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Approximate confidence intervals in ML excimation
   Nodel: y={y,...,yn},obs, 0={0,...,0p3, parameters
   likelihood L(0; y) = p(y10)
   Fisher information matrix: H(\theta) = E_{y|\theta} \left[ -\nabla_{\theta}^{2} \log \left[ p(y|\theta) \right] \right]
   Theorem: Under mild assumptions,
                     \hat{\theta}_{M}, -\theta \approx N(0, \hat{P}(\theta)^{-1})
        When p=1, \theta=0,
                        \frac{\hat{\theta}_{ML} - \theta}{Var(\hat{\theta}_{ML})^{1/2}} \stackrel{d}{\longrightarrow} N(0, 1)
                 and Var(\hat{\Theta}_{ML}) = \left[\hat{H}(\theta)^{-1}\right]_{II}
Ex) y,,,,, y, index Po (2)
          p(y|\theta) = e^{-\lambda n} \frac{\pi}{h} \lambda^{y_i}/(y_i!), \log p(y|\theta) = -\lambda n + \sum_{i=1}^{n} y_i \log(\lambda) + \cos \theta
     $ (ogp(yle) = -n + \ \frac{1}{2} \frac{1}{2} y; , \frac{1}{2} (ogp(yle) = -\frac{1}{2} \frac{1}{2} y;
     \widetilde{H}(\lambda) = \frac{n}{\lambda}, Var(\widehat{\lambda}_{ML}) \approx \frac{\lambda}{n}
                         \hat{\lambda}_{ML} = \frac{1}{n} \stackrel{Z}{\geq} y_i
          \frac{\hat{\lambda} - \lambda}{\text{Var}(\hat{\lambda})^{1/2}} \approx \frac{\hat{\lambda} - \lambda}{\sqrt{2/n}} \approx \frac{\hat{\lambda} - \lambda}{\sqrt{2/n}} \sim N(0, 1)
         P(Z/2 < \frac{\hat{\lambda} - \lambda}{\sqrt{\lambda}/\lambda} < \frac{2}{1 - \psi/2}) \Rightarrow 1 - \psi
        P( â - Vâ/n 21-4/2 < 2 < Â - Vâ/n 20/2) = 1-0
     CI_{\alpha} = (\hat{\lambda} - \sqrt{\hat{\lambda}/n} \, \hat{z}_{1-\alpha/2}) \hat{\lambda} - \sqrt{\hat{\lambda}/n} \, \hat{z}_{\alpha/2}) or (0, \hat{\lambda} - \sqrt{\hat{\lambda}/n} \, \hat{z}_{\alpha/2})
    CI_{\chi^2} = ((-11-)^2, (-11-)^2) (since °2 is incressing)
Alternative parametrisation:
           Varion, y'm ~ N(0,1) for large 1
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$$\begin{split} & p(y|\theta) = e^{-\theta^2 n} \, \frac{\pi}{\pi} \, \theta^{2y_i} / const \, \int (cog \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, \theta + const \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \, (eg \, eg \, p(y|\theta) = -\theta^2 n + \frac{z}{2} \, 2y_i \,$$