Design, Test and Integration of Force Sensor and Strain Gage

Presented by

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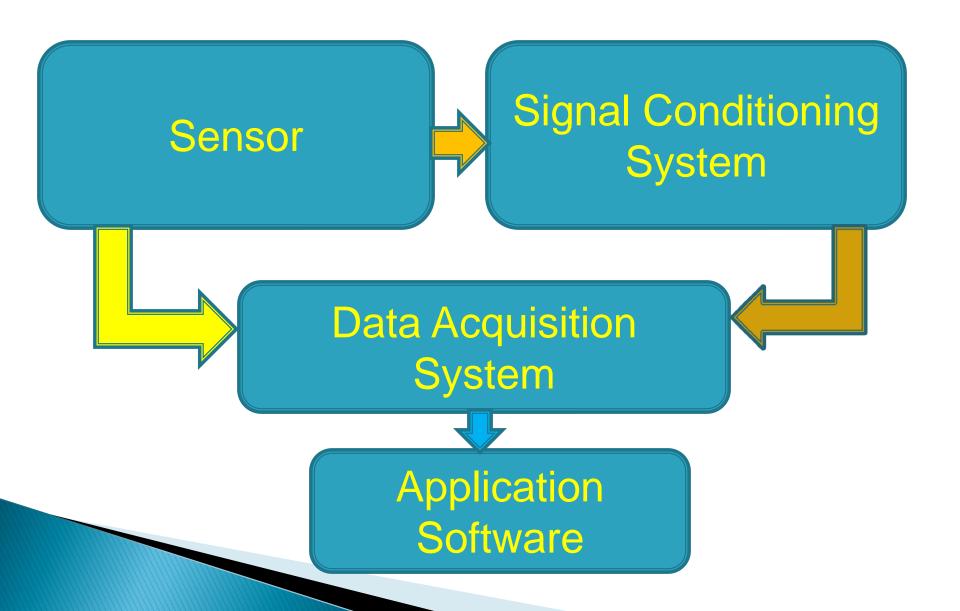
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Outline

- Basic Sensor System Building Blocks
- Force Sensing System Design
- Strain Gage System Design
- Application Software
- Application to Tactile Imaging System

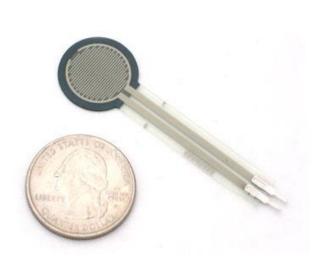
Overview



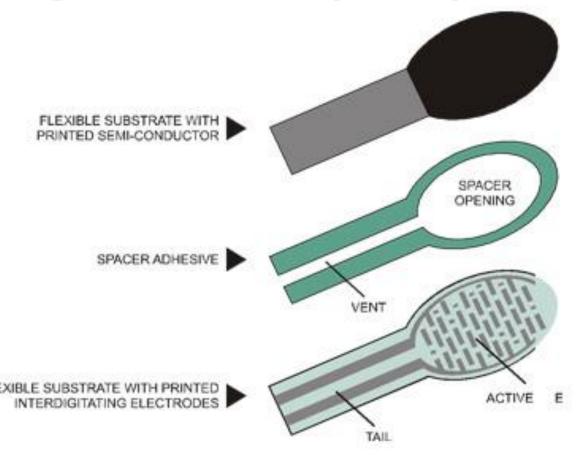
Force Sensing System

- Force Sensing Resistor as Force Sensor
- Measurement Circuit for Force Sensor
- Arduino Uno board and Matlab script as Data Acquisition System
- Application Software written in Matlab R2010b

Force Sensing Resistor (FSR)

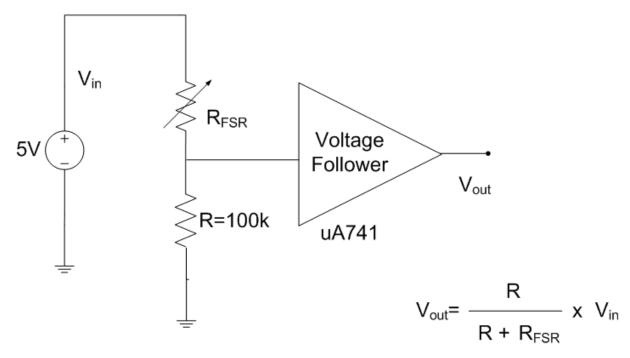


- FSR is a material whose resistance changes when a force is applied.
- Small size, low cost and easy to use.



Interlink Model 402
Sensing area diameter 12.7mm

Measurement Circuit

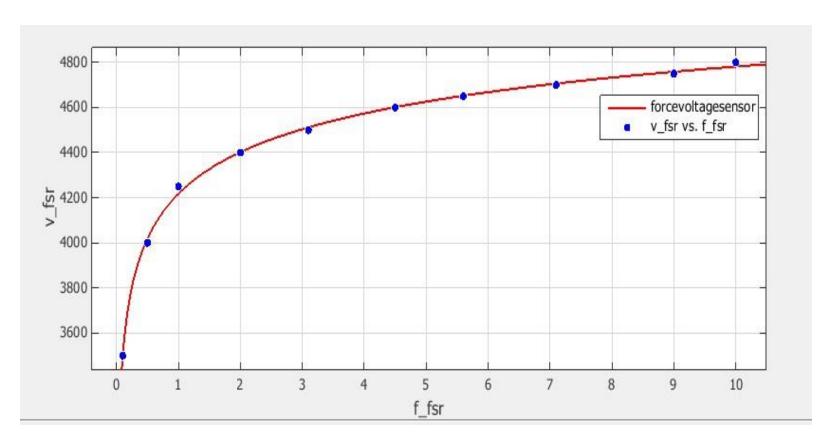


- Measurement based on simple voltage divider rule
- Output voltage changes as resistance of FSR varies by above formula
- A voltage follower is used to match the upstream high impedance circuit.

Data Acquisition from Force Sensor

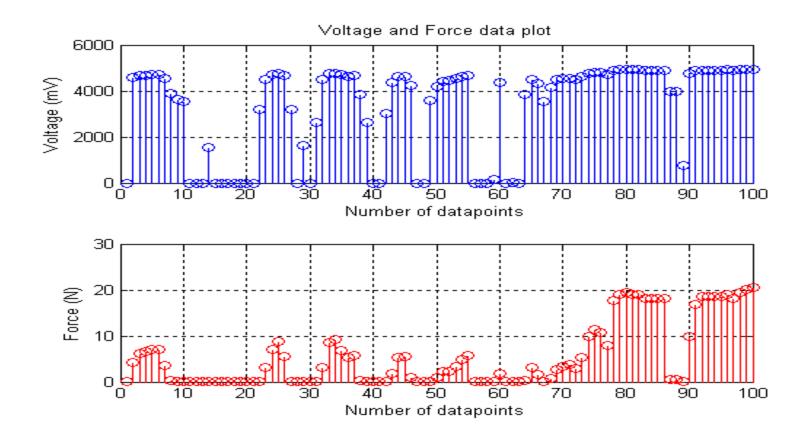
- Divided into two parts:
 - Hardware for data acquisition
 - Software for data acquisition
- Hardware Output of measurement circuit is connected to analog pin Arduino UNO board
- Software
 - Matlab package to support Arduino IDE.
 - Upload matlab written srv.pde file into board
 - Run a script to read the analog pin of Arduino in Matlab

Resistance vs Force Curve



- Used matlab curve fitting tool logarithmic fitting
 - $f_fsr = exp(log((v_fsr-6835)/(-2617))/(-0.1054))$

Force Sensing Graph

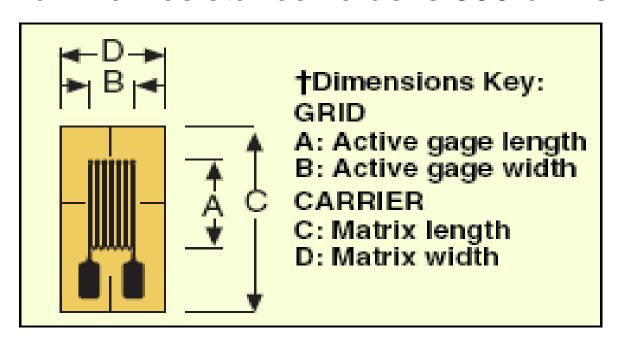


Strain Gage System

- Strain Gage
- Signal Conditioning Circuit
- Arduino Uno board and Matlab script as Data Acquisition System
- Application Software written in Matlab R2010b

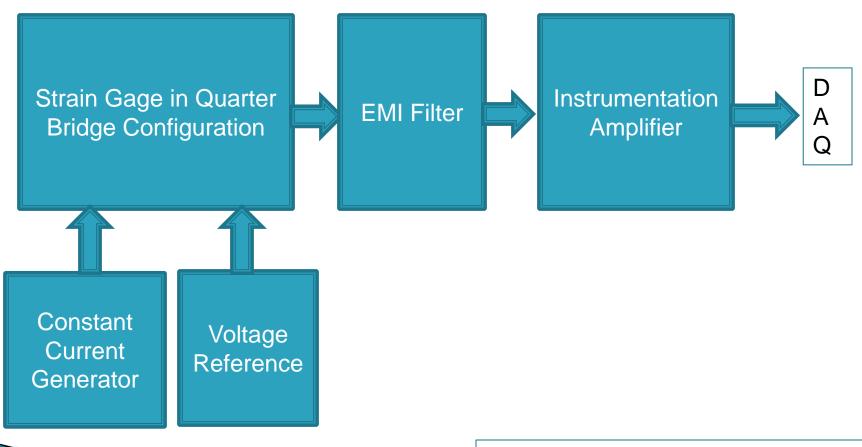
Strain Gage

- SGT-2C/350-TY11 used as strain gage.
- Nominal resistance value is 350 ohms



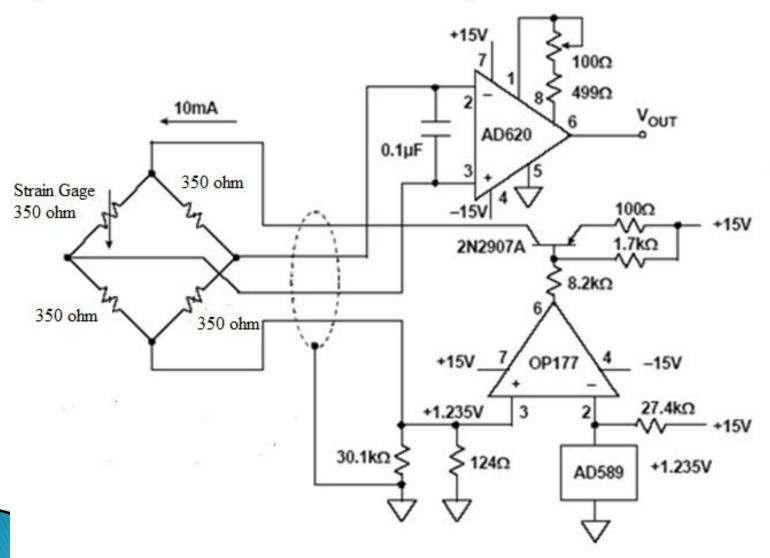
A = 1.5mm, B = 4.6mm, C = 6.4mm and D = 4.6mm.

Basic Building Block for Signal Conditioning



DAQ- Data Acquisition System

Signal Conditioning Circuit



Data Acquisition from Strain Gage

- Divided into two parts:
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Strain Calculation from Signal Conditioning Output

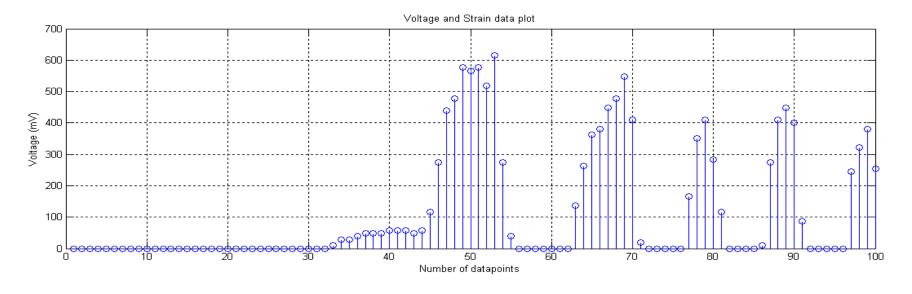
$$strain = \frac{4*Vout}{GF*(Vex-2*Vout)}$$

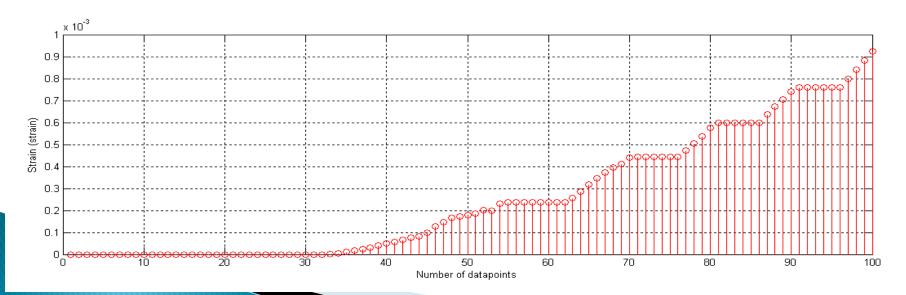
Vout = Output voltage of signal conditioning circuit

GF = Gage factor = 2

Vex = Excitation voltage = 1200mV

Strain Gage Graph





Application Software

Fruit ripeness checker, rubber ball hardness test Simple Algorithm

- 1. Start of Program
- 2. Take user input of force and strain data
- 3. Make force data into stress data by dividing the force with area
- 4. Find Young's modulus for each datapoint
- 5. Take the mean of Young's modulus
- 6. Design a look up table of Young's modulus vs Ripeness rating
- 7. Check the look up table for decision
- 8. Display a decision
- 9. End of Program

Application to Tactile Imaging System

- Force sensor can be put around TIS probe to get the force applied in the neighboring region of tumor
- Instead of a single FSR, four sensors might be used to get an improved force estimation, essentially hardness of tumor estimation
- Improvement of force estimation will cost less than \$100
- Strain gage senses the dimension change of the surface it is mounted on. So it may give an indirect estimation of strain of tumor when force is applied.

