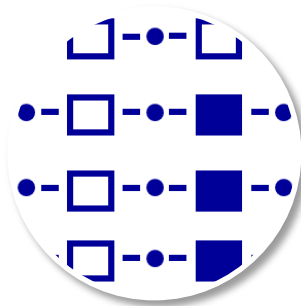


Regulation Analysis using Restricted Boltzmann Machines

Network Modeling Seminar, 10/1/2013

Patrick Michl



Biological Problem

Analysing the regulation of metabolism



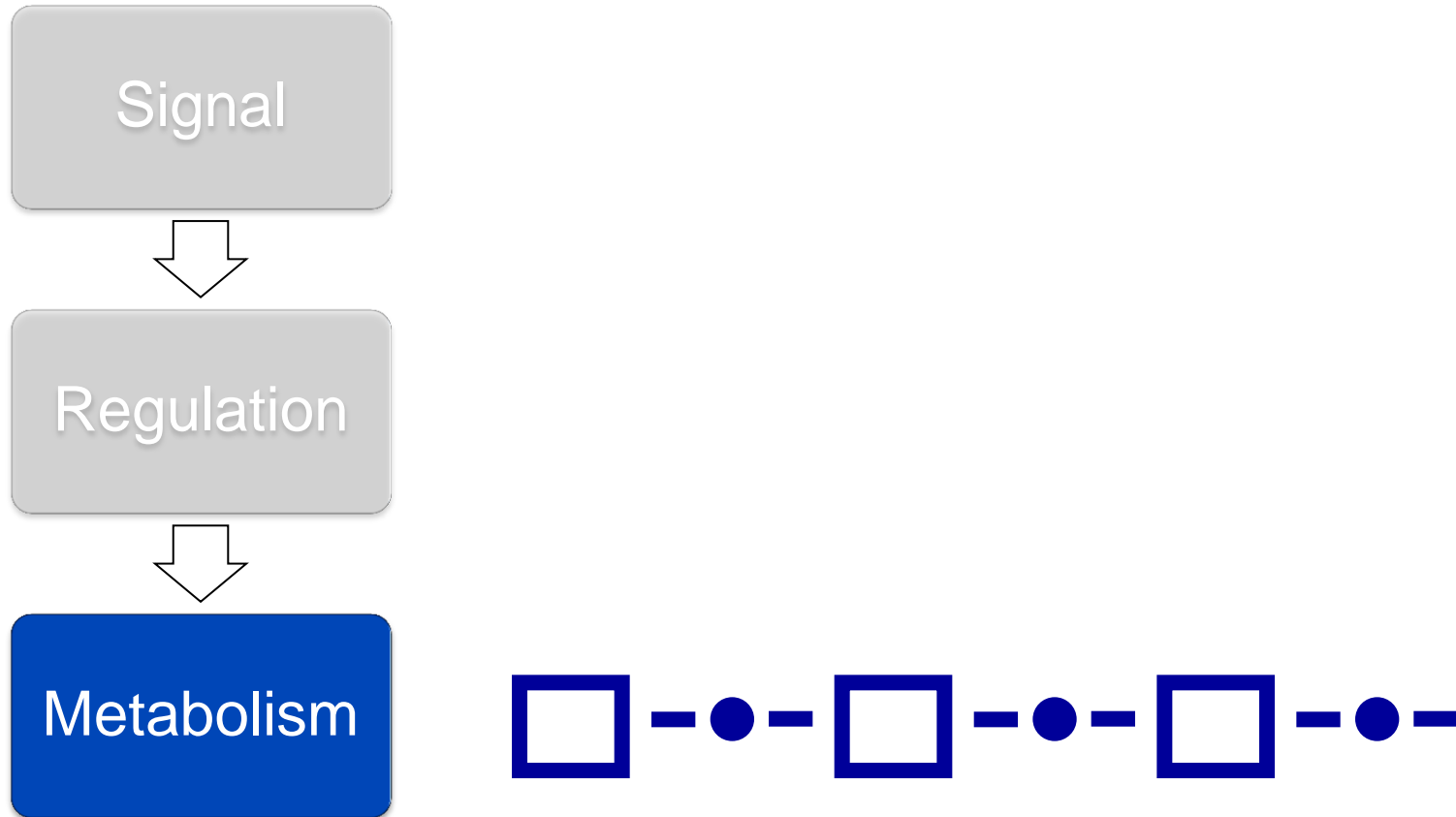
Modeling



Implementation & Results

Biological Problem

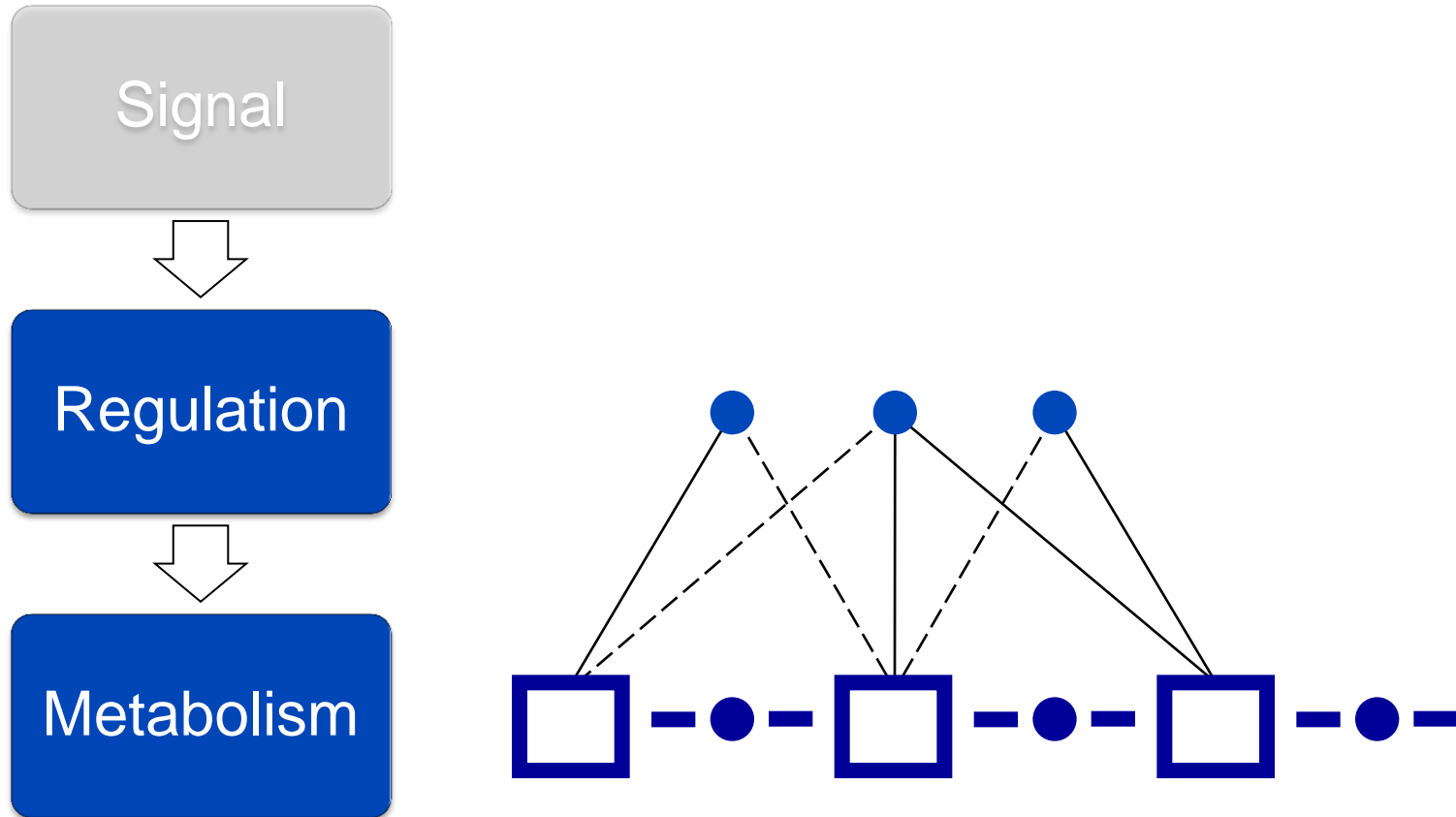
Analysing the regulation of metabolism



A linear metabolic pathway of enzymes (E) ...

Biological Problem

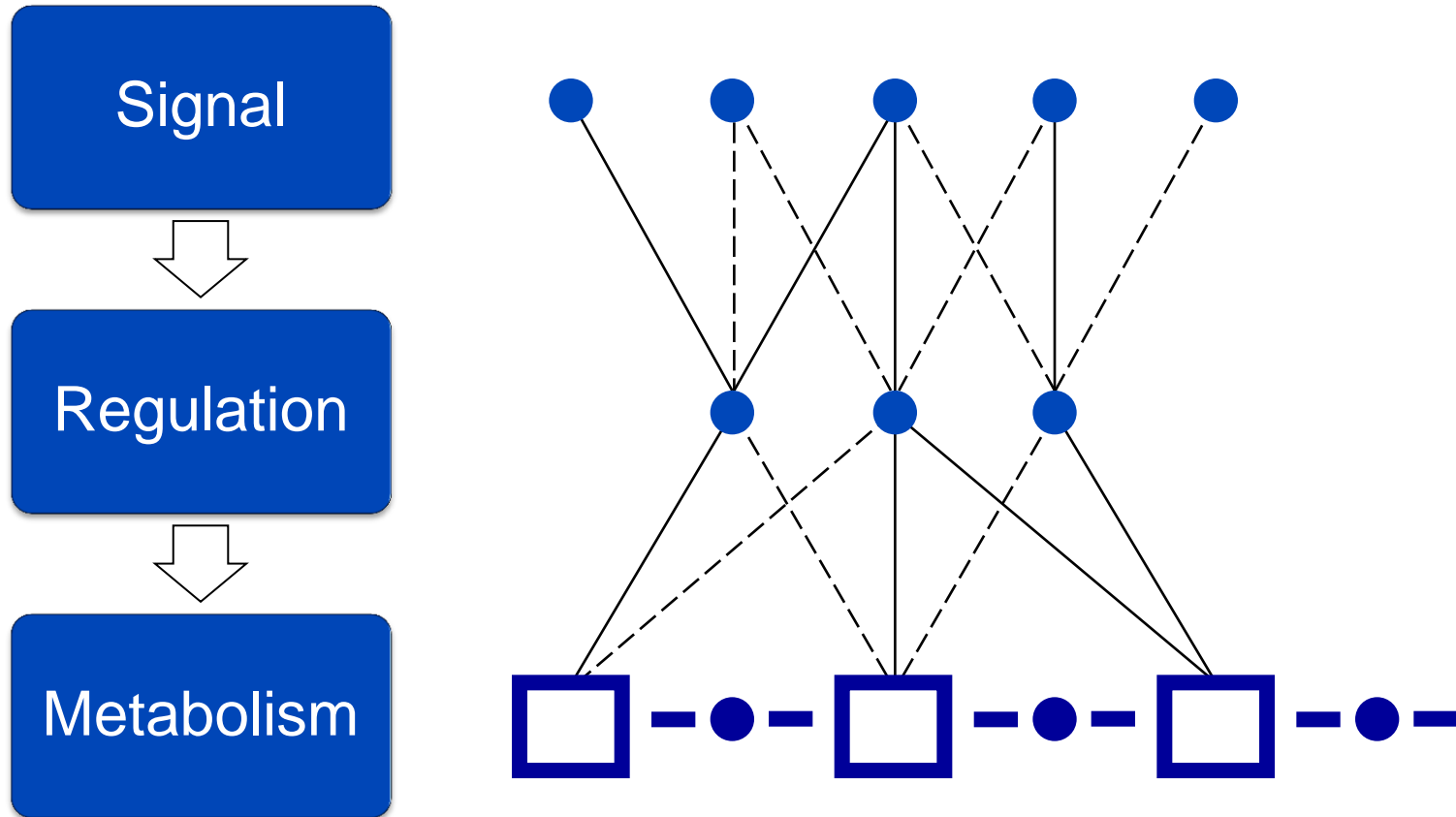
Analysing the regulation of metabolism



... is regulated by **transcription factors (TF)** ...

Biological Problem

Analysing the regulation of metabolism



... which respond to **signals** (S)

Biological Problem

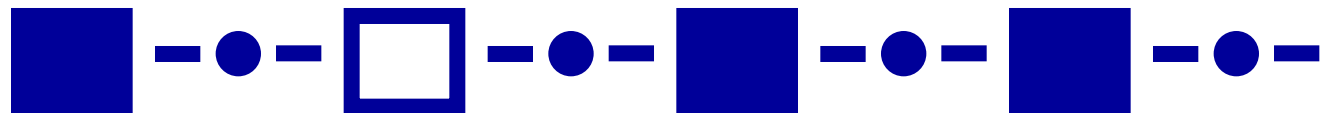
Analysing the regulation of metabolism

P 4

P 3

P 2

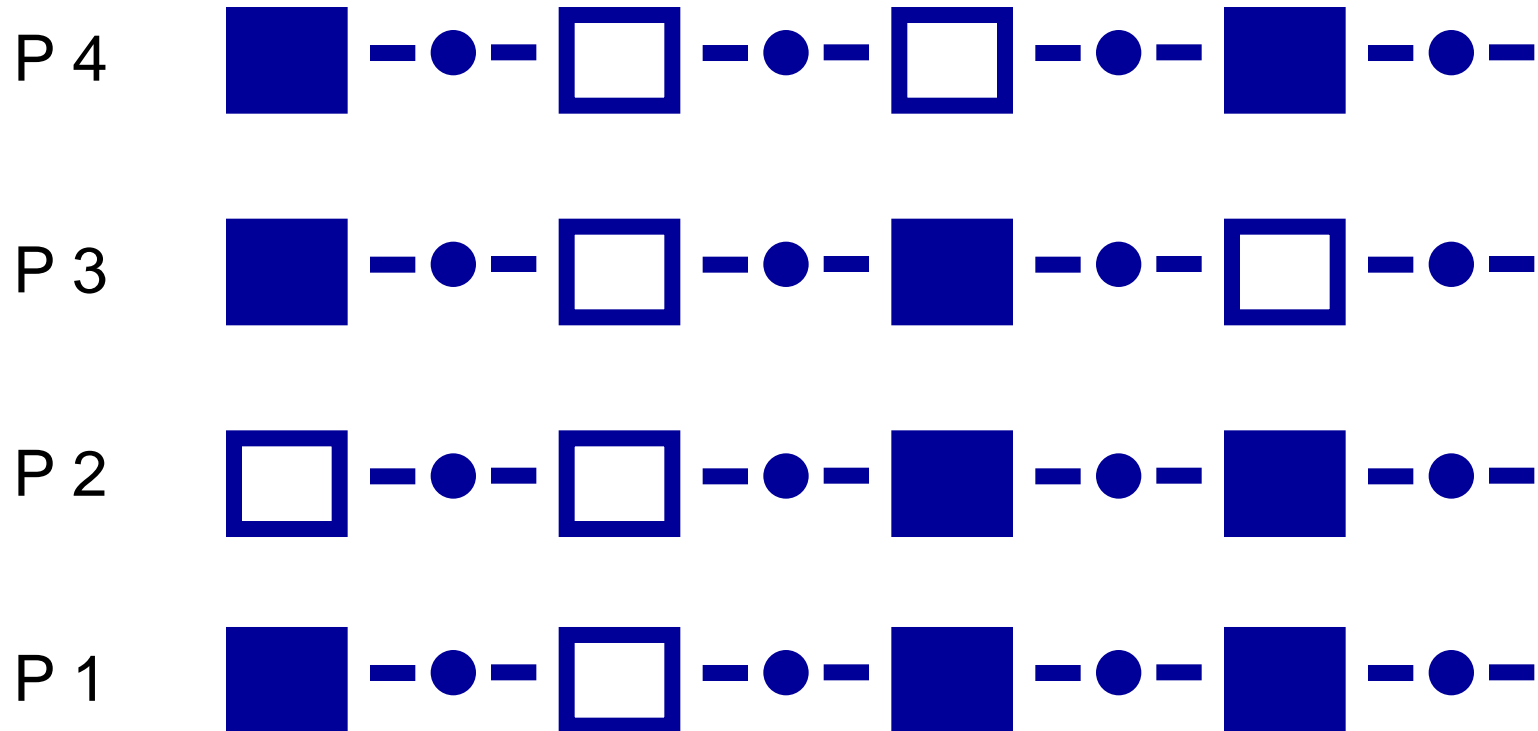
P 1



Upregulated linear pathways ...

Biological Problem

Analysing the regulation of metabolism



... can appear in **different patterns**

Biological Problem

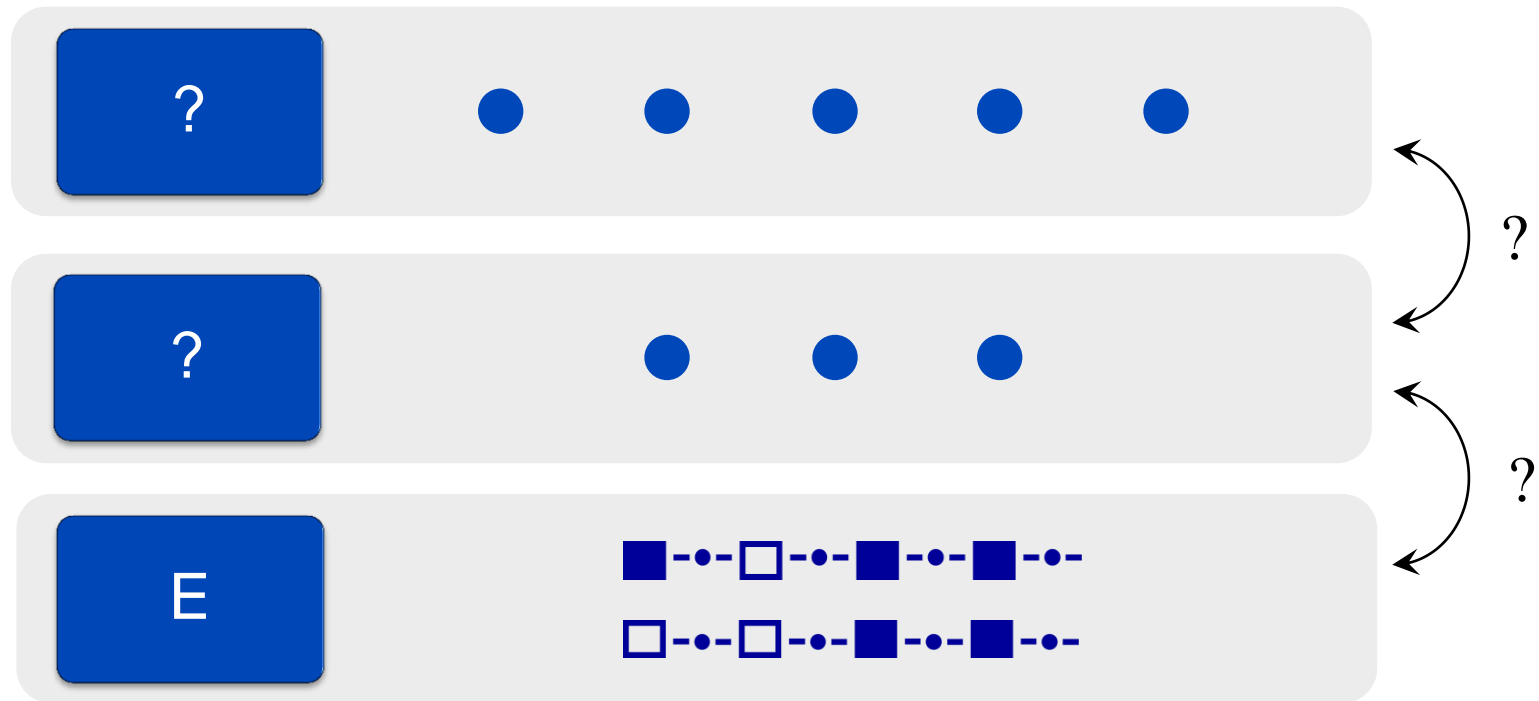
Analysing the regulation of metabolism



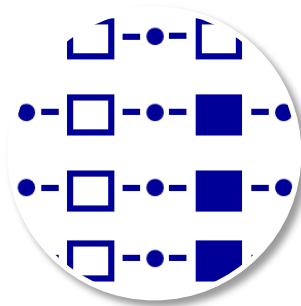
Which transcription factors and signals cause this patterns ...

Biological Problem

Analysing the regulation of metabolism

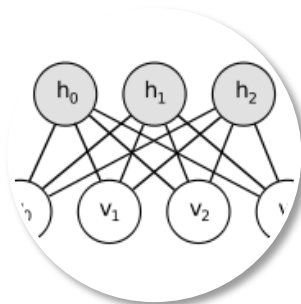


... and how do they interact? (topological structure)



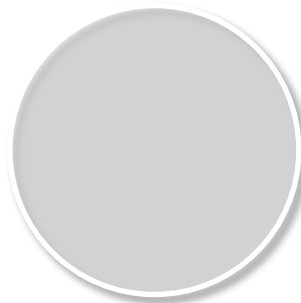
Biological Problem

Analysing the regulation of metabolism



Network Modeling

Restricted Boltzmann Machines (RBM)



Validation & Implementation

Network Modeling

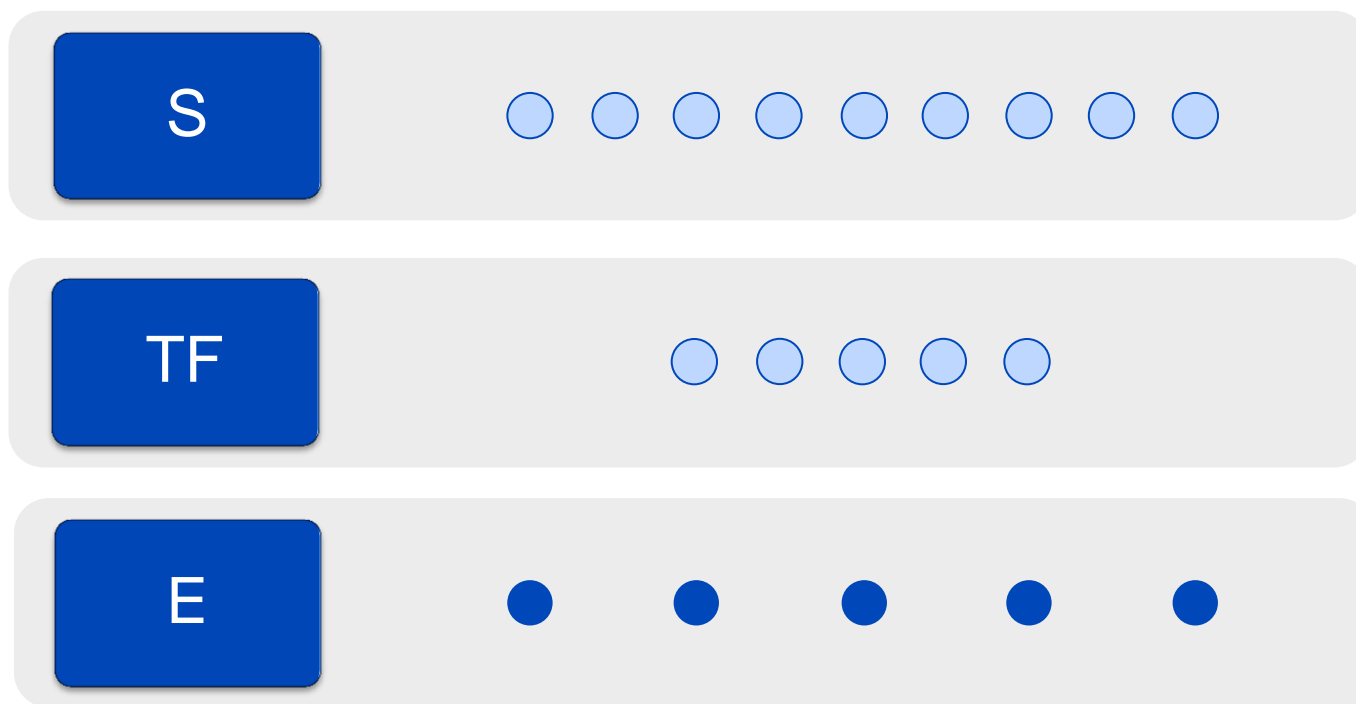
Restricted Boltzmann Machines (RBM)



Lets start with some pathway of our interest ...

Network Modeling

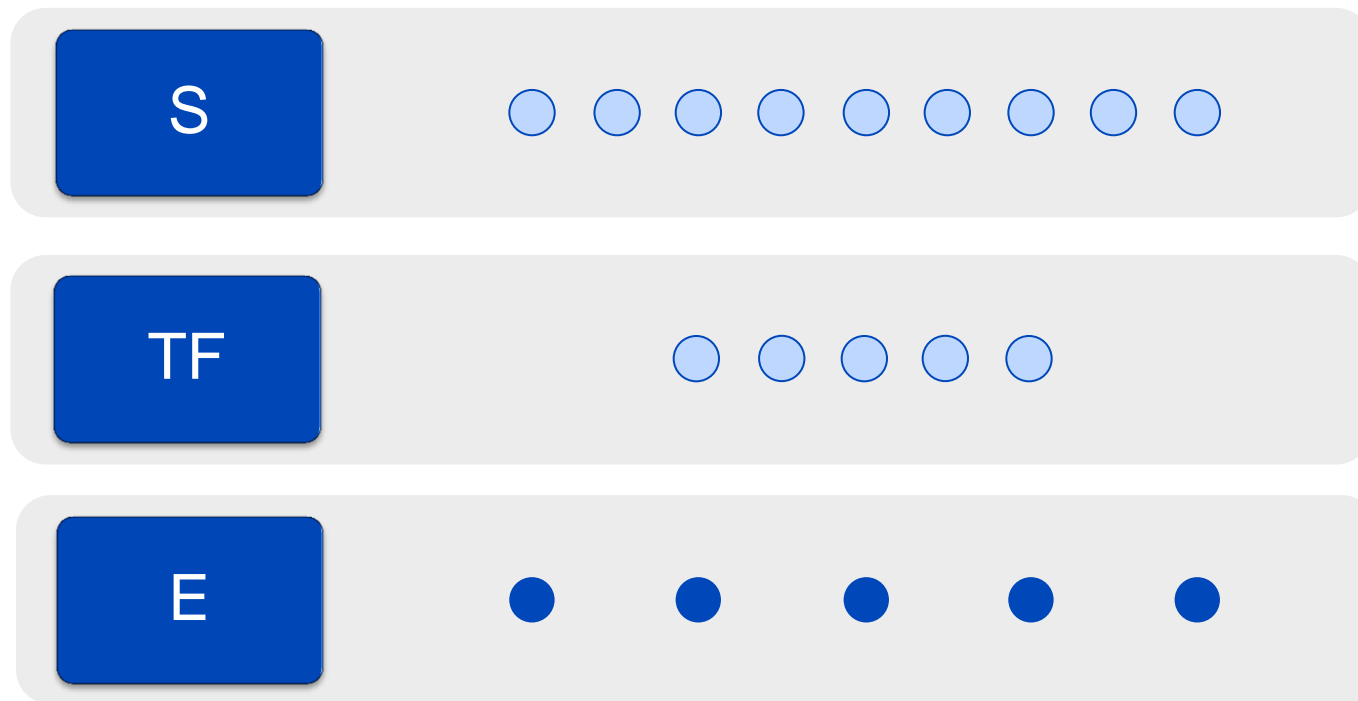
Restricted Boltzmann Machines (RBM)



... and lists of *interesting* TFs and *interesting* SigMols

Network Modeling

Restricted Boltzmann Machines (RBM)



How to model the topological structure?

Network Modeling

Restricted Boltzmann Machines (RBM)

Graphical Models

Graphical Models can preserve topological structures ...

Graphical Models

Directed Graph

...

Undirected Graph

... but there are many types of graphical models

Network Modeling

Restricted Boltzmann Machines (RBM)

Graphical Models

```
graph TD; A[Graphical Models] --> B[Directed Graph  
Bayesian Networks]; A --> C[...]; A --> D[Undirected Graph];
```

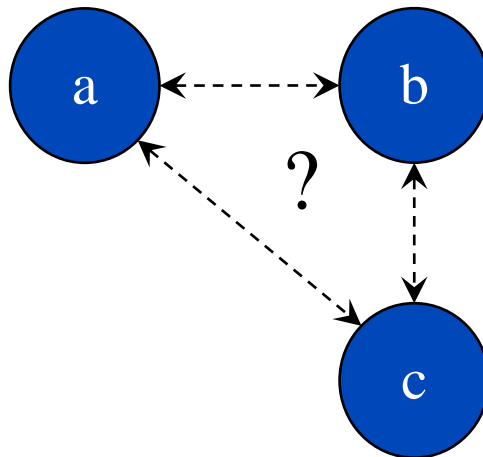
Directed Graph
Bayesian Networks

...

Undirected Graph

The most common type is the **Bayesian Network** (BN) ...

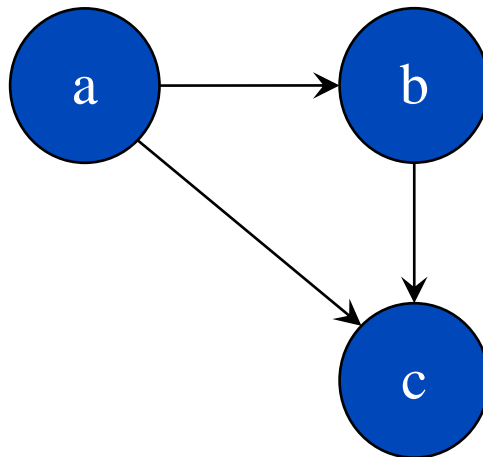
Bayesian Networks



a	b	c	$P[a,b,c]$
0	0	0	0.1
0	0	1	0.9
0	1	0	0.5
0	1	1	0.5
1	0	0	...
...

Bayesian Networks use **joint probabilities** ...

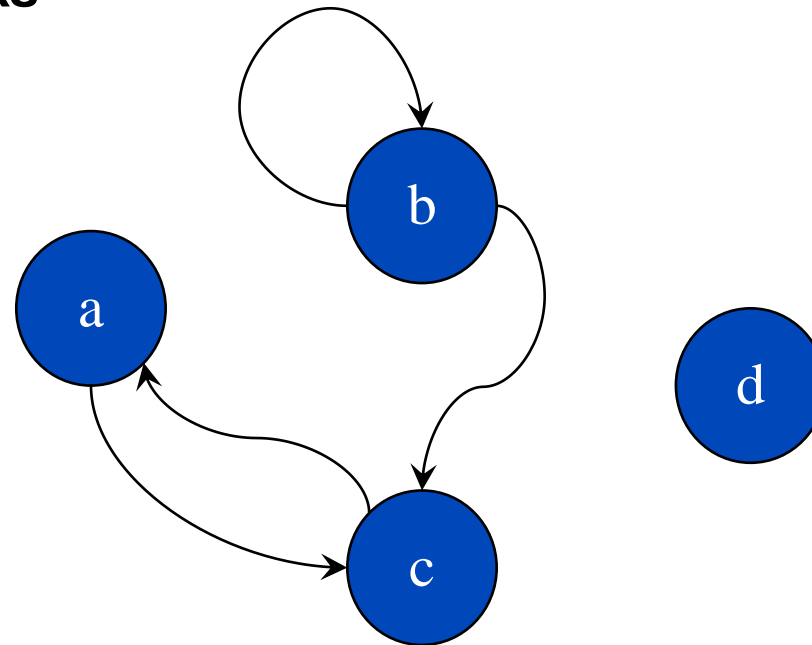
Bayesian Networks



a	b	c	$P[a,b,c]$
0	0	0	0.1
0	0	1	0.9
0	1	0	0.5
0	1	1	0.5
1	0	0	...
...

... to represents **conditional dependencies** in an **acyclic graph** ...

Bayesian Networks



... but the regulation mechanism of a cell can be more complicated

Network Modeling

Restricted Boltzmann Machines (RBM)

Graphical Models

```
graph TD; A[Graphical Models] --> B[Directed Graph<br/>Bayesian Networks]; A --> C[...]; A --> D[Undirected Graph<br/>Markov Random Fields];
```

Directed Graph
Bayesian Networks

...

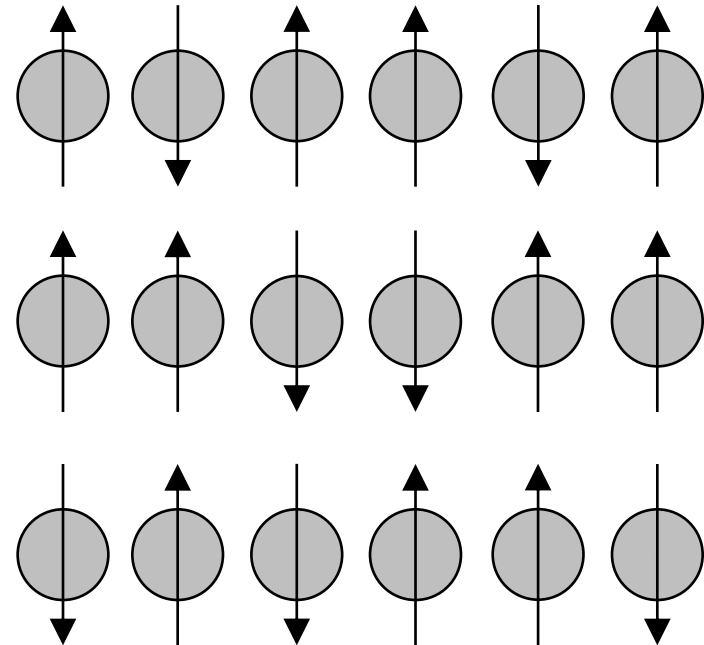
Undirected Graph
Markov Random Fields

Another type of graphical models are **Markov Random Fields** (MRF)...

Markov Random Fields

Motivation (Ising Model)

A set of magnetic dipoles (*spins*) is arranged in a graph (lattice) where neighbors are coupled with a given strength

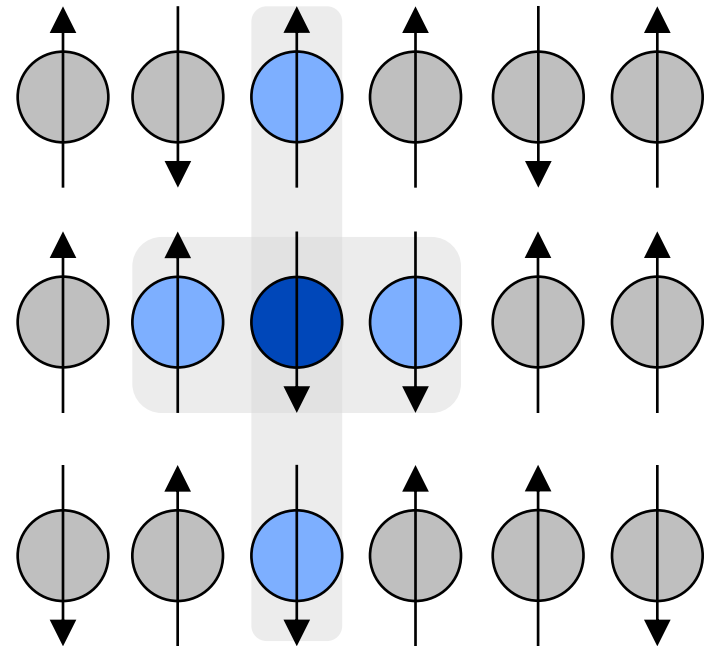


... which emerged with the **Ising Model** from statistical Physics ...

Markov Random Fields

Motivation (Ising Model)

A set of magnetic dipoles (*spins*) is arranged in a graph (lattice) where neighbors are coupled with a given strength

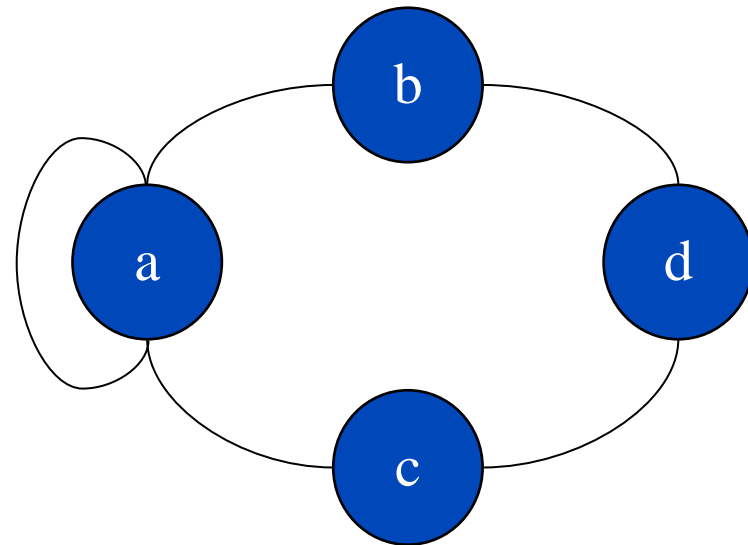


... which uses **local energies** to calculate new states ...

Markov Random Fields

Drawback

By allowing cyclic dependencies
the computational costs
explode



... the drawback are **high computational costs** ...

Network Modeling

Restricted Boltzmann Machines (RBM)

Graphical Models

```
graph TD; A[Graphical Models] --> B[Directed Graph  
Bayesian Networks]; A --> C[...]; A --> D[Undirected Graph  
Markov Random Fields]; D --> E[Restricted Boltzmann  
Machines (RBM)]; D --> F[...];
```

Directed Graph
Bayesian Networks

...

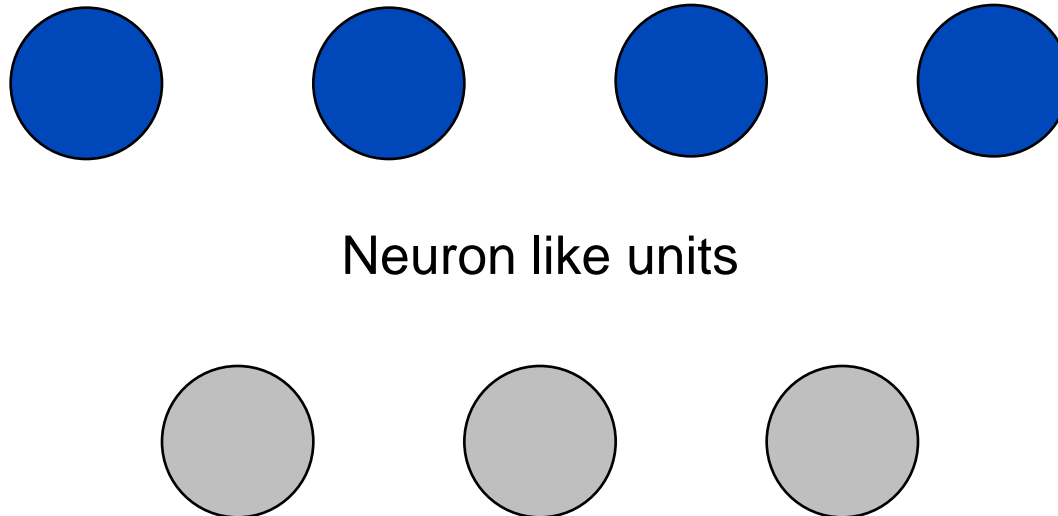
Undirected Graph
Markov Random Fields

*Restricted Boltzmann
Machines (RBM)*

...

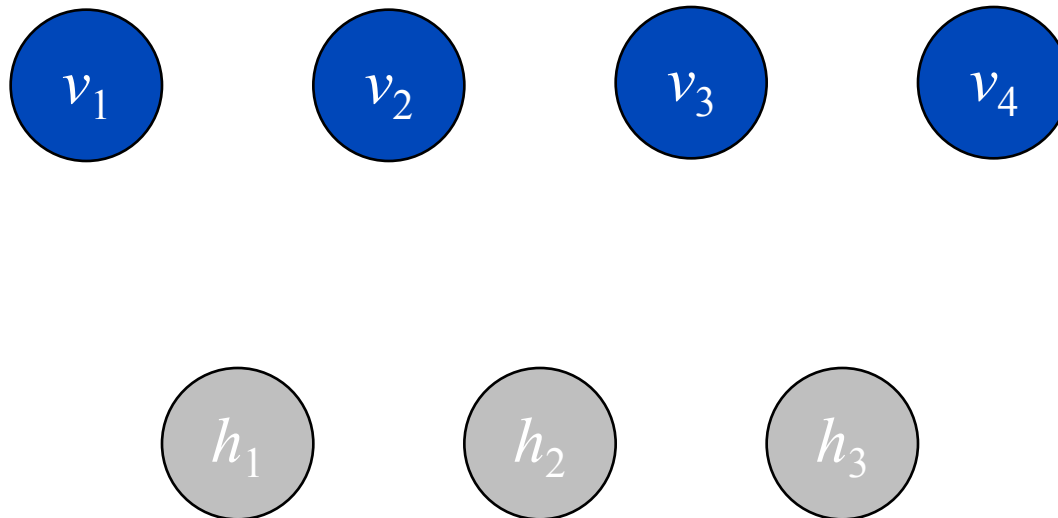
... which can be avoided by using **Restricted Boltzmann Machines**

Restricted Boltzmann Machines



RBM's are Artificial Neuronal Networks ...

Restricted Boltzmann Machines

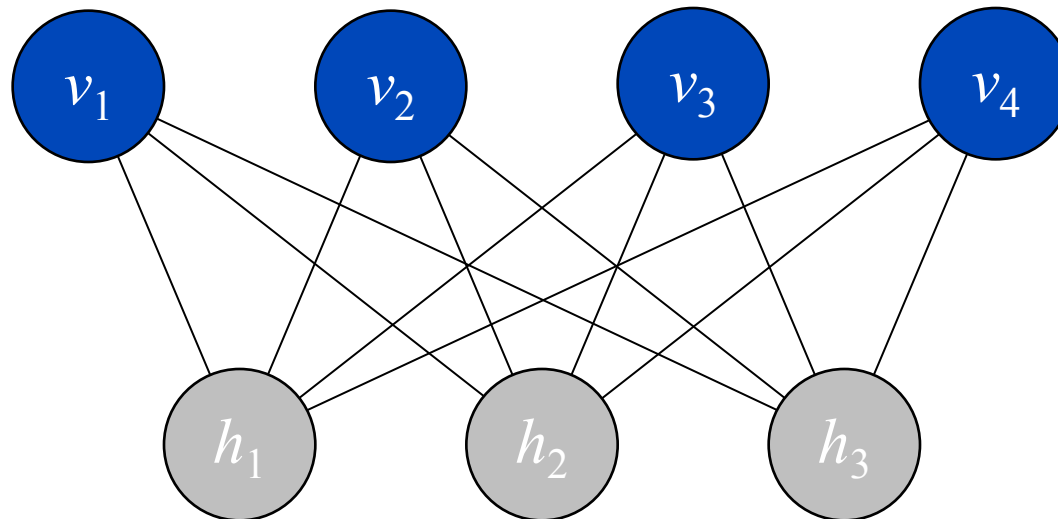


... with two layers: **visible units** (v) and **hidden units** (h)

Network Modeling

Restricted Boltzmann Machines (RBM)

Restricted Boltzmann Machines



Visible units are **strictly** connected with hidden units

Network Modeling

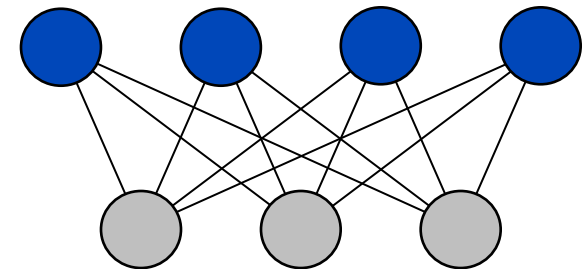
Restricted Boltzmann Machines (RBM)

Restricted Boltzmann Machines

V := set of visible units

x_v := value of unit v , $\forall v \in V$

$x_v \in R$, $\forall v \in V$



In our model the visible units have **continuous values** ...

Restricted Boltzmann Machines

V := set of visible units

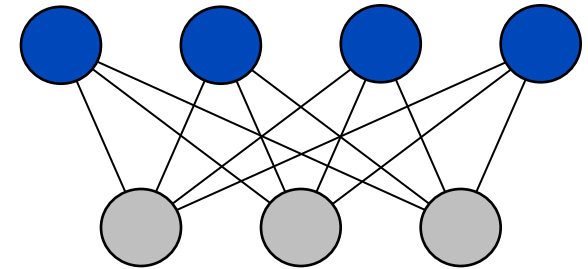
x_v := value of unit v , $\forall v \in V$

$x_v \in R$, $\forall v \in V$

H := set of hidden units

x_h := value of unit h , $\forall h \in H$

$x_h \in \{0, 1\}$, $\forall h \in H$



... and the hidden units **binary values**

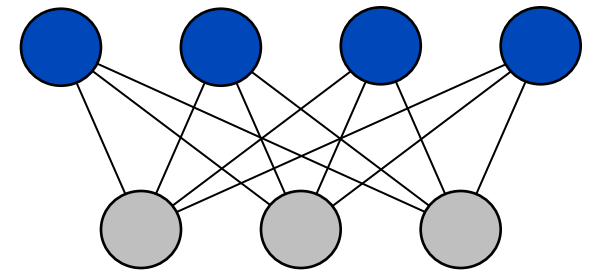
Restricted Boltzmann Machines

$$x_v \sim N(b_v + \sum_h w_{vh} x_h, \sigma_v), \forall v \in V$$

σ_v := std. dev. of unit v

b_v := bias of unit v

w_{vh} := weight of edge (v, h)



Visible units are modeled with **gaussians** to encode **data** ...

Restricted Boltzmann Machines

$$x_v \sim N(b_v + \sum_h w_{vh} x_h, \sigma_v), \forall v \in V$$

σ_v := std. dev. of unit v

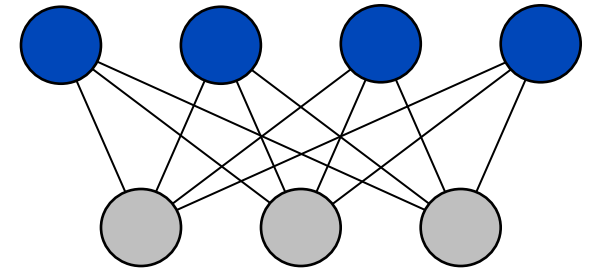
b_v := bias of unit v

w_{vh} := weight of edge (v, h)

$$x_h \sim \text{sigmoid}\left(b_h + \sum_v w_{vh} \frac{x_v}{\sigma_v}\right), \forall h \in H$$

b_h := bias of unit h

w_{vh} := weight of edge (v, h)



... and hidden units with **simoids** to encode **dependencies**

Learning in Restricted Boltzmann Machines

Task: Find dependencies in data

↔ Find configuration of parameters with maximum likelihood (to data)

The challenge is to find the configuration of the parameters ...

Learning in Restricted Boltzmann Machines

Task: Find dependencies in data

↔ Find configuration of parameters with maximum likelihood (to data)

In RBMs configurations of parameters have probabilities,
that can be defined by local energies

Local Energy

1

$$E_v := - \sum_h w_{vh} \frac{x_v}{\sigma_v} x_h + \frac{(x_v - b_v)^2}{2\sigma_v^2}$$

2

$$E_h := - \sum_v w_{vh} \frac{x_v}{\sigma_v} x_h + x_h b_h$$

Like in the Ising model the units states correspond to **local energies** ...

Learning in Restricted Boltzmann Machines

Task: Find dependencies in data

↔ Find configuration of parameters with maximum likelihood (to data)

↔ Minimize global energy (to data)

Global Energy

$$E := \sum_v E_v + \sum_h E_h = - \sum_v \sum_h w_{vh} \frac{x_v}{\sigma_v} x_h + \sum_v \frac{(x_v - b_v)^2}{2\sigma_v^2} + \sum_h w_{vh} \frac{x_v}{\sigma_v} x_h$$

... which sum to a **global energy**, which is our objective function

Learning in Restricted Boltzmann Machines

Task: Find dependencies in data

↔ Find configuration of parameters with maximum likelihood (to data)

↔ Minimize global energy (to data)

↔ Perform stochastic gradient descent on σ_v , b_v , b_h , w_{vh} (to data)

The optimization can be done using stochastic **gradient descent** ...

Learning in Restricted Boltzmann Machines

Task: Find dependencies in data

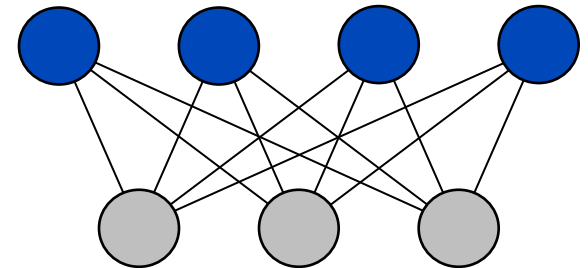
↔ Find configuration of parameters with maximum likelihood (to data)

↔ Minimize global energy (to data)

↔ Perform stochastic gradient descent on σ_v , b_v , b_h , w_{vh} (to data)

Gradient Descent on RBMs

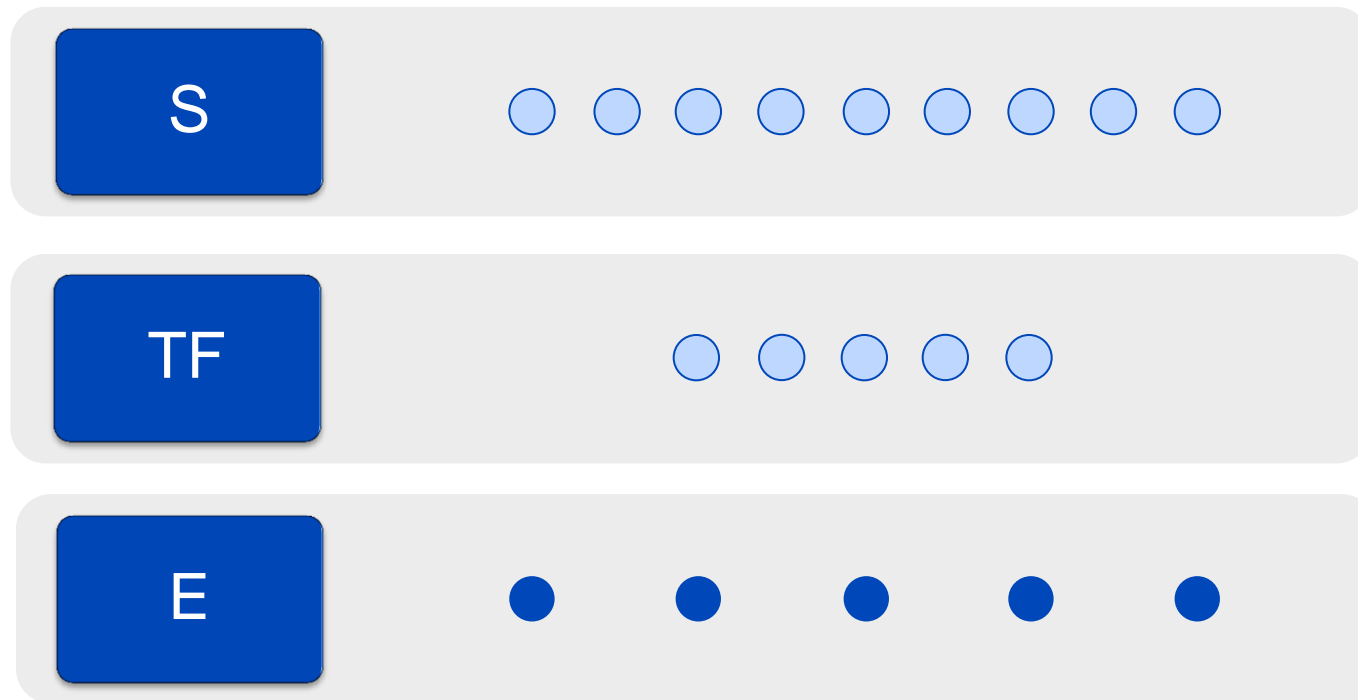
The bipartite graph structure allows
contrastive divergency learning,
using *Gibbs-sampling*



... which has an efficient learning algorithmus

Network Modeling

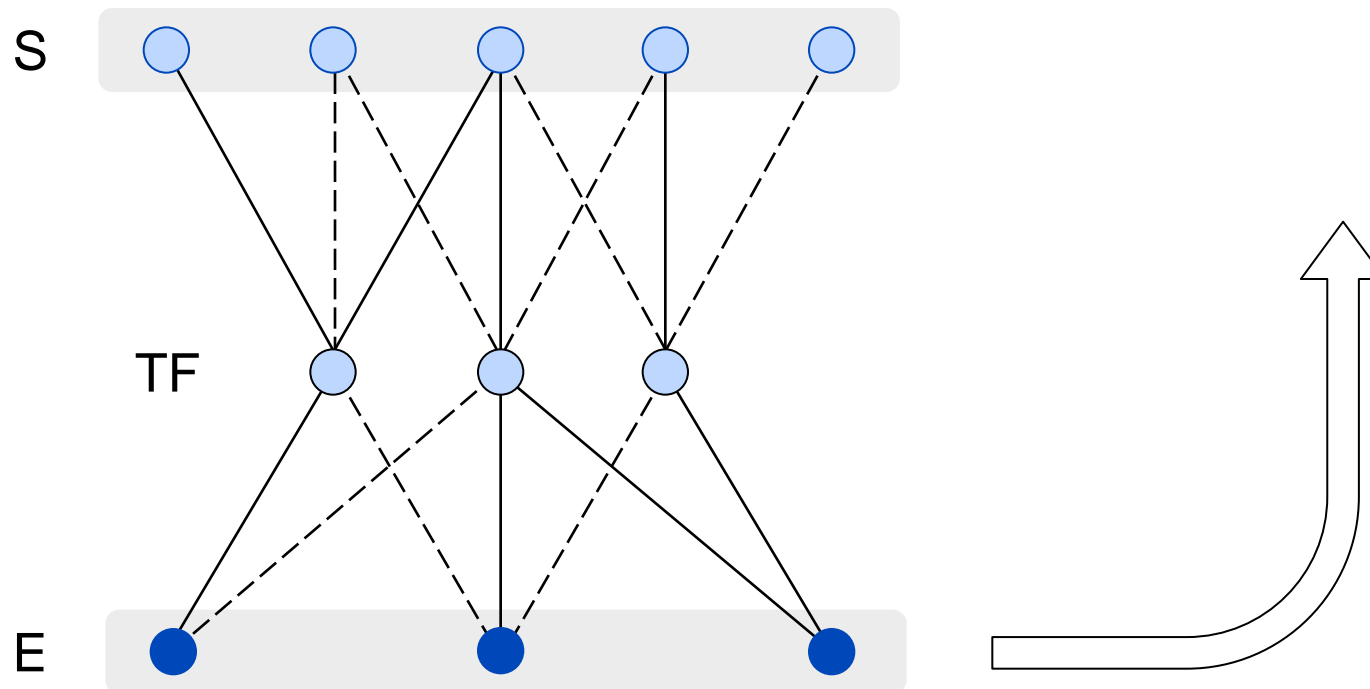
Restricted Boltzmann Machines (RBM)



How to model our initial structure as an RBM?

Network Modeling

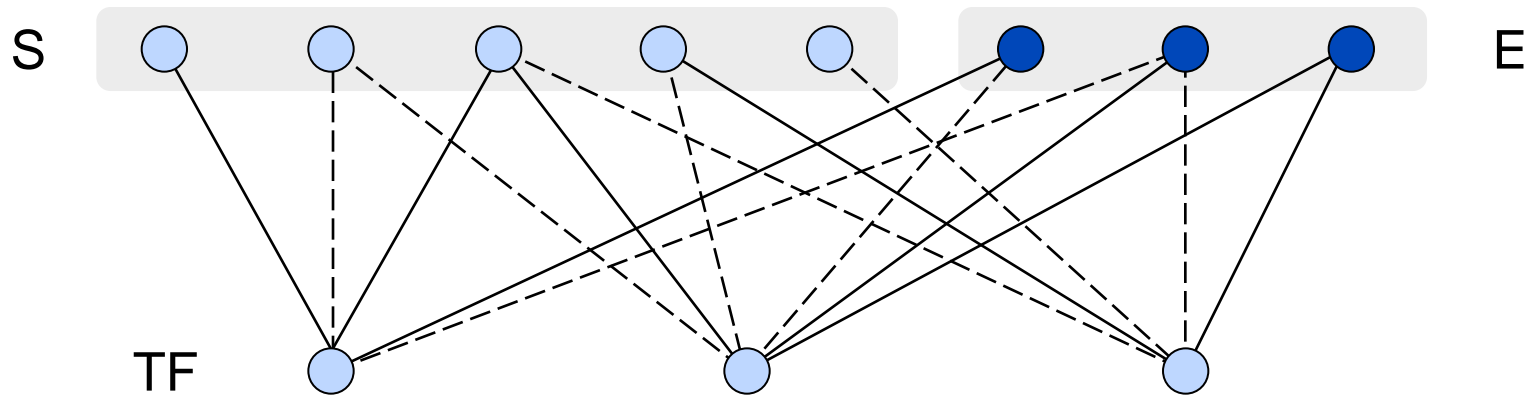
Restricted Boltzmann Machines (RBM)



We define S and E as **visible Layer** ...

Network Modeling

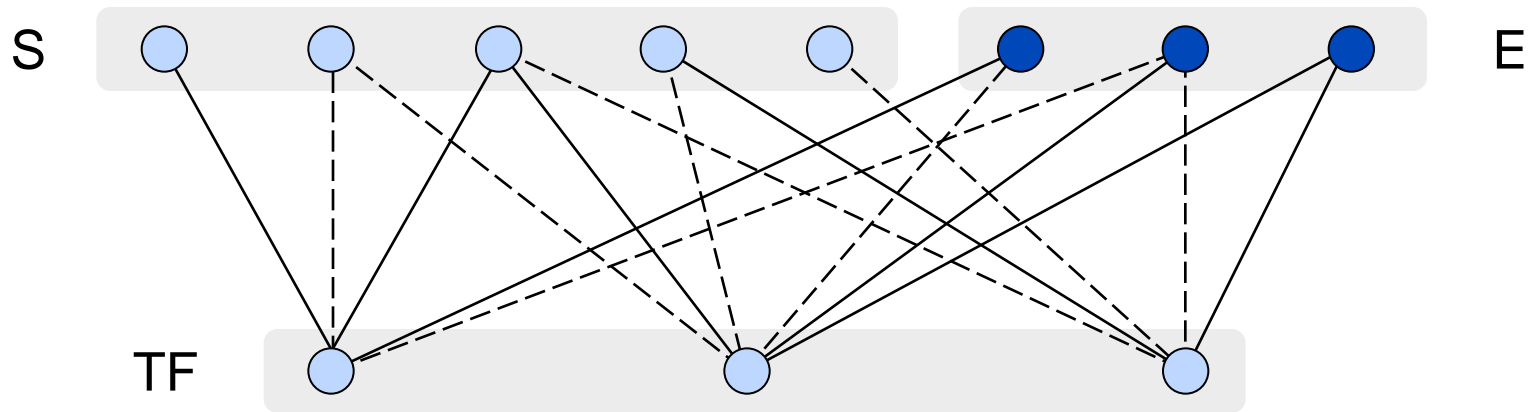
Restricted Boltzmann Machines (RBM)



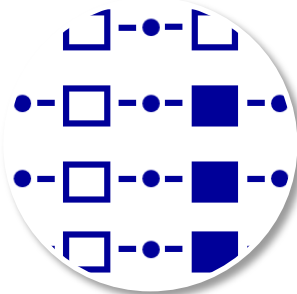
We define S and E as **visible Layer** ...

Network Modeling

Restricted Boltzmann Machines (RBM)

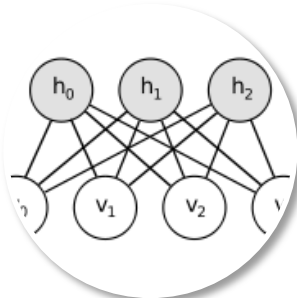


... and TF as **hidden Layer**



Biological Problem

Analysing the regulation of metabolism



Network Modeling

Restricted Boltzmann Machines (RBM)

```
class RBM:
    def __init__(self,
                 self.num_hidden = 10,
                 self.num_visible = 100,
                 self.learning_rate = 0.1):

        # Initialize a weight matrix
        # a Gaussian distribution
        self.weights = 0.01 * np.random.randn(
            self.num_hidden, self.num_visible)
        # Insert weights
```

Implementation & Results

python::metapath

Validation of the results

- Information about the true regulation
- Information about the descriptive power of the data

Validation of the results

- Information about the true regulation
- Information about the descriptive power of the data

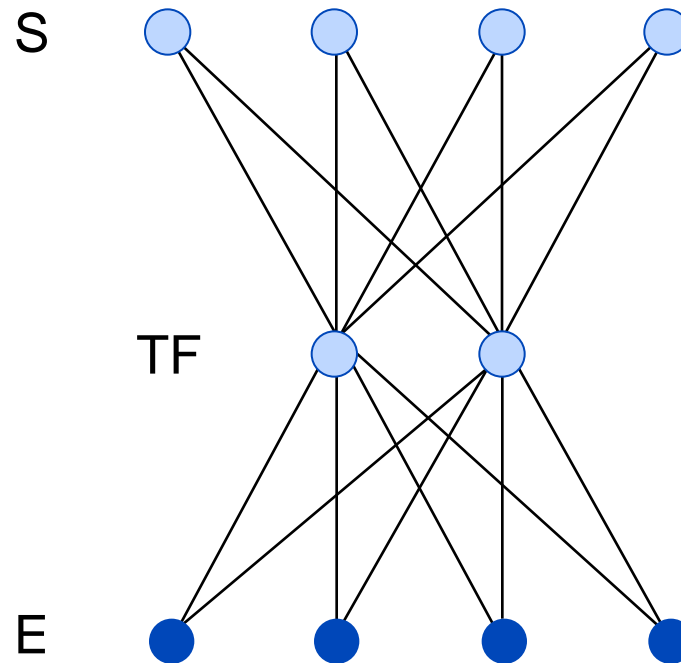
Without this information validation can only be done, using simulated data!

Simulation 1

First of all we need to understand how the modell handles **dependencies** and **noise**

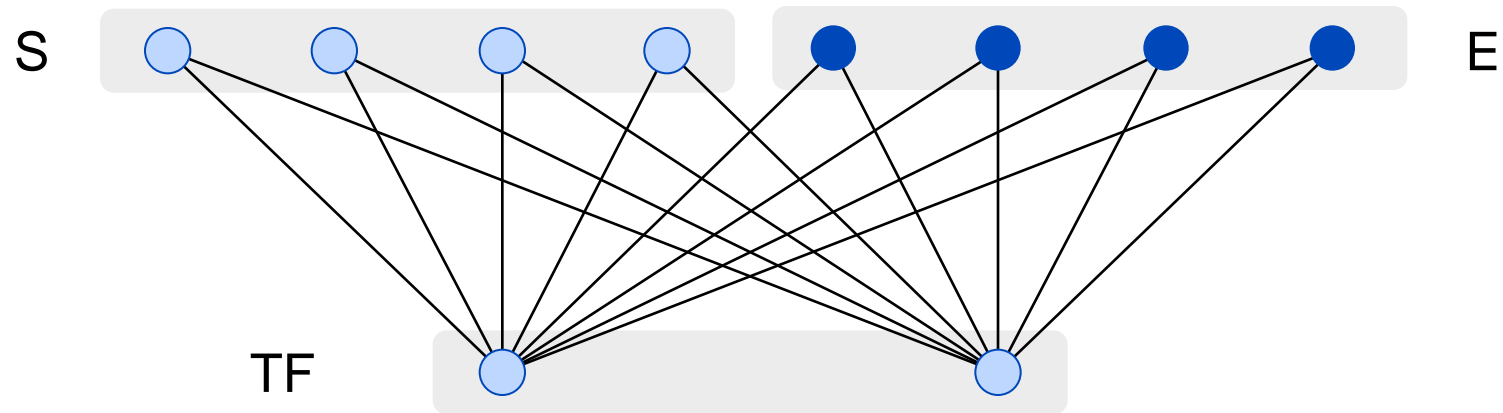
To demonstrate this we create very simple data with a simple structure

Simulation 1



What can we expect from this model?

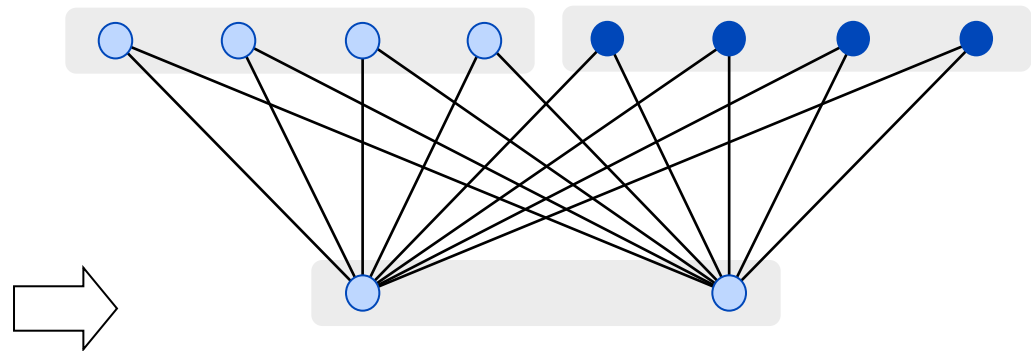
Simulation 1



... as RBM we get 8 visible and 2 hidden units, fully connected

Data

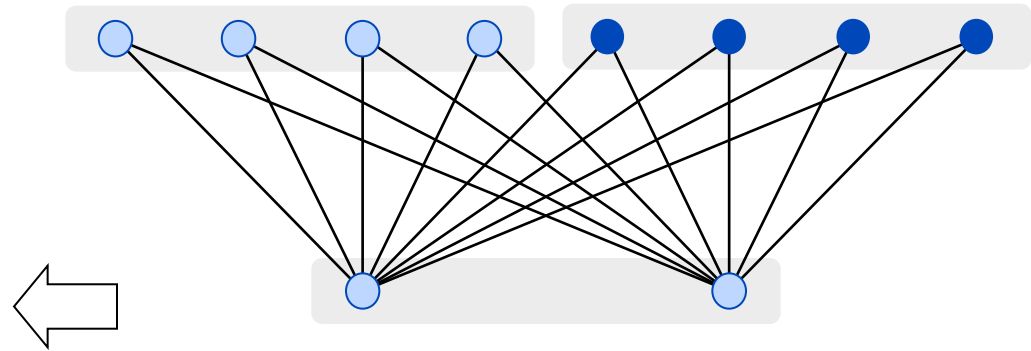
S	E
1,0,0,1	1,0,0,0
1,0,0,1	1,1,0,0
1,0,0,1	1,0,1,0
1,0,0,1	1,0,0,1
1,0,1,1	0,0,0,0
1,0,1,1	0,1,0,0
1,0,1,1	0,0,1,0
1,0,1,1	0,0,0,1



Let's feed the machine with **samples** ...

Weight matrix

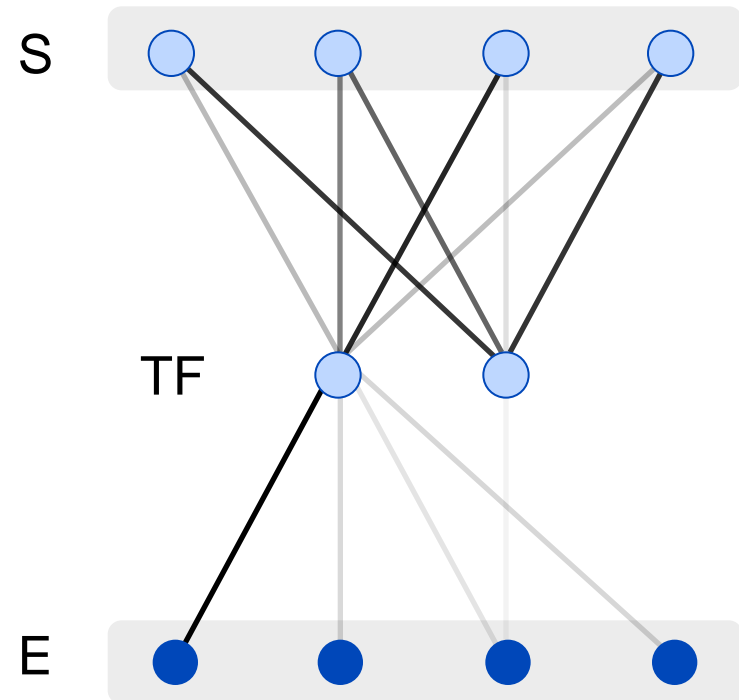
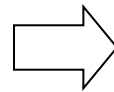
	TF_1	TF_2
S_1	0,3	0,8
S_2	0,5	0,6
S_3	1,0	0,1
S_4	0,3	0,8
E_1	0,8	0,0
E_2	0,1	0,0
E_3	0,1	0,0
E_4	0,2	0,0



.. to get the calculated parameters (especially the **weight matrix**)

Weight matrix

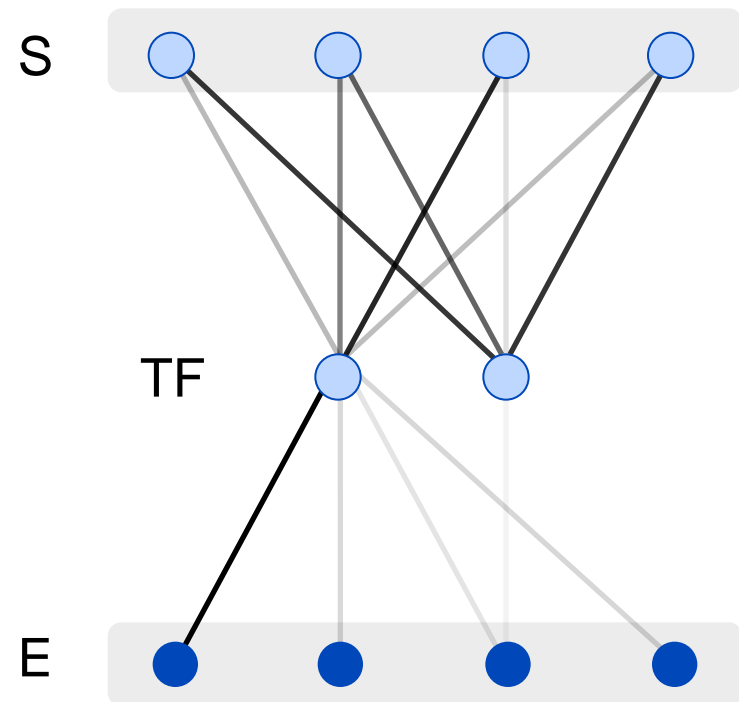
	TF_1	TF_2
S_1	0,3	0,8
S_2	0,5	0,6
S_3	1,0	0,1
S_4	0,3	0,8
E_1	0,8	0,0
E_2	0,1	0,0
E_3	0,1	0,0
E_4	0,2	0,0



The weights are visualized by the **intensity** of the edges

Learning samples

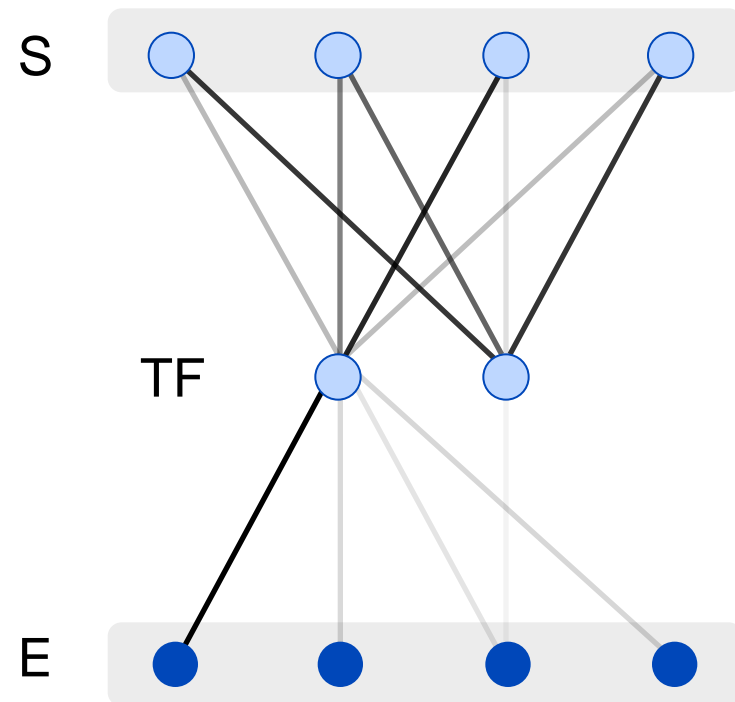
S	E
1,0,0,1	1,0,0,0
1,0,0,1	1,1,0,0
1,0,0,1	1,0,1,0
1,0,0,1	1,0,0,1
1,0,1,1	0,0,0,0
1,0,1,1	0,1,0,0
1,0,1,1	0,0,1,0
1,0,1,1	0,0,0,1



Now we can compare the results with the samples

Learning samples

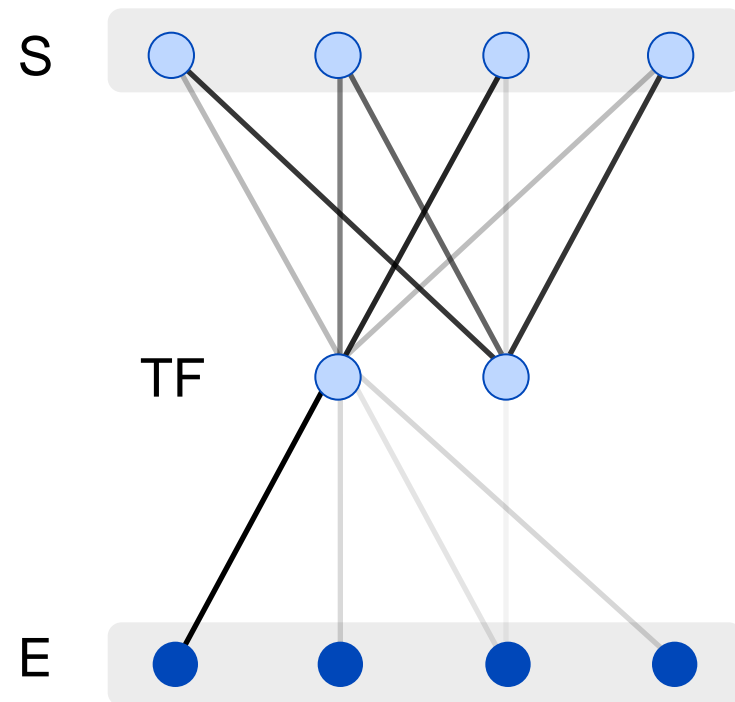
S	E
1,0, 0 ,1	1 ,0,0,0
1,0, 0 ,1	1 ,1,0,0
1,0, 0 ,1	1 ,0,1,0
1,0, 0 ,1	1 ,0,0,1
1,0, 1 ,1	0 ,0,0,0
1,0, 1 ,1	0 ,1,0,0
1,0, 1 ,1	0 ,0,1,0
1,0, 1 ,1	0 ,0,0,1



There's a strong dependency between S_3 and E_1

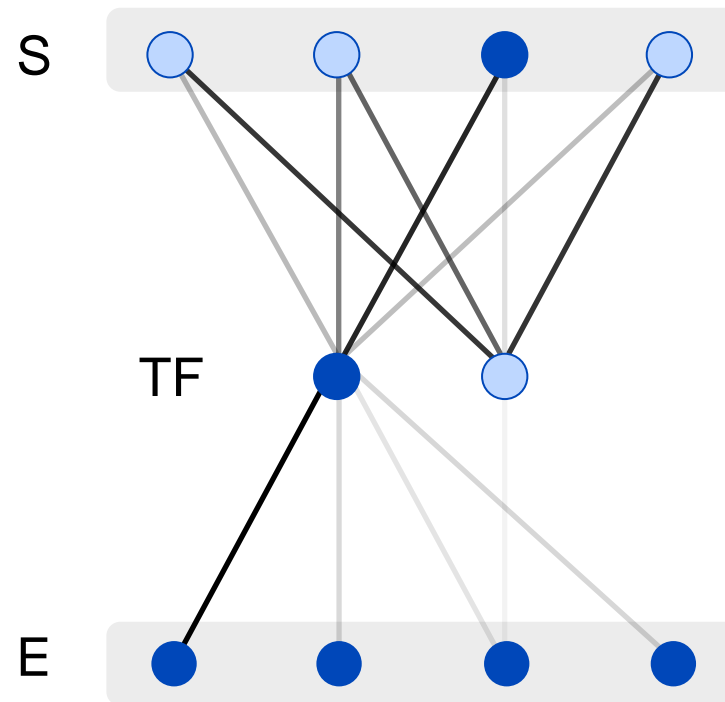
Learning samples

S	E
1,0,0,1	1,0,0,0
1,0,0,1	1,1,0,0
1,0,0,1	1,0,1,0
1,0,0,1	1,0,0,1
1,0,1,1	0,0,0,0
1,0,1,1	0,1,0,0
1,0,1,1	0,0,1,0
1,0,1,1	0,0,0,1



S_1 , S_2 and S_4 do almost not affect the metabolism ...

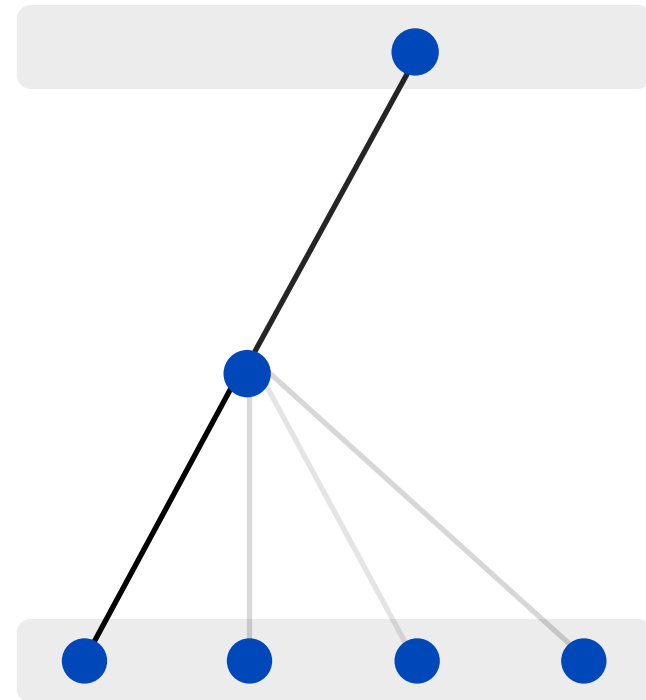
Simulation 1



... so we can forget them and get S_1, TF_1 for our regulation model

Weight matrix

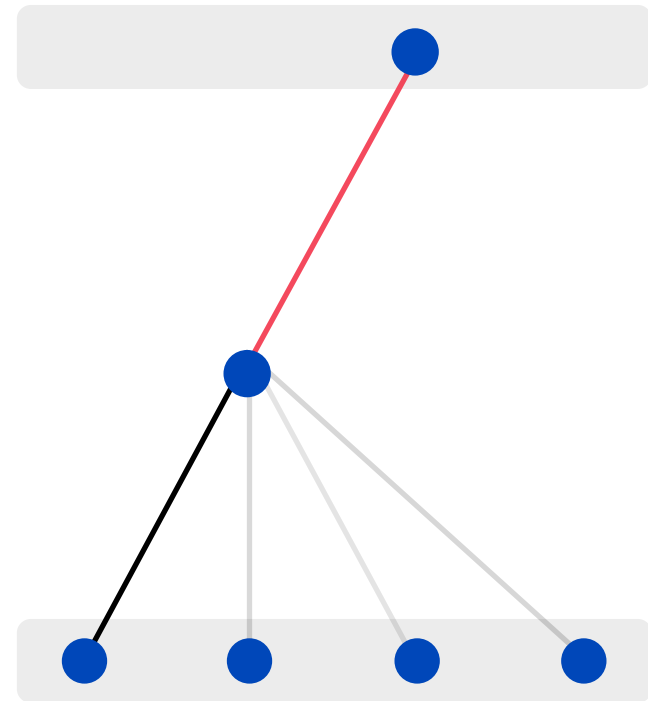
	TF_1	TF_2
S_1	0,3	0,8
S_2	0,5	0,6
S_3	1,0	0,1
S_4	0,3	0,8
E_1	0,8	0,0
E_2	0,1	0,0
E_3	0,1	0,0
E_4	0,2	0,0



We can also take a look at the causal mechanism ...

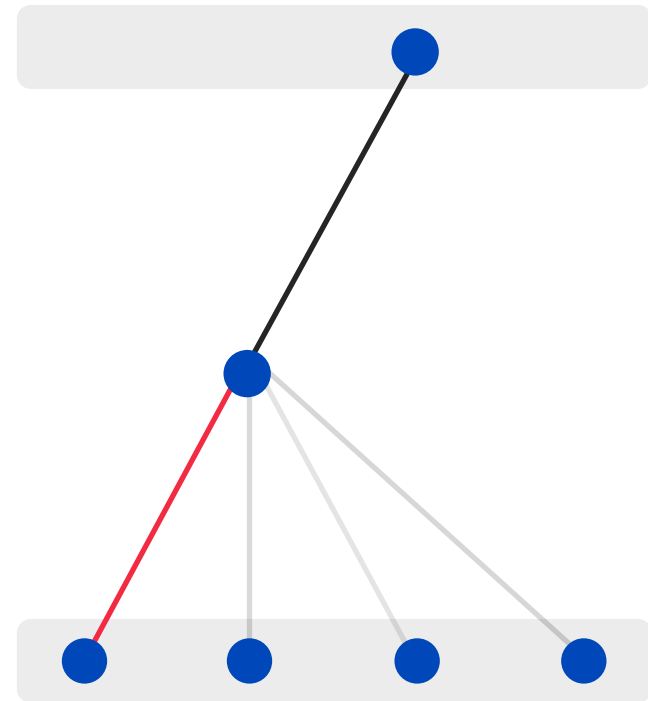
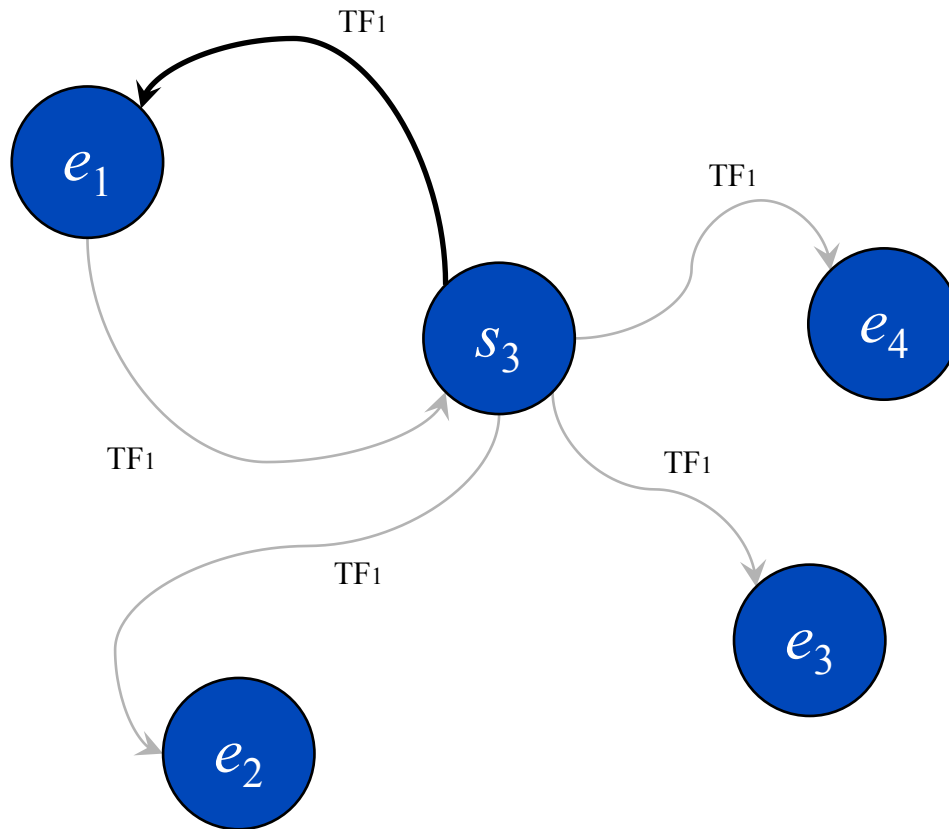
Weight matrix

	TF₁	TF₂
S₁	0,3	0,8
S₂	0,5	0,6
S₃	1,0	0,1
S₄	0,3	0,8
E₁	0,8	0,0
E₂	0,1	0,0
E₃	0,1	0,0
E₄	0,2	0,0



The edge (S₃, TF₁) dominates TF₁ ...

Simulation 1



Also E_1 seems to have an effect on S_3 (fewer than S_3 on E_1)

Comparing to Bayesian Networks

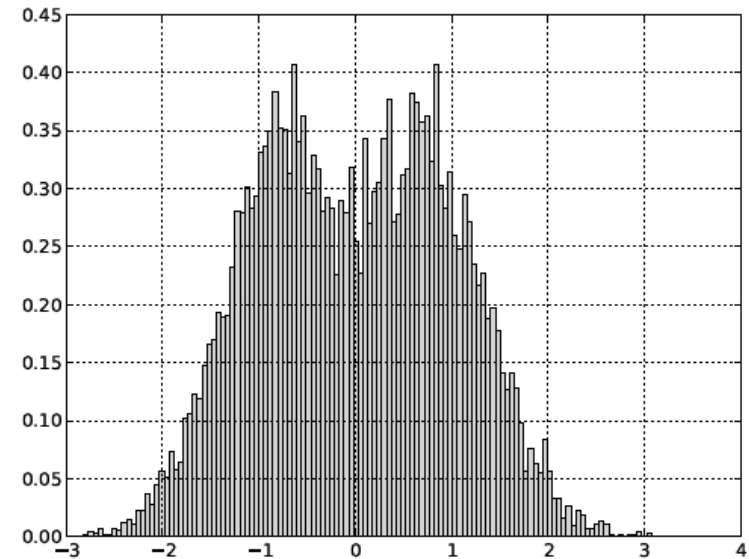
For this purpose we simulate data in three steps

Of course we want to compare the method with Bayesian Networks

Comparing to Bayesian Networks

Step 1

Choose number of Genes (E+S) and
create random bimodal distributed data



Of course we want to compare the method with Bayesian Networks

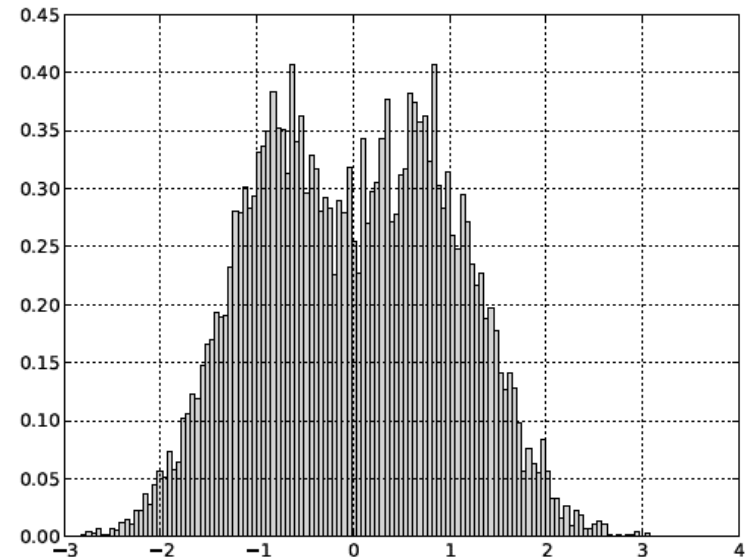
Comparing to Bayesian Networks

Step 1

Choose number of Genes (E+S) and
create random bimodal distributed data

Step 2

Manipulate data in a fixed order



Of course we want to compare the method with Bayesian Networks

Comparing to Bayesian Networks

Step 1

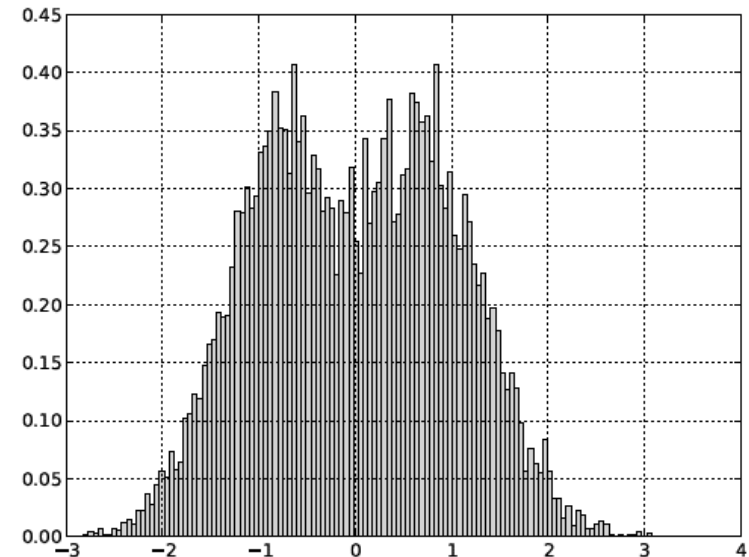
Choose number of Genes (E+S) and create random bimodal distributed data

Step 2

Manipulate data in a fixed order

Step 3

Add noise to manipulated data and normalize data



Of course we want to compare the method with Bayesian Networks

Comparing to Bayesian Networks

Idea

- ‚melt down‘ the bimodal distribution from very sharp to very noisy
- Try to find the original causal structure with BN and RBM
- Measure Accuracy by counting the right and wrong dependencies

Of course we want to compare the method with Bayesian Networks

Simulation 2

Step 1: Number of visible nodes 8 (4E, 4S)

Create intergradient datasets from sharp to noisy bimodal distribution

$\sigma_1 = 0.0, \sigma_1 = 0.3, \sigma_3 = 0.9, \sigma_4 = 1.2, \sigma_4 = 1.5$

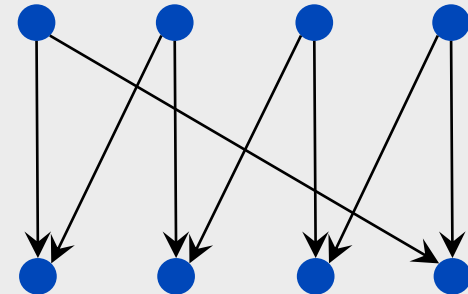
Step 2 + 3: Data Manipulation + add noise

$$e_1 = 0.5s_1 + 0.5s_2 + N(\mu = 0, \sigma)$$

$$e_2 = 0.5s_2 + 0.5s_3 + N(\mu = 0, \sigma)$$

$$e_3 = 0.5s_3 + 0.5s_4 + N(\mu = 0, \sigma)$$

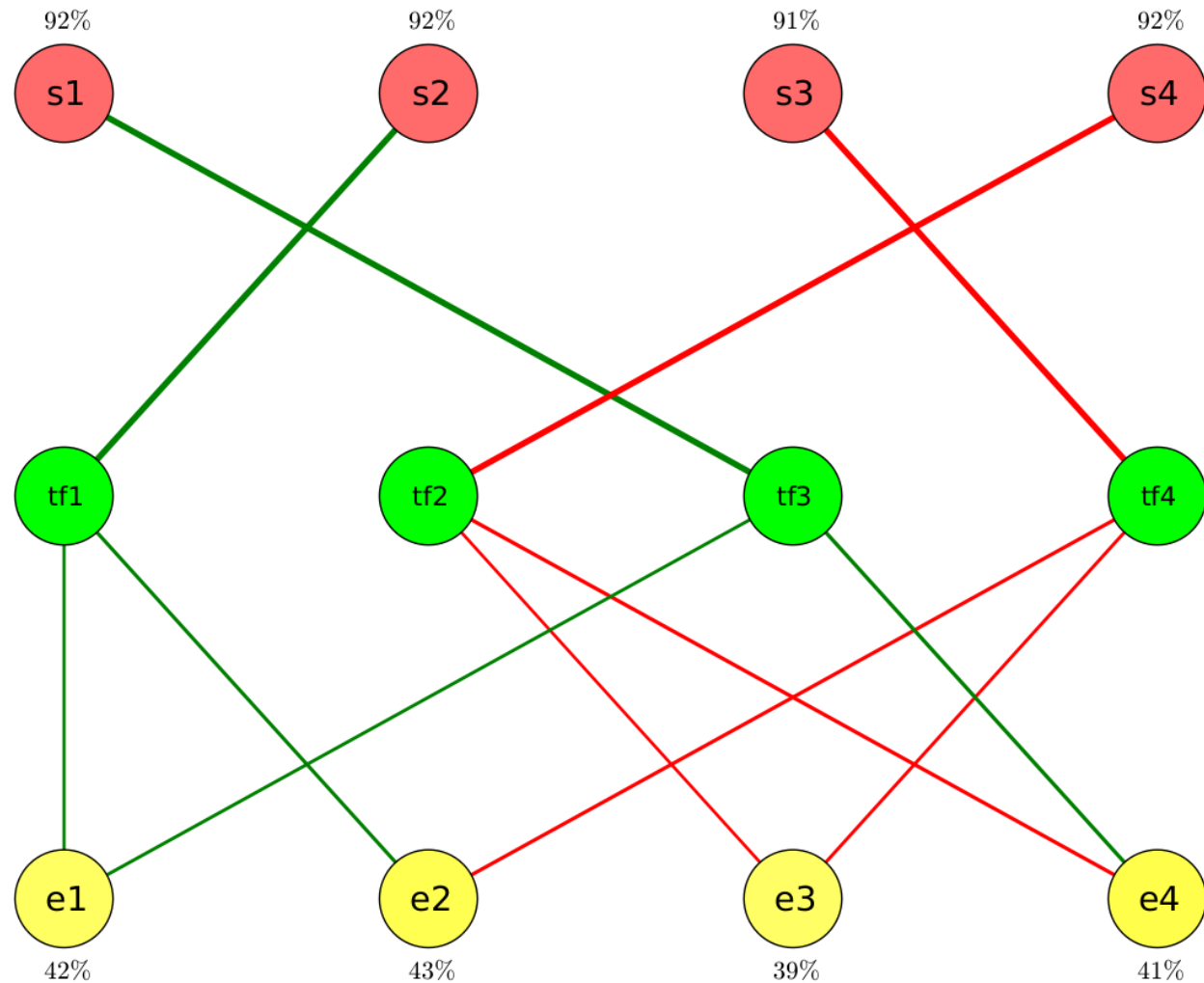
$$e_4 = 0.5s_4 + 0.5s_1 + N(\mu = 0, \sigma)$$



Of course we want to compare the method with Bayesian Networks

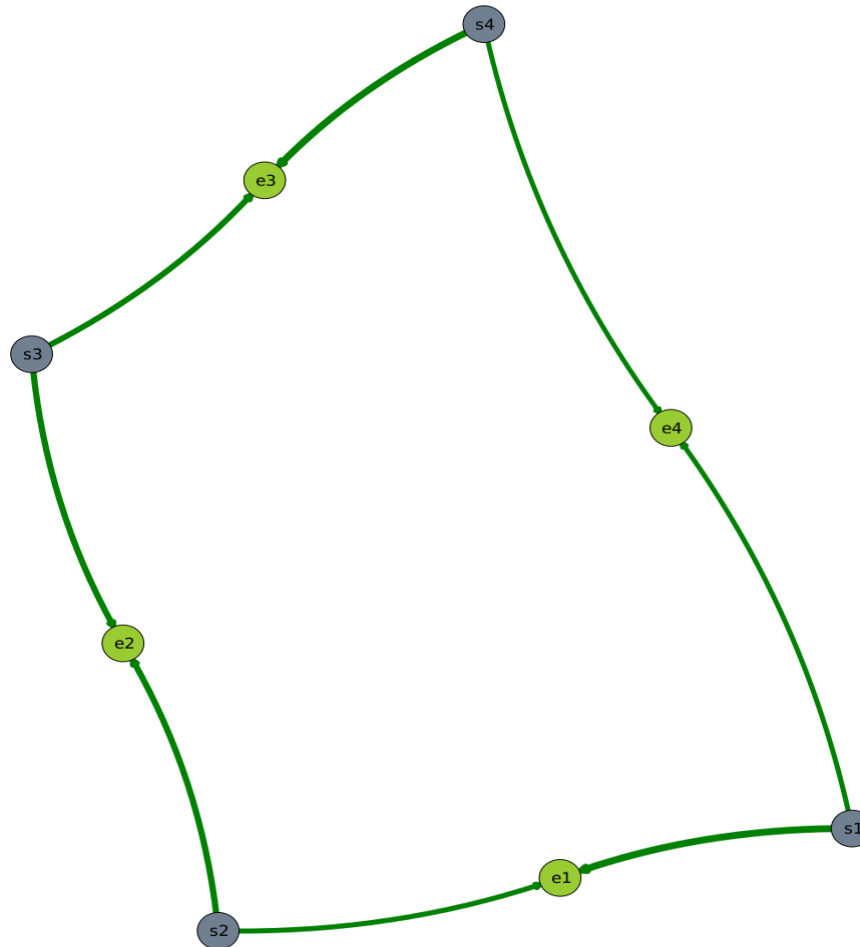
Simulation 2

RBM
Model
($\sigma = 0.0$)



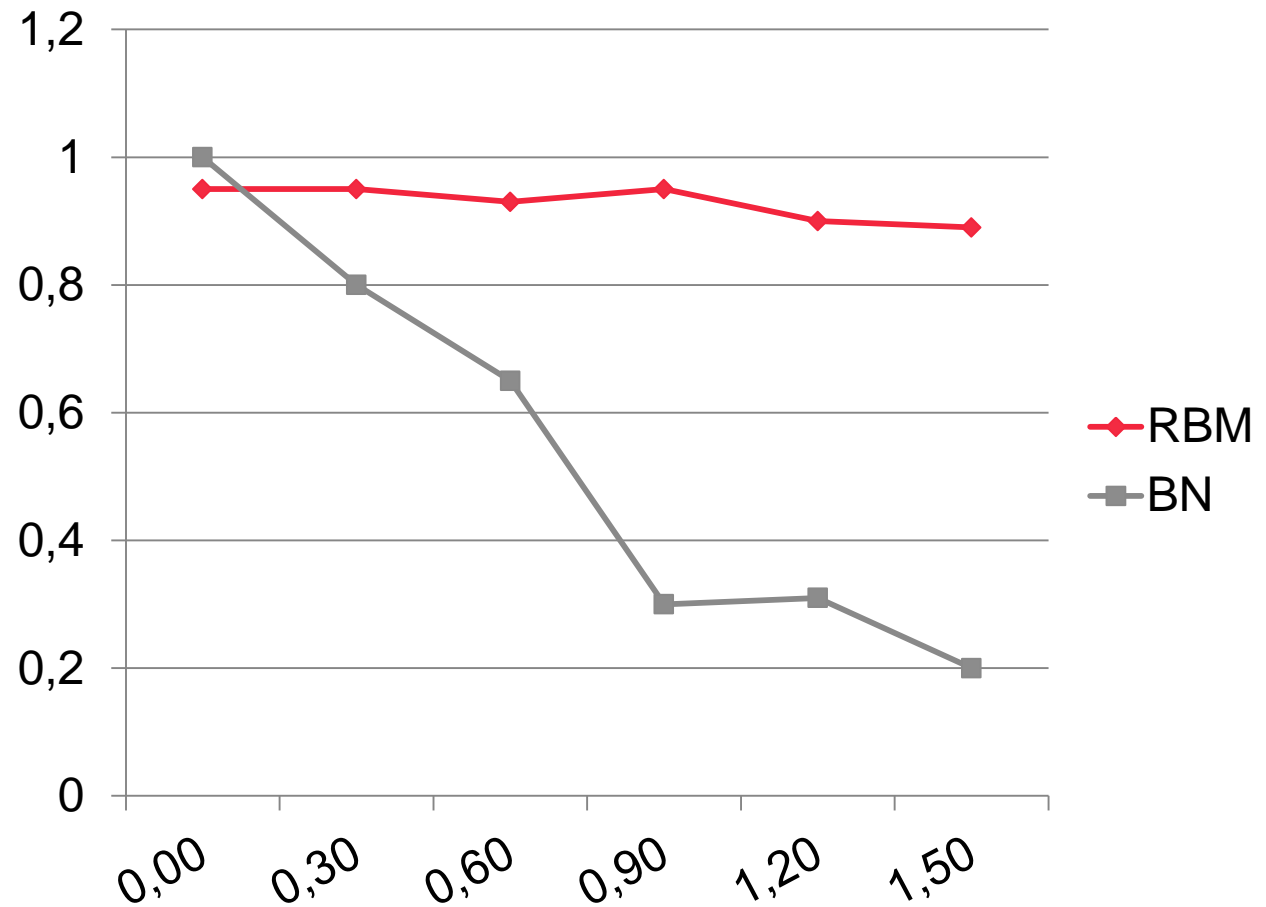
Simulation 2

Causal
Mechanism
($\sigma = 0.0$)



Simulation 2

Comparison
BN / RBM



Conclusion

- RBMs are more **stable against noise** compared to BNs.

It has to be assumed that RBMs have high predictive power regarding the regulation mechanisms of cells

- The drawback are **high computational costs**

Since RBMs are getting more popular (Face recognition / Voice recognition, Image transformation). Many new improvements in facing the computational costs have been made.

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