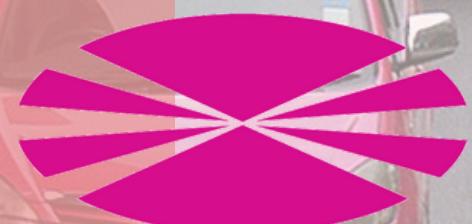


2025

TRAFFIC SIGN CLASSIFIER

by Fiz Garrido Escudero



UNIVERSIDADE DA CORUÑA
Data Mining and Neural Networks Course



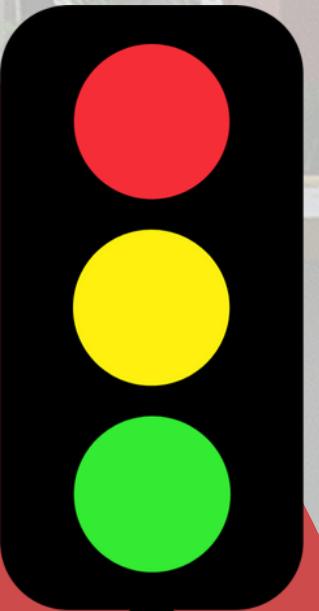
General objective

Enhance road safety and driver assistance by building a model that can reliably recognize traffic signs in real time, reducing human errors and supporting ADAS/autonomous vehicles.

Specific objectives

- Explore a labeled image dataset
- Learn to design and train CNN and KNN models
- Apply data-mining, cleaning, and preprocessing techniques
- Evaluate and interpret results rigorously

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Project scope

Problem

Drivers' weak sign knowledge

+

visual overload

=

Wrong interpretation of signs



In Scope

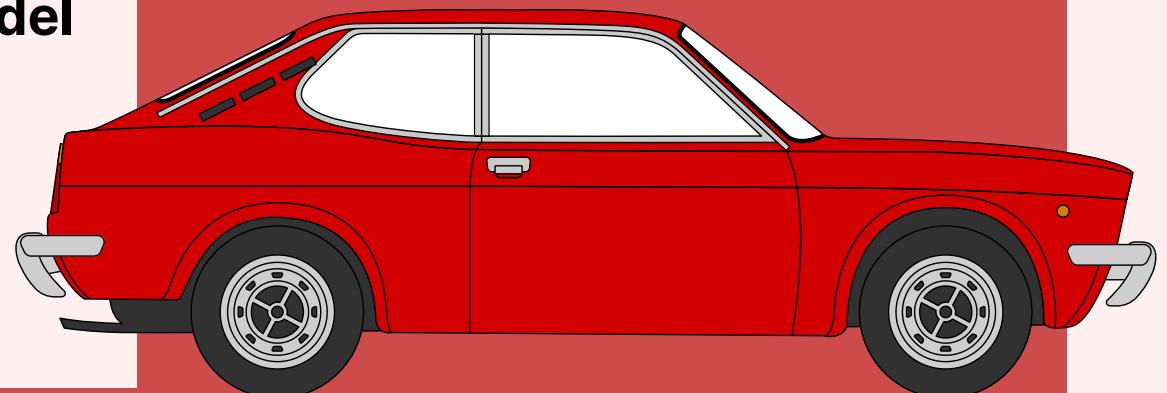
- Use a made of images dataset (43 cropped traffic-sign classes).
- Data pipeline: loading, cleaning, resizing, normalizing, etc
- Develop and train a CNN and a KNN model
- Evaluation & interpretation
- Documentation & reproducibility: runnable notebook + presentation.

Deliverables

- Trained models and evaluation report.
- Executable Jupyter notebook

Out of Scope

- Detecting signs in full road scenes
- Real-time deployment
- Multi-country sign coverage.

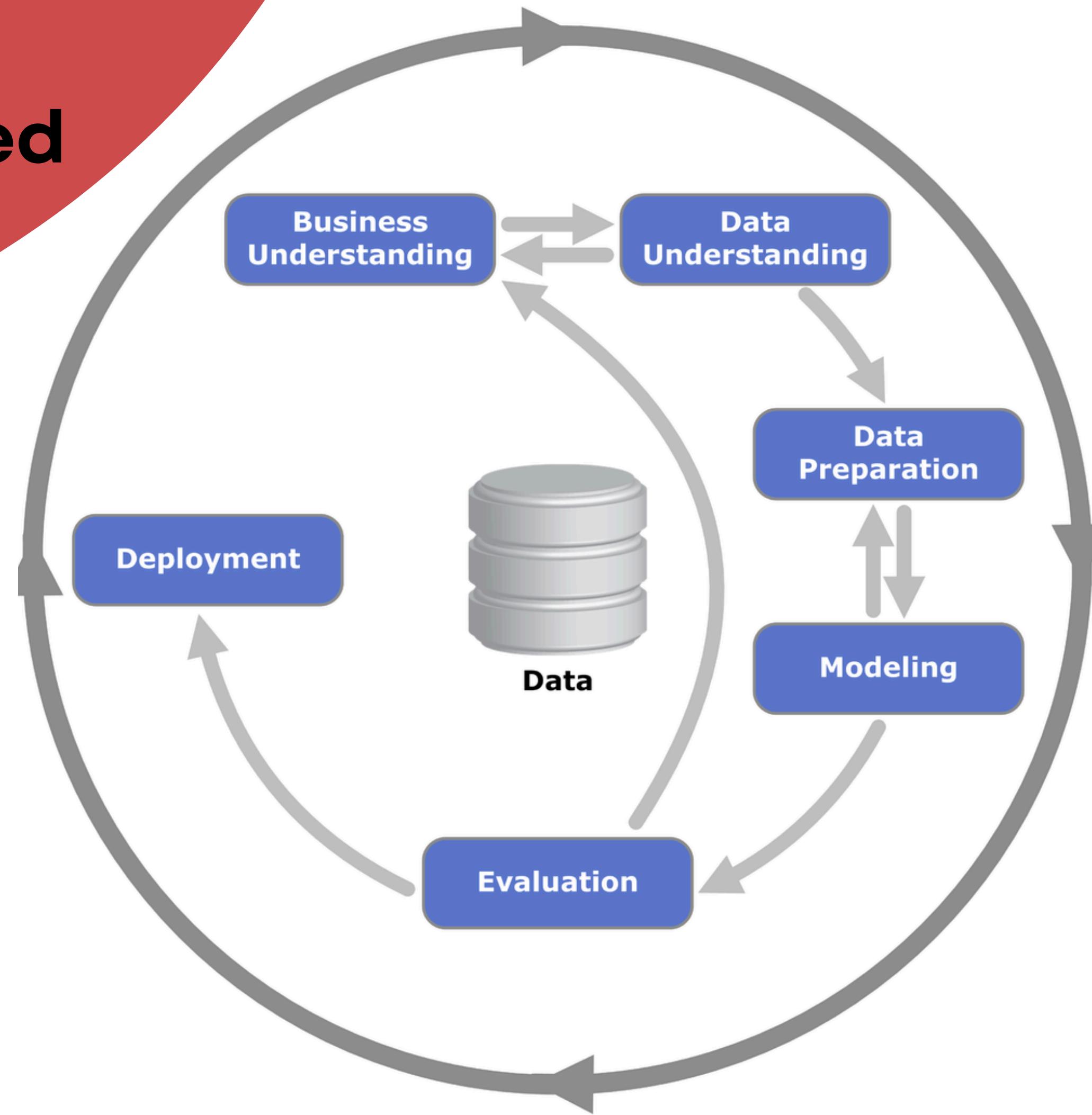


Assumptions

- Correct labels
- Clean data
- Colab's type GPU
- Limited time



Methodology used



Algorithms applied



CNN

Pretrained MobileNetv2

+

classification head



Optimization & Training Tricks

- Adam optimizer
- Dropout
- BatchNormalization
- EarlyStopping



KNN

- It classifies based on the k nearest neighbors of the sample
- Only for checking CNN performance



Key results: CNN

Resultados de Configuraciones del Modelo

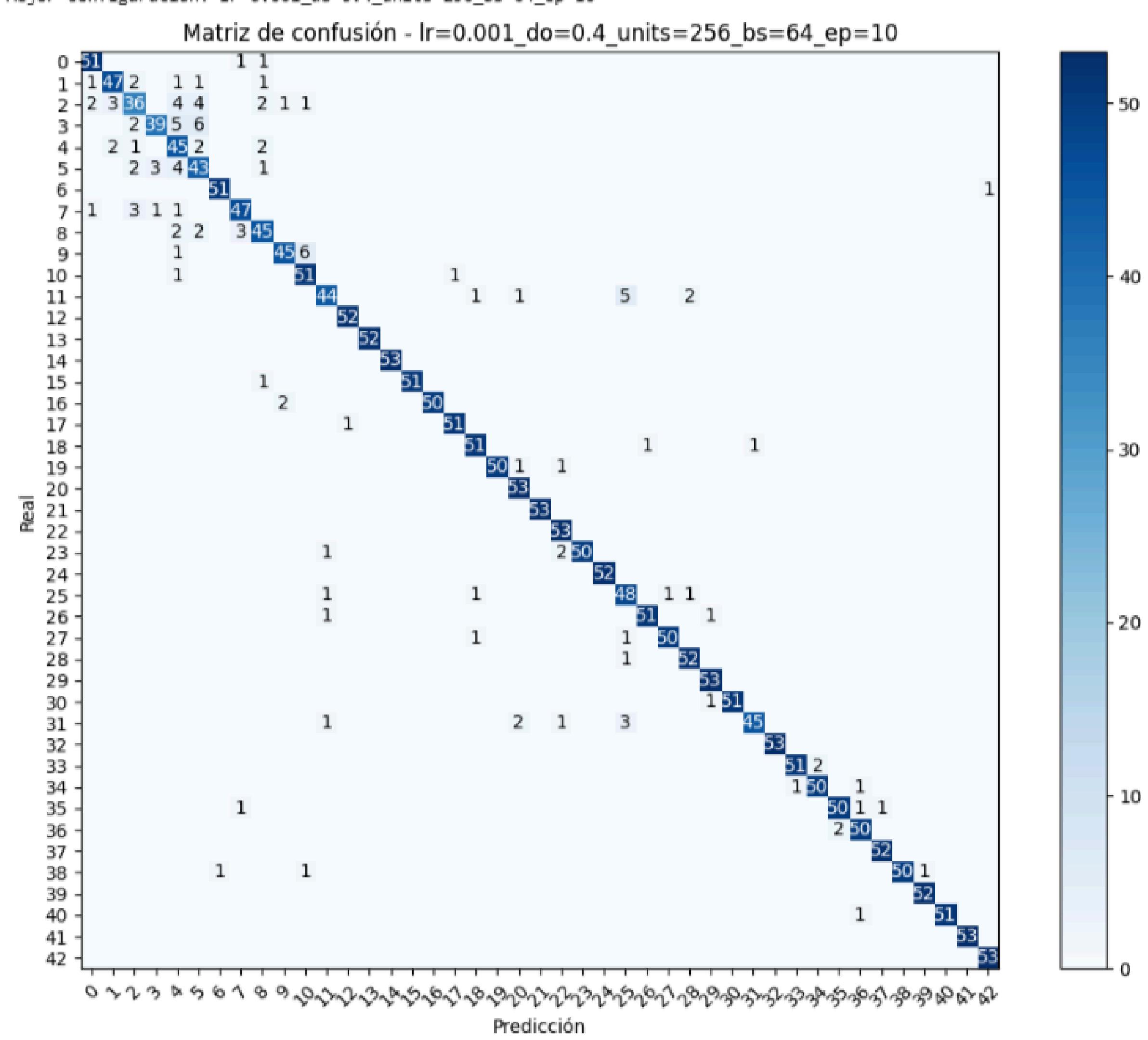
config	learning_rate	dropout	dense_units	batch_size	epochs	val_accuracy	test_accuracy	test_loss	f1_macro	f1_weighted	precision_macro	recall_macro
lr=0.001_do=0.4_units=256_bs=64_ep=30	0.0010	0.4000	256	64	30	0.9393	0.9389	0.1924	0.9389	0.9389	0.9404	0.9389
lr=0.001_do=0.4_units=256_bs=32_ep=30	0.0010	0.4000	256	32	30	0.9376	0.9336	0.2383	0.9338	0.9337	0.9355	0.9337
lr=0.001_do=0.4_units=256_bs=64_ep=10	0.0010	0.4000	256	64	10	0.9327	0.9433	0.2045	0.9434	0.9434	0.9454	0.9433
lr=0.0001_do=0.4_units=256_bs=64_ep=30	0.0001	0.4000	256	64	30	0.9327	0.9283	0.2552	0.9280	0.9279	0.9287	0.9283
lr=0.001_do=0.4_units=256_bs=32_ep=10	0.0010	0.4000	256	32	10	0.9296	0.9221	0.2487	0.9221	0.9220	0.9258	0.9222
lr=0.0001_do=0.4_units=256_bs=32_ep=30	0.0001	0.4000	256	32	30	0.9269	0.9283	0.2586	0.9283	0.9282	0.9293	0.9284
lr=0.0001_do=0.4_units=256_bs=32_ep=10	0.0001	0.4000	256	32	10	0.9114	0.9057	0.3456	0.9054	0.9053	0.9072	0.9058
lr=0.0001_do=0.4_units=256_bs=64_ep=10	0.0001	0.4000	256	64	10	0.8933	0.8835	0.4267	0.8831	0.8830	0.8842	0.8836

Test accuracy (best model): 94.33%



Key results: CNN

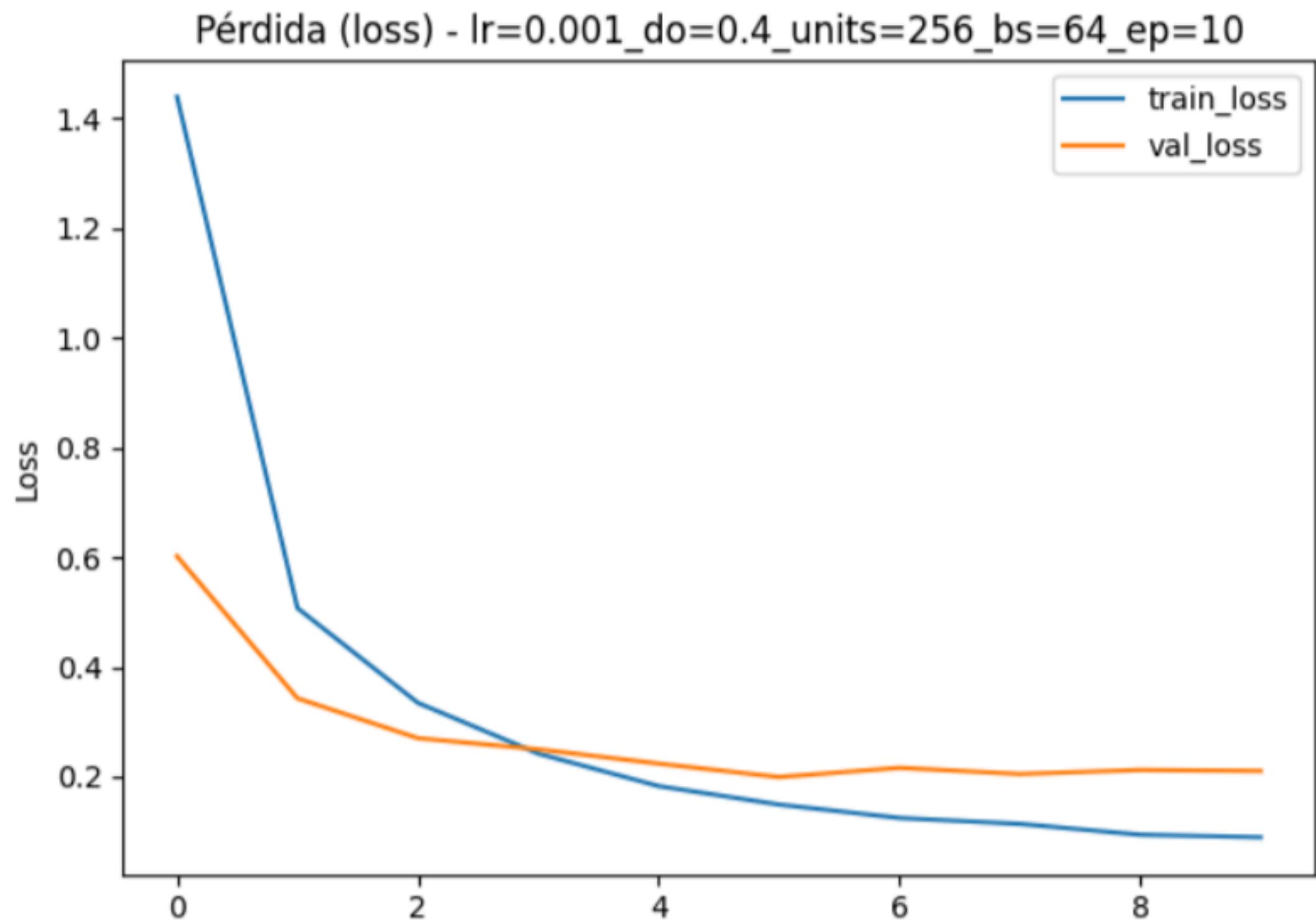
!!Robust model !!



Key results: CNN

**validation loss
vs
train loss**

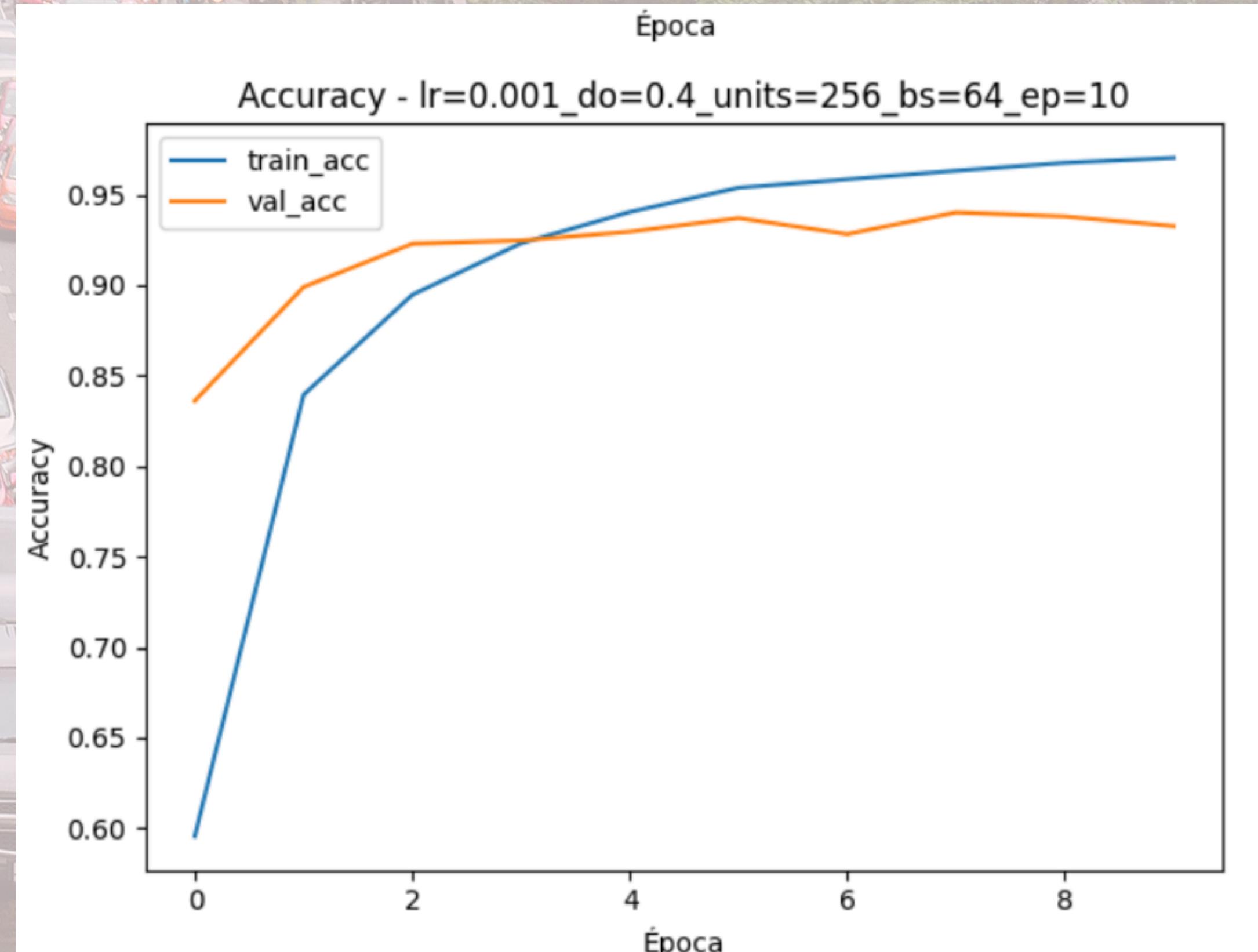
**Good learning
WITHOUT
OVERFITTING**



Key results: CNN

validation accuracy
vs
train accuracy

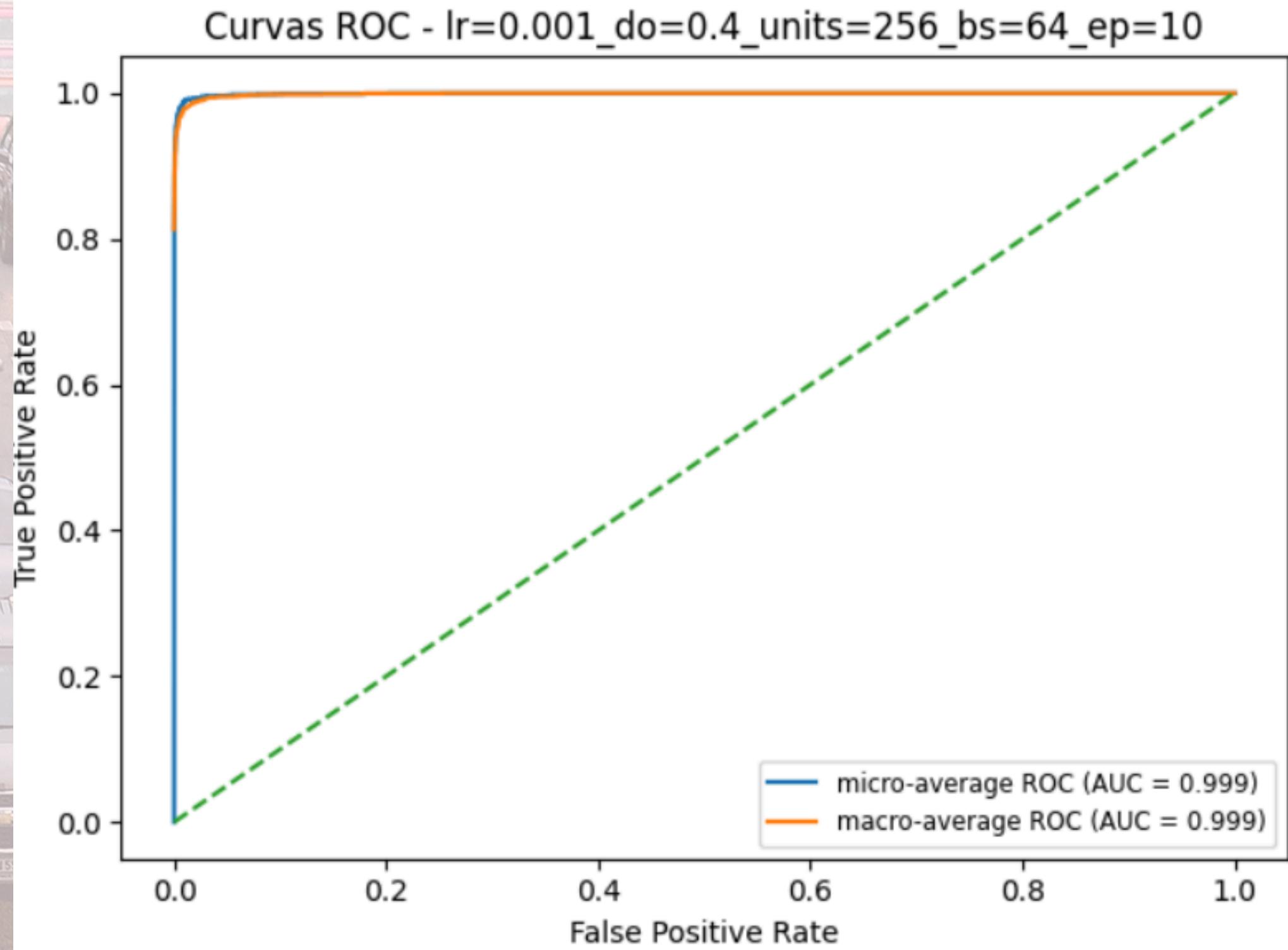
Good learning
WITHOUT
OVERFITTING



Key results: CNN

ROC Curve

Near-perfect separation between classes



Key results: KNN

Resultados de Configuraciones del Modelo KNN

config	k	test_accuracy	precision	recall	f1_score
0	KNN_k=1	1	0.8494	0.8563	0.8496
1	KNN_k=3	3	0.7697	0.7917	0.7700
2	KNN_k=5	5	0.7414	0.7577	0.7416
3	KNN_k=7	7	0.7095	0.7242	0.7097
4	KNN_k=13	13	0.6581	0.6734	0.6584

Test accuracy (best model, k = 1): 84.94%

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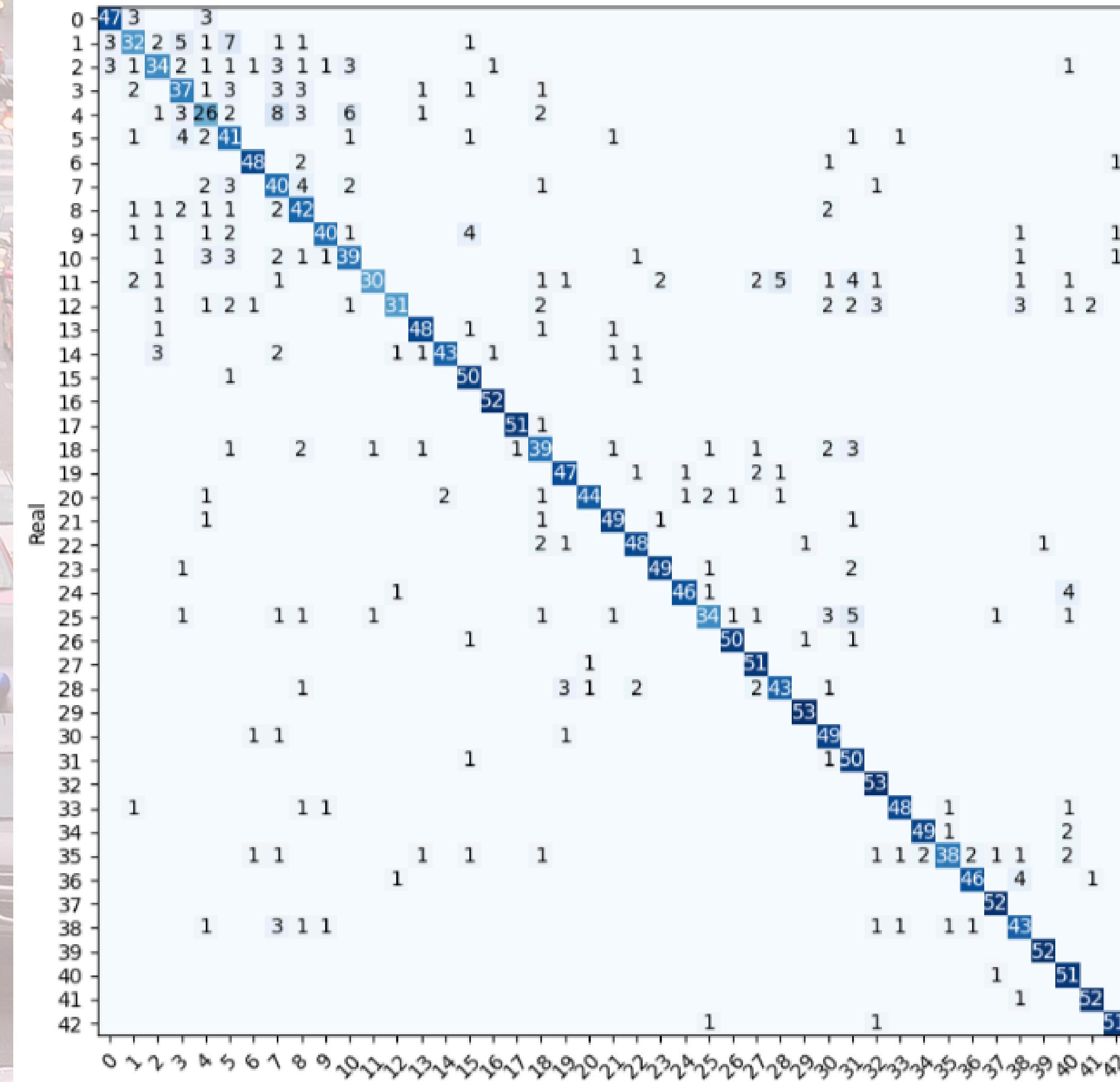


Key results

KNN



Matriz de confusión - KNN (k=1)



Findings



- CNN clearly outperforms kNN
- CNN is expensive to train but cheap to predict; kNN is the opposite.
- Training/validation curves stay close
 - no strong overfitting; early stopping was effective
- Remaining errors appear between visually similar signs.



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Conclusions

- CNN vs ML classic models
- Necessity of cleaning and preprocessing
- Difficulties of implementing a real life problem



Recommendations

- Using more RAM and a powerfull GPU
- Collect the largest dataset possible



FOR HYPOTHETICAL FINAL USERS:

- iii Practice mindful driving and pay attention to road signs !!!