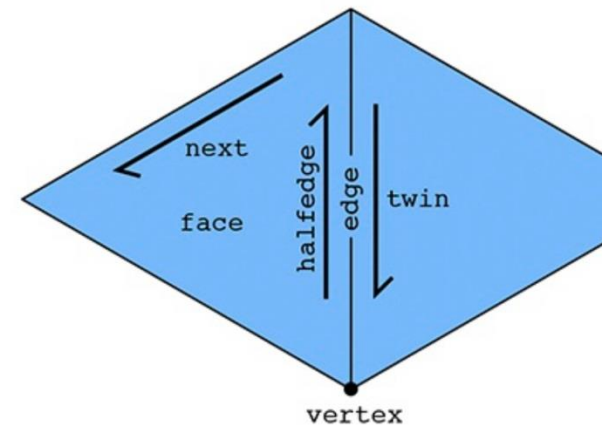
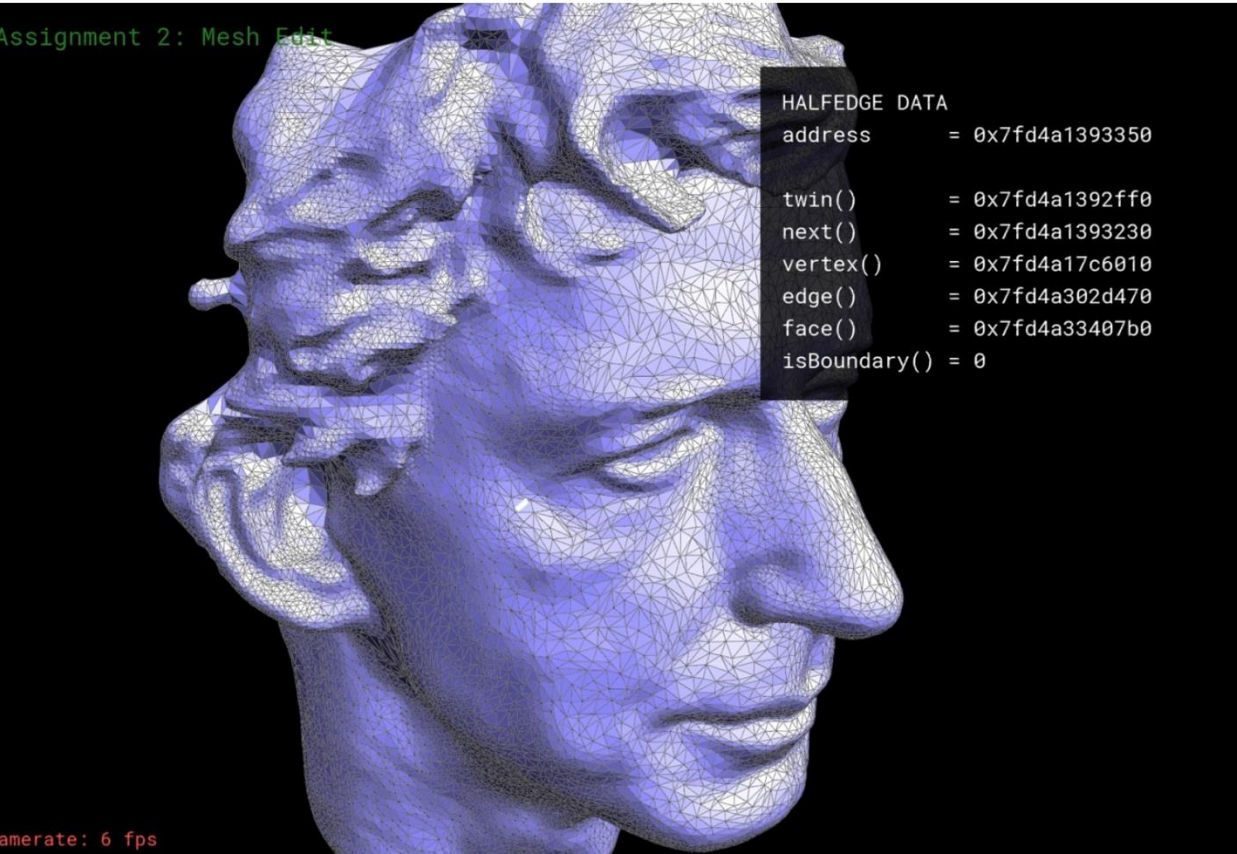
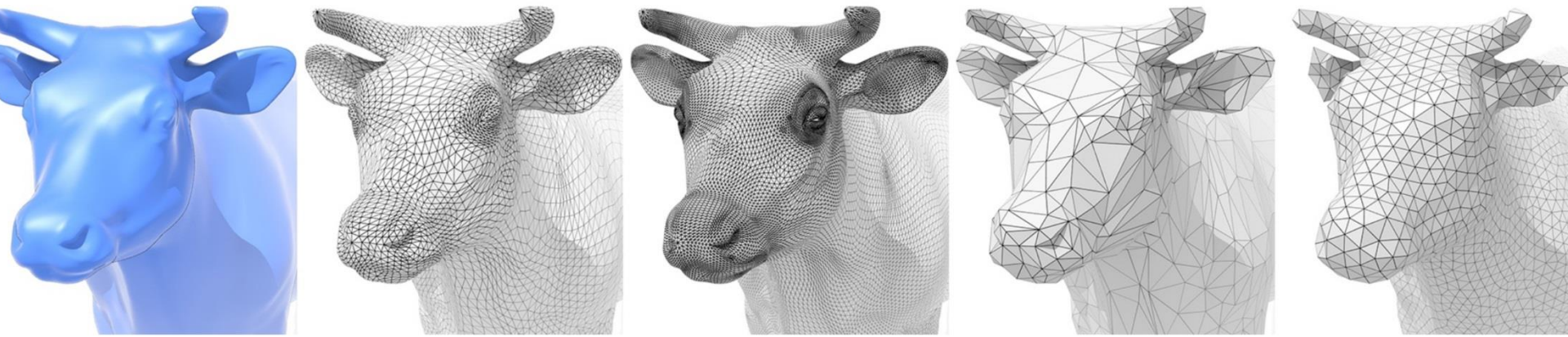


Geometry: curves, surfaces and Polygonal Meshes

NGUYEN THUY LINH



Last time: overview of geometry

- Many types of geometry in nature
- Demand sophisticated representations
- Two major categories:
 - IMPLICIT - “tests” if a point is in shape
 - EXPLICIT - directly “lists” points
- Lots of representations for both
- Today:
 - what is a surface, anyway?
 - nuts & bolts of polygon meshes

Geometry



Q: What is a “surface?”

A: Oh, it's a 2-dimensional manifold.

Q: Ok... but what the heck is a *manifold*?

The Earth looks flat, if you get close enough



Can pretend we're on a grid:

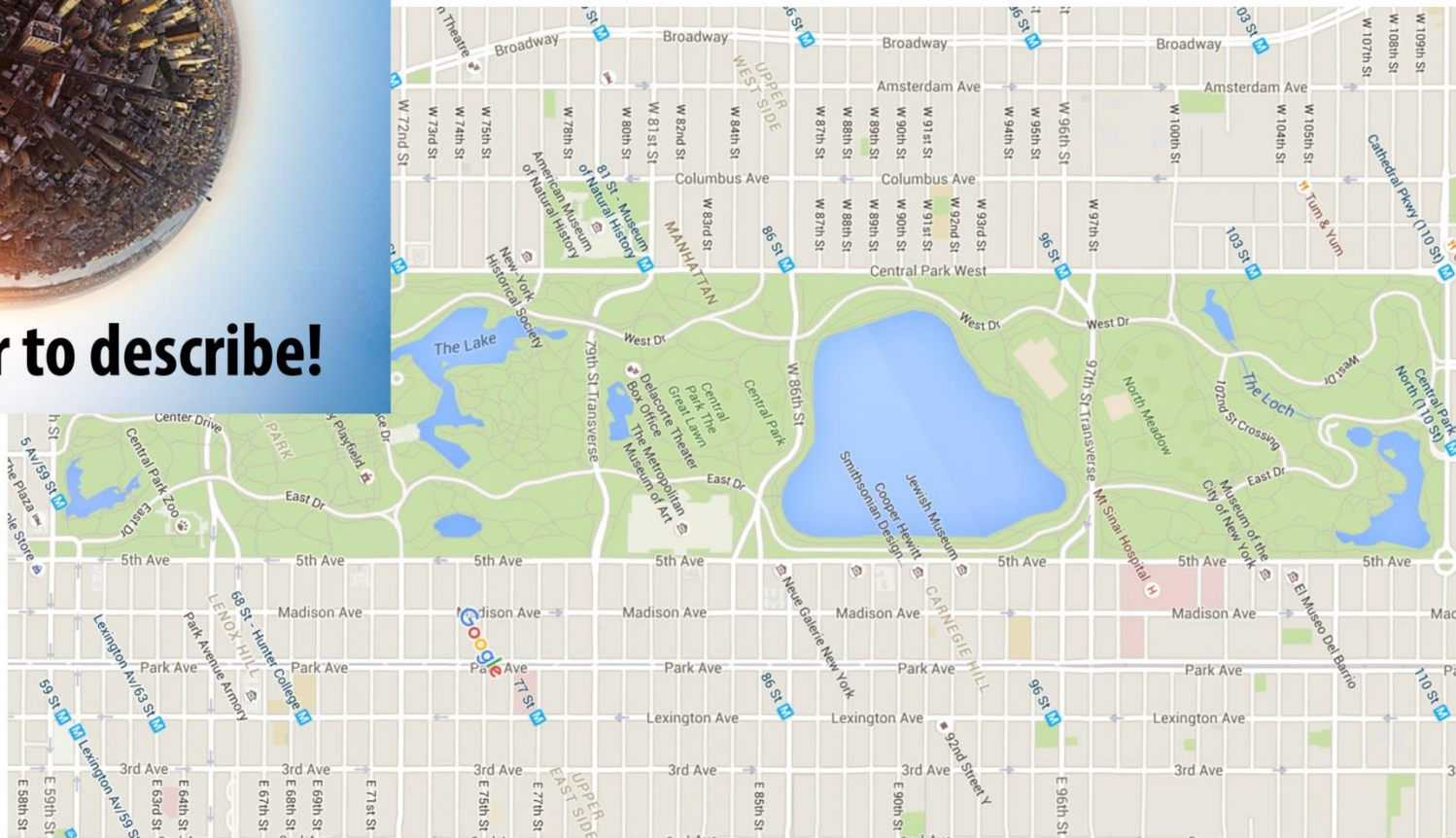


The Earth looks flat, if you get close enough

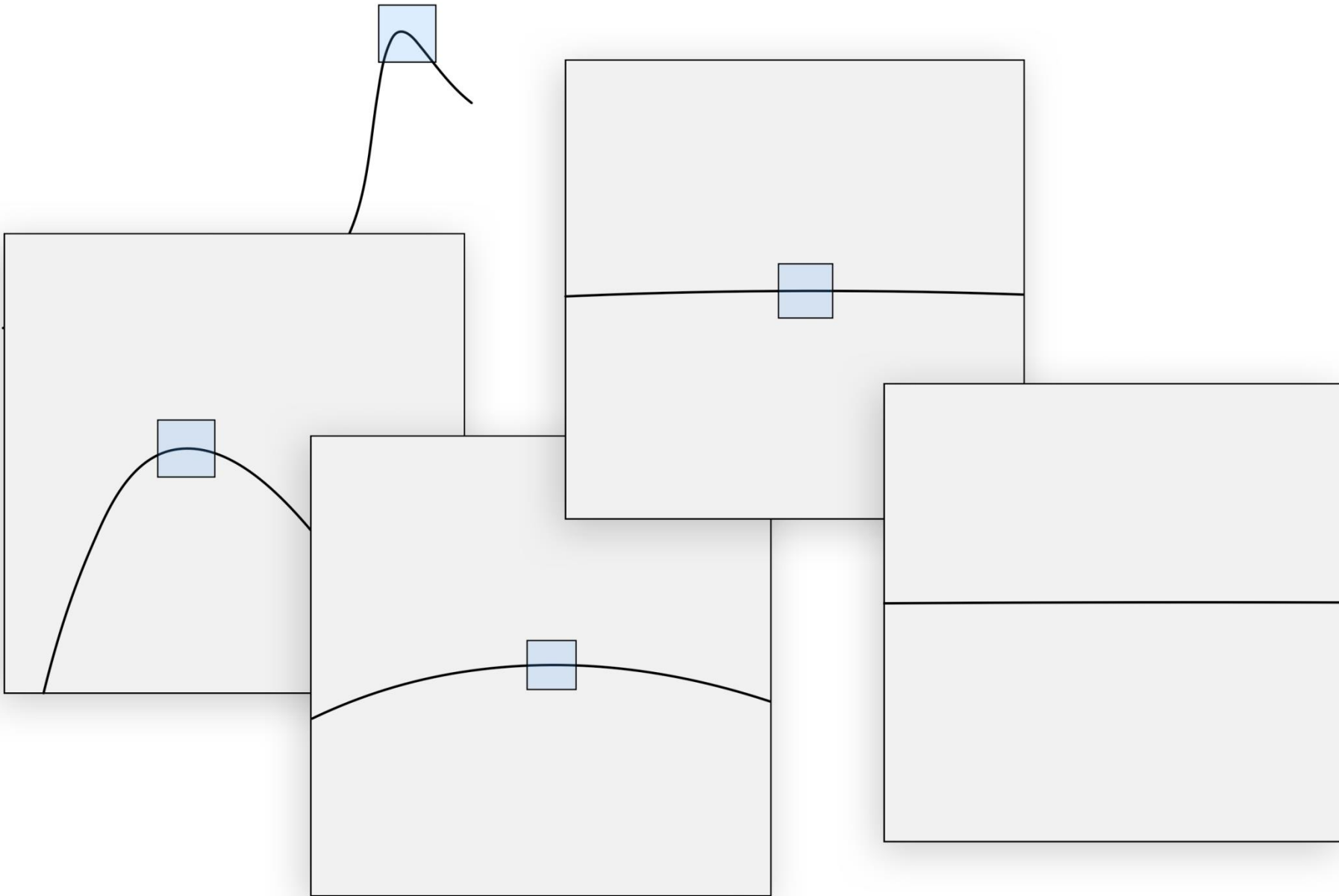


Much harder to describe!

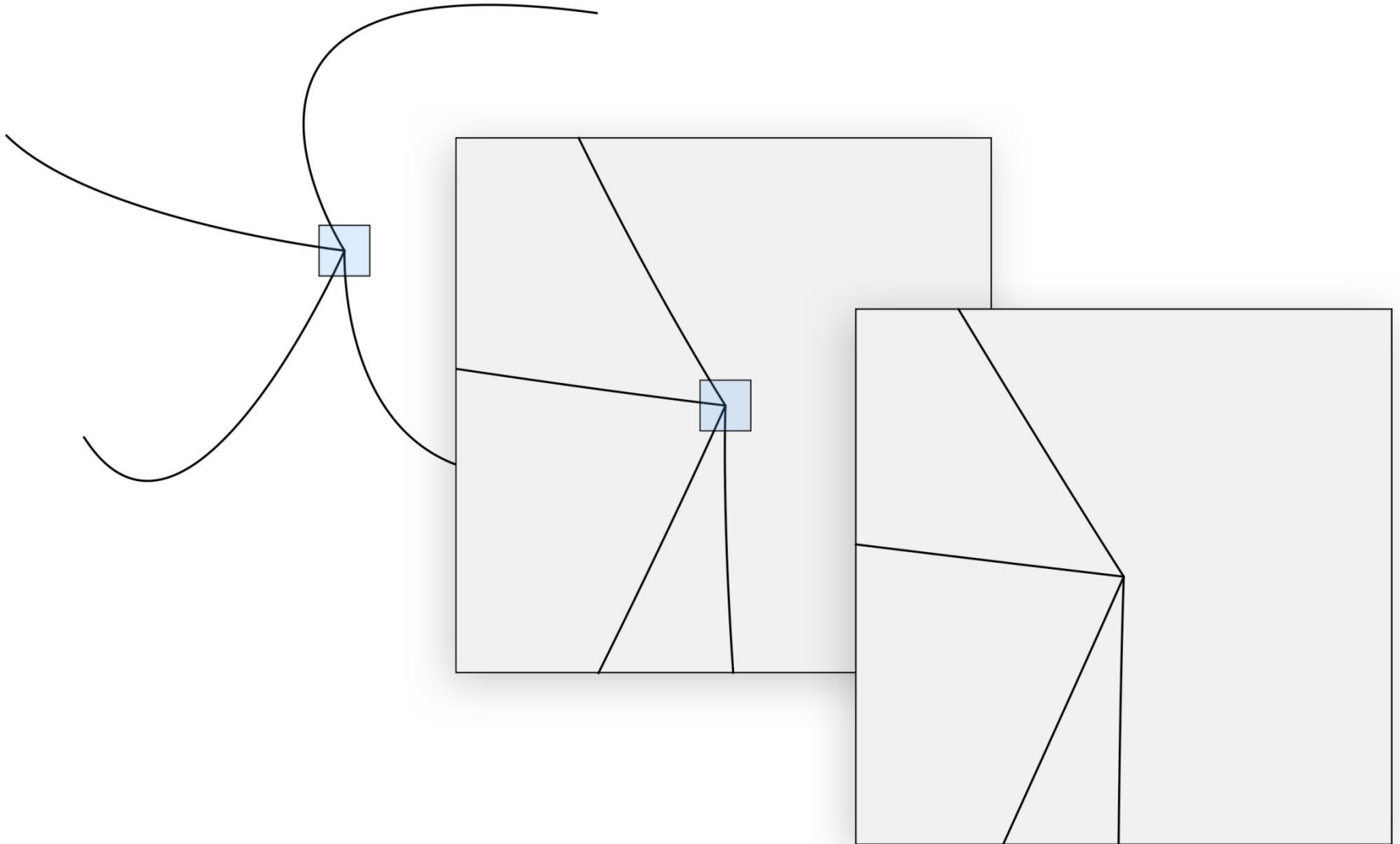
Can pretend we're on a grid:



A smooth manifold also looks flat close up

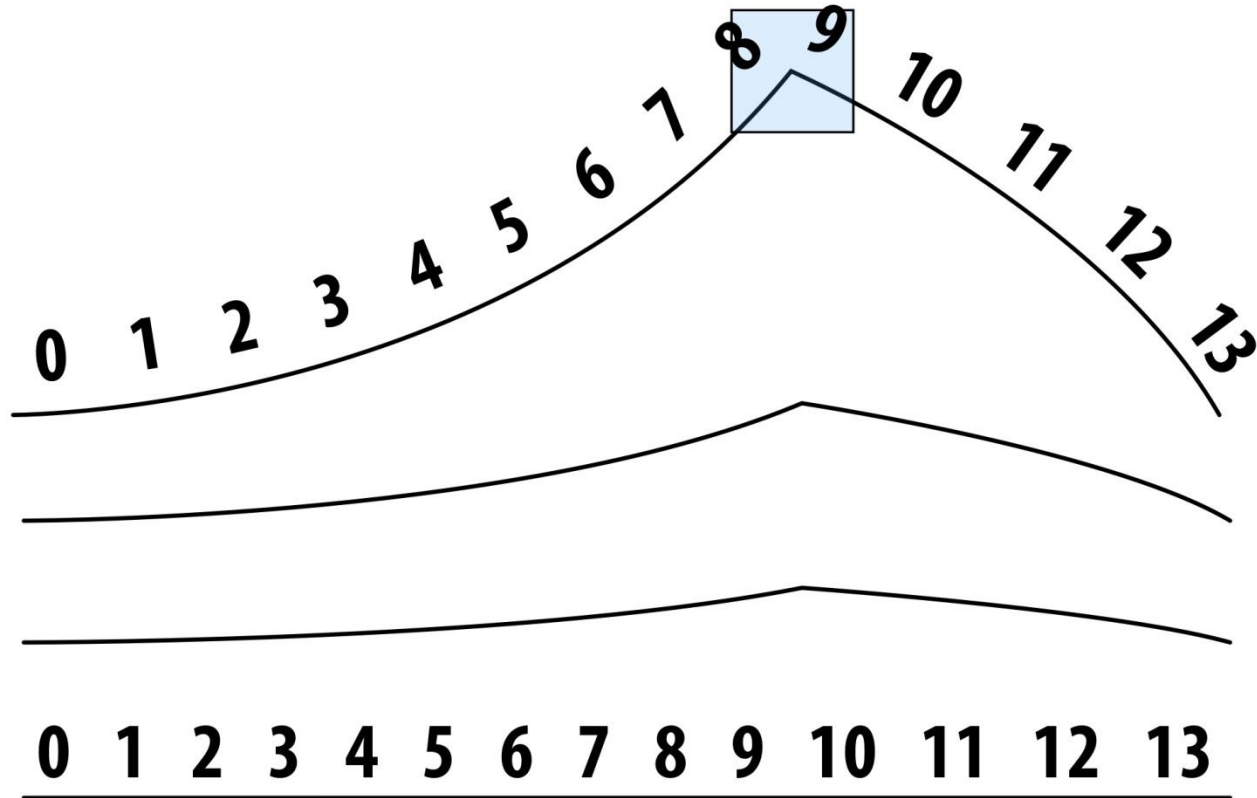


Not all curves are smooth manifolds



No matter how close we get, doesn't look like a single line!

What about sharp corners?



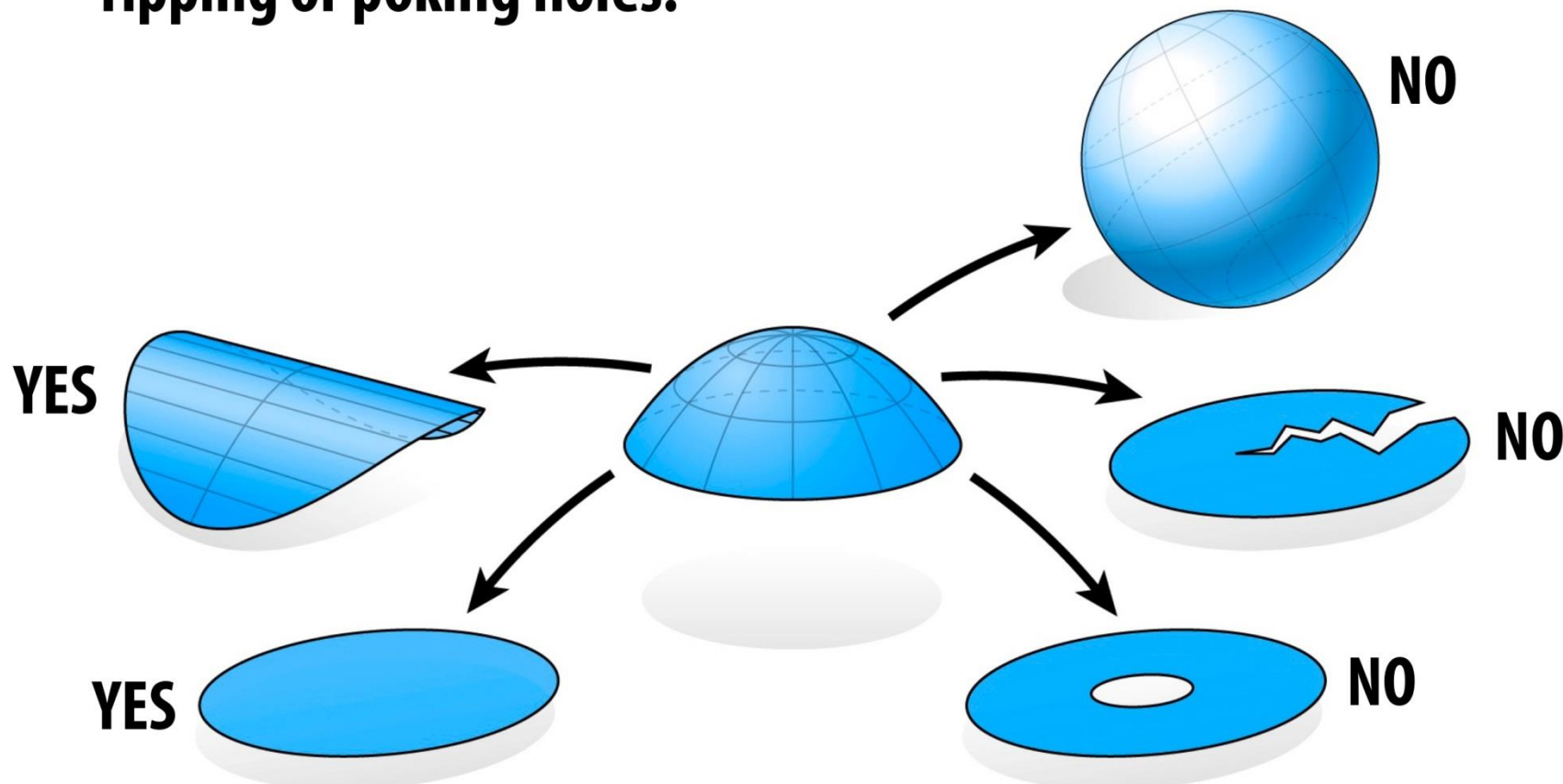
Can easily be flattened *into* a line.

Can still assign coordinates (just like Manhattan!)

...But is it a manifold?

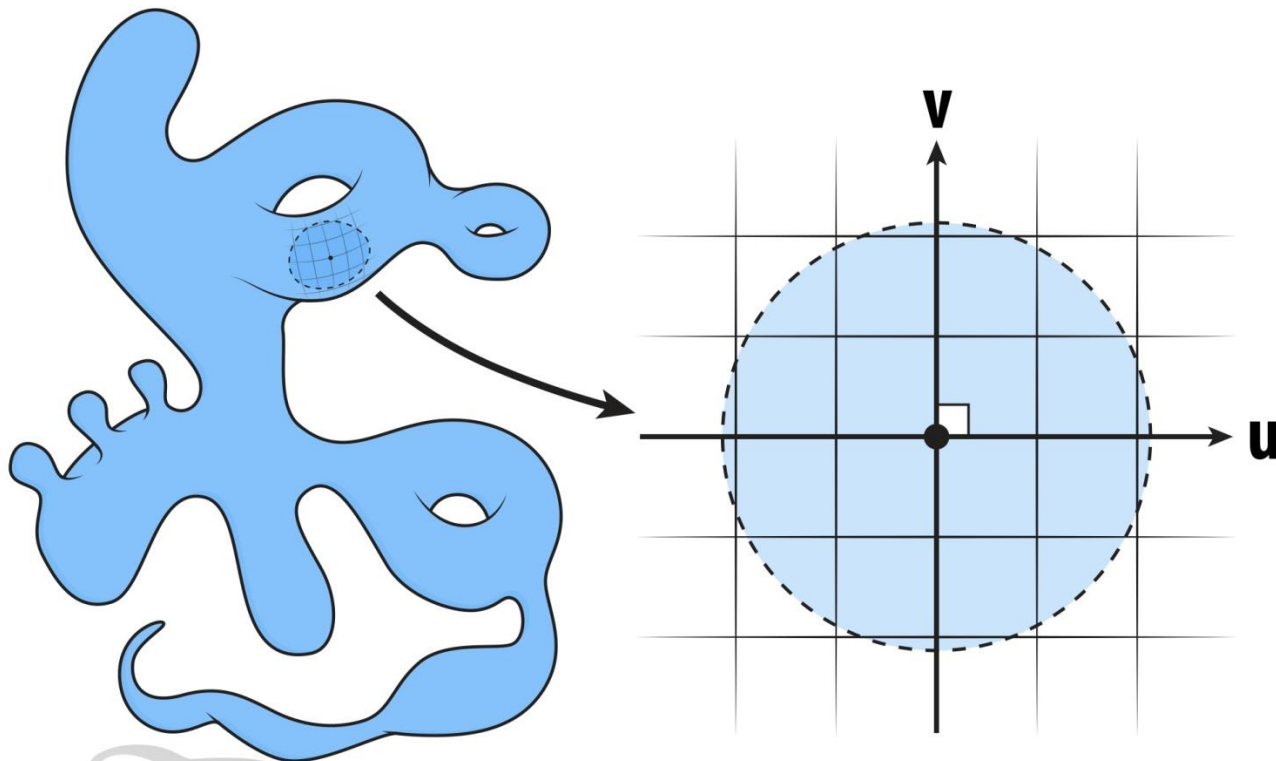
Definition of a manifold

- *"A subset S of R^m is an n -manifold if every point p in S is contained in a neighborhood that can be mapped bijectively and continuously (both ways) to the open ball in R^n ."*
- In other words: each little piece can be made flat without "ripping or poking holes."



Why is the manifold property valuable?

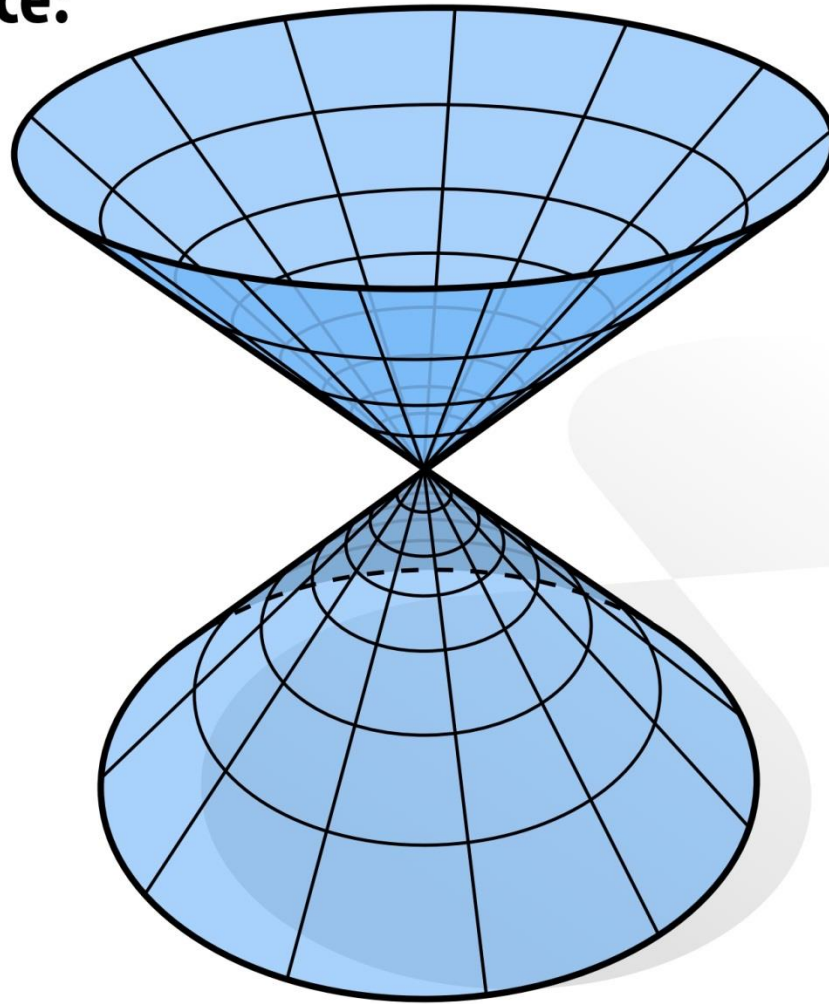
- Makes life simple: all surfaces look the same (at least locally).
- Gives us coordinates! (At least locally.)



- More abstractly, lets us talk about curved surfaces in terms of familiar tools: vector calculus & linear algebra.

Isn't every shape manifold?

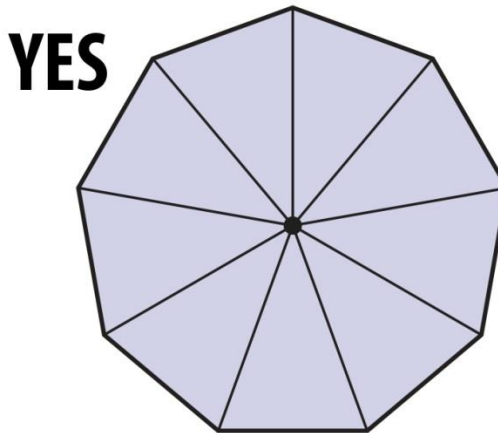
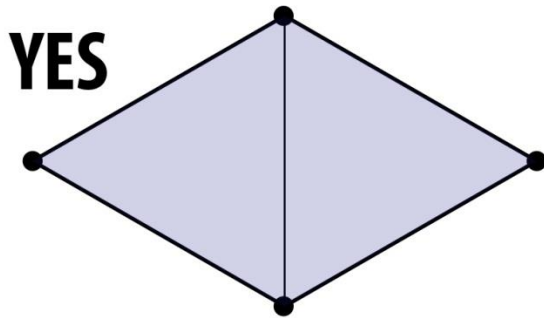
- No, for instance:



No way to put a (simple) coordinate system on the center point!

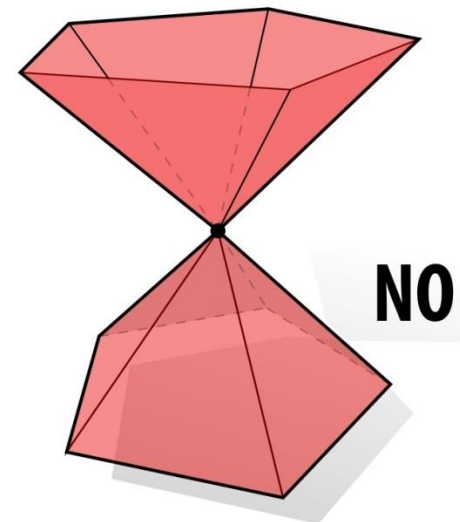
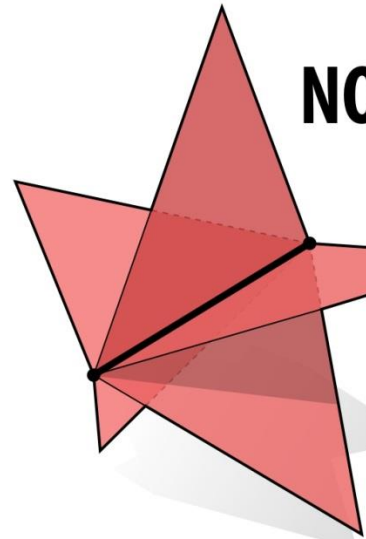
What about discrete surfaces?

- Surfaces made of, e.g., triangle are no longer *smooth*.
- But they can still be *manifold*:
 - two triangles per edge (no “fins”)
 - every vertex looks like a “fan”



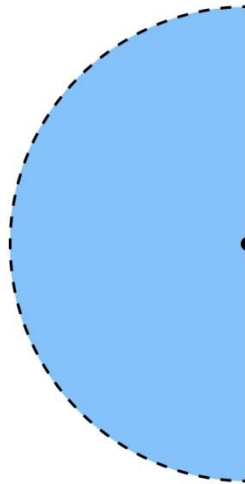
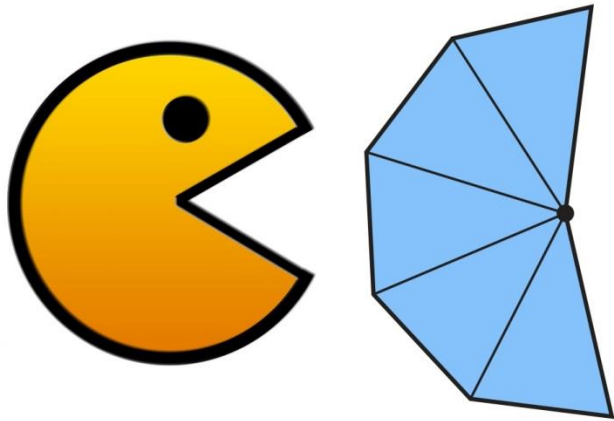
- Why? *Simplicity*.
 - no special cases to handle

keeps data structures (reasonably) simple)



What about boundary?

- The boundary is where the surface “ends.”
- E.g., waist & ankles on a pair of pants.
- Locally, looks like a *half* disk
- Globally, each boundary forms a loop



YES



- Triangle mesh:
 - one triangle per boundary edge
 - boundary vertex looks like “pacman”



Polygonal Meshes

Modeling with basic shapes (cube, cylinder, sphere, etc) too primitive

Difficult to approach realism

Polygonal meshes:

- Collection of polygons, or faces, that form “skin” of object
- Offer more flexibility
- Models complex surfaces better
- Examples:
 - Human face
 - Animal structures
 - Furniture, etc

Polygonal Meshes

Have become standard in CG

OpenGL

- Good at drawing polygon
- Mesh = sequence of polygons

Simple meshes exact. (e.g barn)

Complex meshes approximate (e.g. human face)

Later: use shading technique to smoothen

Non-solid Objects

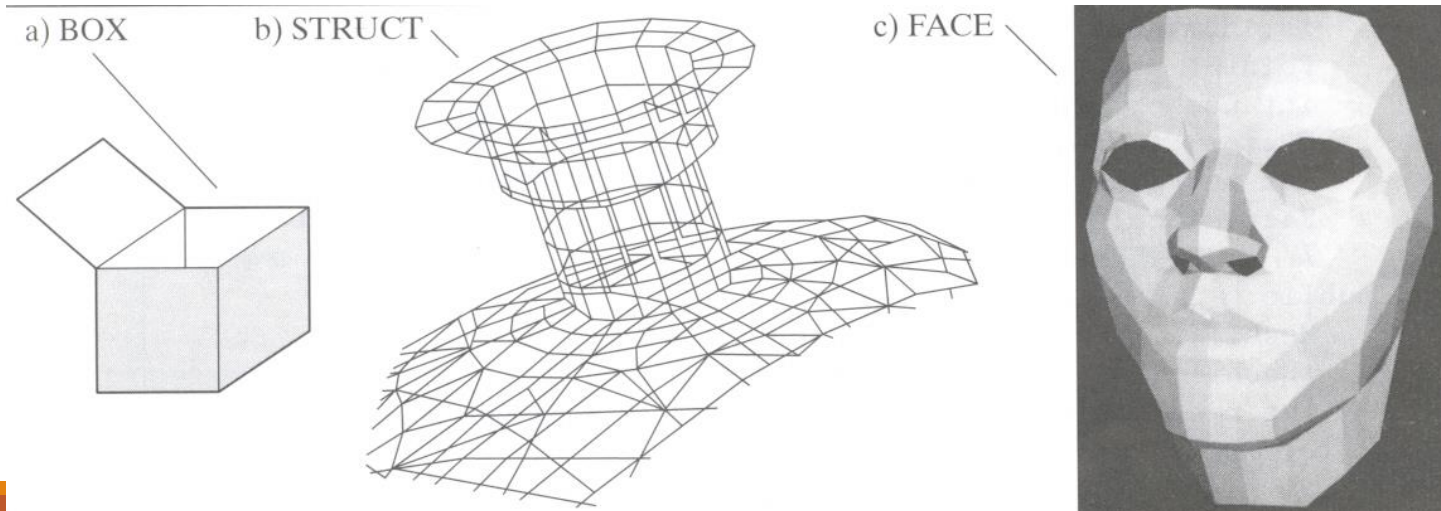
Examples: box, face

Visualize as infinitely thin skin

Meshes to approximate complex objects

Shading used later to smoothen

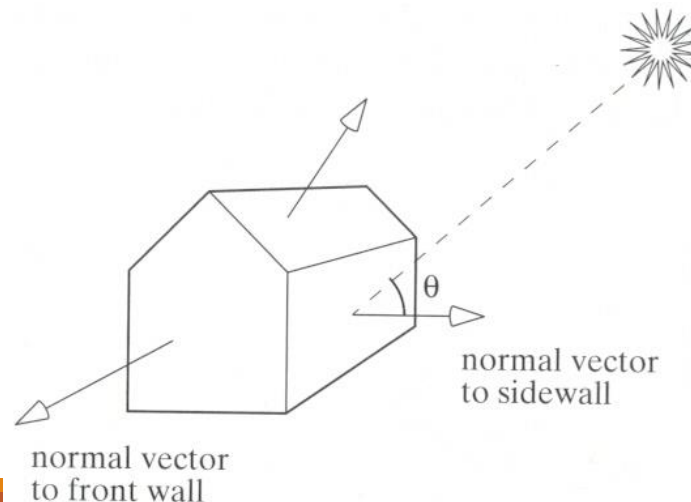
Non-trivial: creating mesh for complex objects (CAD)



What is a Polygonal Mesh

Polygonal mesh given by:

- Polygon list
- Direction of each polygon
- Represent direction as normal vector
- Normal vector used in shading
- Normal vector/light vector determines shading

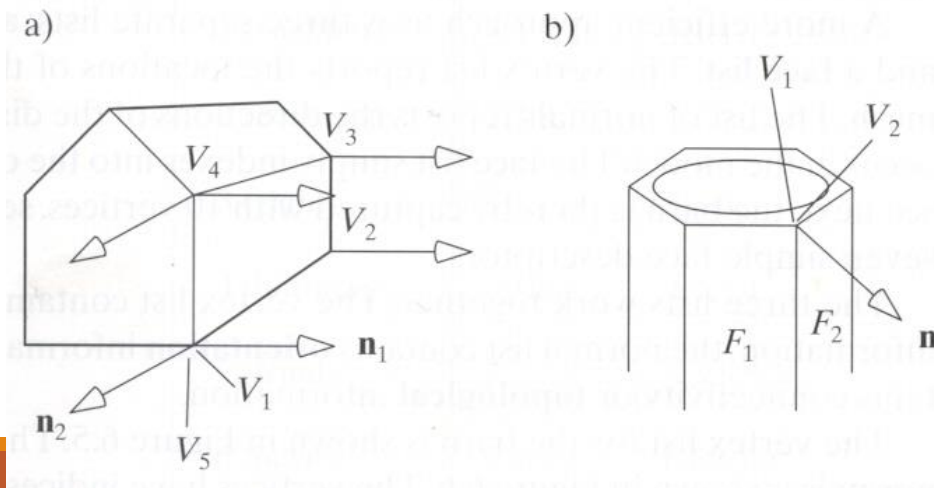


Vertex Normal

Use vertex normal instead of face normal

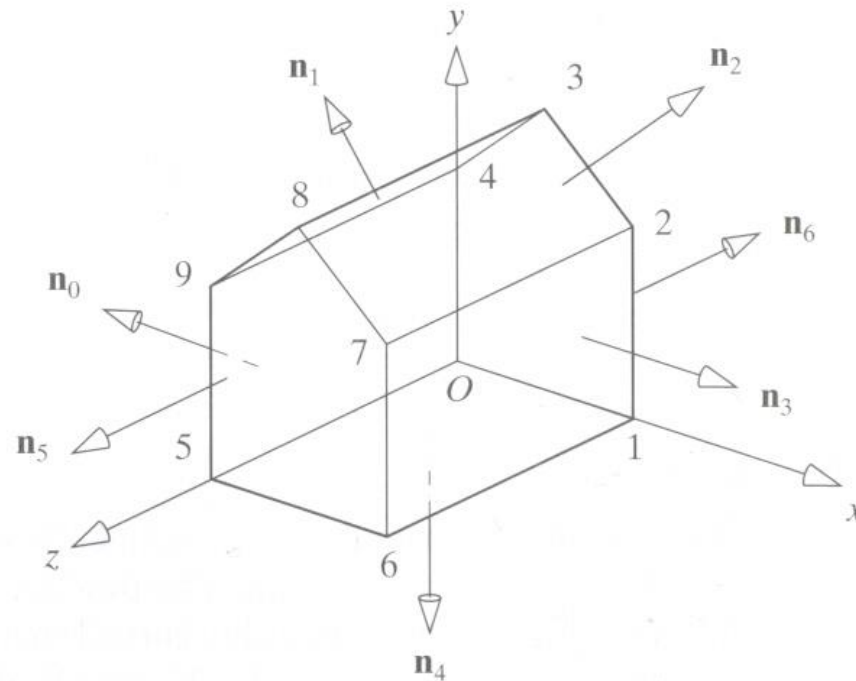
See advantages later:

- Facilitates clipping
- Shading of smoothly curved shapes
- Flat surfaces: all vertices associated with same \mathbf{n}
- Smoothly curved surfaces: V_1 , V_2 with common edge share \mathbf{n}



Defining Polygonal Mesh

Use barn example below:



Defining Polygonal Mesh

Three lists:

- Vertex list: distinct vertices (vertex number, V_x , V_y , V_z)
- Normal list: Normals to faces (normalized n_x , n_y , n_z)
- Face list: indexes into vertex and normal lists. i.e. vertices and normals associated with each face

Face list convention:

- Traverse vertices counter-clockwise
- Interior on left, exterior on right

Newell Method for Normal Vectors

Martin Newell at Utah (teapot guy)

Normal vector:

- calculation difficult by hand
- Given formulae, suitable for computer
- Compute during mesh generation

Simple approach used previously:

- Start with any three vertices V_1, V_2, V_3
- Form two vectors, say V_1-V_2, V_3-V_2
- Normal: cross product (perp) of vectors

Newell Method for Normal Vectors

Problems with simple approach:

- If two vectors are almost parallel, cross product is small
- Numerical inaccuracy may result
- Newell method: robust
- Formulae: Normal $N = (m_x, m_y, m_z)$

$$m_x = \sum_{i=0}^{N-1} (y_i - y_{next(i)}) (z_i + z_{next(i)})$$

$$m_y = \sum_{i=0}^{N-1} (z_i - z_{next(i)}) (x_i + x_{next(i)})$$

$$m_z = \sum_{i=0}^{N-1} (x_i - x_{next(i)}) (y_i + y_{next(i)})$$

Newell Method Example

Example: Find normal of polygon with vertices

$P_0 = (6,1,4)$, $P_1=(7,0,9)$ and $P_2 = (1,1,2)$

Solution:

Using simple cross product:

$$((7,0,9)-(6,1,4)) \times ((1,1,2)-(6,1,4)) = (2,-23,-5)$$

Using Newell method, plug in values result is the same:

Normal is $(2, -23, -5)$

Meshes in Programs

Class *Mesh*

Helper classes

- VertexID
- Face

Mesh Object:

- Normal list
- Vertex list
- Face list

Use arrays of pt, norm, face

Dynamic allocation at runtime

Array lengths: numVerts, numNormals, numFaces

Meshes in Programs

Face:

- Vertex list
- Normal vector associated with each face
- Array of index pairs

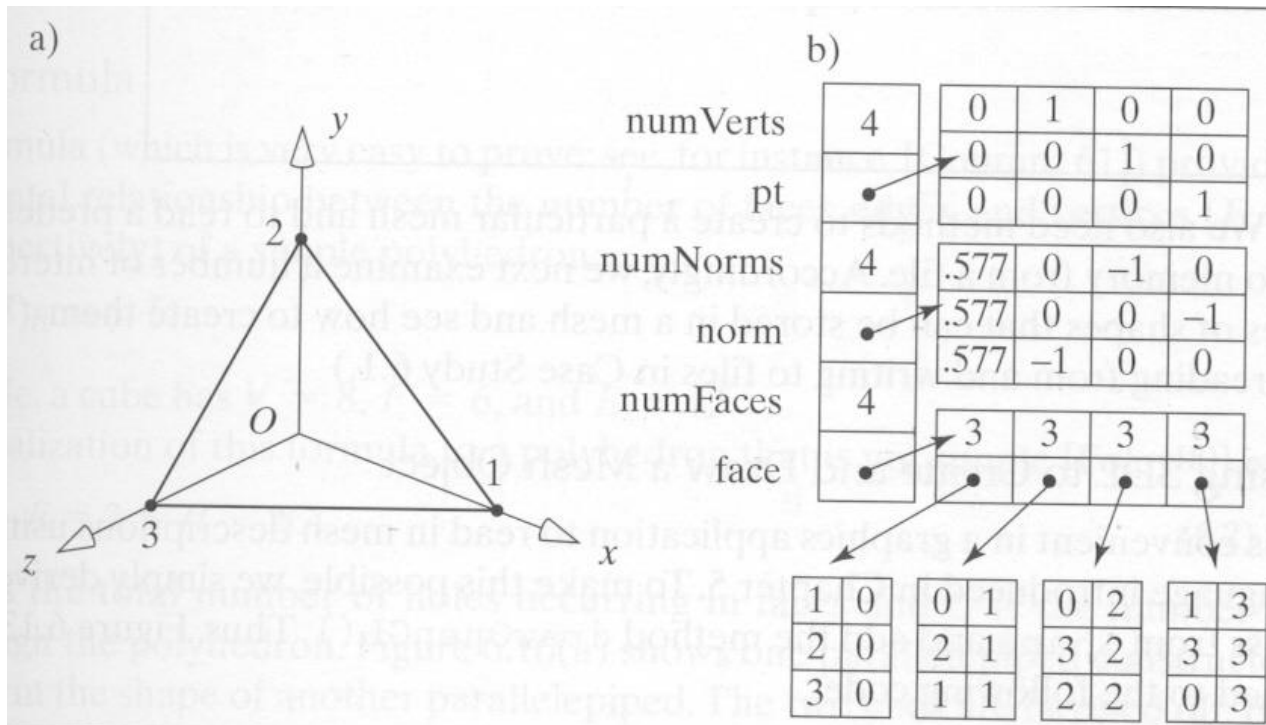
Example, v th vertex of f th face:

- Position: `pt[face[f].vert[v].vertIndex]`
- Normal vector: `norm[face[f].vert[v].normIndex]`

Organized approach, permits random access

Meshes in Programs

Tetrahedron example



Meshes in Programs

Data structure:

```
// ##### VertexID #####

class VertexID

public:

    int vertIndex; // index of this vertex in the vertex list

    int normIndex; // index of this vertex's normal

}

// ##### Face #####

class Face

public:

    int nVerts; // number of vertices in this face

    VertexID *vert; // the list of vertex and normal indices

    Face( ){nVerts = 0; vert = NULL;} // constructor

    ~Face(){delete[] vert; nVerts = 0; // destructor

};
```


Meshes in Programs

```
// ##### Mesh #####

class Mesh{

    private:

        int numVerts;        // number of vertices in the mesh

        Point3 *pt;          // array of 3D vertices

        int numNormals;      // number of normal vertices for the mesh

        Vector3 *norm;       // array of normals

        int numFaces;        // number of faces in the mesh

        Face *face;          // array of face data

        //... others to be added later

    public:

        Mesh( );              // constructor

        ~Mesh( );             // destructor

        int readFile(char *fileName); // to read in a filed mesh

        ..... other methods....

}
```

Drawing Meshes Using OpenGL

Pseudo-code:

```
for(each face f in Mesh)  
{  
    glBegin(GL_POLYGON);  
    for(each vertex v in face f)  
    {  
        glNormal3f(normal at vertex v);  
        glVertex3f(position of vertex v);  
    }  
    glEnd( );  
}
```

Drawing Meshes Using OpenGL

Actual code:

```
Void Mesh::draw()      // use OpenGL to draw this mesh
{
    for(int f = 0;f < numFaces;f++)
    {
        glBegin(GL_POLYGON);
        for(int v=0;v<face[f].nVerts;v++)    // for each one
        {
            int in = face[f].vert[v].normIndex; // index of this normal
            int iv = face[f].vert[v].vertIndex;  // index of this vertex
            glNormal3f(norm[in].x, norm[in].y, norm[in].z);
            glVertex3f(pt[iv].x, pt[iv].y, pt[iv].z);
        }
        glEnd( );
    }
}
```

Drawing Meshes Using SDL

Scene class reads SDL files

Accepts keyword *Mesh*

Example:

- Pawn stored in mesh file pawn.3vn
- Add line:
 - Push translate 3 5 4 scale 3 3 3 mesh pawn.3vn pop

More on Meshes

Simple meshes easy by hand

Complex meshes:

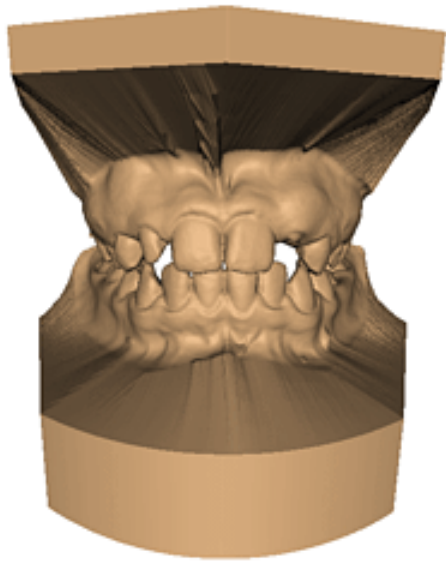
- Mathematical functions
- Algorithms
- Digitize real objects

Libraries of meshes available

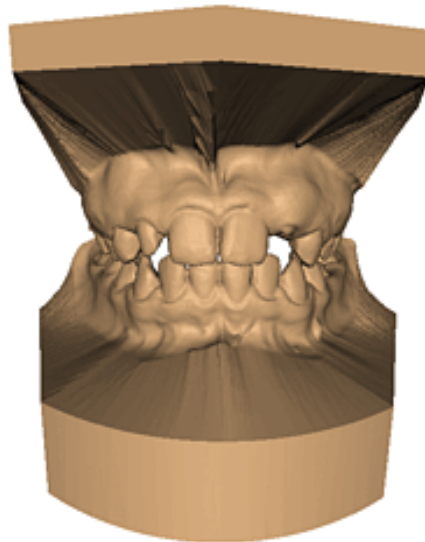
Mesh trends:

- 3D scanning
- Mesh Simplification

3D Simplification Example



**Original: 424,000
triangles**



**60,000 triangles
(14%).**



**1000 triangles
(0.2%)**

(courtesy of Michael Garland and Data courtesy of Iris Development.)

References

Hill, 6.1-6.2