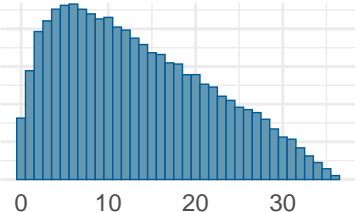


$y_t$  $y_c$ 