In DSA, the quicksort is _____.

- a. none of the above
- b. an algorithm
- c. a data structure of array

Which do you think it is the best case (input array) of QuickSort?

- a. None of the above
- b. 1, 2, 3, 4, 5, 6, 7
- c. 7, 6, 5, 4, 3, 2, 1

Given the Original array: 25, 12, 48, 37, 12, 92, 86, 33.

What is the output result after 1st pass of bubble sort:

- a. 25, 12, 48, 37, 12, 33, 86, 92.
- b. 12, 25, 37, 12, 48, 86, 33, 92.
- c. 25, 12, 48, 37, 12, 92, 86, 33.
- d. 25, 33, 48, 37, 12, 12, 86, 92.

Given this array: 48, 86, 25, 10, 57, 37, 12, 92, 33.

Which is the pivote of the 1st partition in QuickSort?

- a. 48
- b. 86
- c. 57
- d. 25

Which is the correct formular to evaluate the time complexity of QuickSort?

a.
$$T(n) = T(n - i) + T(i) + \alpha n$$

b.
$$T(n) = 2T(n/2) + cn$$

c.
$$T(n) = 3T(n-1) + \alpha n$$

Any sorting algorithm that moves elements only one position at a time mút have time complexity at least _____. a. nlogn b. n^2 c. 1 (x) d. n Given: T(n) = 3 T(n/2) + nWhat do you think it is the general form of T(n) after 'i' steps of expansion? a. $3T(n/(i) + n(1 + 3 + ... + 3^{i+1})$ b. $6T(n/(2^{-i}) + n(1 + 3/2 + ... + 3/(2^{i}))$ c. $T(n/(4) + n(1 + 3/2 + ... + 3/(2^{i}))$ d. $3T(n/(2^{-i}) + n(1 + 3/2 + ... + 3/(2^{i+1}))$ Given: T(n) = 3 T(n/2) + nHow many steps of expansion needed to express T(n) as a polynomial of T(1) or T(2)? a. log2n b. log3n (x) c. log2n + 1 d. log(n) Given: T(n) = 2 T(3n/2)How many steps of expansion needed to express T(n) as a polynomial of T(1) or T(2)? Choose one answer. a. log_{3/4}n

b. None of the above

- c. log3n
- d. log_{3/2}n

What is the time complexity of the function T(n) if

$$T(n) = n + T(n - 1)$$

- a. O(n²)
- b. O(n)
- c. O(log(n)) (x)

Max heap is the array of integer that satisfy:

a. Child >= parent

Root is the smallest

b. Child <= parent

Root is the largest

c. Child => parent

Root is the largest

Given that d(n) is O(f(n)), e(n) is O(g(n)).

What is the complexity of d(n) * e(n)?

- a. O(f + g)
- b. None of the above
- c. O(f * g)

Given that d(n) is O(f(n)), e(n) is O(g(n)).

What is the complexity of d(n) + e(n)?

- a. Both of the above (v)
- b. min(O(f), O(g)
- c. O(f + g) (x)

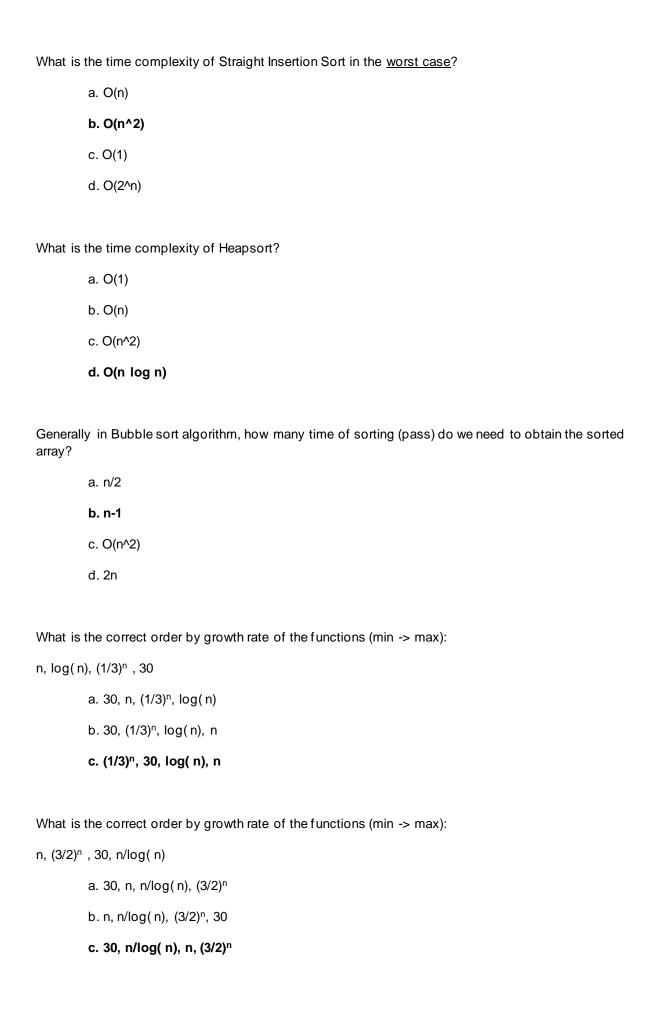
What is the complexity O(n) of the following code:

for
$$(i = 0; i < N; i++)$$

for
$$(j = 0; j < N * N; j++)$$

sum++;

a. N^2
b. 1
c. N
d. N^3
What is the complexity Ono of the following code:
for (i = 0; i < n; i++)
for $(j = 0; j < i * i/2; j++)$
for $(k = 0; k < j; k++)$
sum++;
a. n^2
b. n^5
c. n
d. n^4
What is the time complexity of Selection sort?
a. O(n^2)
b. O(1)
c. O(n/2 +n)
d. O(n)
What is the time complexity of Straight Insertion Sort in <u>best case</u> ?
a. O(n^2)
b. O(n)
c. 1
d. O(n^3)



d. (3/2)ⁿ, n, n/log(n), 30

In order to calculate the complexity of an algorithm, there are some steps that you should know. Please select the correct order of the step to calculate the complexity.

- A. Perform the mathematical analysis to find the relationship between T(n) and n
- B. Simplify the result of complexity
- C. Derive the mathematical formula of T(n) from the code (or pseudo-code)
 - a. **C A B**
 - b. BAC
 - c. A C B

To solve a big problem of Mr.T, Dummy try to call some people to help. Each person found that their assigned task is quite similar to others' and so they usually ask other if they have the solution for the similar problem. The final solution will be collected and combined by Dummy.

So what type of method is best describe the way Dummy used to solve the problem?

- a. FIT student's method
- b. Divide and conquer method
- c. Dynamic programming method
- d. Balancing subproblems method

In terms of complexity analysis, _____ is more important (more informative).

- a. worst case
- b. Normal case
- c. best case

The _____ can't give us an upper bound on performance.

- a. Worst case
- b. Best case

The best case of an algorithm A is a function:

BA: N \rightarrow N where BAno is the ____ number steps performed by A on an input of size n.

	a. Not of all the above
	b. minimum
	c. maximum
The nur	mber of steps of the recursive (devide and conquer) algorithm for the Tower of Hanoi those of the simple non-recursive algorithm described at the textbook!
	a. equals
	b. is less than
	c. is more than
Dijkstra	algorithm is to find the
	a. shortest parth based on number of edges
	b. shortest parth based on cloud computing
	c. shortest parth based on edge weight
The run	time complexity of Dijkstra's Algorithm of a connected graph depends mainly on
	a. the operations of graph
	b. None of the above
	c. the number of Edges and number of Vertices of the graph
WHICH	PREQUISITE IS NEEDED BY DIJKSTRA ALGORITHM?
	a. Non cycles
	b. No vertex with more than 4 edges
	c. Non-negative edge weights
	d. Both of the above
What is	true about stack?
	a. It is Last In First Out
	b. Stack is a variation of List.
	c. All of the above

d. It is First In Last Out

What is true about stack?
a. It is First In First Out List
b. Stack and List have no relation
c. All of the above
d. It is Last In First Out List
What is true about Queue?
a. It is a variation of List
b. All of the above
c. It is FIFO
In Stack, insertions and deletions can be performed at of it.
a. one end
b. both head and tail
c. two termials
What happend if we pop() all the elements from a stack and insert() into a queue, after that, we delete() all the elements from the queue and push() them to the Stack?
a. we have the stack with revert order of element
b. we have an empty stack
c. I don't know
d. we have done a stupid job
What happend if we sequentially POP all the elements from a stack and sequentially INSERT into a queue, after that, we DELETE all the elements from the queue and PUSH them back to the Stack?
a. we have the stack with revert order of element
b. we have an empty stack (x)
c. I don't know
d. we have done a stupid job

In ADT definition of FIFO queue, what operation cannot be ignored?
a. lsFull()
b. Size()
c. All of the above
d. Insert() /// Enqueue
What operation(s) can be ignored when defining the ADT of Stack?
a. IsFull()
b. Pop()
c. Push()
In a Singly linked list that has only one node, if a Nodes (data, pointer) is a head, the pointer points to
a. head
b. somewhere in the memory.
c. null
d. tail
In a Circular linked liste, if a Nodes (data, pointer) is a tail, the pointer points to
Choose one answer.
a. tail
b. somewhere in the memory
c. head
d. null
A linear list, for which all insertions and deletions (and usually all accesses) are made at both ends of the list, is called:
a. Dequeue
b. all-day queue
c. Singly Linked Queue

In the definition of abtract data type of a List, isEmpty() is the method which returns value.	
a. true	
b. boolean	
c. wrong	
d. void	
In the definition of abtract data type of a List, remove (int position) is the method which returnsvalue.	
a. integer	
b. string	
c. long	
d. void	
In the definition of abtract data type of a List, size() is the method which returns value.	
a. no	
b. integer	
c. yes	
d. void	
You write a program to find the LARGEST AND SMALLEST elements in an array of n elements. Generally, this can be done in at least comparisions.	
a. n/2	
b. 2n -1 (x)	
c. n - 1	
d. 2n - 3	

What is true about array-based list and reference-based list?

a. reference-based list cannot perform insertion and deletion

b. array-based list is not as flexible in size as reference-based list

d. None of the above

c. array-based list is more flexible in size than reference-based list

What is true about array-based list and reference-based list?

- a. array-based list is lower cost of insertation but not deletion.
- b. reference-based list can not perform insertion and deletion
- c. for the same problem, reference-based list has larger size than array-based list.

What is true about array-based list and reference-based list?

- a. reference-based list is lower cost of insertation and deletion.
- b. array-based list is completely bad.
- c. array-based list is lower cost of insertation but not deletion.

What is true about array-based list and reference-based list?

- a. reference-based list is harder to perform lookup operation compared to array-based list
 - b. They can be implemented by Java language only.
 - c. elements of array can be located dinamically and discontinuous like reference-based list
 - d. reference-based list is an other name of array-based list

What is the result of this code below:

```
for (int i=1; i<5; i++)
{
  for (int j = 1; j < i-5; j++)
  {
    System.out.print("*");
  }
  System.out.println();
}</pre>
```

```
b. //result:
         c. //result:
What is the result of this code below:
for (int i=1; i<5; i++)
{
for (int j = 1; j < 5-i; j++)
{
System.out.print("*"); //Similar to print in C
}
System.out.println(); //similar to print new line in C
}
        a. //result:
         b. //result:
        c. //result:
```

a. nothing

```
What is the result of this code below:
for (int i=1; i<5; i++)
{
for (int k=5-i;k<5;k++)
System.out.print("!");
for (int j = 1; j < 5-i; j++)
{
System.out.print("*");
}
System.out.println();
}
Choose one answer.
         a. //result:
        ***
         b. nothing
         c. //result:
        !***
        !!**
        !!!!*
        !!!!
What is the result of this code below:
for (int i=1; i<5; i++)
```

for (int k=i;k<5;k++)

```
System.out.print("!");
for (int j = 5-i; j < 5; j++)
{
System.out.print("*");
}
System.out.println();
}
Choose one answer.
         a. //Result:
         b. //Result:
         ****
         c. //Result:
         !!!!!*
         !!!!**
         !!***
         <u>|</u>****
         d. nothing
```

If we use Adjacency matrix for weighted undirected graph, we will have:

a. None of the above

b. A symmetric matrix over its diagonal

c. An asymmetric matrix

Which is the appropriate implementation of Graph a. Adjacency matrix b. Adjacency list c. All of the above What is maximum number of nodes in a binary tree of depth 5? a. 15 b. 63 c. 30 What is number of nodes in a full binary tree of depth 4? a. 32 b. 10 c. 17 d. 31 What is maximum number of nodes in level 4 of a binary tree could have? a. 16 b. 7 c. I don't know d. 4 How many nodes in total of a full binary that has 33 leaves? a. 49 b. 40

How many leaves does the complete binary tree that has 19 nodes in total have?

c. 50

d. 65

a. 9

(x)

b. 11
c. 12
d. 10
How many internal nodes of a full binary tree that has 10001 nodes in total?
a. 333
b. 600
c. 768
d. 500
Given 2 result of a binary tree traversal:
preorder: YZCDEXBUTA
inorder : DCEZYUBTXA
What is the root node of the tree?
a. B
b. X
c. Y
d. A
What is the left child of node B?
a. C
b. X
c. U
d. A
What is the right child of node Z?
a. D
b. T
c. Y
d. null

Calculate the result of Prefix expression:

- a. 24
- b. 18
- c. -8
- d. 0

Calculate the result of Prefix expression:

- a. 31
- b. 75
- c. 55
- d. 35

Calculate the result of Postfix expression:

- a. 20
 - b. 23
- c. 17
- d. 40

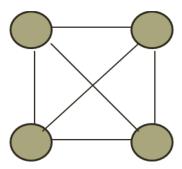
Calculate the result of Postfix expression:

- a. 30
- b. 10
- c. 7
- d. 5

Calculate the result of Postfix expression:

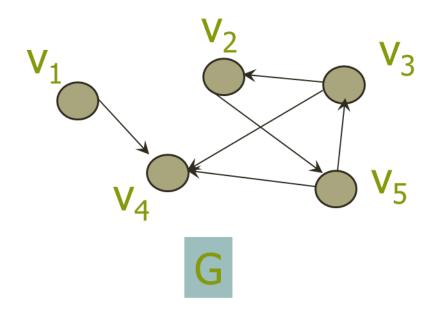
a. 120

- b. 80
- c. 72
- d. 36



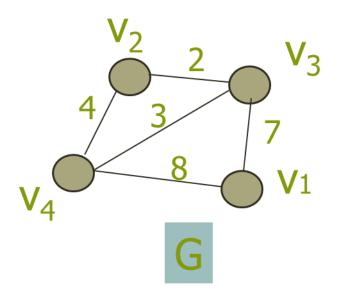
WHICH IS THE BEST DESCRIBE OF THE GRAPH?

- a. Unweighted, Undirected, Complete Graph
- b. Unweighted, undirected, connected graph
- c. Complete Graph
- d. Unweighted, connected graph



Please fill the table of adjacency matrix for node V1 -> V5 of the graph:

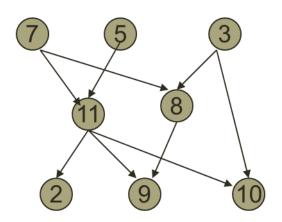
	V1	V2	V3	V4	V5
V1	0	0	0	1	0
V2	0	0	0	0	1
V3	0	1	0	1	0
V4	0	0	0	0	0
V5	0	0	1	1	0



Rule to fill the list:

-Increasing index of node

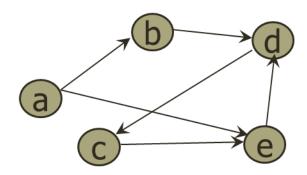
-Node format example v6(10)



WHAT IS NOT THE RESULT OF TOPOLOGY SORT?

a. 5, 7, 11, 2, 3, 8, 9, 10

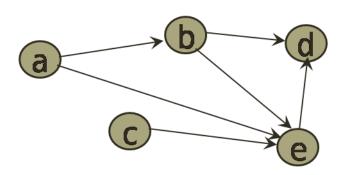
b. 5, 7, 8, 11, 3, 2, 9, 10



CAN THIS GRAPH PERFORM TOPOLOGICAL SORT?

a. YES

b. NO



//This is topological sort based on given criterium

//CHOOSE THE CORRECT OUTPUT

Algorithm TopoSort

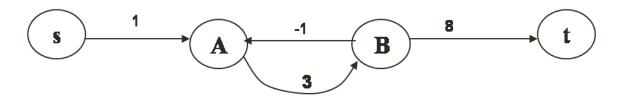
n = |V|;
for i = 1 to n {
 _____ select a node v that has the most successors;
 ____ print this vertex;
 ____ delete node v and its edges from the graph;
}

a. CABDE

b. CAEBD

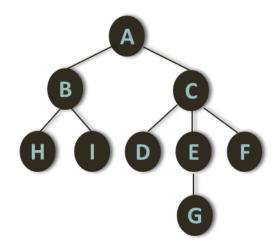
c. ABCED

d. A C B E D



//CAN WE FIND THE SHORTEST PATH FROM S --> T IN THIS SITUTATION?

- a. YES
- b. DON'T KNOW
- c. NO



In the picture, the degree of node C is:

- a. 3
- b. 4
- c. 7
- d. 2

In the picture, the degree of node E is:

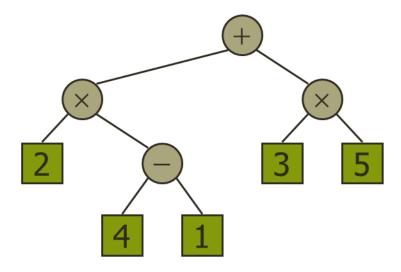
- a. 1
- b. 4
- c. 5
- d. 2

In the picture, which statement is correct about ($\ensuremath{\mathsf{I}}$):

- a. (i) has degree of 3
- b. (i) is the subtree of B
- c. (i) is the left child of B

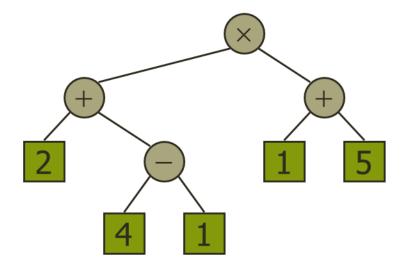
In the picture, Depth of this tree is:

- a. 3
- b. 9
- c. 7
- d. 4



What is the result of this expression using binary tree:

- a. 12
- b. 40
- c. 50
- d. 21



What is the result of this expression using binary tree:

- a. 12
- b. 30
- c. 21
- d. 15

This is an Array Representation of a Complete Binary Tree:

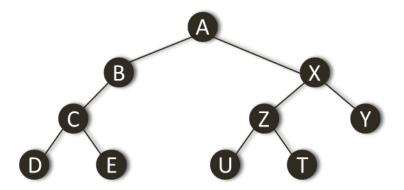


What is the left child of G:

- a. E
- b. Z
- c. D
- d. H

What is the right child of D:

- a. I
- b. P
- c. L



What is the result of inorder tree traversal? Fill the blanks with correct letter order:

D	C	E	В	Α	U	Z	Т	X	Υ

What do you think about the statement below?

In DSA, Tree, Stack, Queue are algorithms to solving common data problem!

- a. False
- b. True

A stack is similar to a list, especially they can both perform insertion a new node to the middle of the them.

- a. False
- b. True

Heap data structure is a binary search tree?

- a. False
- b. True

Complete the code to delete all the nodes from pointer P to the tail of the Singly linked list.

1. P->link = ____; //A

- a. null
- b. head

Complete the code to delete a node: Node(item, link), which P is the pointer pointing to the node right before it in the list.
1. P->link =; //A
a. (A) tail
b. (A) null
c. (A) P->link->link
Complete the code to delete all the nodes from "current" to the tail of the Singly linked list.
1. current.setNext() ; //C code: P->link =;
a. current.getNext().getNext()
//C code: P->link->link
b. head
c. current.getNext().getNext()
//C code: P->link->link
d. null
What is the implementation of following code:
1 void main()
2 { int i;
3 int A[10];
4
5 for (i=0;i<10;i++)

c. P->link->link->link

d. P->link->link

6	A[i]=i*i;
7	}
	a. reference-based
	b. array-based
	c. nothing
1. #def	ine TOTAL_SLOTS 100
2. type	def struct queue Queue;
3. struc	t queue
4. {	int front;
5. int re	ar;
6. int ite	ems[TOTAL_SLOTS];
7. };	
What in	nplementation type of the queue from the code?
	a. J-based implemenation
	b. Dont know
	c. Linked Implemenation
	d. array based implementation
What is	the maximum nodes in this queue?
	a. 99
	b. 100
	c. n
	d. Don't know
What is	the maximum nodes in this queue?

1. //Initialize MAX_SIZE=1000

```
2. public class Queue {
3. Queue()
4. \{ int front = 0;
5. int rear = 0;
int data[MAX_SIZE];
7. };
       a. Don't know
       b. 1000
       c. n
       d. 999
void bubblesort_checkpasses(int x[ ], int N)
{
int temp, i,j;
boolean switched = TRUE;
{...}
}
WITH THE INTRODUCTION OF A BOOLEAN VARIABLE switched, WHAT IS THE BEST CASE
TIME COMPLEXITY OF THE CODE?
Choose one answer.
       a. O(log n)
       b. O(n^2)
       c. O(n)
       d. O(1)
//LOOK AT THE GRAPH OPERATION BELOW
//WHAT DOES IT DO?
unmark all vertices in G;
Creat a queue q;
```

mark s;
insert(s,q)
while (!isempty(q))
curr = delete(q);
_visit curr; // e.g., print its data
for each edge
if V is unmarked
mark V;
insert(V,q);
a. breadth first search
b. post order graph traversal
c. in order graph traversal
d. depth first search
What is the condition of this queue to be empty?
1. #define TOTAL_SLOTS 100
2. typedef struct queue Queue;
3. struct queue
4. { int front;
5. int rear;
6. int items[TOTAL_SLOTS];
7. };
Choose one answer.
a. front = 0;
b. front == rear;
c. rear = 0;
d. rear = null

What does this piece of code do to a List?
1. Node current = head;
2. while(current != null)
3. {
4. current=current.getNext(); //C code: current = current->next;
5.}
a. insert new node
b. delete the tail
c. Traversing the list
Pseudo code:
Use a pointer p to traverse the list and search the node and compare the data.
If found: return the pointer to the node.
Otherwise return NULL. Node(data, next)
NodePtr SearchNode(NodePtr pList, int data)
2. { NodePtr p=pList;
3. while (p!=NULL)
4. { if (p->data==) //(A)
5. return p;
6. p =; //(B)
7. }
8. return NULL;
9.}
Choose one answer.
a (A) 0

(B) head

```
(A) data
        C.
                (B) p->next
**** FILL THE BLANK ****
//THIS CODE IS SELECTION SORT
//PLEASE FILL THE BLANKS WITH THE CORRECT ANSWER
void selection_sort(float x[], int N)
{
____int target_index, large_index, i;
____float large;
____//Update the data at each target position one by one, from right to left
____for (target_index =N-1; target_index >0; target_index --)
 ____{
____large = x[ 0 ];//<--TODO
_{\text{large\_index}} = 0;
____for (i=1; i <= target_index; i++)
____if (x[i] > large)
____{
 ____large = x[ i ]; //<--TODO
  _____large_index = i; /* and its position number into large_index */
____}
____ x[ large_index ] = x[ target_index ]; /* swap */
____ x[target_index] = large;
}
```

b.

(A) data

(B) p->data

//THIS IS STRAIT INSERTION SORT //PLEASE FILL IN THE BLANKS WITH THE CORRECT ANSWERS 0.Insertion-Sort(A) 1.____ for j = 1 to n-1 { 2.____ key = A[j]; 3._____ i = j-1; 4.____ while $i \ge 0$ and A[i] > key5.____ { A[i+1] = A[i]; 6._____ i = i - 1; 7.____ } 8.____ A[i+1] = key; 9.} //THIS IS THE PARTITION FUNCTION OF QUICKSORT ALGORITHM //PLEASE FILL THE BLANKS WITH CORRECT ANSWERS void partition(int x[], int idLeftMost, int idRightMost, int *pj) { ____ int down, up, a, temp; $\underline{}$ a = x[idLeftMost]; ____ up = idRightMost; ____ down = idLeftMost; _____ while (down < up) _____ { while ((x[down] <= a) && (down < idRightMost)) _____ down ++; /* move up the array */ _____ while (x[up] > a) _____ up--; /* move down the array */

_____ if (down < up) /* interchange x[down] and x[up] */

```
_____{
\underline{\hspace{1cm}}temp = x[down];
 ____x[ down ] = x[up];
 x[up] = temp;
_____} }
_____} }
____x[ idLeftMost ] = x[up];
____x[up] = a;
____*pj = up;
}
//MERGE SORT:
//split the array into two roughly equal subarrays
//sort the subarrays by recursive applications of Mergesort and merge the sorted subarray
void merge-sort(int x[], int lower_bound, int upper_bound)
{
_____ int pivote;
_____ if (lower_bound != upper_bound)
_____{
_____ pivote = (lower_bound + upper_bound) / 2;
   _____ merge-sort(x, lower_bound, pivote);
   _____ merge-sort(x, pivote +1, upper_bound);
   _____ merge(x, lower_bound, pivote, upper_bound);
_____} }
}
//THIS FUNCTION IS TO MOVE the root value to make the whole tree a max-heap
```

// Some steps in the functions:

```
//x is the heap array, no. of elements = N
//Start considering the root node.
//The replacement candidate is Right (or Left) child of id2Down
// If replacement is not necessary then don't do it, stop trickling otherwise replace.
// Prepare for next trickling
void trickle_down (int x[], int N)
[_____ int id2Down, idReplace; //idReplace is child of id2Down
_____ int temp; //for swapping data
_____ id2Down = 0;
  ____ idReplace = 2* id2Down +2;
_____ while (idReplace <= N-1)
_____{
   if (idReplace < N-1 && x[idReplace] < x[idReplace -1])
            ____ idReplace -- ;
 _____ if (x[id2Down] >= x[idReplace])
  _____ break;
 \underline{\qquad} temp = x[id2Down];
  x[id2Down] = x[idReplace];
  _____ x[idReplace] = temp;
 _____ id2Down = idReplace;
   _____ idReplace = 2* idReplace +2;
_____} }
}
//Program to create Binary tree, with left and right child
```

NodePtr maketree(int value) //create a new.

```
{ NodePtr p;
p= (NodePtr)malloc(sizeof(struct node));
p->info = value;
p->right = NULL;
p->left = NULL;
return(p);
}
void setleft(NodePtrp, int value) //create a new left child
        if (p==NULL)
printf("void insertion\n");
else if (p-> left != NULL)
printf("invalid insertion");
else
p-> left = maketree(value);
}
void setright(NodePtr p, int value) //create a new right child
        if (p==NULL)
{
printf("void insertion\n");
else if (p-> right != NULL)
printf("invalid insertion");
else
p-> right = maketree(value);
}
//To count the number of leaf nodes
//The recursive function to count the number of leaves of a tree
int count_leaf(NodePtr tree)
{_____ if (tree == NULL)
```

```
_____ return( 0 );
_____ else if ((tree->left == NULL) && (tree->right == NULL))
  _____ return( 1 );
____ else
   _____ return( count_leaf (tree->left) + count_leaf (tree->right));
}
//tree in-order traversal
//definition: intrav is the function to print all tree nodes using in-order, which follows the rules defined
struct node {
int info;
struct node* left;
struct node* right;
}
void intrav(NodePtr tree)
{ if (tree != NULL)
{ intrav(tree-> left );
ntrav(tree-> info );
printf("%d\n", tree-> right);
}
}
//tree post order traversal
//definition: posttrav is the function to print all tree nodes using post-order, which follows the rules
        defined in lecture.
struct node {
int info;
struct node* left;
struct node* right;
```

```
void posttrav(NodePtr tree)
{ if (tree != NULL)
{ posttrav(tree-> left );
posttrav(tree-> right );
printf("%d\n", tree-> info );
}
}
//The algorithm of finding duplicate values in array as follow:
//Create root node to store first no.
//Handle each remaining input no.
//----Start at the root, traverse the tree
            from top to bottom until we meet
//----the same value.
//----- At each node,
//-----
                          If input no. < current node
//-----
                          (we'll look at the left sub-tree)
//----- If the left sub-tree is empty,
//-----
                                       create a left child to
                          -----
//-----
                         -----
                                       store input no. and stop traversing
//----else go to left subtree.
//-----
                         else (input no. > current node)
//---- (we'll look at the right sub-tree)
//-----
//----- If no new node has been created for
//---- the input number, it is a duplicate
//GIVEN:
```

}

```
typedef struct node *NodePtr;
struct node
      int info;
NodePtr left;
NodePtr right;
};
NodePtr maketree(int value) {..} //create a new
void setleft(NodePtr p, int value) {..} //create a new left child of a given node
void setright(NodePtr p, int value) {..} //create a new right child of a given node
void main()
             int i, seq[12]={3,5,0,2,7,9,5,6,3,7,0,8};
 _____ NodePtr p, T=maketree(seq[0]);
 _____ for(i=1;i<12;i++)
_____ {
             BOOL bNewNodeCreated=FALSE;
 _____ p=T;
  _____ while (p->info != seq[i])
  _____{
                   if (seq[i] < p-> info )
                           if (p->left==NULL)
                           { setleft (p, seq[i] );
                            bNewNodeCreated=TRUE;
                            break;
                            p=p->left;
          ____ else
           _____ if (p->right==NULL)
     _____ { setright
                                  (p, seq[i] );
```

bNewNodeCreated=TRUE;
break;
} }
else
p=p->right;
}
if (!bNewNodeCreated)
printf("%d is a duplicate\n",seq[i]);
}
}
//Complete the code to delete an element from a queue:
* Check if the queue is empty
* get the value at the front of the queue
* Correct the front of the queue
* return the value
//
1. //Initialize MAX_SIZE=1000
2. public class Queue {
3. Queue()
4. { int front = 0;
5. int rear = 0;
6. int data[MAX_SIZE];
7. };
8. boolean isEmpty()
9. {
10. return (this.front % this.rear);
11. }

```
int delete()
       int rtn_val;
        if (isEmpty())
        {
                printf("underflow error\n"); return null;
        }
        rtn_val = this.data[ MAX_SIZE ];
        front = ( front + 1) % MAX_SIZE;
        return ( rtn_val );
}
Given an array-based Stack.
The pseudo-code of operation Push() is defined as:
* connect new node to stack
* Set new top stack
Complete the code below that use the above pseudo-code:
public class SINode{
    public void setNext();
    public XData getNext();
}
1. public stack()
2.{
3.
       top = new SINode();
4.};
5.
```

```
7. public void push(SINode x)
8. {
9.
       x. AAA = BBB;
 10.
        CCC = x;
11. }
In link-based Stack, Size() method is descripted as below:
* travel through the stack
* count increases by one if current node is not null
* Return the saved value.
Complete the code below:
public class SINode{
    public void setNext();
    public XData getNext();
}
1. public stack()
2.{
3.
       top = new SINode();
4.};
5. public boolean isEmpty() {..}
6. public boolean isFull() {..}
7. public int size()
8. {
       SINode current = top;
```

6. public boolean isEmpty() {..} //check if stack is empty

```
int count = 0;

9.     while(current != null )

10.     {

11.           count++ ;

12.           current = current.getNext();

13.     }

15.     return count ;

16. }
...
```