

→ 1 transformation.

Given Point $P = (8, 4, 4)$.

1) Rotate around z by 30° .

Rotation matrix

$$R_z(\theta) = \begin{bmatrix} \cos(\theta) & -\sin(\theta) & 0 & 0 \\ \sin(\theta) & \cos(\theta) & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \Rightarrow \begin{aligned} x' &= x \cos \theta - y \sin \theta \\ y' &= x \sin \theta + y \cos \theta \\ z' &= z. \end{aligned}$$

$$\begin{aligned} \Rightarrow x' &= 8 \cos 30^\circ - 4 \sin 30^\circ = \frac{8\sqrt{3}}{2} - 2 = 4\sqrt{3} - 2 \\ y' &= 8 \sin 30^\circ + 4 \cos 30^\circ = \frac{8}{2} + \frac{4\sqrt{3}}{2} = 4 + 2\sqrt{3} \\ z' &= 4 \end{aligned}$$

2) $(4\sqrt{3}-2, 4+2\sqrt{3}, 4)$. Around y axis by 45°

$$\begin{bmatrix} \cos \theta & 0 & \sin \theta & 0 \\ 0 & 1 & 0 & 0 \\ -\sin \theta & 0 & \cos \theta & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} \Rightarrow \begin{aligned} x' &= x \cos \theta + z \sin \theta \\ y' &= y \\ z' &= -x \sin \theta + z \cos \theta \end{aligned}$$

$$\begin{aligned} \Rightarrow x' &= (4\sqrt{3}-2) \cos 45^\circ + 4 \sin 45^\circ = \frac{2\sqrt{6}-\sqrt{2}}{2} + 2\sqrt{2} = 2\sqrt{6} + \sqrt{2} \\ y' &= 4 + 2\sqrt{3} \end{aligned}$$

$$\begin{aligned} z' &= -(4\sqrt{3}-2) \sin 45^\circ + 4 \cos 45^\circ = \frac{2-4\sqrt{3}}{2} \sqrt{2} + 2\sqrt{2} = \sqrt{2} - 2\sqrt{6} + 2\sqrt{2} \\ &= 3\sqrt{2} - 2\sqrt{6} \end{aligned}$$

$$I = IP. \quad I = (5, -8, 08).$$

$$P' = \begin{bmatrix} 1 & 0 & 0 & 5 \\ 0 & 1 & 0 & -8 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2\sqrt{6} + \sqrt{2} \\ 4 + 2\sqrt{3} \\ 3\sqrt{2} - 2\sqrt{6} \\ 1 \end{bmatrix} = \begin{bmatrix} 2\sqrt{6} + \sqrt{2} + 5 \\ 4 + 2\sqrt{3} - 8 \\ 3\sqrt{2} - 2\sqrt{6} \\ 1 \end{bmatrix}.$$

For quaternions:

Rotation Matrix:

$$M = 2 \cdot \begin{bmatrix} q_0^2 + q_1^2 + 0.5 & q_1 q_2 - q_0 q_3 & q_0 q_2 + q_1 q_3 \\ q_0 q_3 + q_1 q_2 & q_0^2 + q_2^2 - 0.5 & q_2 q_3 - q_0 q_1 \\ q_1 q_3 - q_0 q_2 & q_0 q_1 + q_2 q_3 & q_0^2 + q_3^2 - 0.5 \end{bmatrix} \Rightarrow$$

$$|q_0| = \cos \frac{\theta}{2}.$$

$$|q_1| = |q_2| = 0.$$

$$|q_3| = \sin \frac{\theta}{2}.$$

1) First rotation:

$$M = \begin{bmatrix} \cos 30^\circ & -\sin 30^\circ & 0 \\ \sin 30^\circ & \cos 30^\circ & 0 \\ 0 & 0 & 1 \end{bmatrix} \Rightarrow |q_1| = |q_2| = 0.$$

$$|q_0| = \frac{\sqrt{6} + \sqrt{2}}{4}.$$

$$|q_3| = \frac{\sqrt{6} - \sqrt{2}}{4}.$$

$$q_R = \frac{\sqrt{6} + \sqrt{2}}{4} + \left(\frac{\sqrt{6} - \sqrt{2}}{4} \right) k.$$

The point is $(8, 4, 4) \Rightarrow$

$$q_A = 0 + 8i + 4j + 4k. \Rightarrow$$

$$q_R \cdot q_A \cdot q_R^* =$$

$$\left(\frac{\sqrt{6} + \sqrt{2}}{4} + \left(\frac{\sqrt{6} - \sqrt{2}}{4} \right) k \right) (8i + 4j + 4k) \left(\frac{\sqrt{6} + \sqrt{2}}{4} - \left(\frac{\sqrt{6} - \sqrt{2}}{4} \right) k \right).$$

$$= \left(2(\sqrt{6} + \sqrt{2})i + 2(\sqrt{6} - \sqrt{2})j + (\sqrt{6} + \sqrt{2})j - (\sqrt{6} - \sqrt{2})j + (\sqrt{6} + \sqrt{2})k + \left(\frac{\sqrt{6} - \sqrt{2}}{4} \right)^2 \right) \left(\frac{\sqrt{6} + \sqrt{2}}{4} - \left(\frac{\sqrt{6} - \sqrt{2}}{4} \right) k \right)$$

$$= \left((\sqrt{6} + \sqrt{2})i + (2(\sqrt{6} - \sqrt{2}) + (\sqrt{6} + \sqrt{2}))j + (\sqrt{6} + \sqrt{2})k + \left(\frac{\sqrt{6} - \sqrt{2}}{4} \right)^2 \right) \left(\frac{\sqrt{6} + \sqrt{2}}{4} - \left(\frac{\sqrt{6} - \sqrt{2}}{4} \right) k \right)$$