

of spero.

$$\frac{1}{3 \cdot 10^{3}} \left[\frac{1}{3 \cdot 10^{3}} \left((R + 2_{1})^{\frac{3}{2}} \cdot (R^{\frac{3}{2}} + 2_{1})^{\frac{3}{2}} \cdot (R^{\frac{3}$$

 $Q > J_{q} = 6.277RJ\theta = 256R^2 \sin\theta J\theta$ 7=R55n(J-7)=R55n0 R -> R sind 2-> 2-R (050) $\phi = \frac{\sigma R^2}{2 \varepsilon_0} \left(\frac{5 \pi \theta}{\sqrt{R^2 + z^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z} \left(\frac{1}{\sqrt{u}} - \frac{\sigma R}{2 \varepsilon_0 z_0} \right) = \frac{\sigma R}{2 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 + 2 \varepsilon R \cos \theta}} \right) d\theta = \frac{\sigma R}{4 \varepsilon_0 z_0} \left(\frac{1}{\sqrt{R^2 +$ $= \frac{Q}{4\pi R^{2}} \left(|R+2| - \sqrt{R^{2}+2^{2}} \right)$ (u = R2+ =2-2=Rcos A $\frac{\pi}{2} \to R^{2} + 2^{2}$ $\pi \to R^{2} + 2^{2} + 2 = R + 2$ Potteula po=d Q -, dy = J - 2 JT 2 J ~ $d\phi = \frac{d\psi}{4\pi r z_0 \epsilon_0} \left(\left| r + z_0 \right| - \sqrt{r^2 + z_0^2} \right) = \frac{f^2}{2 z_0 \epsilon_0} \left(\left| r + z_0 \right| - \sqrt{r^2 + z_0^2} \right) dr$ $\phi = \frac{1}{2 \epsilon_0 z_0} \left(\frac{1}{3} r / r + \frac{1}{2} r \right) dr - \left(\frac{1}{3} r + \frac{1}{2} r \right) dr = \frac{1}{2 \epsilon_0 z_0} \left(\frac{1}{3} r + \frac{1}{2} r \right) dr - \frac{1}{3} \left(\frac{1}{3} r \right) dr + \frac{1}{3} \left(\frac{1} r \right) dr + \frac{1}{3} \left(\frac{1}{3} r \right) dr + \frac{1}{3} \left(\frac{1}{3} r \right)$ $I_{\eta} = \int r |r+z_0| dr = \int (r^2 + rz_0) dr = \frac{R}{3} + \frac{R^2}{3}$ $\frac{1}{12} = \frac{1}{12} \left[\sqrt{12} \left(\sqrt{12} \right)^{2} + 2 \left(\sqrt{12} \right)^{2} \right] = \frac{1}{3} \left(\sqrt{12} + 2 \left(\sqrt{12} \right)^{2} - \frac{1}{3} \left(\sqrt{12} \right)^{2} \right)$

x + = 2 = 4

2 r Vr = ola