

Self driving car

PEAS

- **Performance** : Fast ,Safe and comfortable car with good profits .
- **Environment** : City roads , streets , traffics , trees , pedestrians (people) ,customers , shops and houses .
- **Actuators** : Wheels ,accelerator, brakes ,signal and horns .
- **Sensors** : Camera , GPS ,engine sensor and speedometer .

ODESDA

- **O**:Partially observable .
- **D** :Stochastic and Random .
- **E** :Sequential .
- **S** :Dynamic .
- **D** :Continuous .
- **A** :Multi agent and cooperation .

Type of agent program :

Utility based agent because safety is against speed . Goal based reflex agent .

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