Operating Systems ECE344

Lab assignment 1: Synchronization

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Overview of the lab assignment

- Task 1: implementing synchronization primitives
 - 1a: implement lock
 - 1b: implement condition variable
- Task 2: use synchronization primitives to solve problems
 - 2a: Mice and cats
 - 2b: traffic lights

Lock and cond. var.

```
V(sem) {
  Disable interrupts;
  sem->count++;
  thread_wakeup (sem); /* this will wake
     up all the threads waiting on this
     sem. Why wake up all threads? */
  Enable interrupts;
}
```

- Needs atomic region
 - Atomic region can be done in a similar way to semaphore
- If you understand how semaphore is implemented, should be trivial!
 - Cannot use semaphore to implement lock or cond. var.

Synchronization problems

- How to start?
 - First: write operation code
 - Next: carefully reason about all the possible interleaving and timing scenarios
 - Add synchronization

Mice and cats

- Two bowls, multiple cats and mice
- Safety criteria:
 - If a cat is eating at either dishes, no mouse can eat
 - If a mouse is eating at either dishes, no cat can eat

Operation code

```
void sem eat(const char *who, int num, int bowl, int iteration) {
  kprintf("%s: %d starts eating: bowl %d, iteration %d\n", who, num,
           bowl, iteration);
  clocksleep(1);
  kprintf("%s: %d ends eating: bowl %d, iteration %d\n", who, num,
              bowl, iteration);
}
void mousesem(void * p, unsigned long mousenumber) {
  int bowl, iteration;
  for (iteration = 0; iteration < 4; iteration++) {</pre>
    sem eat ("mouse", mousenumber, bowl, iteration);
int catmousesem(...) {
 for (index = 0; index < NCATS; index++)</pre>
   thread fork("catsem Thread", NULL, index, catsem, NULL);
 for (index = 0; index < NMICE; index++)</pre>
   thread fork("mousesem Thread", NULL, index, mousesem, NULL);
}
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```

About starvation

- You do not need to consider priority or starvation
 - e.g., mice can prevent cat from eating
- Since cats/mice will eventually finish eating, won't starve forever