

Floodgate: inference for model-free variable importance

Dempster's Colloquium 2021

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Zhang, L. and Janson, L., 2020. Floodgate: inference for model-free variable importance. arXiv preprint arXiv:2007.01283.

Collaborator



Lucas Janson

Overview

1. Introduction

Setup

Motivation

2. Methodology

Floodgate

Properties

3. Numerical Results

Simulation

Data application

4. Takeaways

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Problem setup

Setup: data (Y, X, Z) from some joint distribution.

- Y a **outcome** variable of interest (AKA response or dependent variable),
- X a explanatory **variable** of interest (AKA treatment, covariate, feature)
- $Z := (Z_1, \dots, Z_p)$ a set of p further variables (AKA confounders, nuisance variables)

Examples:

Phenotype: Height



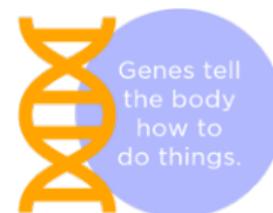
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Examples:

Levels (Various options available per feature)			
Brand			
Price	\$500	\$300	\$400
Operating System			
Screen Size			
Camera Resolution	2 to 4 MP	4 to 6 MP	Above 6 MP

↑
Features
(Various parameters to make decisions)

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Examples:



Proposed feature set for highest successful probability

Levels
(Various options available per feature)

Brand	Apple	SONY	NOKIA
Price	\$500	\$300	\$400
Operating System	Apple	Android	Windows
Screen Size	4 to 5 Inch	4 to 6 MP	Above 6 MP
Camera Resolution	2 to 4 MP	4 to 6 MP	Above 6 MP

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Motivation

Question 1

Is the variable X important or not?

a

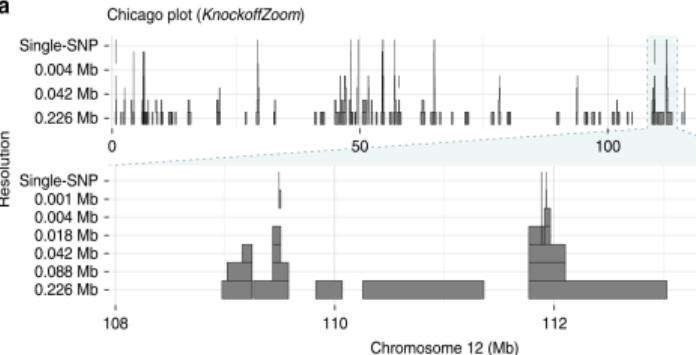
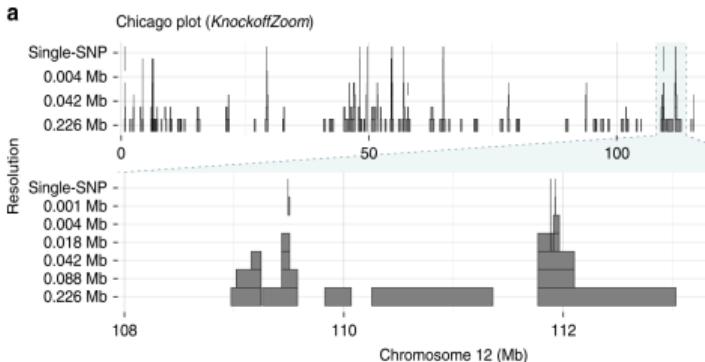


Figure: Select important groups of SNPs

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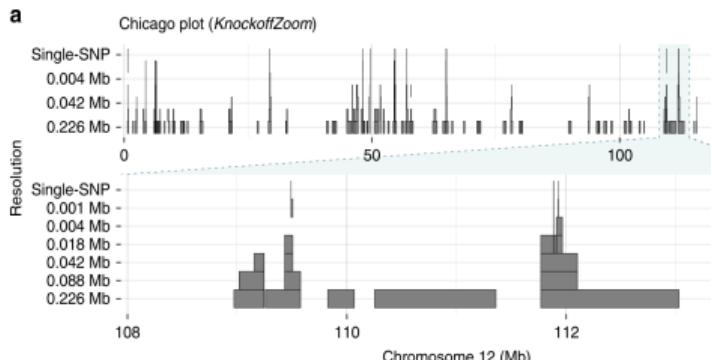
Go Beyond

Figure: Select important groups of SNPs

Motivation

Question 1

Is the variable X important or not?



Go Beyond

Question 1*

How important is the variable X ?

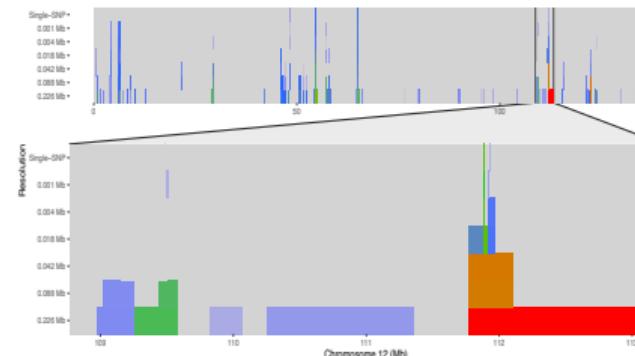


Figure: Select important groups of SNPs

Figure: Infer the importance of a group of SNPs

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Related work

- *Parametric approaches:* Bühlmann et al. (2013), Zhang and Zhang (2014), Javanmard and Montanari (2014), Bühlmann et al. (2015), Dezeure et al. (2017), Zhang and Cheng (2017), Van de Geer et al. (2014), Nickl et al. (2013).
- *Projection approaches:* Buja et al. (2015, 2019a,b), Rinaldo et al. (2019), Lee et al. (2016), Taylor et al. (2014), Berk et al. (2013), Buja and Brown (2014).
- *Semi-parametric approaches:* $\mathbb{E}[\text{Cov}(Y, X | Z)]$; Robins et al. (2008, 2009); Li et al. (2011); Robins et al. (2017); Newey and Robins (2018), Shah and Peters (2018).
- *Random estimands:* Lei et al. (2018), Watson and Wright (2019), Rinaldo et al. (2019).
- *Same MOVI as us:* Saltelli et al. (2008), Williamson et al. (2017, 2020).

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A1 : present a MOVI, the mMSE gap.

Comparing the conditional mean function and the true function

Comparing the conditional variance function and the true function

Comparing the conditional covariance function and the true function

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A1 : present a MOVI, the mMSE gap.

Null compatible Zero under the conditional independence $Y \perp\!\!\!\perp X | Z$.

Sensitive Strictly positive unless $\mathbb{E}[Y | X, Z]$ has no dependence on X at all.

Interpretable Direct predictive, causal and explanatory interpretations.

A2 : propose a method for inference for it: **floodgate**.

Valid Asymptotically-valid inference.

General Does not make any parametric/smoothness/sparsity assumptions about $Y | X, Z$ and built around any regression estimator.

Accurate Width of confidence bounds proportional to the predictive performance.

Robust Assume $P_{X|Z}$ known; quantified robustness to misspecification and extension allowing known up to a parametric model.

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Our target MOVI: the mMSE gap

Definition (mMSE Gap)

The minimum mean squared error (mMSE) gap for variable X is defined as

$$\mathcal{I}^2 = \mathbb{E} \left[(Y - \mathbb{E}[Y | Z])^2 \right] - \mathbb{E} \left[(Y - \mathbb{E}[Y | X, Z])^2 \right].$$

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- **Predictive:** immediate from above.
- **Variance decomposition:** $\mathcal{I}^2 = \text{Var}(\mathbb{E}[Y | X, Z]) - \text{Var}(\mathbb{E}[Y | Z]).$
- **Causal:** $\mathcal{I}^2 = \frac{1}{2} \mathbb{E}_Z \left[\mathbb{E}_{\substack{x_1, x_2 \\ i.i.d. P_{X|Z}}} \left[(\mathbb{E}[Y | X = x_1, Z] - \mathbb{E}[Y | X = x_2, Z])^2 \right] \right].$
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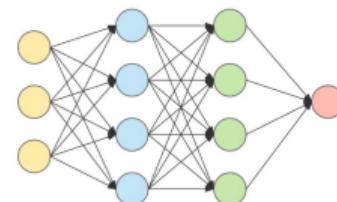
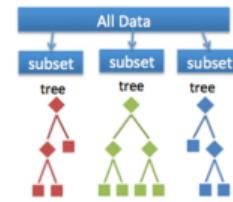
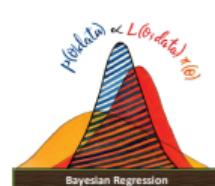
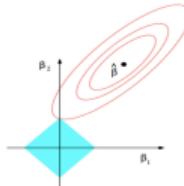
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How to do inference on \mathcal{I} ?

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- Only known for limited class of estimators and data-generating distributions.
- Precludes most modern machine learning algorithms and methods that integrate hard-to-quantify domain knowledge.



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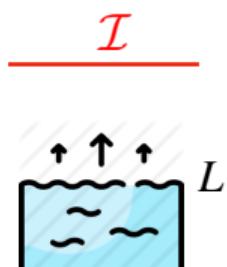
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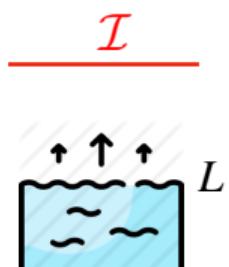
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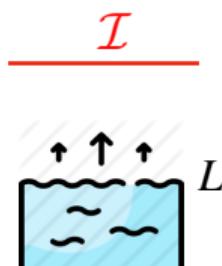
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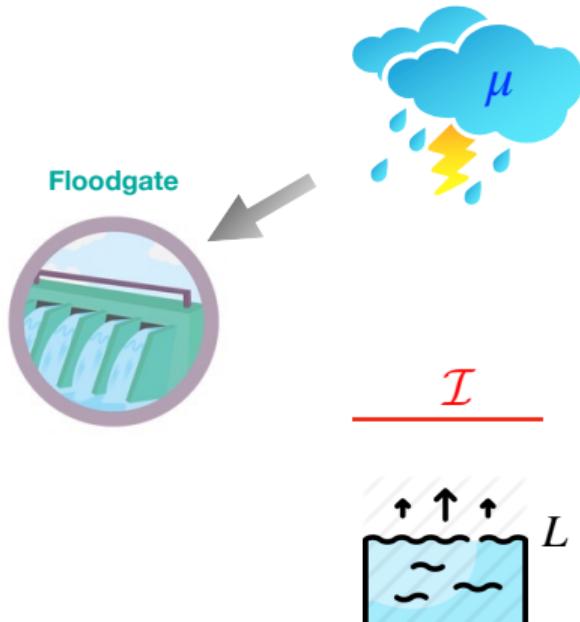
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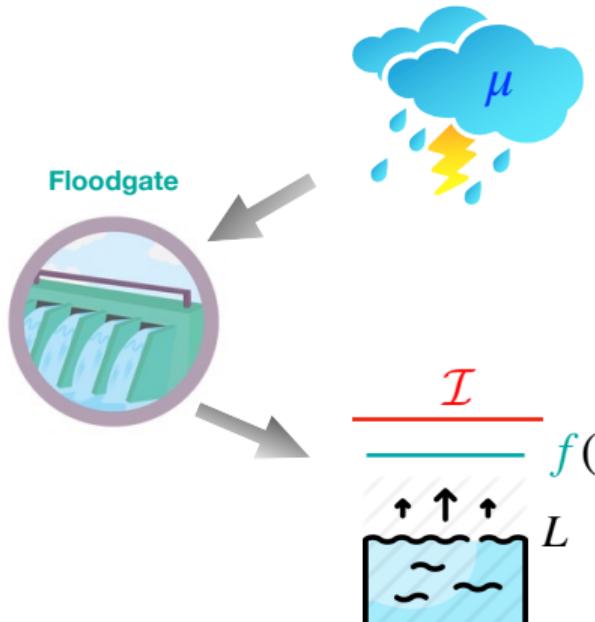
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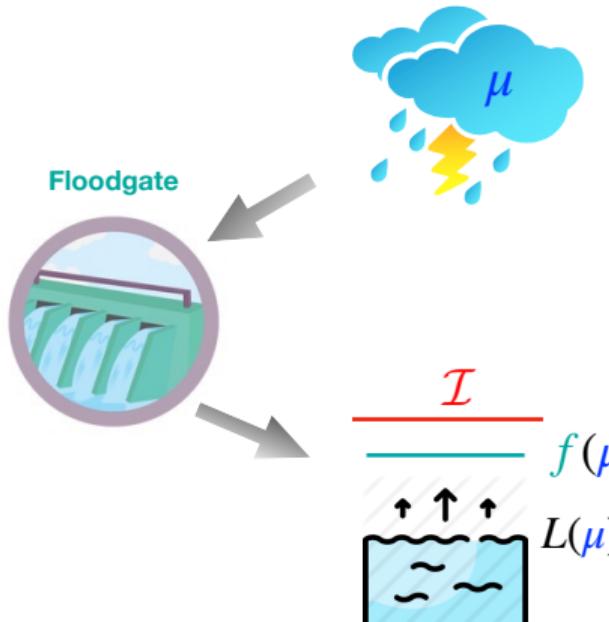
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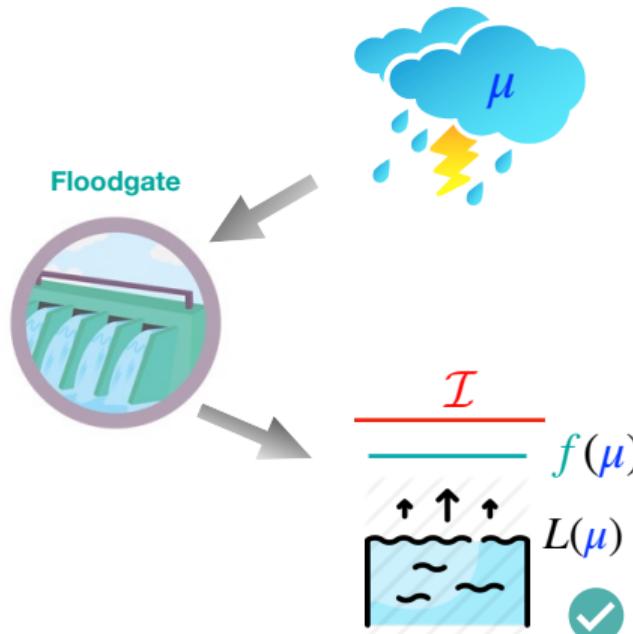
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Our choice of Floodgate functional

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$$f(\mu) := \frac{\mathbb{E} [\text{Cov}(\mu^*(X, Z), \mu(X, Z) | Z)]}{\sqrt{\mathbb{E} [\text{Var}(\mu(X, Z) | Z)]}}$$

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$$f(\mu) = \frac{\mathbb{E} [Y(\mu(X, Z) - \mathbb{E} [\mu(X, Z) | Z])]}{\sqrt{\mathbb{E} [\text{Var}(\mu(X, Z) | Z)]}} = \frac{\text{a linear functional of } P_{(Y,X,Z)}}{\sqrt{\text{a linear functional of } P_Z}}$$

Inferential procedures

Input: $\mathcal{D} = \{(Y_i, X_i, Z_i)\}_{i=1}^n$; \mathcal{D}' ; any regression algorithm \mathcal{A} ; assume $P_{X|Z}$ known.

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2. Compute $\mathbb{E}[\mu(X, Z) | Z]$, $\text{Var}(\mu(X, Z) | Z)$.
3. Construct CLT-based LCB for $f(\mu)$: $L_n^\alpha(\mu)$ (with confidence level α) by Delta method.

$$\begin{pmatrix} \frac{1}{n} \sum_{i=1}^n Y_i (\mu(X_i, Z_i) - \mathbb{E}[\mu(X_i, Z_i) | Z_i]) \\ \frac{1}{n} \sum_{i=1}^n \text{Var}(\mu(X_i, Z_i) | Z_i) \end{pmatrix} \xrightarrow{\text{asympt.}} \mathcal{N} \begin{pmatrix} \mathbb{E}[\text{Cov}(\mu^*(X, Z), \mu(X, Z) | Z)] \\ \mathbb{E}[\text{Var}(\mu(X, Z) | Z)] \end{pmatrix}$$

Asymptotic validity

Theorem (Zhang and Janson (2020); informal)

Under mild moment conditions on Y and $\mu(X, Z)$, we have

$$\mathbb{P}(L_n^\alpha(\mu) \leq \mathcal{I}) \geq 1 - \alpha - O(n^{-1/2}).$$

- Point-wise result: the convergence rate result builds on recent Berry–Esseen type bounds for Delta method (Pinelis et al., 2016).

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- Constant in $O(n^{-1/2})$ has complicated dependence on μ and $P_{(Y,X,Z)}$.

Asymptotic validity

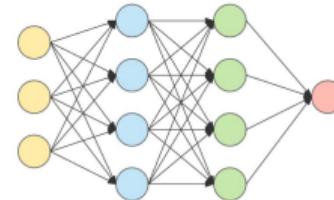
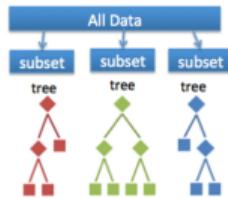
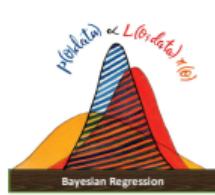
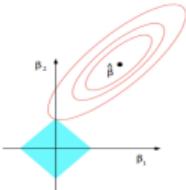
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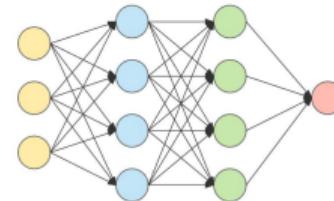
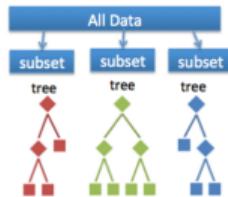
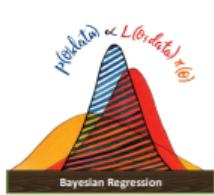
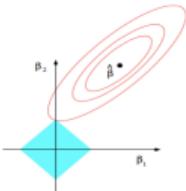
- Invariance of the floodgate procedure: e.g., $\mu(x, z) = ax + g(z)$, constant only depends on $\text{sign}(a)$ and bivariate distribution of $\left(Y, \frac{X - \mathbb{E}[X | Z]}{\sqrt{\text{Var}(X - \mathbb{E}[X | Z])}}\right)$.

Computation



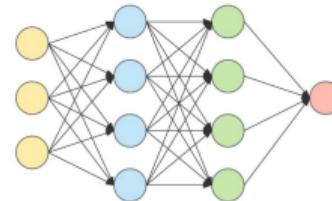
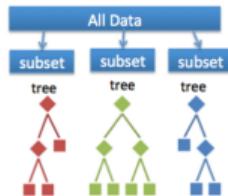
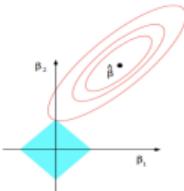
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- Only involve one time of model fitting.
- Under certain fitted models, can compute $\mathbb{E} [\mu(X, Z) | Z]$, $\text{Var} (\mu(X, Z) | Z)$ analytically, e.g., partial linear model with Gaussian design.

General computation

How to compute $\mathbb{E} [\mu(X, Z) | Z]$, $\text{Var} (\mu(X, Z) | Z)$ in a general way (e.g., μ is fitted based on random forest or neural networks)?

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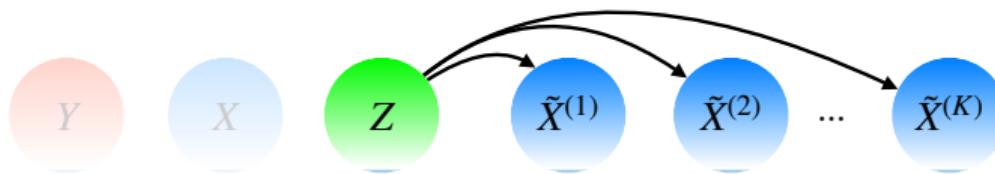
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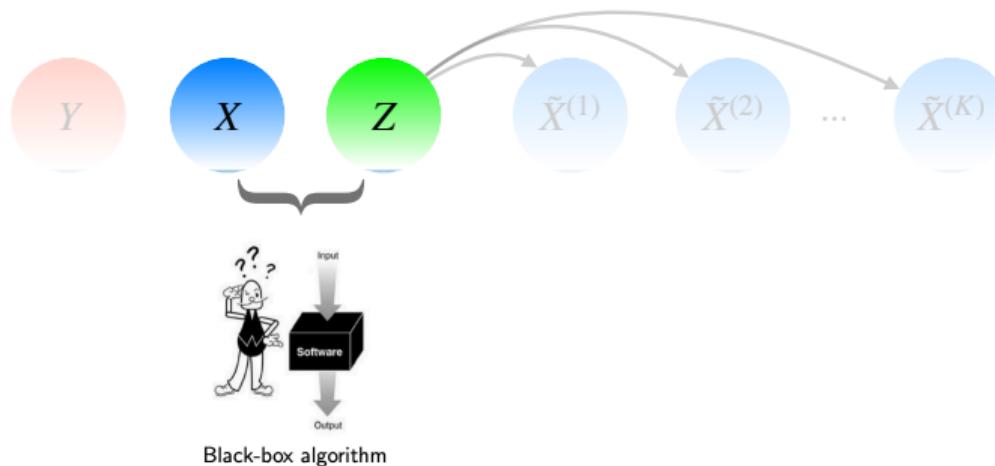
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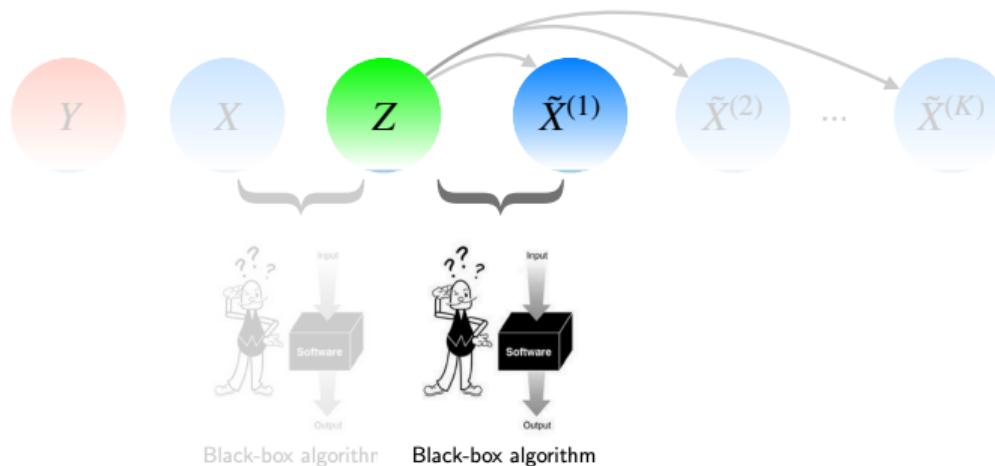


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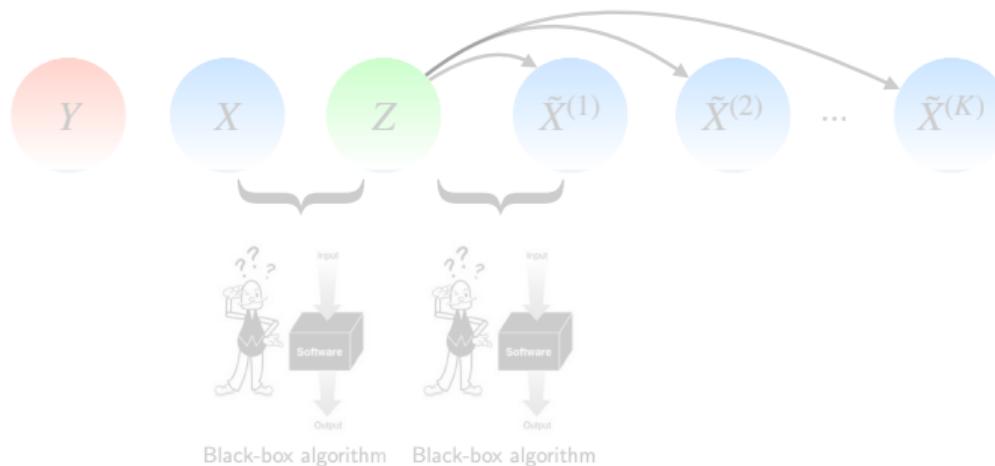
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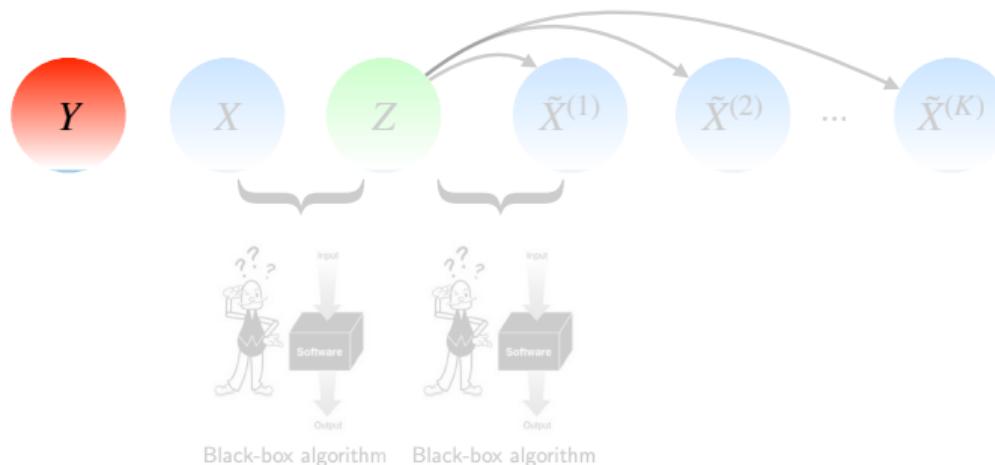
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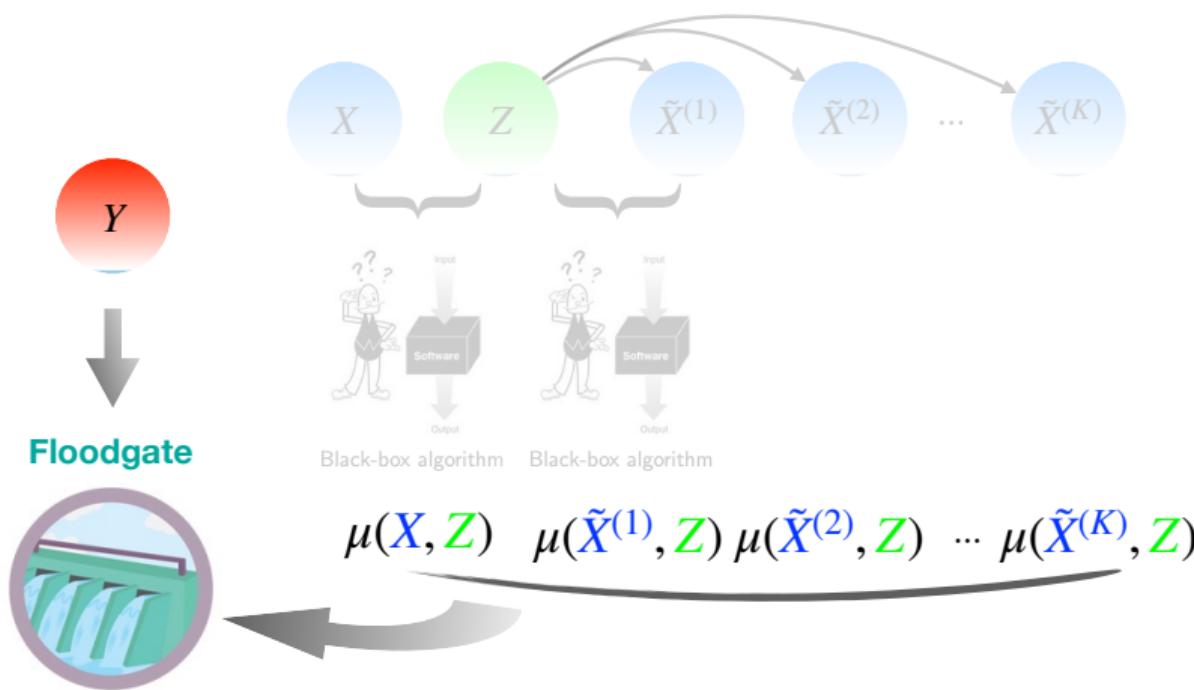
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- Sample \tilde{X} from $P_{X|Z}$, conditionally independently of X, Y .
- We know

$$\mathbb{E} \left[Y(\mu(X, Z) - \mu(\tilde{X}, Z)) \right] = \mathbb{E} \left[Y \left(\mu(X, Z) - \mathbb{E} [\mu(X, Z) | Z] \right) \right]$$

$$\frac{1}{2} \mathbb{E} \left[\left(\mu(X, Z) - \mu(\tilde{X}, Z) \right)^2 \right] = \mathbb{E} [\text{Var}(\mu(X, Z) | Z)]$$

Upper confidence bound

Suppose there were no Z .

- $\mathcal{I}^2 = \text{Var}(\mathbb{E}[Y | X])$.
- $\text{Var}(Y)$ is a trivial UCB, as $\mathcal{I}^2 \leq \text{Var}(Y)$.

Theorem (Zhang and Janson (2020); informal)

Under our assumptions, any asymptotically-valid UCB_α will asymptotically be $\geq \text{Var}(Y)$ with probability at least $1 - \alpha$.

Valid, nontrivial UCB **impossible** without structure on $Y | X$.

Intuition behind the UCB result

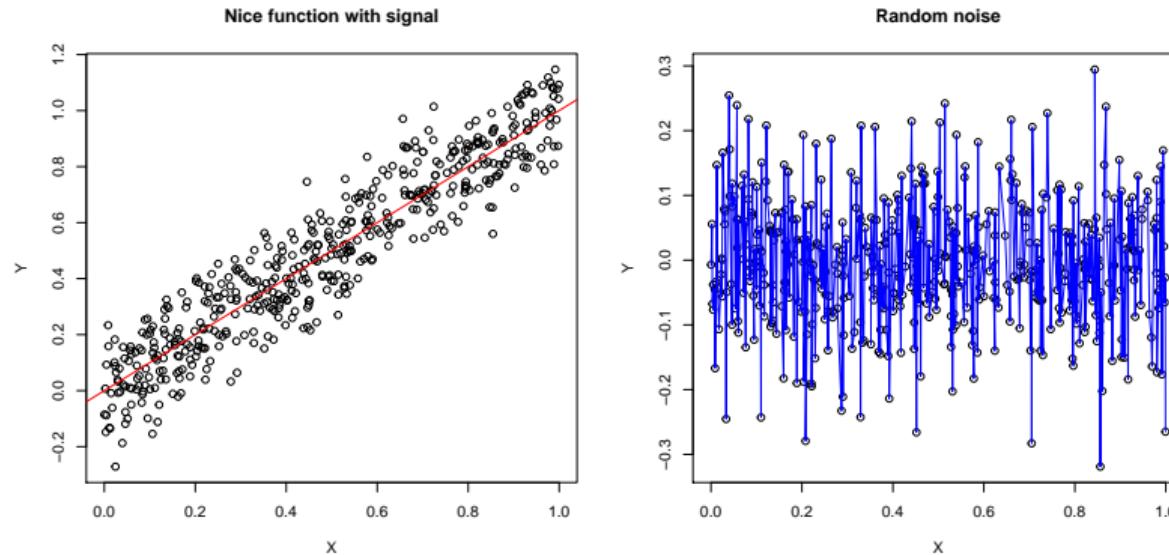


Figure: Left: $Y = X + \mathcal{N}(0, 0.1)$; Right: $Y \sim \mathcal{N}(0, 0.1)$.

Statistical accuracy

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Floodgate procedure is invariant with respect to a “equivalent” function class of μ ,

$$S_\mu = \{c\mu(x, z) + g(z) : c > 0, g : \mathbb{R}^p \rightarrow \mathbb{R}\}.$$

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Under mild moment conditions on Y and noises, for μ_n with well-behaved moments,

$$\mathcal{I} - L_n^\alpha(\mu_n) = O_p \left(\inf_{\mu \in S_{\mu_n}} \mathbb{E} [(\mu(X, Z) - \mu^\star(X, Z))^2] + n^{-1/2} \right).$$

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Floodgate is **adaptive** to the **accuracy** of μ_n
(through the MSE of the best element of its equivalence class S_{μ_n})

Robustness

Suppose $P_{X|Z}$ unknown, we instead use its estimate $Q_{X|Z}^{(n)}$ to run floodgate.

Theorem (Zhang and Janson (2020); informal)

Under moment conditions on Y and noises, for μ_n with well-behaved moments under both the true distribution P and the specified one $Q^{(n)}$, then for floodgate with $Q_{X|Z}^{(n)}$ we have

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Note: by definition of $\bar{\mu}_n$, we have: $\mathcal{I} = 0 \Rightarrow \mathbb{E} [(\bar{\mu}_n(X, Z) - \mu^*(X, Z))^2] = 0$.

Floodgate is robust if $P_{X|Z}$ well-estimated.

If $\mathcal{I} > 0$, floodgate is robust if $P_{X|Z}$ better-estimated than $\mathbb{E}[Y | X, Z]$.

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Simulation setup

- $n = 1100$, $p = 1000$, and a sparsity of 30 unless stated otherwise.
- Linear: $X \sim \mathcal{N}(0, \Sigma)$, AR(1); $Y = X\beta + \mathcal{N}(0, 1)$, $\|\beta\|_0 = 30$, $|\beta_j| \in \{0, \frac{\text{amplitude}}{\sqrt{n}}\}$.
- Nonlinear: each component chosen from below; up to 3rd order interactions.

$\sin(\pi x)$, $\cos(\pi x)$, $\sin(\pi x/2)$, $\cos(\pi x)I(x > 0)$, $x \sin(\pi x)$, x , $|x|$, x^2 , x^3 , $e^x - 1$.

- Number of replicates: 64.
- Default sample splitting proportion: 0.50.
- Four fitting algorithms: LASSO, Ridge, SAM, Random Forest.
- Number of null samples: $K = 500$.

Splitting proportion

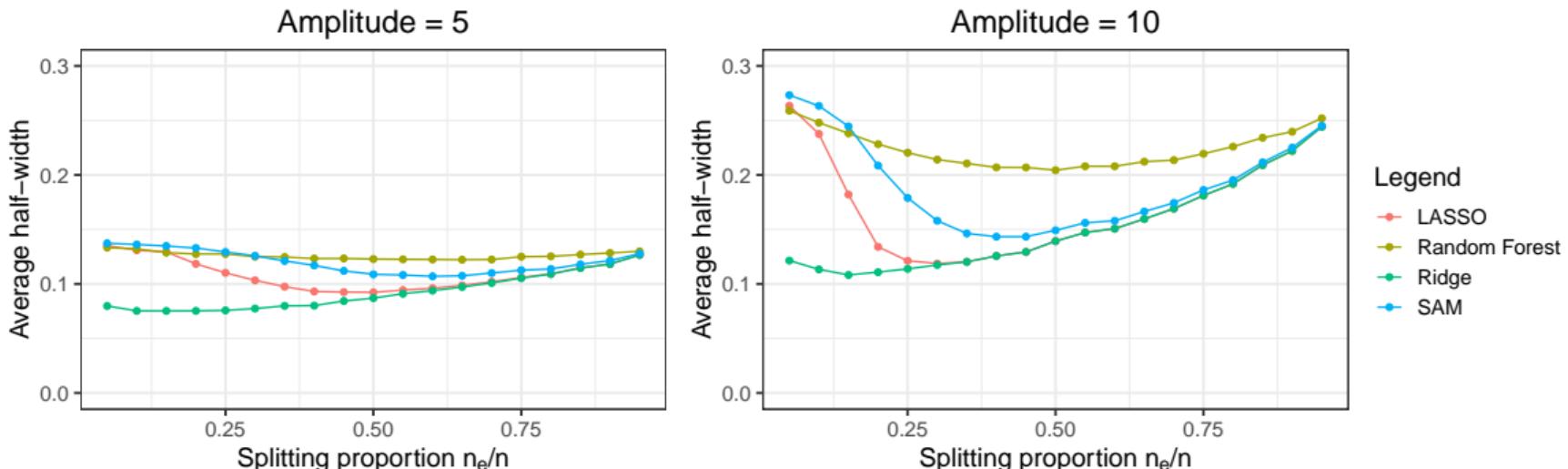


Figure: Linear setting.

Splitting proportion

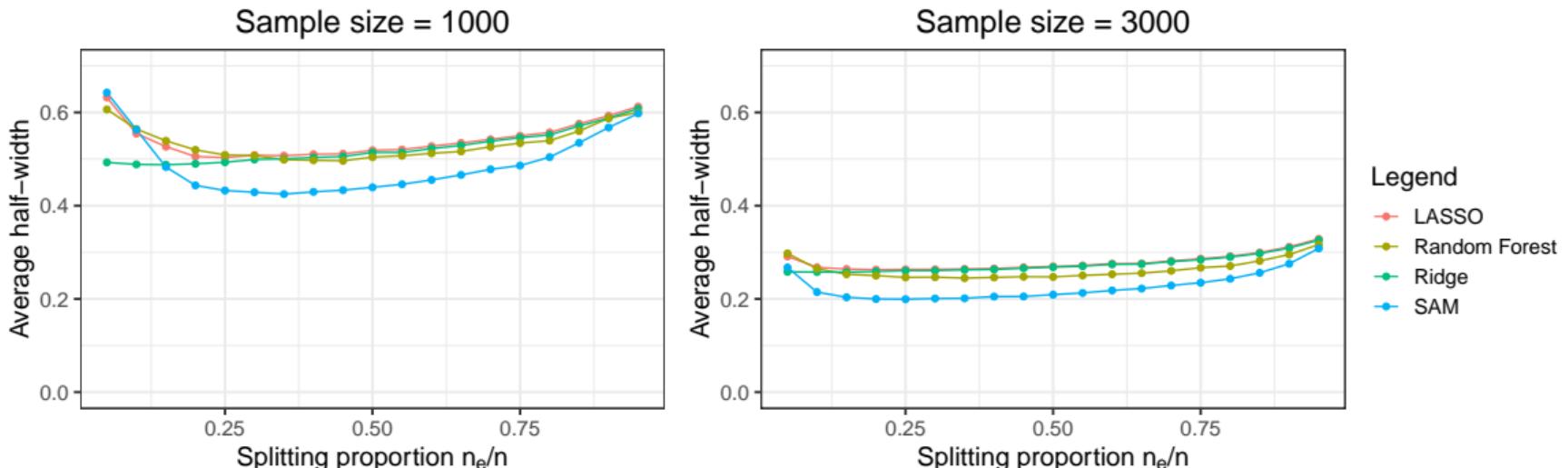


Figure: Nonlinear setting.

Covariate dimension

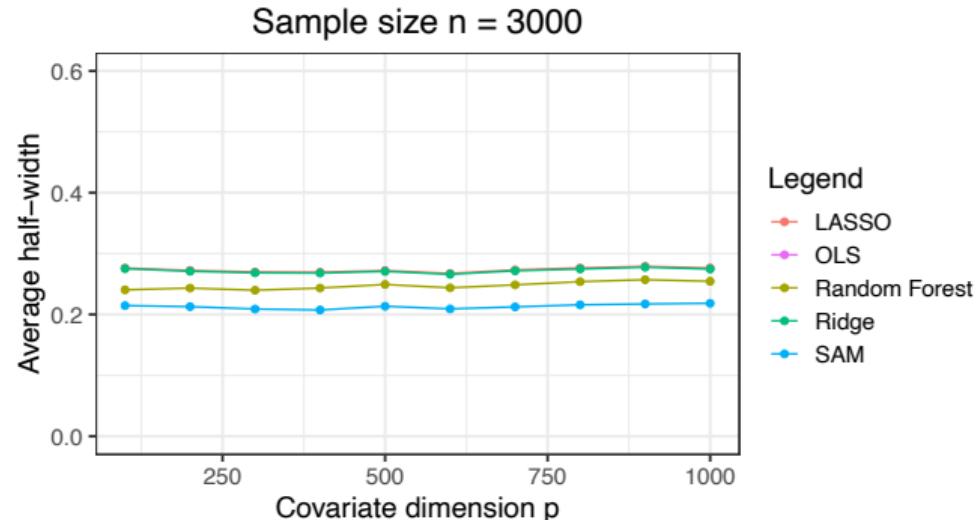
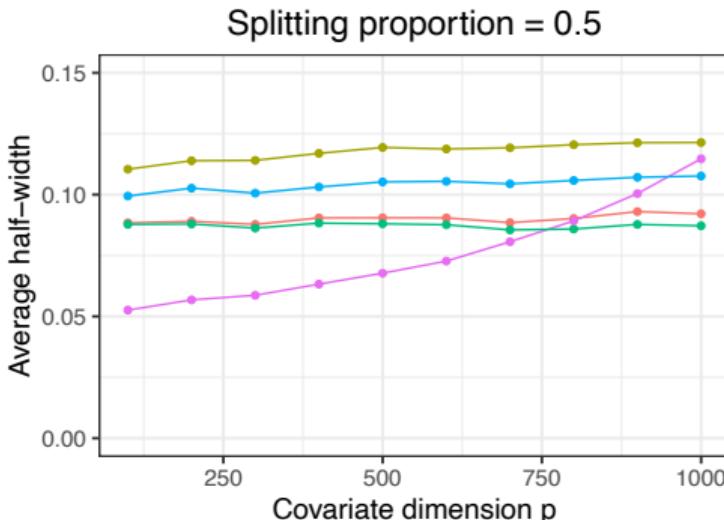


Figure: Left: Linear setting; Right: Nonlinear setting.

Robustness

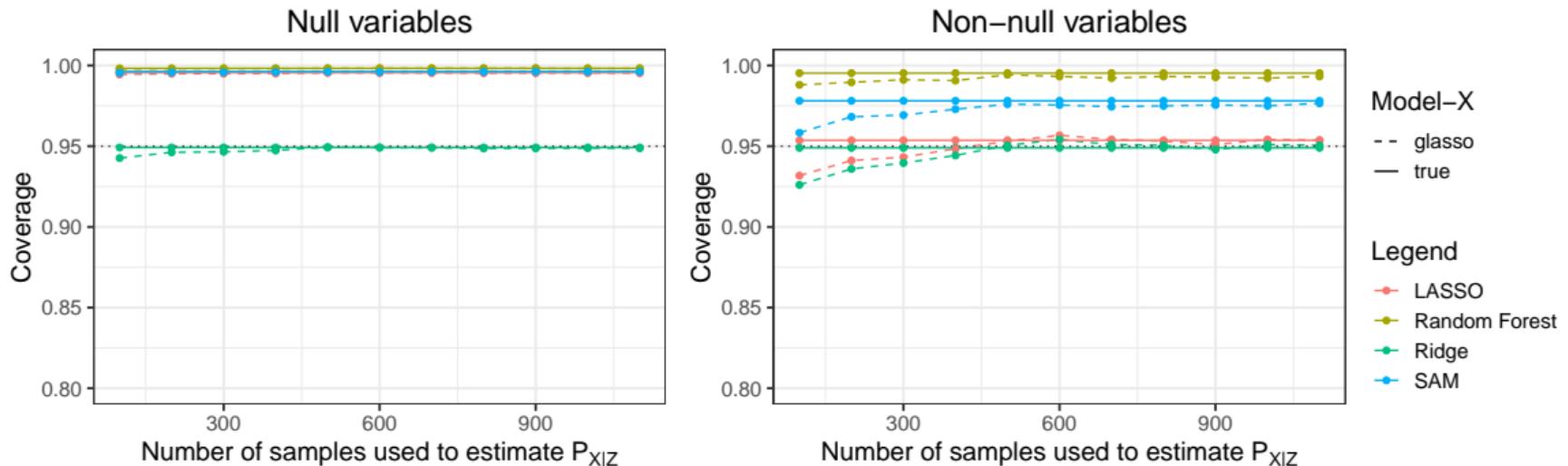


Figure: Linear setting.

Robustness

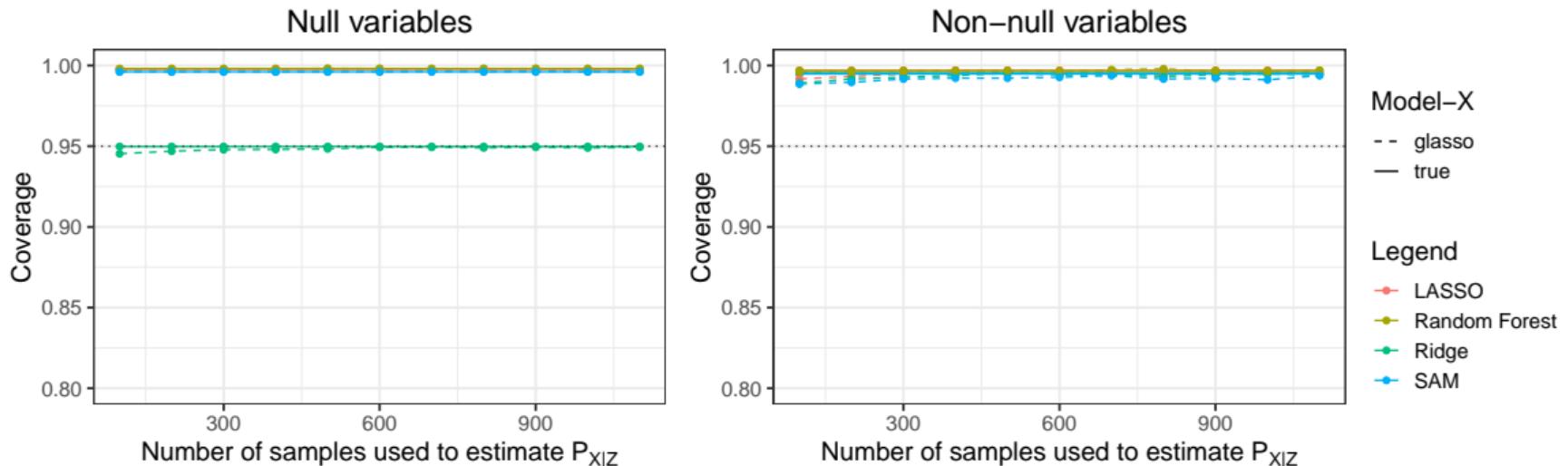


Figure: Nonlinear setting.

Genomic study of platelet count

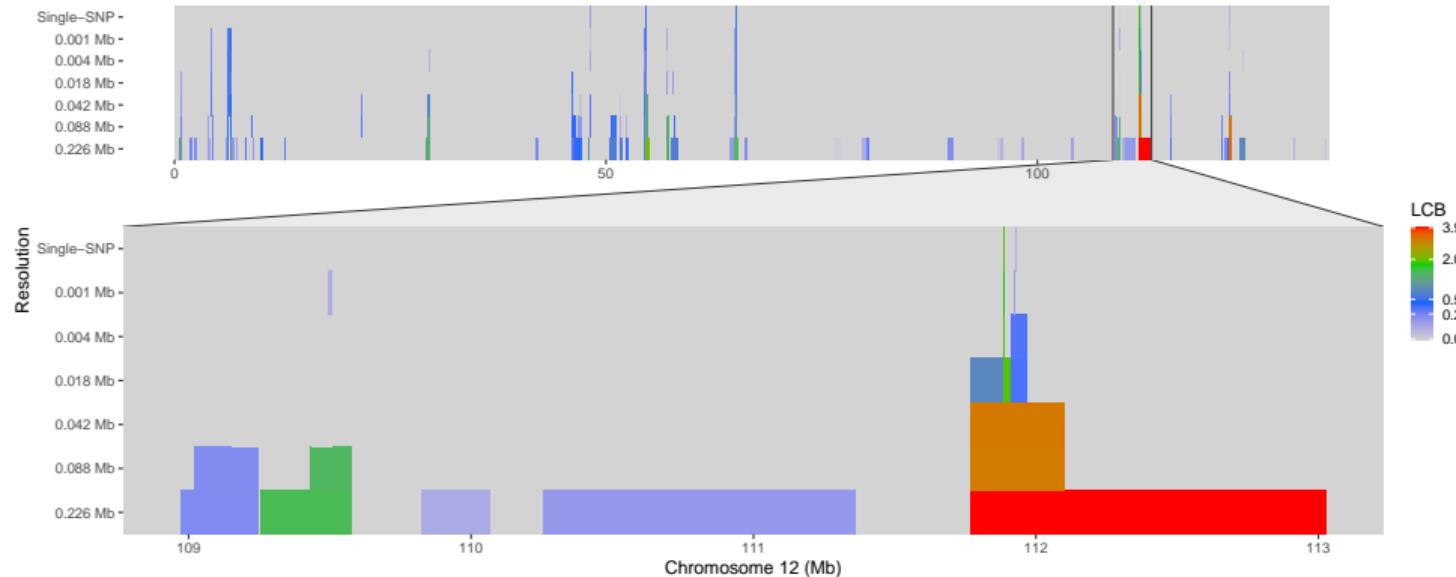


Figure: Colored Chicago plot (Sesia et al., 2020) with the color of each point representing the floodgate LCB for the importance of a group of SNPs on Chromosome 12 in the UK Biobank data at different resolutions (y-axis). Bottom plot shows a zoomed-in region of strong importance.

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Answers

Extensions

Questions

What if only know a model for $P_{X|Z}$?

Answers

Co-sufficient floodgate.

Extensions

Questions

What if only know a model for $P_{X|Z}$?

Beyond the mMSE gap?

Answers

Co-sufficient floodgate.

Floodgate for MACM gap.

Extensions

Questions

What if only know a model for $P_{X|Z}$?

Beyond the mMSE gap?

Inferring the MOVI w.r.t $\{X_j\}_{j \in \mathcal{G}}$?

Answers

Co-sufficient floodgate.

Floodgate for MACM gap.

Easily extends.

Extensions

Questions	Answers
What if only know a model for $P_{X Z}$?	<input checked="" type="checkbox"/> Co-sufficient floodgate.
Beyond the mMSE gap?	<input checked="" type="checkbox"/> Floodgate for MACM gap.
Inferring the MOVI w.r.t $\{X_j\}_{j \in \mathcal{G}}$?	<input checked="" type="checkbox"/> Easily extends.
Transporting inference from $P_{(X,Z)}$ to $Q_{(X,Z)}$?	<input checked="" type="checkbox"/> Easily extends.

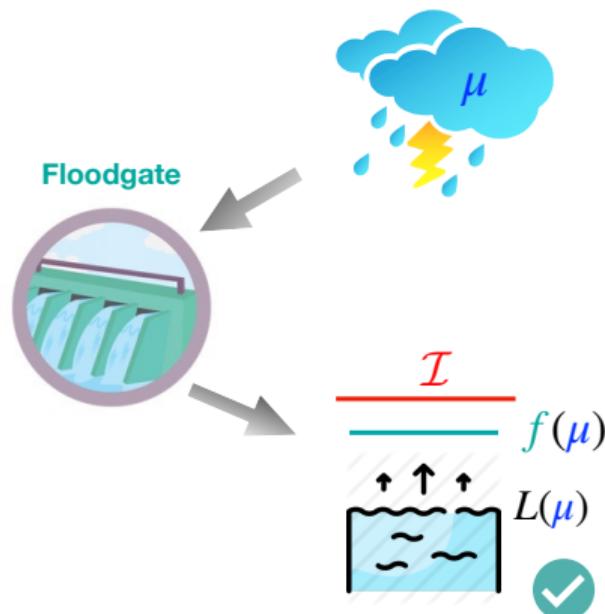
Extensions

Questions	Answers
What if only know a model for $P_{X Z}$?	<input checked="" type="checkbox"/> Co-sufficient floodgate.
Beyond the mMSE gap?	<input checked="" type="checkbox"/> Floodgate for MACM gap.
Inferring the MOVI w.r.t $\{X_j\}_{j \in \mathcal{G}}$?	<input checked="" type="checkbox"/> Easily extends.
Transporting inference from $P_{(X,Z)}$ to $Q_{(X,Z)}$?	<input checked="" type="checkbox"/> Easily extends.
Adjusting for multiplicity and selection effects?	<input checked="" type="checkbox"/> Has answers.

Extensions

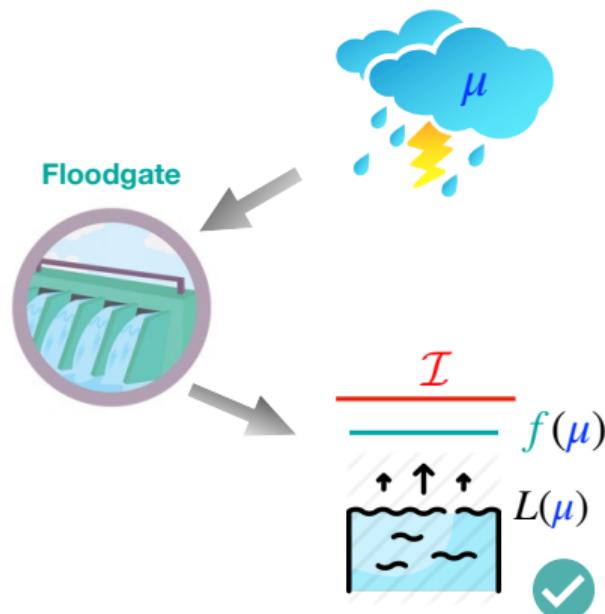
Questions	Answers
What if only know a model for $P_{X Z}$?	<input checked="" type="checkbox"/> Co-sufficient floodgate.
Beyond the mMSE gap?	<input checked="" type="checkbox"/> Floodgate for MACM gap.
Inferring the MOVI w.r.t $\{X_j\}_{j \in \mathcal{G}}$?	<input checked="" type="checkbox"/> Easily extends.
Transporting inference from $P_{(X,Z)}$ to $Q_{(X,Z)}$?	<input checked="" type="checkbox"/> Easily extends.
Adjusting for multiplicity and selection effects?	<input checked="" type="checkbox"/> Has answers.
Inferring the normalized mMSE gap $\frac{\mathcal{I}}{\sqrt{\text{Var}(Y)}}$?	<input checked="" type="checkbox"/> Easily extends.

Summary



Floodgate: a new inferential approach for variable importance.

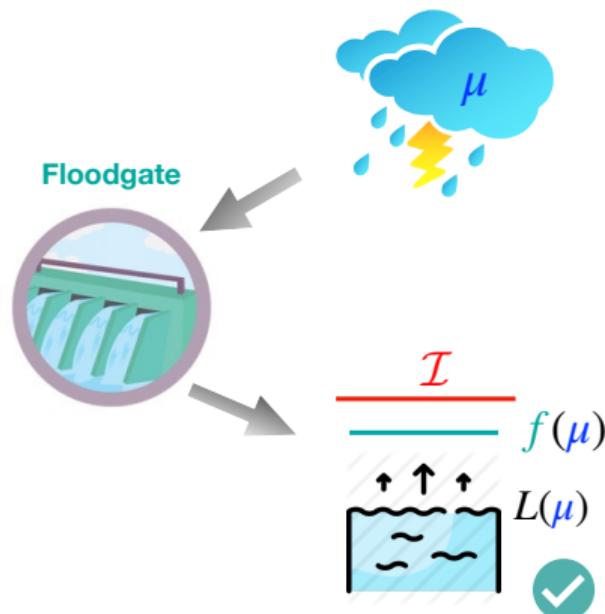
Summary



Floodgate: a new inferential approach for variable importance.

- Focus on an interpretable, sensitive and model-free MOVI: the mMSE gap.

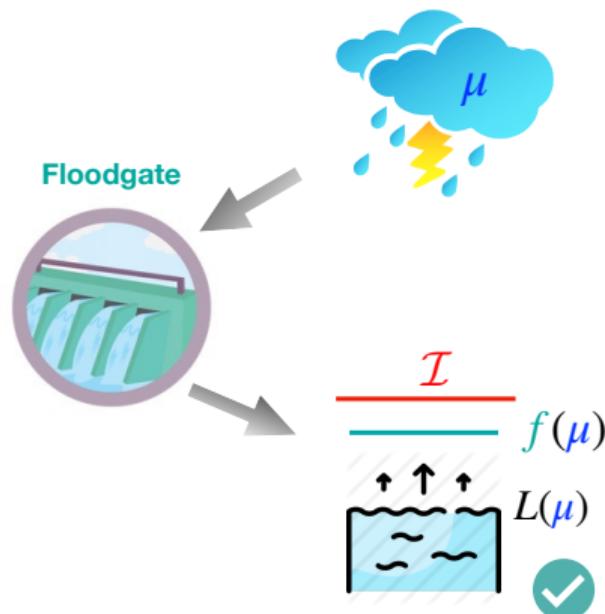
Summary



Floodgate: a new inferential approach for variable importance.

- Provide valid and robust LCBs for the mMSE gap.

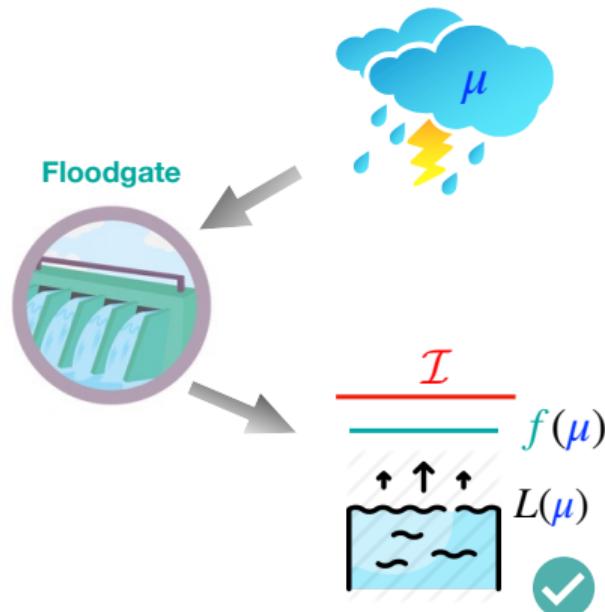
Summary



Floodgate: a new inferential approach for variable importance.

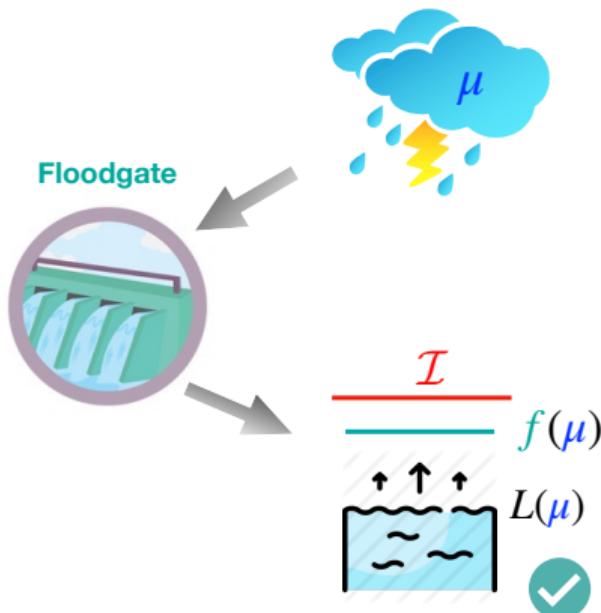
- Allow flexible regression algorithms, and is adaptive to the MSE.

Discussion: beyond this paper



Floodgate: a new inferential approach for
?

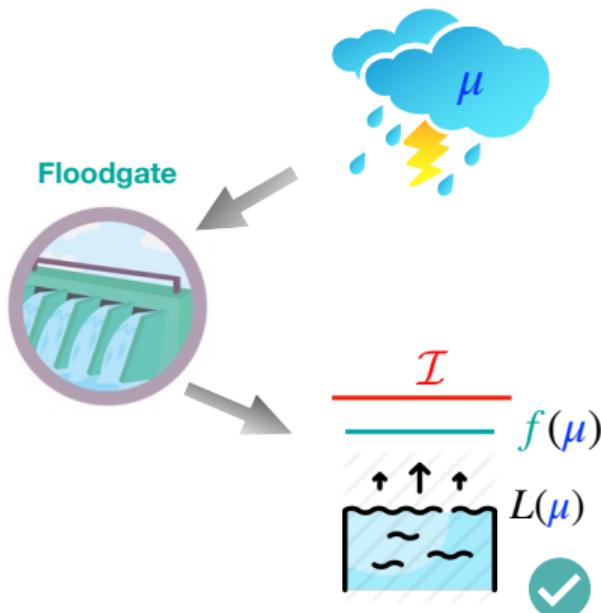
Discussion: beyond this paper



Floodgate: a new inferential approach for
?

- How to characterize a class of feasible model-free targets?

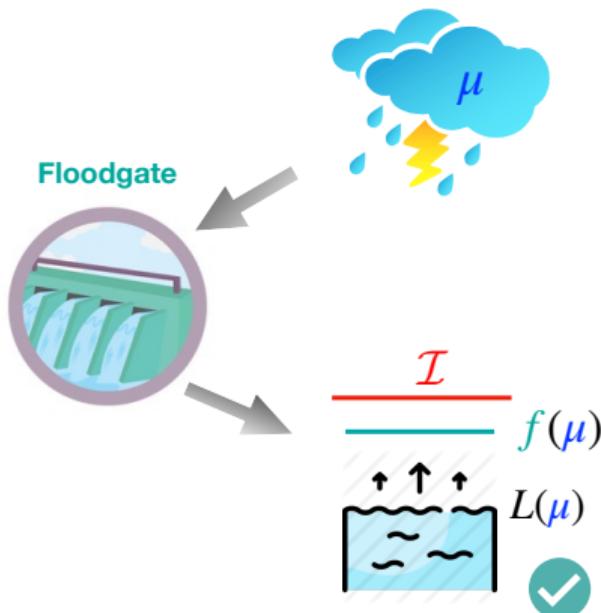
Discussion: beyond this paper



[Floodgate](#): a new inferential approach for
?

- How to characterize a class of feasible model-free targets?
- How to construct floodgate functional f ?

Discussion: beyond this paper



Floodgate: a new inferential approach for
?

- How to characterize a class of feasible model-free targets?
- How to construct floodgate functional f ?
- How to obtain LCBs for $f(\cdot)$ under reasonable conditions?

Appendix

MACM gap

Definition (Mean absolute conditional mean gap)

The *mean absolute conditional mean (MACM) gap* for variable X is defined as

$$\mathcal{I}_{\ell_1} = \mathbb{E} [|\mathbb{E}[Y | Z] - \mathbb{E}[Y | X, Z]|]$$

whenever all the above expectations exist.

The subscript in \mathcal{I}_{ℓ_1} reflects its similarity to $\mathcal{I}^2 = \mathbb{E} [(\mathbb{E}[Y | Z] - \mathbb{E}[Y | X, Z])^2]$ except with the square replaced by the absolute value (also known as the ℓ_1 norm).

Covariate dimension

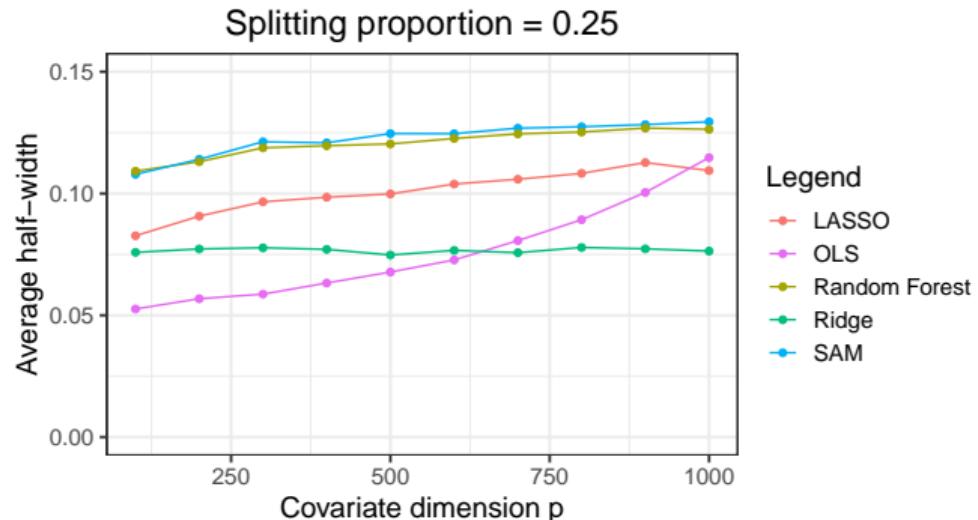
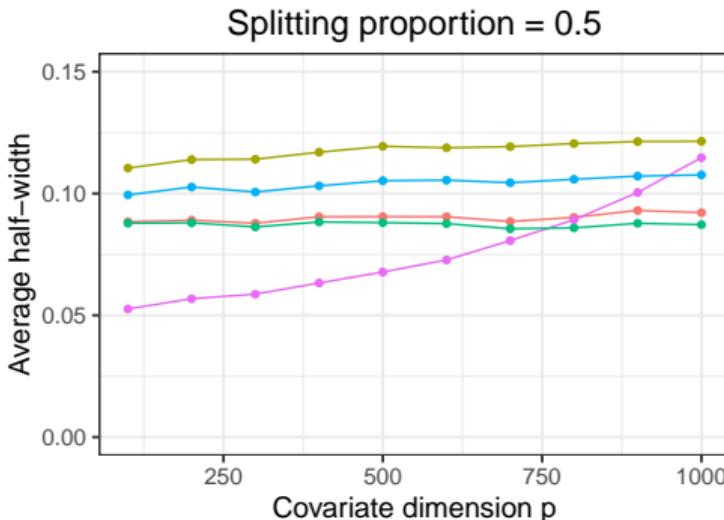


Figure: Linear setting.

Covariate dimension

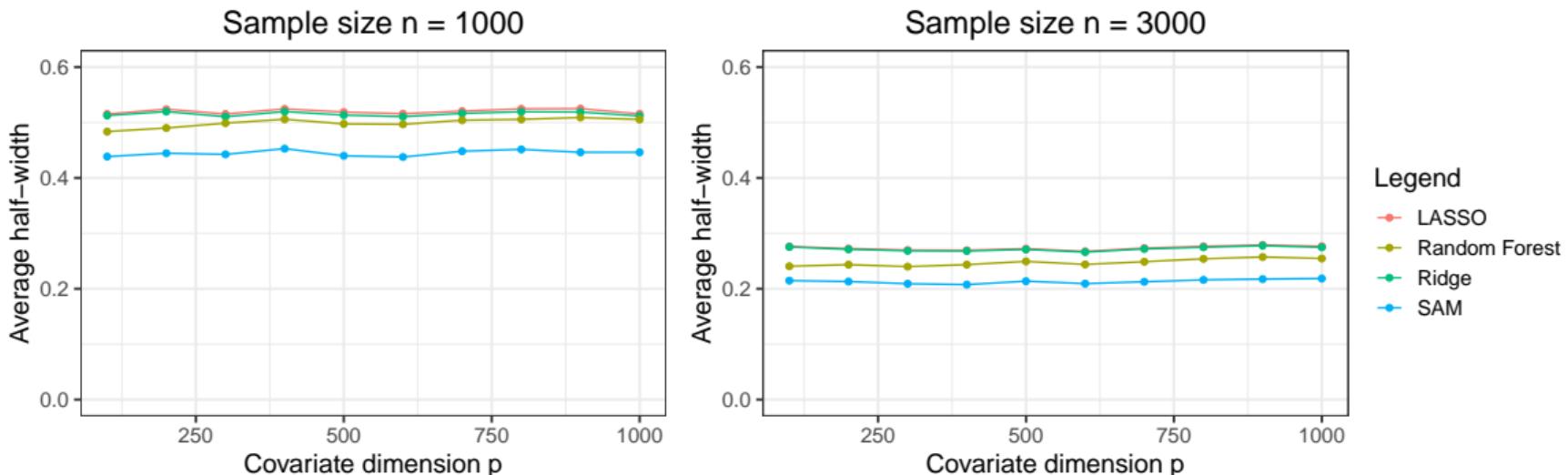


Figure: Nonlinear setting.

Sample size

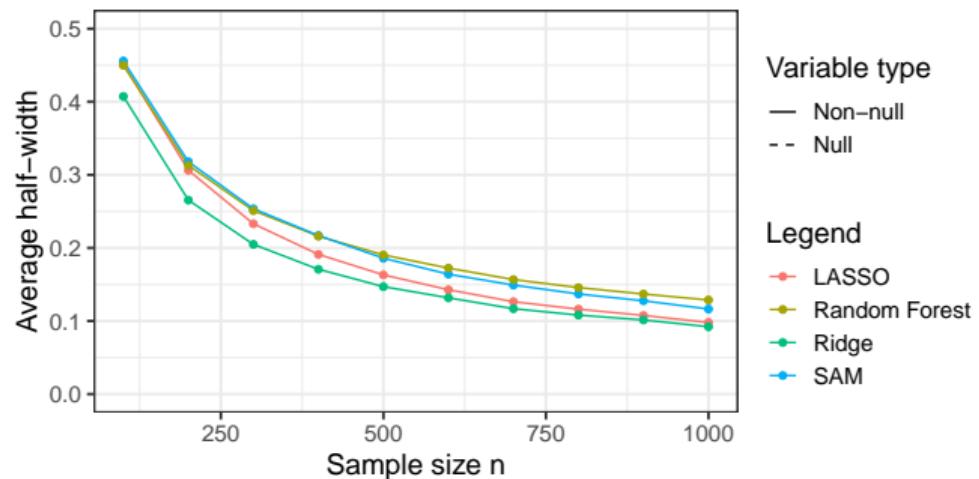
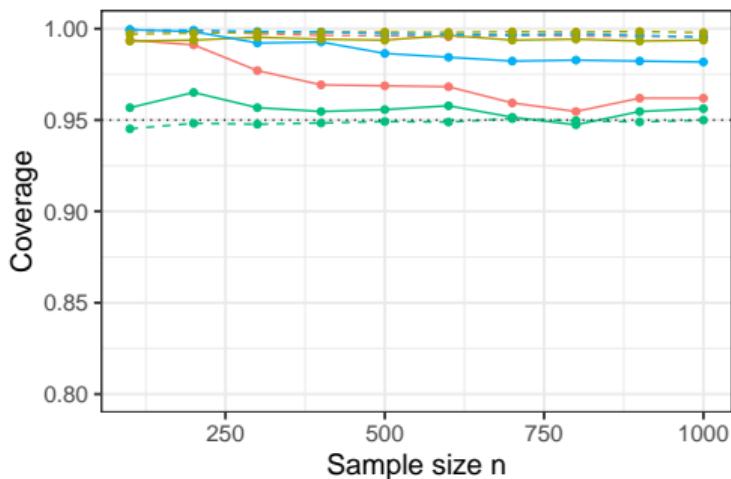


Figure: Linear setting.

Sample size

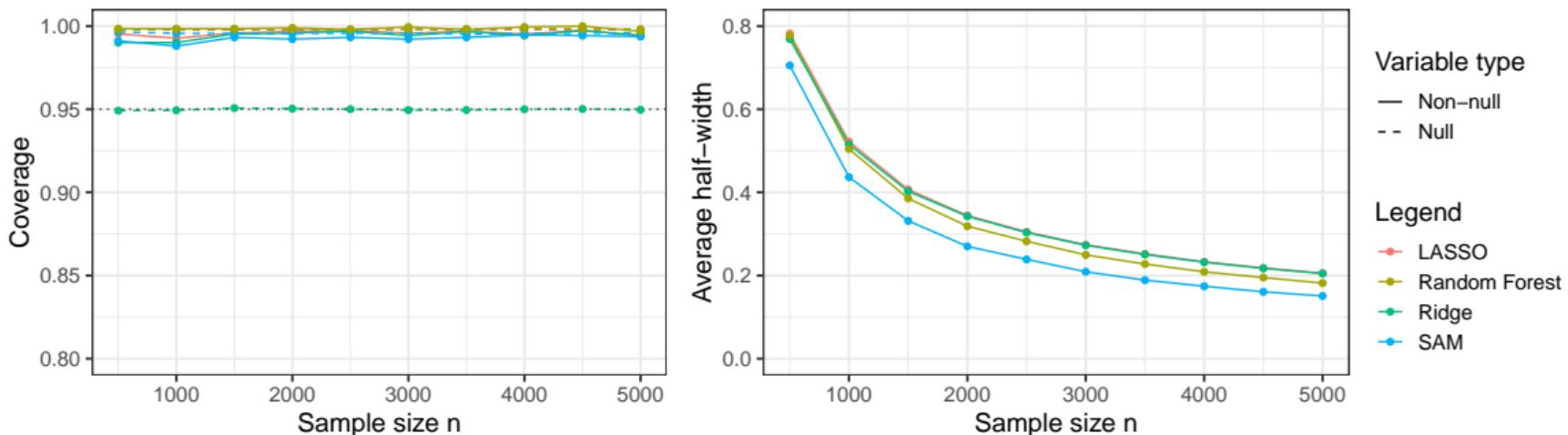


Figure: Nonlinear setting.

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