



$$\vec{N}_B = \vec{N} \times \vec{B} = I (\vec{s} \times \vec{B} N)$$

$$I = \frac{\epsilon}{R} \quad \vec{s} \times \vec{B} = a^2 B \sin\left(\frac{\pi}{2} - \theta\right) = a^2 B \cos \theta$$

$$\vec{\Phi} = a^2 B \sin \theta N \quad \frac{d\Phi}{dt} = a^2 N B \cos \theta \dot{\theta}$$

$$\mathcal{E} = U_0 \sin(\omega t) - \frac{d\Phi}{dt} = U_0 \sin(\omega t) - a^2 N B \cos \theta \dot{\theta}$$

$$N_B = \frac{1}{R} (U_0 \sin(\omega t) - a^2 B N \cos \theta \dot{\theta}) \quad a^2 N B \cos \theta$$

$$N_c = N_B - mg \frac{a}{2} \sin \theta$$

$$\sin \theta \rightarrow \theta \quad \cos \theta \rightarrow 1$$

$$I \ddot{\theta} = \frac{U_0 \sin(\omega t) a^2 N B}{R} - \frac{a^4 B^2 N^2}{R} \dot{\theta} - \frac{mg a}{2} \theta$$

$$\theta = A e^{i\omega t}$$

$$-A \omega^2 e^{i\omega t} = \frac{U_0 \sin(\omega t) a^2 N B}{R I} - A \frac{a^4 B^2 N^2}{R I} i \omega e^{i\omega t} - \frac{mg a}{2 I} A e^{i\omega t}$$

$\underbrace{\frac{U_0 a^2 N B}{R I}}_{\text{ym}\left(i \frac{U_0 a^2 N B}{R I} e^{i\omega t}\right)}$

$$A = \frac{U_0 a^2 N B}{R I} \cdot \frac{1}{\frac{mg a}{2 I} + i \omega \frac{a^4 B^2 N^2}{R I} - \omega^2}$$

$$A = \frac{U_0 a^2 N B}{\left(\frac{mg a R}{2} - \omega^2 R I\right) + i \omega a^4 B^2 N^2}$$

$$z = \frac{1}{a + ib} = \frac{a - ib}{a^2 + b^2}$$

$$|z| = \sqrt{\frac{a^2 + b^2}{(a^2 + b^2)^2}} = \frac{1}{\sqrt{a^2 + b^2}}$$

$$|A| = \frac{U_0 a^2 N B}{\sqrt{\left(\frac{mg a R}{2} - \omega^2 R I\right)^2 + \left(\omega a^4 B^2 N^2\right)^2}}$$