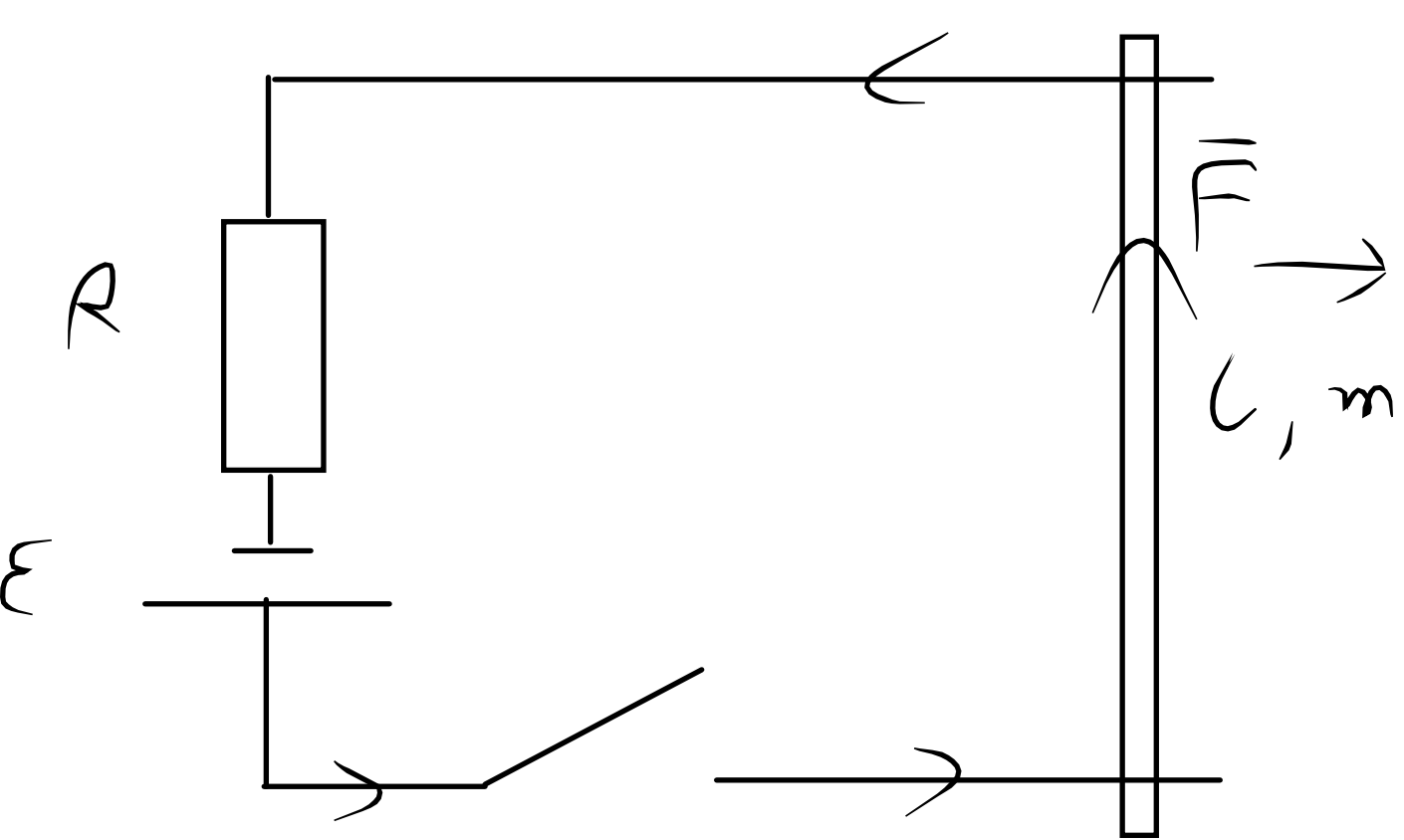


OB

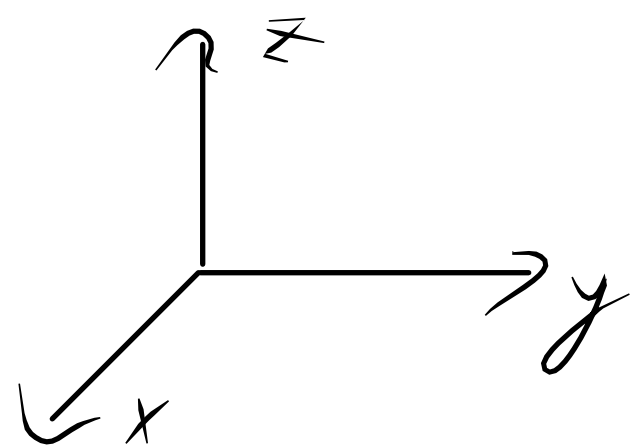


$$d\phi_B = B l dy$$

$$\mathcal{E}_{ind} + \mathcal{E} = I R$$

$$\mathcal{E}_{ind} = -\frac{d\phi_B}{dt} = -B l v$$

$$I = \frac{\mathcal{E} - B l v}{R}$$



Sila elektromotorna na popreku

$$\vec{v}_m = \vec{F} = I \vec{l} \times \vec{B} = I l B \hat{e}_z \times \hat{e}_x = I l B \hat{e}_y$$

$$\dot{v} = \frac{\mathcal{E} - B l v}{R_m} l B$$

$$v = A e^{\lambda t} \quad R \cup R \cup$$

$$\dot{v} + \frac{B^2 l^2}{R_m} v = \frac{\mathcal{E} l B}{R_m}$$

$$A \lambda e^{\lambda t} + A \frac{B^2 l^2}{R_m} e^{\lambda t} = 0$$

$$\lambda = -\frac{B^2 l^2}{R_m}$$

$$v = A(t) e^{-\frac{B^2 l^2}{R_m} t}$$

$$\dot{v} = \dot{A}(t) e^{-\frac{B^2 l^2}{R_m} t} - A(t) e^{-\frac{B^2 l^2}{R_m} t}$$

RSRN

$$\dot{A}(t) e^{-\frac{B^2 l^2}{R_m} t} - A(t) e^{-\frac{B^2 l^2}{R_m} t} + \frac{B^2 l^2}{R_m} A(t) e^{-\frac{B^2 l^2}{R_m} t} = \frac{\mathcal{E} l B}{R_m}$$

$$\dot{A}(t) = \frac{\mathcal{E} l B}{R_m} e^{\frac{B^2 l^2}{R_m} t}$$

$$A(t) = \frac{\mathcal{E}}{B l} e^{\frac{B^2 l^2}{R_m} t} + C$$

$$v(t) = \left(\frac{\mathcal{E}}{B l} e^{\frac{B^2 l^2}{R_m} t} + C \right) e^{-\frac{B^2 l^2}{R_m} t}$$

$$v(0) = 0 \Rightarrow C = -\frac{\mathcal{E}}{B l}$$

$$v(t) = \frac{\mathcal{E}}{B l} \left(1 - e^{-\frac{B^2 l^2}{R_m} t} \right)$$

$$I = \frac{\mathcal{E}}{R} e^{-\frac{B^2 l^2}{R_m} t}$$