Min		248	MSB = 1 = Minute; MSB = 0 = Seconds	
8 120 Sec	Default	120	All "delays" use the above format	
8 12.0 hrs	Default	120	x.x hrs; 0-255, 25 would be two and half hours; 0.1 hr = 6 minutes	
8		0xA1 Hex		
	8 12:00A 8 12:00A 8 14.4v Float 8 120 Sec 120 Min 8 120 Sec 8 12.0 hrs	8 12:00A Default 8 12:00A Default 8 14.4v Default Float 8 120 Sec Default 120 Min 8 120 Sec Default 8 120 Sec Default	8 12:00A Default 0 8 12:00A Default 0 8 14.4v Default 144 Float 255 8 120 Sec Default 120 120 Min 248 8 120 Sec Default 120 8 12.0 hrs Default 120	

es 14-20 were added for AGS in	ME-ARC	Works with A	GS revision 5.0 and later	
14 AGS SOC Start	8 Off	Default	0	1 count = 1%
15 AGS SOC Stop	8 90%	Default	90	1 count = 1%
16 AGS Amps Start	8 Off	Default	0	1 count = 1 Amp
17 AGS Amps Start	8 120 Sec	Default	120	MSB bit controls minute/second selection; Range 0 - 127
Delay				MSB = 1 = Minute; MSB = 0 = Seconds
18 AGS Amps Stop	8 5 amps	Default	5	1 count = 1 Amp
19 AGS Amps Stop	8 120 Sec	Default	120	MSB bit controls minute/second selection; Range 0 - 127
Delay				MSB = 1 = Minute; MSB = 0 = Seconds
20 Footer	8		0xA2 Hex	

Bytes	14-20 were added for AGS in MI	E-ARC	Works with A	GS revision 5.0 and later	
	14 AGS Quiet Time begin	8 8:00P	Default	80	0 = 12:00 AM one count = 15 minutes
	15 AGS Quiet Time end	8 10:00A	Default	40	0 = 12:00 AM one count = 15 minutes
					** Byte 19 in footer A0 must be set to 1 to enable function
					* If begin/end are set equal, function is disabled
	16 AGS Exerise Days	8 Off	Default	0	1 Count = 1 Day; Range 0 - 255
	17 AGS Exerise Start Time	8 8:00A	Default	32	0 = 12:00 AM one count = 15 minutes
	18 AGS Exerise Runtime	8 1.0 hrs		10	x.x hrs; 0-255, 25 would be two and half hours; 0.1 hr = 6 minutes
	19 Top off	8 Off	Default	0	1 count = 1 minute; Range 0 - 255
	20 Footer	8		0xA3 Hex	

Bytes 14-20 were added for AGS in I	ytes 14-20 were added for AGS in ME-ARC		GS revision 5.0 and later	
14 AGS Warm up	8 60 Sec	Default	60	MSB bit controls minute/second selection; Range 0 - 127
				MSB = 1 = Minute; MSB = 0 = Seconds
15 AGS Cool down	8 60 Sec	Default	60	MSB bit controls minute/second selection; Range 0 - 127
				MSB = 1 = Minute; MSB = 0 = Seconds
16 Empty / Not used	8		0	Possible future settings
17 Empty / Not used	8		0	
18 Empty / Not used	8		0	
19 Empty / Not used	8		0	
20 Footer	8		0xA4 Hex	

Bytes 16-20 were added for BMK in	rtes 16-20 were added for BMK in ME-RC Rev 1.7 and later.			rision 1.0 and later
16 Battery efficiency	8 Auto	Default	0	1 count = 1%
17 Resets	8		0	Normal running
			1	Reset minimum volts DC
			2	Reset maximum volts DC
			3	Reset Amp Hour "Trip"
			4	Reset KAmp Hours
18 Battery size	8 400Ah	Default	40	1 count = 10 Amp Hours; 200 amp hour minimum
19 Empty / Not used	8		0	
20 Footer	8		0x80 Hex	

ME-AGS Send	ds						
	AGS t	transmits every time a remote transmits a footer 0xA0 or 0xA1 hex					
Only revision 3.5 and later of	communicate	es on the network					
te order Data name	bits	value assignments	Value sent	Comments			
0 Header		8	0xA1 Hex				
1 Status		8 Not valid	0	No Comm on remote			
		Off	1	Not enabled			
		Ready	2	Enabled			
		Manual Run	3	Generator manually started			
		AC In	4	Inverter is in charge mode			
		In quiet time (hours)	5				
		Start in test mode	6	30 second run, then shutdown			
		Start on temperature	7				
		Start on voltage	8				
		Fault start on test	9				
		Fault start on temp	10				
		Fault start on voltage	11				
		Start Time of Day	12				
		Start State of charge	13	SOC comes from BMK			
		Start Exercise	14				
		Fault start Time of Day	15				
		Fault start State of charge	16				
		Fault start Exercise	17				
		Start on Amp	18				
		Start on Topoff	19				
		Not used	20				
		Fault start on Amp	21				
		Fault on Topoff	22				
		Not used	23				
		Fault max run	24	Max run time exceeded			
		Gen Run Fault	25				
		Gen in Warm up	26				
		Gen in Cool down	27				
2 Revision		8 5.0	50	i.e. 10 = 1.0 Started TX at 3.5			
3 Temperature		8 33 to 104		In degrees Fahrenheit (33-104F)			
4 Gen Runtime		8 0.0 Hours	0	Gen running for h.m, so 2.5 would be two and half hours x.x hrs; 0-255, 25 would be two and half hours; 0.1 hr = 6 minutes			
5 AGS vdc		8 12.6	126	xx.x VDC (Scaled to 12V numbers)			

0 Header	8	0xA2 Hex	
Days since last generator run	8 0 days	0	0 - 255 days
2 Empty / Not used			
3 Empty / Not used			
4 Empty / Not used			
5 Empty / Not used			

	ME-RTR Sends				
Byte orde	r Data name	bits	value assignments	Value sent	Comments
(0 Header		8	0x91 Hex	
:	2 Revision		8 1.0	10	i.e. 10 = 1.0 i.e. 11 = 1.1
TR TX ev	very 0.5 seconds	with a deadti	me of 18msec after		1.6. 11 – 1.1

te order Data name bit	s value	assignments	Value sent	Comments
0 Header	8		0x81 Hex	8 means ME-BMK
1 State of Charge	8			0-100 - 0 - 100% or 1 count / 1% (255 = Think'n)
2,3 DC volts	16* 12.60	volts	1260	0-64K = 0 - 640.00V or 1 count/ 0.01V (real range = 0-70.00V)
4,5 DC amps	16*	10.1	101	0-64K = -3.2K to 3.2KAmps or 1 count/ 0.1A (real range +-1000A)
6,7 Min Volts	16* 12.61	volts	1261 gVDC	0-64K = 0 - 640.00V or 1 count/ 0.01V (real range = 0-70.00V)
8,9 Max Volts	16* 12.59	volts	1259 gVDC	0-64K = 0 - 640.00V or 1 count/ 0.01V (real range = 0-70.00V)
10,11 AmpH in/out	16* 220 A	Amp Hr	220	0-64K = -32K to 32KAmpH or 1 count/ 1AmpH (real range = -9999 to 9999 AmpH)
12,13 AmpH Trip	16*	220.2	2202	0-64k = 0 to 6.4kAmpH or 1 count/ 0.1AmpH
14,15 Cumulative AmpH out (16*			0-64k = 0 to 6.4MAmpH or 1 count/ 100AmpH
,17 Number of Discharge C 16	<u>*</u>			0-64k - 1 count / 1 Discharge Cycle
18 Software Ver	8 0 to 2	256	Version	
16 Revision	8 0 to 256			i.e. 10 = 1.0
17 Fault	8 Rese	rved	0	

16* = NOTE that for all 16 bit variables, they are sent in two bytes, the high byte sent first. So for DC volts, high byte is sent in third position (byte 2) and low byte is sent in fourth position or byte 3.

Third Party Notes

If your company is considering building a product to connect to the Magnum Network:

- Please contact someone in the Engineering Department at Magnum for approval.
 Understand that no power is available for third party devices on the network.
 You should design your product so that it looks like a "wire" to the network. This is so that the timing of the data is not affected adversely and so that the devices on the network will operate properly. Also, when your product is off or not operational, it will not affect existing communication on the network.