### SCAMPTM COMBINATION I/O

### **FEATURES**

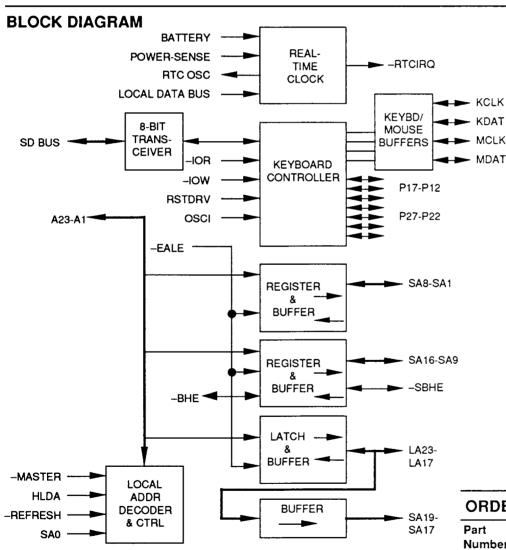
- Integrated peripheral controller for SCAMP™ VL82C310/VL82C311/ VL82C311L Single Chip PC/AT® Controllers
- 146818A-compatible real-time clock
- 64 additional bytes of battery-backed CMOS RAM
- AT-compatible keyboard controller with integrated PS/2® mouse support
- SCAMP-compatible processor to ISA bus address latches and buffers

- Real-time clock relocateable via SA15-SA0 address registers
- 1.0-micron CMOS in a 100-lead MQFP

### **DESCRIPTION**

The VL82C113/VL82C113A SCAMP Combination I/O chip, when used with VLSI SCAMP chips, allows designers to implement a very cost-effective minimum chip count motherboard. This chip combines a keyboard controller

and a real-time clock with the address registers/latches and buffers which are normally required in PC/AT-compatible systems. The VL82C113/VL82C113A features an AT-compatible keyboard controller with integrated PS/2 mouse support and a 146818A-compatible real-time clock. In addition, the VL82C113/VL82C113A has 64 additional bytes of battery-backed CMOS RAM for use in extended system setup.



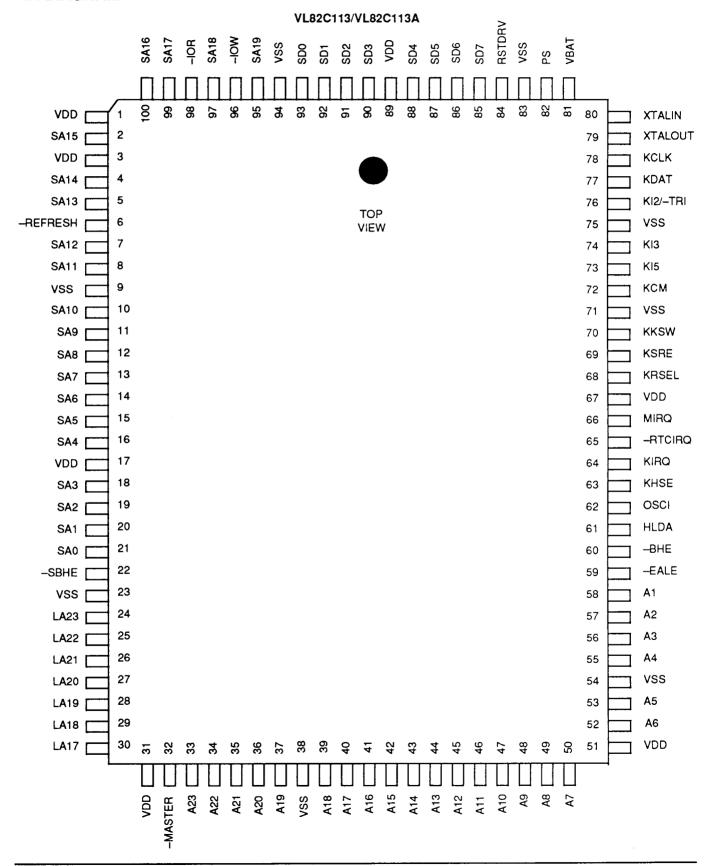
### ORDER INFORMATION

Part Number	Package
VL82C113-FC	Metric Quad Flat Pack
VL82C113A-FC	Metric Quad Flat Pack

Note: Operating temperature range is 0°C to +70°C.



### **PIN DIAGRAM**





# VL82C113/VL82C113A

### **SIGNAL DESCRIPTIONS**

Signal Name	Pin Number	Signal Type	Signal Description
CPU INTERFA	CE SIGNALS		
HLDA	61	I-TTL	Hold Acknowledge - This is the hold acknowledge pin directly from the CPU. It is used to control direction on address and to enable the -DACK decoder.
A23-A1	33-37, 39-50, 52, 53, 55-58	IO-TTL (8 mA)	Address bus bits 23 through 1 - When HLDA is high, -MASTER is low and -REFRESH is high these signals are outputs. They are inputs at all other times.
-BHE	60	IO-TTL (8 mA)	Byte High Enable - This pin is an output during Master Mode non-refresh cycles and it tracks the -SBHE input. It is an input at all other times.
ISA BUS SIG	NALS		
RSTDRV	84	I-TTL	System Reset - This active high input is a system reset generated from the POWERGOOD input.
-IOR	98	I-TTL	I/O Read command.
-IOW	96	I-TTL	I/O Write command.
-MASTER	32	I-TTL	Master - This active low input is used by an external device to disable the internal DMA controllers and get access to the system bus. When asserted, it indicates that an external Bus Master has control of the bus.
-REFRESH	6	I-TTL	Refresh - This active low I/O signal is pulled low whenever a refresh cycle is initiated.
LA23-LA17	24-30	IO-TTL (24 mA)	Latchable Address bus bits 23 through 17 - This bus is an input when HLDA is high, -REFRESH is high and -MASTER is low. It is an output bus driven by the values from the A bus when HLDA is low and -REFRESH is high. It is three-stated when HLDA is high and -REFRESH is low. The LA bus is latched internally with the -EALE input.
SA19-SA9	95, 97, 99, 100, 2, 4, 5, 7, 8, 10, 11	IO-TTL (24 mA)	System Address bus bits 19 through 9 - This bus is an input when HLDA is high, -REFRESH is high and -MASTER is low. It is an output bus driven by the values from the A bus when HLDA is low and -REFRESH is high. It is three-stated when HLDA is high and -REFRESH is low. The SA19-SA9 bus is registered internally with the -EALE input.
SA8-SA1	12-16, 18-20	IO-TTL (24 mA)	System Address bus bits 8 through 1 - This bus is an input when HLDA is high, -REFRESH is high and -MASTER is low. It is an output bus driven by the values from the A bus at all other times. The SA8-SA1 bus is registered internally with the -EALE input. In the VL82C113A only, this bus is an output driven by the value of the internal refresh counter, rather than by the values on the A bus, when -REFRESH is low.
SA0	21	I-TTL	System Address bus least significant bit (LSB) - This is an input at all times and is used in the address decode of internal peripheral registers/ports.
-SBHE	22	IO-TTL (24 mA)	System Byte High Enable - This pin is controlled the same way as the SA busSBHE is latched internally with the -EALE input.
OSCI	62	I-TTL	Oscillator Input - The input for the 14.318 MHz oscillator.



# VL82C113/VL82C113A

### SIGNAL DESCRIPTIONS (Cont.)

Signal Name	Pin Number	Signal Type	Signal Description	on		
KEYBOARD	CONTROLLER SIG	SNALS				
			Keyboard Controller Mode			
				T Mode TRL1 = 1	PS/2   KBDCTI	
KCLK	78	PC/AT Mode IO-TTL (12 mA) PS/2 Mode IO-TODS (12 m/	T0/-P26 A)	Kbd Clock	T0/-P26	Kbd Clock
KDAT	77	PC/AT Mode IO-TTL (12 mA) PS/2 Mode IO-TODS (12 m/	T1/P27 A)	Kbd Data	P10/-P27	Kbd Data
KCM	72	I-TPU	P16	Color Input	P16	Input
KKSW	70	I-TPU	P17	Key Switch	P17	Input
KHSE	63	IO-TODS (12 mA)	P22	High Speed	P11/-P22	Mouse Data
KSRE	69	IO-TODS (12 mA)	P23	Shadow RAM	T1/-P23	Mouse Clock
KIRQ	64	IO-TPU (4 mA)	P24 Kbd Int Req P24 Kbd Int Req This pin is sampled on the high-to-low transition of RSTDRV. If KII low, the keyboard function within the VL82C113/VL82C113A is dis KIRQ is high, the keyboard is enabled. This pin is internally pulled VDD.			n of RSTDRV. If KIRQ is 3/VL82C113A is disabled. If
MIRQ	66	O (4 mA)	P25	General Purpose Output	P25	Mouse Int Req
KRSEL	68	I-TTL	P14	RAM Slct	P14	Input
KI2/-TRI	76	I-TPU	low, all out	Input sampled on the high-t puts will be three-state ormally. This pin is int	ed. If KI2/–TRI	
KI3	74	IO-TPU (4 mA)	P13 MISC0	Input Output	P13 MISC0	Input Output
KI5	73	IO-TPU (4 mA)	P15 MISC1	Input Output	P15 MISC1	Input Output
SD DATA BU SD7-SD0	S SIGNALS 85-88, 90-93	IO-TTL (24 mA)				nnects directly to the slots. f local and system devices.
PERIPHERAL XTALIN	L INTERFACE SIGI 80	NALS I-CMOS		al oscillator input for re nal crystal or stand-alc		rystal. It requires a 32.768
XTALOUT	79	0		al oscillator input for re connect" when an ex		rystal. See XTALIN. This r is used.
PS	82	I-TST	RAM and failed, and	Time (VRT) bit. This b	oit is used to inc ne real-time clo	eset the status of the Valid dicate that the power has ck may not be valid. This



# VL82C113/VL82C113A

### SIGNAL DESCRIPTION (Cont.)

Signal Name	Pin Number	Signal Type	Signal Description	
VBAT	81	I-TTL	Connected to the real-time clock's hold up battery between 2.4 and 5 volts.	
-RTCIRQ	65	IO-TODP (12 mA)	Real-Time Clock Interrupt Request output (active low) - This pin is an in when RSTDRV is high. It is sampled on the high-to-low transition of RSTDRV. If -RTCIRQ is low, the real-time clock's function within the VL82C113/VL82C113A is disabled. If -RTCIRQ is high, the real-time clock is enabled. Open drain output.	
ADDRESS BUS	S CONTROL SIGN	IAL		
-EALE	59	I-TTL	Early Address Latch Enable - An active low pulse that is generated at the beginning of any bus cycle initiated from the CPU which is not directed at the on-board DRAM.	
POWER AND	GROUND PINS			
VDD	1, 3, 17, 31, 51, 67, 89	PWR	Power Connection, nominally +5 volts.	
VSS	9, 23, 38, 54, 71, 75, 83, 94	GND	Ground Connection, 0 volts.	

### SIGNAL LEGEND

Signal Code	Signal Type
I-CMOS	CMOS level input
I-TTL	TTL level input
I-TPU	TTL level input with 30k ohm pull-up resistor
I-TST	TTL level Schmitt-trigger input
IO-TTL	TTL level input/output
IO-TOD	TTL level input/output open drain
IO-TODNP	TTL level input/output open drain with 3k ohm NMOS pull-up
IO-TODPU	TTL level input/output open drain with 30k ohm pull-up resistor
IO-TODS	TTL level with open drain output/Schmitt-trigger input
Ю-ТРИ	TTL level input/output with 30k ohm pull-up resistor
0	CMOS and TTL level compatible output
GND	Ground
PWR	Power

# GENERAL DESCRIPTION & PROGRAMMER'S MODEL

The VL82C113/VL82C113A SCAMP Combination I/O chip combines a keyboard controller and real-time clock (RTC) with the address registers/latches buffers which are normally required in SCAMP-based systems. While the VL82C113/VL82C113A has been optimized for use with the VL82C310/VL82C311/VL82C311L SCAMP Controllers, its uses are not restricted to this device combination.

The keyboard controller and real-time clock are enabled/disabled through a combination of hardware and software accessible mechanisms. Software accessible registers are programmed through a series of indexing registers. In this scheme, one register (Index Register) is loaded with an 8-bit value which represents the address of the control/data register located within the VL82C113/VL82C113A which is to be read or written. The second register (Data Register) represents the datapath to the register pointed to by the Index Register. One pair of indexed registers are used with the VL82C113/ VL82C113A and are extensions of the registers used by the VL82C310/ VL82C311/VL82C311L SCAMP Controllers. These index/data registers are located at the same location within the VL82C310/VL82C311/VL82C311L SCAMP Controller as they are in the VL82C113/VL82C113A. The INDEX2 Register is write-only. DATA2 can be read as well as written. Table 1 details the ISA I/O address for the Index Registers as well as the default addresses for the real-time clock and keyboard controller.

Default values for these control registers have been selected so as to eliminate the need to change their values in typical system configurations when the VL82C113/VL82C113A is configured for Chip Select Mode of operation.

Table 2 shows the the INDEX2 addresses.

Table 3 details the Control, Status and Configuration Registers for the VL82C113/VL82C113A.

### TABLE 1. ISA I/O ADDRESS MAP

I/O Address	Register Name	Description	
0060 Hex	KBDAT	Keyboard Controller Input/Output Buffer	
0064 Hex	KBDCTL	Keyboard Controller Status/Command Register	
0070 Hex	RTCADD	Real-Time Clock Address Register	
0071 Hex	RTCDAT	Real-Time Clock Data Registers	
00EC Hex	INDEX2	Configuration INDEX2 Register	
00ED Hex	DATA2	Configuration DATA2 Register	

### **TABLE 2. INDEX2 ADDRESSES**

(INDEX2 loc = 00ECh, DATA2 loc = 00EDh)

Index Address	Register Name	Description	Read/ Write
1B Hex	RTCLSB	RTC Register Address Register - Low Byte	R/W
1C Hex	RTCMSB	RTC Register Address Register - High Byte	R/W
1D Hex	KBDCTRL	Keyboard Controller Control Port	R/W
1F Hex	REVID	ID/Revision Register	R-O

# RTC ADDRESS MAPPING REGISTER - LOW ADDRESS BYTE (RTCLSB)

Index Register: ECh Index Address: 1Bh Data Register: EDh

Default: 71h

Bit 0 RENA - RTC Enable: If set, when SA15-SA1 match the 15-bit compare value in RTCLSB and RTCMSB, an access to the RTC is generated. If cleared, all accesses to the RTC are disabled. Power-on reset default = 1.

Bits 1-7 Lower Seven bits of RTC
Mapping Address: Combined
with RTCMSB, this determines
the address at which the RTC
is accessed.

# RTC ADDRESS MAPPING REGISTER - HIGH ADDRESS BYTE (RTCMSB)

Index Register: ECh Index Address: 1Ch Data Register: EDh Default: 00h

Bits 0-7 Upper Byte of RTC Mapping Address: Combined with RTCLSB, this determines the address at which the RTC is accessed.

# MISCELLANEOUS CONTROL REGISTER (KBDCTRL)

Index Register: ECh Index Address: 1Dh Data Register: EDh

Bit 0 Reserved: This bit must be written as 1. Power-on reset

default = 1.

Bit 1 MODE - AT/PS2 Mode Select:
If set, the keyboard operates in
the AT compatibility mode. If
cleared, the keyboard operates in the PS/2 keyboard and
mouse mode. Power-on reset
default = 1.

# TABLE 3. CONTROL, STATUS AND CONFIGURATION REGISTERS BIT DEFINITIONS

Register Name	D7	D6	D5	D4	D3	D2	D1	DO
RTCLSB	A7	A6	A5	A4	А3	<b>A</b> 2	A1	RENA
RTCMSB	A15	A14	A13	A12	A11	A10	A9	<b>A</b> 8
KBDCTRL	RES	RES	INOROUT	MISC1	MISC0	PRV	MODE	RES
REVID	1	1	0	0	0	0	0	0

Bit 2 PRV - Private Controls Enable:
If set, this bit prevents the
KHSE, KSRE, and MIRQ pins
from changing current state. If
cleared, normal operation of
these pins result. Power-on
reset default = 0.

Bit 3 MISCO - KI3 Output: If the INOROUT bit is set, then this bit controls the KI3 output pin directly. If the INOROUT bit is cleared, then this bit's state has no effect. This bit is typically used for Turbo Mode control.

Bit 4 MISC1 - KI5 Output: If the INOROUT bit is set, then this bit controls the KI5 output pin directly. If the INOROUT bit is cleared, then this bit's state has no effect

Bit 5 INOROUT - If this bit is set to 1, then KI3 and KI5 will be outputs. If set to 0, then KI3 and KI5 will be inputs, read via Port 1 of the keyboard controller. Power-on reset default = 0

Bit 6 Reserved: This bit is reserved for possible future use. It must be written as a 1.

Bit 7 Reserved: This bit is reserved for possible future use. It must be written as a 1.

# REVISION/CHIP ID REGISTER (REVID)

Index Register: ECh Index Address: 1Fh Data Register: EDh

Bits 0-7 REVID - Revision/ID: Returns value based on the version of the VL82C113. The value for the VL82C113 is C0h.



### VL82C113/VL82C113A

### ADDRESS BUFFERING AND **AUXILIARY LOGIC**

The address buffering and logic provide buffered addresses to and from the slot bus to the CPU. Depending on machine state, the SA and LA slot address lines can either be directly driven, driven from clocked data from the CPU A address lines, three-stated,

or become inputs to drive the address back toward the CPU. These states are given in Table 6 as a function of the HLDA, -MASTER, and -REFRESH input lines.

#### **Refresh Counter**

In the VL82C113A, a counter is provided to drive the refresh address on SA8-SA1 when -REFRESH is low. The refresh address does not have to be provided on the local CPU A bus, thus allowing decoupled refresh operation when used with the VL82C486. The counter increments on the rising edge of -REFRESH and is cleared during reset.

### TABLE 4. ADDRESS LINE DECODE

HLDA	-MASTER	-REFRESH	Cycle Type	SA1- SA8	SA9-SA16, -SBHE	SA17- SA19	LA17- LA23	CPU A Bus
0	0	0	Illegal					
0	0	1	lilegal					
0	1	0	Illegal					
0	1	1	CPU	Clocked	Clocked	Clocked	Latched	Input
1	0	0	Master Refresh	Direct/ Counter	Three-state	Three- state	Three- state	Input
1	0	1	Master	Input	Input	Three- state	Input	Output Direct
1	1	0	Normal Refresh	Direct/ Counter	Three-state	Direct	Direct	Input
1	1	1	DMA	Direct	Direct	Direct	Direct	Input

Clocked:

The value of the CPU A address line is clocked into a flip-flop on the rising edge of the -EALE and

output on the SA lines.

Latched:

The value of the CPU A address line is latched when -EALE is high.

Direct:

The value of the CPU A address line is buffered and output on the SA/LA lines.

Output Direct: The value of the SA/LA lines are buffered and output to the CPU.

Three-state:

The SA lines are floating.

Counter:

In the VL82C113A only, the contents of the internal refresh counter are driven onto SA8-SA1 when -REFRESH is low. The refresh counter is not in the VL82C113, thus A8-A1 are directly buffered

and output on SA8-SA1 during refresh.



### VL82C113/VL82C113A

#### **KEYBOARD CONTROLLER**

The keyboard controller is accessed via internally decoded port 060h (read/write data) and port 064h (read status/write command).

PC/AT or PS/2 compatibility is controlled via bit 1 in the KBDCTRL Register.

# KEYBOARD CONTROLLER FUNCTIONAL DESCRIPTION

The VL82C113/VL82C113A keyboard controller's microcontroller unit (MCU) offers a subset of the instruction set of the 8042, with 8042-like instructions. Enhancements have been made to conditional jumps (jumps may be made between pages). The on-chip ROM is loaded with the code that is required to support the PC/AT and PS/2 command sets and 128 bytes of conversion code. A small amount of scratch-pad RAM is provided as an extension of the MCU register set for the purpose of keyboard to host interfacing.

Keyboard serial I/O is handled with hardware implementations of the receiver and transmitter. Both functions depend on an 8-bit timer for time-out detection. Enhanced status reporting is provided in hardware to simpilify error handling in software. This logic is duplicated for the mouse interface.

User RAM support is provided. The program writes the 5-bit address (32-byte range) to a register, and then reads or writes the data through accesses to another register, port 60h DBB.

Parallel ports 1 and 2 are provided, but are restricted to inputs only for P1 and outputs only for P2. In the VL82C113/ VL82C113A, the P10 and P11 input pins are shared with P27 and P22 outputs, and the P20 and P21 outputs are eliminated.

Support for port 60h DBB (reads and writes) and the Status Register (reads and writes) is provided in hardware for interface to the PC host.

Common PC/AT uses for the parallel I/O bits are shown below.

- P16 Color/monochrome input
- P17 Key switch input
- P22 Speed select output

# KEYBOARD CONTROLLER INTERFACE TO PC/AT

The interface to the PC/AT consists of one register pair (60h/64h) for the keyboard and mouse. Access to the registers is determined by the state of A2 and the chip select. For host control signals involved, the Command, Status and Data Registers are accessed as shown in Table 5.

Port 60h DBB read operations output the contents of the output buffer to D7-D0 (host bidirectional, three-state data bus), and clears the status of the Output Buffer Full (OBF/Status Register bit 0) bit.

Status read operations output the contents of the Status Register to D7-D0. No status is changed as a result of the read operation.

Port 60h DBB write operations cause the input buffer DBB to be changed. The state of the C/D bit is cleared (Status Register bit 3, a 0 indicates data) and the Input Buffer Full (IBF/ Status Register, bit 1) bit is set (1). Command write operations are the same as DBB writes, except that the address is 64h. The C/D bit will be set (1) when a command has been written to address 64h.

# KEYBOARD CONTROLLER INTERFACE PROTOCOL

Data transmission between the controller and the keyboard or mouse consist of a synchronous bit stream over the data and clock lines. The bits are defined as follows:

Bit	Function
1	Start bit (always 0)
2	Data bit (LSB)
3-8	Data bits 1-6
9	Data bit 7 (MSB)
10	Parity bit (odd)
11	Stop bit (always 1)

# RECEIVE AND TRANSMIT OPERATIONS

The states that are implemented for receive and transmit operations are in shown in Figures 1 and 2.

TABLE 5. ACCESSING THE COMMAND, STATUS, AND DATA REGISTERS

-cs	–IOR	-IOW	- <b>A</b> 2	Register
0	0	1	0	Read - Data DBB Output Buffer
0	0	1	1	Read - Status
0	1	0	0	Write - Data DBB Input Buffer
0	1	0	1	Write - Command
1	Х	Х	Х	Not Valid

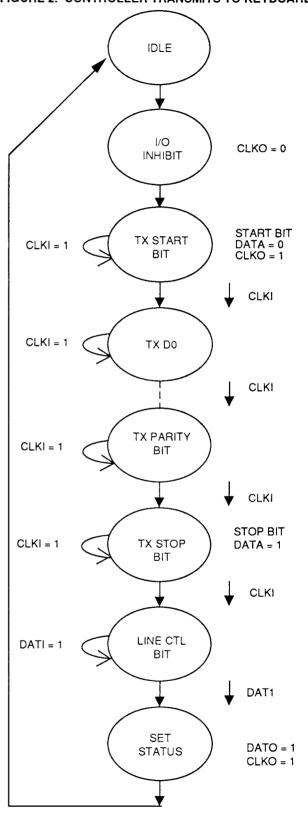
**Note:** –CS is an internal signal which is the decode of A0-A15 from the register pair 60h/64h.



#### FIGURE 1. CONTROLLER RECEIVES FROM KEYBOARD

## CLKI = 1 IDLE CLKI RX START BIT CLKI = 0 CLKI SAMPLE BIT 0 CLKI = 0 CLKI SAMPLE BIT 1 CLKI = 0 CLKI SAMPLE BIT 7 CLKI = 0 CLKI SAMPLE PARITY BIT CLKI = 0 CLKI SAMPLE **STOP** BIT INHIBIT CLOCK **GENERATE** INTERRUPT PC/AT MODE BIT 5 = 1 CLKO = 0 **RD PORT**

#### FIGURE 2. CONTROLLER TRANSMITS TO KEYBOARD



### VL82C113/VL82C113A

#### PROGRAMMER INTERFACE

The programmer interface to the keyboard controller is quite simple. It consists of the following four registers:

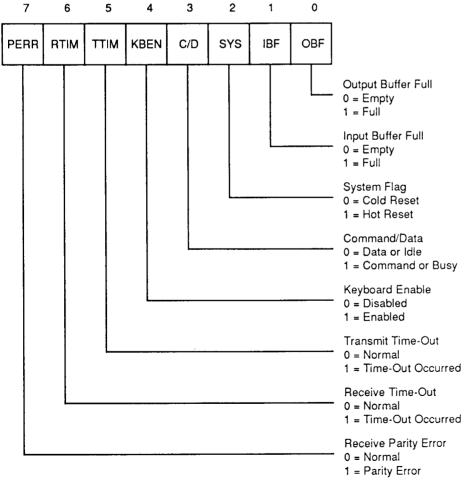
Register	R/W	I/O
Status	R	64h
Command	W	64h
Output Buffer	R	60h
Input Buffer	W	60h

The behavior of these registers differs according to the mode of operation (PC/AT or PS/2). There exists only one Status Register with different bit definitions for PC/AT Mode and PS/2 Mode. The bit definitions for the Status Register in each mode are listed in Tables 6 and 7.

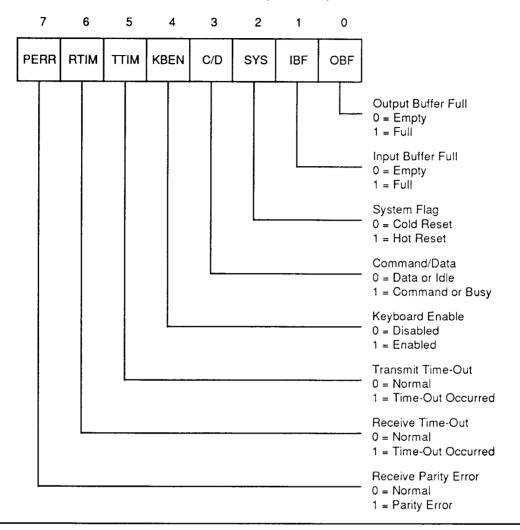
#### PC/AT Status Register

- Bit 0 OBF Output Buffer Full: This flag is automatically set when the microcontroller loads DBBOUT. It is cleared on a read to port 60h.
- Bit 1 IBF Input Buffer Full: This flag is set on a write to port 60h or 64h. It is cleared when the microcontroller reads the DBBIN contents into the accumulator.
- Bit 2 SYS System Flag: When this bit is set (1), it indicates that the CPU has changed from Virtual to Real Mode.
- Bit 3 C/D Command/Data: When set (1), this bit indicates that a command has been placed into the input data buffer of the controller. A 0 indicates data. The controller uses this bit to determine if the byte written is a command to be executed. This bit is updated when the next byte is written to the input data buffer.
- Bit 4 KBEN Keyboard Enable:
  When set (1), this bit indicates
  that the keyboard is currently
  enabled. When reset, it indicates that the keyboard is
  inhibited.
- Bit 5 TTIM Transmit Time-Out:
  When set (1), it indicates that a transmission to the keyboard was not completed before the controller's internal timer timedout.
- Bit 6 RTIM Receive Time-Out:
  When set (1), it indicates that a
  transmission from the keyboard
  was not completed before the
  controller's internal timer timed-
- Bit 7 PERR Parity Error: When set (1), it indicates that a parity error (even parity = error) occurred during the last transmission (received scan code) from the keyboard. When a parity error is detected, the output buffer is loaded with FFh, the OBF status bit is set, and the KIRQ pin is set (1 if the EKI bit/Mode Register bit 0 is set(1)).

### TABLE 6. PC/AT STATUS REGISTER (Read-only, Port 64h)



### TABLE 7. PS/2 STATUS REGISTER (Read-only, Port 64h)



#### PS/2 Status Register

- Bit 0 OBF Output Buffer Full: This flag is automatically set when the microcontroller loads DBBOUT. It is cleared on a read to port 60h.
- Bit 1 IBF Input Buffer Full: This flag is set on a write to port 60h or 64h. It is cleared when the microcontroller reads the DBBIN contents into the accumulator.
- Bit 2 SYS System Flag: When set (1), it indicates that the CPU has changed from Virtual to Real Mode.
- Bit 3 C/D Command/Data: When set (1), it indicates that a command has been placed into the input data buffer of the controller. A 0 indicates data.

The controller uses this bit to determine if the byte written is a command to be executed. This bit is updated when the next byte is written to the input data buffer.

- Bit 4 KBEN Keyboard Enable:
  When set (1), it indicates that
  the keyboard is currently
  enabled. When reset, it indicates that the keyboard is
  inhibited.
- Bit 5 ODS Output Buffer Data Source: When set (1), it indicates that the data in the output buffer is mouse data. When reset, it indicates the data is from the keyboard.
- Bit 6 GTO General Time-Out Error: When set (1), it indicates that a

transmission was started and that it did not complete within the normal time taken (approximately 11 KCLK cycles). If the transmission originated from the controller, a FEh is placed in the output buffer. If the transmission originated from the keyboard, a FFh is placed in the output buffer.

Bit 7 PERR - Parity Error: When set (1), it indicates that a parity error (even parity = error) occurred during the last transmission from the keyboard. When a parity error is detected, the output buffer is loaded with FFH, the OBF status bit is set, and the KIRQ pin is set (1 if the EKI bit/ Mode Register bit 0 is set (1)).

## VL82C113/VL82C113A

# KEYBOARD CONTROLLER COMMAND SET

This command supports two modes of operation and a set of extensions to the AT command set for the PS/2. In both modes, the command is implemented by writing the command byte to 64h. Any susequent data is read from 60h (see description for command 20 in Table 7) or written to 60h (see description of command 60, also in Table 7). The commands for each mode are shown in Tables 8 and 9.

#### **Command Descriptions**

The keyboard controller will support the following command set, which is described as the hex command code, followed by a description:

Read keyboard controller's Mode Register (PC/AT and PS/2). The keyboard controller sends its current mode byte to the output buffer (accessed by a read of port 60h).

60 Write keyboard controller's Mode Register (PC/AT and PS/2). The next byte of data written to the keyboard data port (60h) is placed in the controller's Mode Register.

The bit definitions of the Mode Register for each mode (PC/AT or PS/2) are described in Tables 10 and 11.

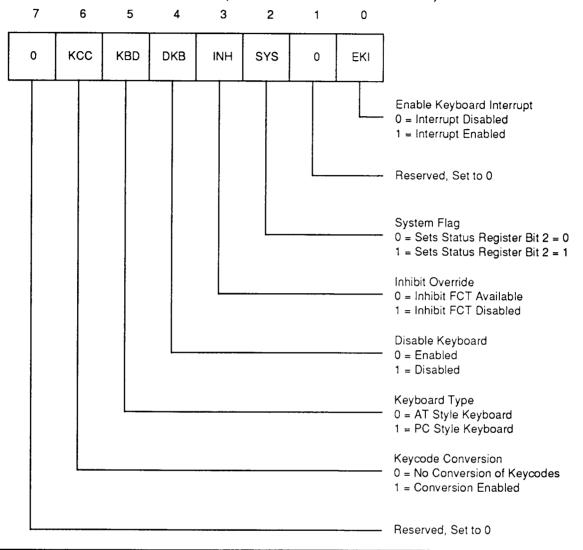
### TABLE 8. PC/AT & PS/2 COMMANDS

TABLE 8. PC/AT & PS/2 COMMINIANDS	
Command	Description
20	Read Mode Register
60	Write Mode Register
21-3F	Read Keyboard Controller RAM (Byte 1-31)
61-7F	Write Keyboard Controller RAM (Byte 1-31)
AA	Self Test
AB	Keyboard Interface Test
AC	Diagnostic Dump
AD	Disable Keyboard
AE	Enable Keyboard
CO	Read Input Port (P10-P17)
D0	Read Output Port (P20-P27)
D1	Write Output Port (P20-P27)
E0	Read Test Inputs (T0, T1)
F0-FF	Pulse Output Port (P20-P27)

### TABLE 9. ADDED PS/2 COMMANDS

Description
Test Password
Load Password
Enable Password
Disable Mouse
Enable Mouse
Mouse Interface Test
Poll Input Port Low (P10-P13 = S4-S7)
Poll Input Port High (P14-P17 = S4-S7)
Write Keyboard Output Buffer
Write Mouse Output Buffer
Write to Mouse

### TABLE 10. PC/AT MODE REGISTER (R/W - Command 20h/60h to Port 60h)



#### PC/AT Mode Register

Bit 0 EKI - Enable Keyboard Interrupt:
When set (1), it allows the controller to generate a keyboard interrupt whenever data (keyboard or controller) is written into the output buffer.

Bit 1 Reserved: This bit should be written as 0.

Bit 2 SYS - System Flag: When set (1), it writes the system flag bit 2 of the Status Register to 1. This

bit is used to indicate a switch from Virtual to Real Mode when set.

Bit 3 INH - Inhibit Override: When set (1), it disables the keyboard inhibit function (P17 switch).

Bit 4 DKB - Disable Keyboard: When set (1), it disables the keyboard by holding the KCLK line high.

Bit 5 KBD - Keyboard Type: When set (1), it allows for compatibility

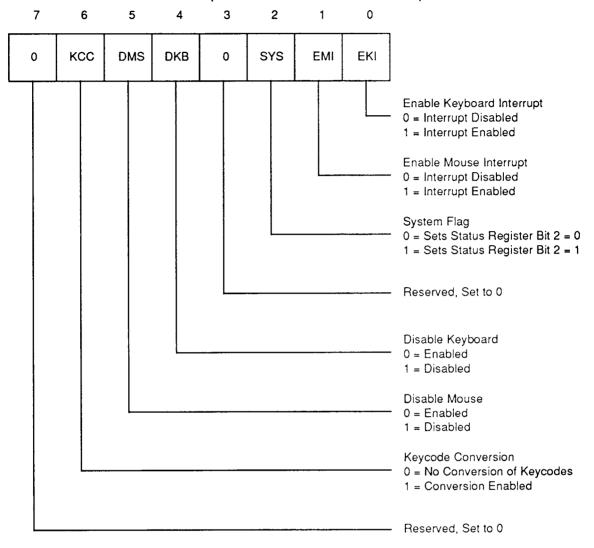
with PC-style keyboards. In this mode, parity is not checked and scan codes are not converted.

Bit 6 KCC - Keycode Conversion: When set (1), it causes the controller to convert the scan codes to PC format. When reset, the codes are passed along unconverted.

Bit 7 Reserved: This bit should be written as 0.

## VL82C113/VL82C113A

### TABLE 11. PS/2 MODE REGISTER (R/W - Command 20h/60h to Port 60h)



### PS/2 Mode Register

- Bit 0 EKI Enable Keyboard Interrupt:
  When set (1), it allows the controller to generate a keyboard interrupt whenever data (keyboard or command) is written into the output buffer.
- Bit 1 EMI Enable Mouse Interrupt: When set (1), it allows the controller to generate a mouse interrupt when mouse data is available in the output buffer.
- Bit 2 SYS System Flag: When set (1), it writes the system flag bit 2 of the Status Register to 1. This bit is used to indicate a switch from Virtual to Real Mode when set.
- Bit 3 Reserved: This bit should be written as 0.
- Bit 4 DKB Disable Keyboard: When set (1), it disables the keyboard by holding the KCLK output high.
- Bit 5 DMS Disable Mouse: When set (1), it disables the mouse by holding the KSRE output high in PS/2 Mode.
- Bit 6 KCC Keycode Conversion:
  When set (1), it causes the
  controller to convert the scan
  codes to PC format. When
  reset, the codes are passed
  along unconverted.
- Bit 7 Reserved: This bit should be written as 0.

## VL82C113/VL82C113A

#### Command Descriptions (Cont.)

- 21-3F Read Keyboard Controller RAM (PC/AT and PS/2): Bits D4-D0 specify the address.
- 61-7F Write the Keyboard Controller RAM (PC/AT and PS/2): This command writes to the keyboard controller RAM with the address specified in bits D4-D0.
- A4 Test Password Installed (PS/2 only): This command checks if there is currently a password installed in the controller. The test result is placed in the output buffer (the OBF bit is set) and KIRQ is asserted (if the EKI bit is set). Test result FAh means that the password is installed, and F1h means that the password is not installed.
- A5 Load Password (PS/2 only):
  This command initiates the password load procedure.
  Following this command, the controller will take data from the input buffer port (60h) until a 00h is detected or a full 8-byte password, including a delimiter (00h), is loaded into the password latches.
  - Note: This means that during password validation, the password can be a maximum of seven bytes plus a delimiter such as 00h.
- A6 Enable Password (PS/2 only):
  This command enables the
  security feature. The command
  is valid only when a password
  pattern is written into the
  controller (see A5 command).
  All keyboard or mouse characters will be discarded until the
  correct security sequence is
  completed. System commands
  are still accepted.
- A7 Disable Mouse (PS/2 only):
  This command sets bit 5 of the
  Mode Register which disables
  the mouse by driving the KSRE
  line (mouse clock) high.

- A8 Enable Mouse (PS/2 only): This command resets bit 5 of the Mode Register, thus enabling the mouse again.
- A9 Mouse Interface Test (PS/2 only): This command causes the controller to test the mouse clock and data lines. The results are placed in the output buffer (the OBF bit is set) and the KIRQ line is asserted (if the EKI bit is set). The results are as follows:

### Data Meaning

- 00 No Error
- 01 Mouse Clock Line Stuck Low
- 02 Mouse Clock Line Stuck High
- 03 Mouse Data Line Stuck Low
- 04 Mouse Data Line Stuck High
- AA Self Test (PC/AT and PS/2):
  This commands the controller to perform internal diagnostic tests.
  A 55h is placed in the output buffer if no errors were detected.
  The OBF bit is set and KIRQ is asserted (if the EKI bit is set).
- AB Keyboard Interface Test (PC/AT and PS/2): This command causes the controller to test the keyboard clock and data lines. The test result is placed in the output buffer (the OBF bit is set) and the KIRQ line is asserted (if the EKI bit is set). The results are as follows:

#### Data Meaning

- 00 No Error
- 01 Keyboard Clock Line Stuck Low
- 02 Keyboard Clock Line Stuck High
- 03 Keyboard Data Line Stuck Low
- 04 Keyboard Data Line Stuck High
- AC Diagnostic Dump (PC/AT only, reserved on PS/2): Sends 16 bytes of the controller's RAM, the current state of the input port, and the current state of the output port to the system.
- AD Disable Keyboard (PC/AT and PS/2): This command sets bit 4 of the Mode Register to a 1. This disables the keyboard by driving the clock line (KCLK)

- low. Data will not be received. The keyboard will be enabled after the system sends data to be transmitted to the keyboard.
- AE Enable Keyboard (PC/AT and PS/2): This command resets bit 4 of the mode byte to a 0. This enables the keyboard again by allowing the keyboard clock to free-run.
- CO Read P1 Input Port (PC/AT and PS/2): This command reads the keyboard input port and places it in the output buffer. This command overwrites the data in the buffer.
- C1 Poll Input Port Low (PS/2 only):
  P1 bits 0-3 are written into
  Status Register bits 4-7. The
  bits are restored to their original
  status upon a write to port 64h.
- C2 Poll Input Port High (PS/2 only): P1 bits 4-7 are written into Status Register bits 4-7. The bits are restored to their original status upon a write to port 64h.
- D0 Read Output Port (PC/AT and PS/2): This command causes the controller to read the P2 output port and place the data in its output buffer. The definitions of the bits are as follows:

#### PC/AT Mode PS/2 Mode Bit Pin P20 1 P21 P22 Speed Sel 2 Mouse Data (ENMOD) 3 P23 Shadow Enable Mouse Clk 4 P24 Output Buffer **KIRQ** Full 5 P25 MIRQ 6 P26 -KCKOUT -KCKOUT P27 KDOUT -KDOUT



## VL82C113/VL82C113A

- D1 Write Output Port (PC/AT and PS/2): The next byte of data written to the keyboard data port (60h) will be written to the controller's output port. The definitions of the bits are as defined previously stated. In PC/AT Mode, P26 and P27 will not be altered. In PS/2 Mode, P22, P23, P26, and P27 cannot be altered.
- D2 Write Keyboard Output Buffer (PS/2 only): The next byte written to the data buffer (60h) is written by the output buffer (60h) as if initiated by the keyboard (the OBF bit is set (1) and KIRQ will be set if the EKI bit is set (1)).
- D3 Write Mouse Output Buffer (PS/2 only): The next byte written to the data buffer (60h) is written to the output buffer as if initiated by the mouse (the OBF bit is set (1), and MIRQ will be set if the EMI bit is set (1)).
- D4 Write to Mouse (PS/2 only): The next byte written to the data buffer (60h) is transmitted to the mouse.

Note: If data is written to the data buffer (60h) and the command preceding it did not expect data from the port (60h), the data will be transmitted to the keyboard.

E0 Read Test Inputs (PC/AT and PS/2): This command causes the controller to read the T0 and T1 input bits. The data is placed in the output buffer with the following meanings:

Bit PC/AT Mode PS/2 Mode
0 Keyboard Clk Keyboard Clk
1 Keyboard Data Mouse Clk
3-7 Read as 0s Read as 0s

F0-FF Pulse Output Port (PC/AT and PS/2): Bits 2 and 3 of the controller's output port may be pulsed low for approximately 6 μs. Bits 2 and 3 of the command specify which bit will be pulsed. A 0 indicates that the bit should be pulsed, a 1 indicates that the bit should not be modified. FF is treated as a special case (Pulse Null Port).

Note: In PS/2 Mode, bits P22 and P23 will not be pulsed.



### **REAL-TIME CLOCK DESCRIPTION**

The real-time clock (RTC) portion of the VL82C113/VL82C113A performs the following functions:

- · Time of day clock
- · Alarm function
- · 100 year calendar function
- Programmable periodic interrupt output
- · Programmable square wave output
- · 50 bytes of user RAM
- · User RAM preset feature

The RTC memory consists of ten RAM bytes which contain the time, calendar, and alarm data, four control and status bytes, and 50 general purpose RAM bytes. The address map of the real-time clock is shown as follows:

Addr	Function	Range
0	Seconds (time)	0-59
1	Seconds (alarm)	0-59
2	Minutes (time)	0-59
3	Minutes (alarm)	0-59
4	Hours (time)	0-11, 12
		Hr Mode
4	Hours (time)	0-23, 24
		Hr Mode
5	Hours (alarm)	0-23
6	Day of Week	1-7
7	Date of Month	1-31
8	Month	1-12
9	Year	0-99
10	RTC Register A	(R/W/)
11	RTC Register B	(R/W)
12	RTC Register C	(R-O)
13	RTC Register D	(R-O)
14-127	User RAM (standby)	

All 64 bytes are directly readable and writeable by the processor program except for the following:

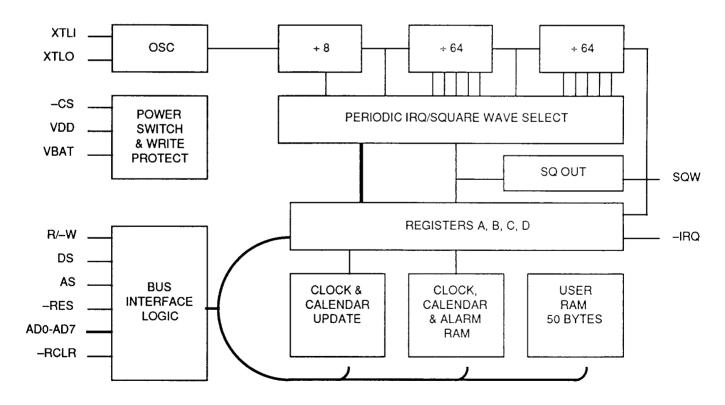
- 1) Registers C and D are read-only.
- 2) Bit 7 of Register A is read-only.
- 3) Bit 7 of the seconds byte is readonly.

The total address map is shown below:

Addr	Function
0-13	Time portion
14-63	Scratch-pad RAM portion
64-127	Additional scratch-pad RAM

The processor program obtains time and calendar information by reading the appropriate locations. The program may initialize the time, calendar, and alarm by writing to these RAM locations. The contents of the ten time, calendar, and alarm bytes may be either binary or binary-coded decimal (BCD).

#### FIGURE 3. REAL-TIME CLOCK BLOCK DIAGRAM





# TIME OF DAY REGISTER DESCRIPTIONS

The contents of the Time of Day Registers can be either in binary or BCD format. They are relatively straight-forward, but are detailed here for completeness. The address map of these registers is shown below:

Addr	<b>Function</b>	Range
0	Seconds (time)	0-59
1	Seconds (alarm)	0-59
2	Minutes (time)	0-59
3	Minutes (alarm)	0-59
4	Hours (time)	0-11, 12
		Hr Mode
4	Hours (time)	0-23, 24
		Hr Mode
5	Hours (alarm)	0-23
6	Day of Week	1-7
7	Date of Month	1-31
8	Month	1-12
9	Year	0-99

Address 0 - Seconds:

The range of this register is 0-59 in BCD Mode and 0-3Bh in Binary Mode.

Address 1 - Seconds Alarm: The range of this register is 0-59 in BCD Mode and 0-3Bh in Binary Mode.

Address 2 - Minutes:

The range of this register is 0-59 in BCD Mode and 0-3Bh in Binary Mode.

Address 3 - Minutes Alarm: The range of this register is 0-59 in BCD Mode and 0-3Bh in Binary Mode.

Address 4 - Hours:

The range of this register is:

Range	Mode	Time
1-12	BCD	AM
81-92	BCD	PM
01h-0Ch	Binary	AM
81h-8Ch	Binary	PM

Address 5 - Hours Alarm: The range of this register is:

Range	Mode	Time
1-12	BCD	AM
81-92	BCD	PM
01h-0Ch	Binary	AM
81h-8Ch	Binary	PM

Address 6 - Day of Week:

The range of this register is 1-7 in BCD Mode and 1-7h in Binary Mode.

Address	7 -	Date:
---------	-----	-------

The range of this register is 1-31 in BCD Mode and 1-1Fh in Binary Mode.

#### Address 8 - Month:

The range of this register is 1-12 in BCD Mode and 1-0Ch in Binary Mode.

#### Address 9 - Year:

The range of this register is 0-99 in BCD Mode and 0-63h in Binary Mode.

# RTC CONTROL REGISTER DESCRIPTIONS

The VL82C113/VL82C113A has four registers which are accessible to the processor program. The four registers are also fully accessible during the update cycle.

Addr	Function	Type
10	RTC Register A	R/W
11	RTC Register B	R/W
12	RTC Register C	R-O
13	RTC Register D	R-O
14-63	User RAM (Standby)	R/W

#### Register A Description

This register contains control bits for the selection of periodic interrupt, input divisor, and the update-in-progress (UIP) status bit. The bits in the register are defined as follows:

Bit	Description	Abbr
0	Rate Select Bit 0	RS0
1	Rate Select Bit 1	RS1
2	Rate Select Bit 2	RS2
3	Rate Select Bit 3	RS3
4	Divisor Bit 0	DV0
5	Divisor bit 1	DV1
6	Divisor bit 2	DV2
7	Update-in-Progress	UIP

Bits 0-3 RS0-RS3 - Rate Selection:
These bits select one of 15
taps on the 22-stage divider,
or disable the divider output.
The tap selected may be used
to generate a periodic interrupt. These four bits are read/
write bits which are not
affected by reset. The periodic
interrupt rate that results from
the selection of various tap
values is as follows:

RS Value	Periodic Inter	rupt Rate
0	None	
1	3.90625	ms
2	7.8125	ms
3	122.070	μs
4	244.141	μs
5	488.281	μs
6	976.562	μs
7	1.953125	ms
8	3.90625	ms
9	7.8125	ms
0Ah	15.625	ms
0Bh	31.25	ms
0Ch	62.5	ms
0Dh	125	ms
0Eh	250	ms
0Fh	500	ms

Bits 4-6 DV0-DV2 - Divisor: These divisor selection bits are fixed to provide for only a five-state divider chain, which would be used with a 32 kHz external crystal. Only bit 6 of this register can be changed allowing control of the reset for the divisor chain. When the divider reset is removed, the first update cycle begins one-half second later. These bits are not affected by power-on reset (external pin).

DV Value	Condition
2	Operation Mode
	divider running
6	Reset Mode,
	divider in reset
	state

Bit 7 UIP - Update-In-Progress: This bit is a status flag that may be monitored by the program. When UIP is a 1, the update cycle is in progress or will soon begin. When UIP is a 0, the update cycle is not in progress and will not be for at least 244 us. The time, calendar, and alarm information in RAM is fully available to the program when the UIP bit is 0. The UIP bit is a read-only bit, and is not affected by reset. Writing the SET bit in Register B to a 1 will inhibit any update cycle and then clear the UIP status bit.

### VL82C113/VL82C113A

#### Register B Description

Register B contains command bits to control various modes of operations and interrupt enables for the RTC. The bits in this register are defined as follows:

Bit	Description	Abbr
0	Daylight Savings Enable	DSE
1	24/12-Hour Mode	24/12
2	Data Mode (Binary or BCD)	DM
3	Reserved	

7 Set Command

Update-End Interrupt Enable UIE Alarm Interrupt Enable AIE Periodic Interrupt Enable PIF

SET

Bit 0 DSE - Daylight Savings Enable: A read/write bit which allows the program to enable two special updates (when DSE is 1). On the last Sunday in April, the time increments from 1:59:59 AM to 3:00:00 AM. On the last Sunday in October when the time first reaches 1:59:59 AM it changes to 1:00:00 AM. These special updates do not occur when the DSE bit is a 0. DSE is not changed by any internal operations or reset.

- Bit 1 24/12 - 24/12-Hour Mode: This control bit establishes the format of the hours bytes as either in 24-Hour Mode (1) or in 12-Hour Mode (0). This is a read/write bit, which is affected only by software.
- Bit 2 DM - Data Mode: This bit indicates whether time and calendar updates are to use binary or BCD formats. The DM bit is written by the processor program and may be read by the program, but is not modified by any internal functions or reset. A 1 in DM signifies binary data, while a 0 in specifies BCD data.
- Bit 3 Reserved: This bit is unused in this version of the RTC.
- Bit 4 UIE - Update-End Interrupt Enable: A read/write bit which enables the update-end flag (UF) bit in Register C to assert an -RTCIRQ. The RSTDRV pin being asserted or the SET

bit going high clears the UIE bit.

Bit 5 AIE - Alarm Interrupt Enable: This bit is a read/write bit which when set to a 1 permits the alarm flag (AF) bit in Register C to assert an -RTCIRQ. An alarm interrupt occurs for each second that the three time bytes equal the three alarm bytes (including a "don't care" alarm code of 11XXXXXXb). When the AIE bit is a 0, the AF bit does not initiate an -RTCIRQ signal. The RSTDRV pin clears AIE to 0. The internal functions do not affect the AIE bit.

Bit 6 PIE - Periodic Interrupt Enable: This bit is a read/write bit which allows the periodicinterrupt flag (PF) bit in Register C to cause the -RTCIRQ pin to be driven low. A program writes a 1 to the PIE bit in order to receive periodic interrupts at the rate specified by the RS3-RS0 bits in Register A. A 0 in PIE blocks -RTCIRQ from being initiated by a periodic interrupt, but the periodic flag (PF) bit is still set at the periodic rate. PIE is not modified by any internal functions, but is cleared to 0 by a reset.

Bit 7 SET - Set Command: When this bit is a 0, the update cycle functions normally by advancing the counts once-persecond. When written to a 1, any update cycle in progress is aborted and the program may initialize the time and calendar bytes without an update occurring in the midst of initializing. SET is a read/write bit which is not modified by reset or internal functions.

### Register C Description

Register C contains status information about interrupts and internal operation of the real-time clock. The bits in this register are defined as follows:

Abbr

Bit	Description
0	Reserved, Read as 0
1	Reserved, Read as 0

2 Reserved, Read as 0

3 Reserved, Read as 0 4 UF Update-Ended Flag

5 AF Alarm Interrupt Flag PF Periodic Interrupt Flag

6 7 -RTCIRQ Pending Flag **IRQF** 

Bits 0-3 Reserved: These bits are read as 0s and cannot be written.

UF - Update-Ended Interrupt Bit 4 Flag: The UF bit is set after each update cycle. When the UIE bit is a 1, the 1 in UF causes the IRQF bit to be a 1. asserting -RTCIRQ. UF is cleared by a Register C read or a reset.

Bit 5 AF - Alarm Interrupt Flag: A 1 indicates that the current time has matched the alarm time. A 1 also causes the -RTCIRQ pin to go low, and a 1 to appear in the IRQF bit, when the AIE bit also is a 1. A reset or a read of Register C clears AF.

Bit 6 PF - Periodic Interrupt Flag: This a read-only bit which is set to a 1 when a particular edge is detected on the selected tap of the divider chain. The RS3-RS0 bits establish the periodic rate. PF is set to a 1 independent of the state of the PIE bit. PF being a 1, initiates an -RTCIRQ signal and sets the IRQF bit when PIE is also a 1. The PF bit is cleared by a reset or a software read of Register C.

Bit 7 IRQF - Interrupt Request Flag: IRQF is set to a 1 when one or more of the following are true:

> PF = PIE = 1 AF = AIE = 1

UF = UIE = 1

The logic can be expressed in equation form as:

IRQF = PF • PIE + AF • AIE + UF • UIE

Any time the IRQF bit is a 1, the -RTCIRQ pin is asserted. All flag bits are cleared after Register C is read by the program or when the RSTDRV pin is asserted.

### VL82C113/VL82C113A

#### Register D Description

This register contains a bit that indicates the status of the on-chip standby RAM. The contents of the registers are described as the following:

Bit	Description	Abbr
0	Reserved, Read as 0	
1	Reserved, Read as 0	
2	Reserved, Read as 0	
3	Reserved, Read as 0	
4	Reserved, Read as 0	
5	Reserved, Read as 0	
6	Reserved, Read as 0	
7	Valid RAM Data & Time	VRT

Bits 0-6 Reserved: These bits are read as 0s and cannot be written.

Bit 7 VRT - Valid RAM Data and Time: This bit indicates the condition of the contents of the RAM, provided the powersense (PS) pin is satisfactorily connected. A 0 appears in the VRT bit when the PS pin is low. The processor program can set the VRT bit when the time and calendar are initialized to indicate that the RAM and time are valid. The VRT is a read-only bit which is not modified by the reset pin. The VRT bit can only be set by reading Register D.

## RTC CMOS STANDBY RAM DESCRIPTION

In addition to the 50 dedicated general purpose RAM bytes that are dedicated within the RTC, the VL82C113 provides an additional 64 bytes of battery-backed RAM for general purpose uses. They can be used by the system BIOS or user program, and are available during the RTC update cycle.

# **GENERAL OPERATION NOTES Set Operation**

Before initializing the internal registers, the SET bit in Register B should be set to a 1 to prevent time/calendar updates from occurring. The program initializes the ten locations in the selected format (binary or BCD), then indicates the format in the Data Mode (DM) bit of Register B. All ten time, calendar, and alarm bytes must use the same Data Mode, either binary or BCD. The SET bit may now be cleared to allow

updates. Once initialized, the real-time clock makes all updates in the selected Data Mode. The Data Mode cannot be changed without re-initializing the ten data bytes.

#### 24/12-Hour Modes

The 24/12 bit in Register B establishes whether the hour locations represent 0-11 or 0-23. The 24/12 bit cannot be changed without re-initializing the hour locations. When the 12-Hour Mode is selected, the high-order bit of the hours byte represents PM when it is set a 1.

#### **Update Operation**

The time, calendar, and alarm bytes are not always accessible by the processor program. Once-per-second the ten bytes are switched to the update logic to be advanced by one second and to check for an alarm condition. If any of the ten bytes are read at this time, the data outputs are undefined. The update lock-out time is 1948 µs for the 32.768 kHz time base. The update cycle section shows how to accommodate the update cycle in the processor program.

#### **Alarm Operation**

The three alarm bytes may be used in two ways. First, when the program inserts an alarm time in the appropriate hours, minutes, and seconds alarm locations, the alarm interrupt is initiated at the specified time each day if the alarm enable bit is high. The second usage is to insert a "don't care" state in one or more of three alarm bytes. The "don't care" code is any byte from 0C0h-0FFh. An alarm interrupt each hour is created with a "don't care" code in the hours alarm location. Similarly, an alarm is generated every minute with "don't care" codes in the hours and minutes alarm bytes. The "don't care" codes in all three alarm bytes create an interrupt every second.

#### Interrupts

The RTC plus RAM includes three separate fully automatic sources of interrupts to the processor. The alarm interrupt may be programmed to occur at rates from one-per-second to one-aday. The periodic interrupt may be selected for rates from one-half second to 30.517 µs. The update-ended

interrupt may be used to indicate to the program that an update cycle is completed.

The processor program selects which interrupts, if any, it wishes to receive. Three bits in Register B enable the three interrupts. Writing a 1 to an interrupt enable bit permits that interrupt to be initiated when the event occurs. A 0 in the interrupt-enable bit prohibits the -RTCIRQ pin from being asserted due to the interrupt cause.

If an interrupt flag is already set when the interrupt becomes enabled, the —RTCIRQ pin is immediately activated, though the interrupt initiating the event may have occurred much earlier. Thus, there are cases where the program should clear such earlier initiated interrupts before first enabling new interrupts.

When an interrupt event occurs, a flag bit is set to a 1 in Register C. Each of the three interrupt sources have separate flag bits in Register C, which are set independent of the state of the corresponding enable bits in Register B. The flag bit may be used with or without enabling the corresponding enable bits.

### **Divider Control**

The divider control bits are fixed for only 32.768 kHz operation. The divider chain may be held reset, which allows precision setting of the time. When the divider is changed from reset to an operating time base, the first update cycle is one-half second later. The divider control bits are also used to facilitate testing the VL82C113/VL82C113A.

Square Wave Output Selection This version of the VL82C113/ VL82C113A does not support the square wave output function.

#### **Periodic Interrupt Selection**

The periodic interrupt allows the -RTCIRQ pin to be triggered from once every 500 ms to once every 30.517  $\mu$ s. The periodic interrupt is separate from the alarm interrupt which may be output from once-per-second to once-per-day.

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### VL82C113/VL82C113A

#### **Update Cycle**

The VL82C113/VL82C113A executes an update cycle one-per-second, assuming one of the proper time bases is in place, the DV0-DV2 divider is not clear, and the SET bit in Register B is clear. The SET bit in the 1 state permits the program to initialize the time and calendar bytes by stopping an existing update and preventing a new one from occurring.

The primary function of the update cycle is to increment the seconds byte, check for overflow, increment the minutes byte when appropriate and so forth through to the year of the century byte. The update cycle also compares each alarm byte with the corresponding time byte and issues an alarm if a match or if a "don't care" code (11XXXXXX) is present in all three positions.

With a 32,768 kHz time base update cycle takes 1984 µs, during which, the time, calendar, and alarm bytes are not accessible by the processor program. The 146818 protects the program from reading transitional data. This protection is provided by switching the time, calendar, and alarm portion of the RAM off the microprocessor bus during the entire update cycle. If the processor reads these RAM locations before the update is complete, the output will be undefined. The update-in-progress (UIP) status bit is set during the interval.

A program which randomly accesses the time and date information finds data unavailable statistically once every 4032 attempts. Three methods of accommodating non-availability during update are usable by the program. In discussing the three methods it is assumed that at random points user programs are able to call a subroutine to obtain the time of day.

The first method of avoiding the update cycle uses the update-ended interrupt. If enabled, an interrupt occurs after every update cycle which indicates that over 999 ms are available to read valid time and date information. Before leaving the interrupt service routine, the IRQF bit in Register C should be cleared.

The second method uses the updatein-progress bit (UIP) in Register A to determine if the update cycle is in progress or not. The UIP bit will pulse once-per-second. Statistically, the UIP bit will indicate that time and date information is unavailable once every 2032 attempts. After the UIP bit goes high, the update cycle begins 244 µs later. Therefore, if a low is read on the UIP bit, the user has at least 244 us before the time/calendar data will be changed. If a 1 is read in the UIP bit, the time/calendar data may not be valid. The user should avoid interrupt service routines that would cause the time needed to read valid time/calendar data to exceed 244 us.

The third method uses a periodic interrupt to determine if an update cycle is in progress. The UIP bit in Register A is set high between the setting of the PF bit in Register C.

To properly setup the internal counters for daylight savings time operation, the user must set the time at least two seconds before the roll-over will occur. Likewise, the time must be set at least two seconds before the end of the 29th or 30th day of the month.

#### Power-Down Mode

The passive components that are critical for low-power operation are shown in Figure 4.

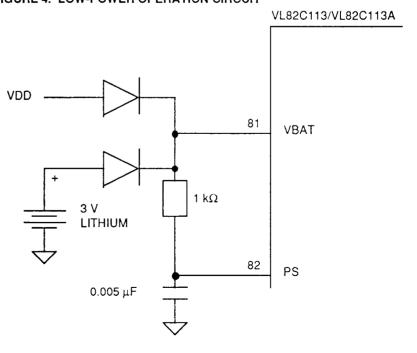
Figure 4 is an example only. A NiCad battery can be used also. The powersense signal is used to reset the state of of the valid RAM and time bit (VRT) and clear all internal RAM. This input must be asserted after power is applied to the RTC to set the state of the VRT bit properly. With a power consumption target specification of 5 µA, and a lithium battery with a capacity of 100 mA-Hr, time will be properly kept for approximately 2.25 years.

#### **BOARD TESTING FEATURES**

The VL82C113/VL82C113A is designed to make system board testing as easy as possible. When the -CE/-CS0/-TRI input is held low at POR (power-on reset, i.e., the falling edge of RSTDRV), it causes all pins on the VL82C113/ VL82C113A to go to a high impedance state. This can be used to electrically isolate the VL82C113/VL82C113A so that other components in the system may be tested.

Exit from the high impedance state is accomplished by a normal reset with RSTDRV.

### FIGURE 4. LOW-POWER OPERATION CIRCUIT



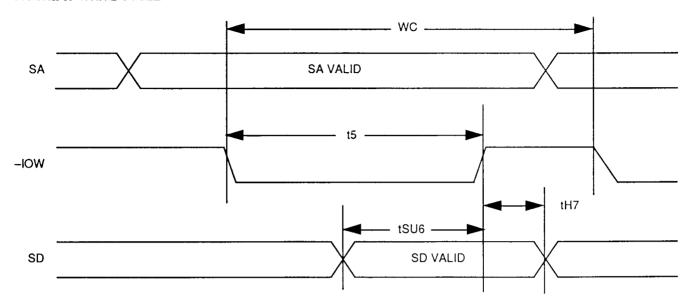
# VL82C113/VL82C113A

### AC CHARACTERISTICS: TA = 0°C to +70°C, VDD = 5 V ±5%, VSS = 0 V

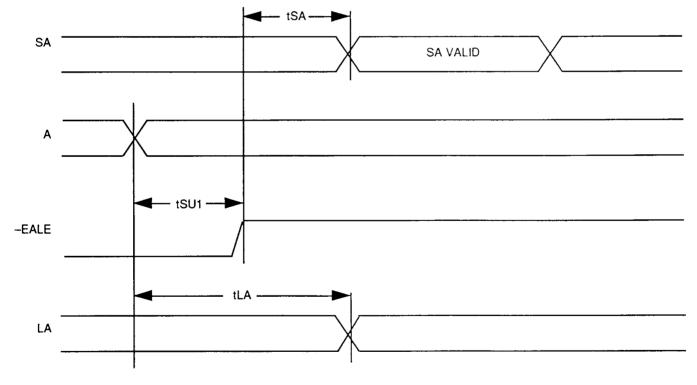
Symbol	Parameter	Min	Max	Unit	Conditions
I/O Read/\	Write Timing				
t5	Command Pulse Width	125		ns	
tSU6	Write Data Setup	60		ns	
tH7	Write Data Hold	20		ns	
tD8	Read Data Delay	0	130	ns	CL = 200 pF
tH9	Read Data Hold	5	60	ns	CL = 50 pF
wc	Write Cycle	280		ns	
RC	Read Cycle	280		ns	
tSU1	Address Valid to –EALE Rising	23		ns	
tSA	SA Valid from –EALE Rising		35	ns	CL = 200 pF
tLA	Address Valid to LA Valid		36	ns	CL = 200 pF
Master Mo	ode Timing				
tAM	A bus Valid from SA/LA Input (Master Mode)		15	ns	CL = 200 pF
Real-Time	Clock Timing				
tPSPW	Power-Sense Pulse Width	2		μs	
tPSD	Power-Sense Delay	2		μs	
tVRTD	VRT Bit Delay		2	μs	



### FIGURE 5. WRITE CYCLE

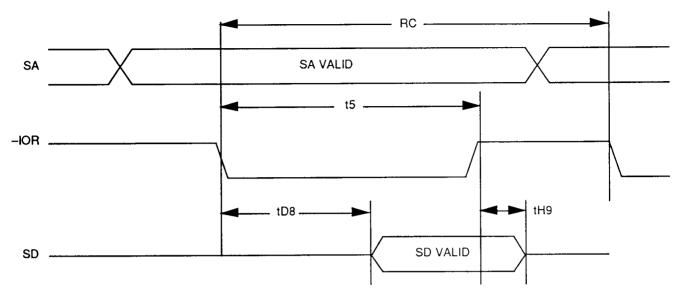


### FIGURE 5A. WRITE CYCLE

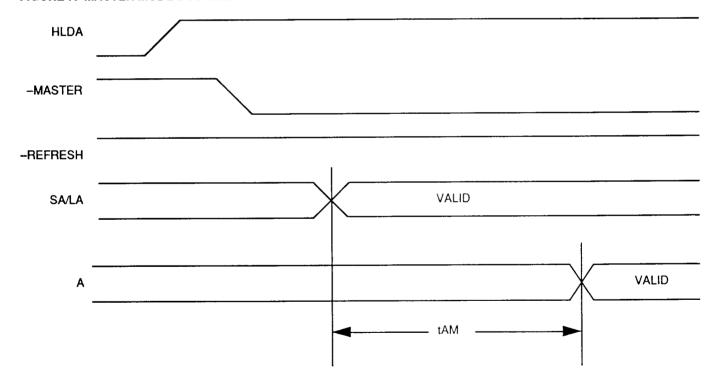




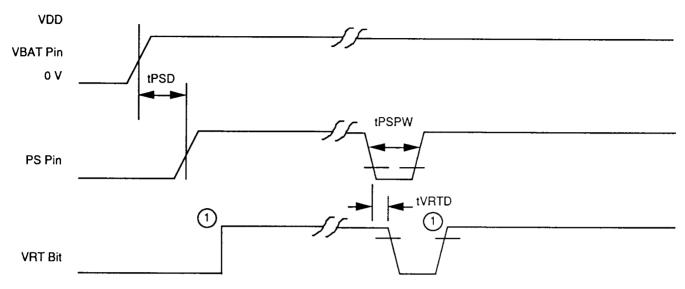
### FIGURE 6. READ CYCLE



### FIGURE 7. MASTER MODE BUS TIMING

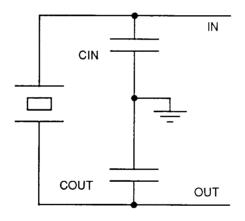


### FIGURE 8. REAL-TIME CLOCK TIMING



(1) The VRT bit is set a "1" by reading Register D. The VRT bit can only be cleared by pulling the PS pin low (see REGISTER D(\$0D)).

#### FIGURE 9. CRYSTAL OSCILLATOR CONFIGURATION



Notes: Frequency = 32.768 kHz CIN = COUT = 10-22 pF

CIN may be a trimmer for precision timekeeping applications.

Recommended Crystal Parameters:

Rs  $(max) \le 40 \text{ k}\Omega$ Co  $(max) \le 1.7 \text{ pF}$ Ci  $(max) \le 12.5 \text{ pF}$ Parallel Resonance



## VL82C113/VL82C113A

### **ABSOLUTE MAXIMUM RATINGS**

Ambient Temperature -10°C to +70°C Storage Temperature -65°C to +150°C

Supply Voltage to

Ground Potential -0.5 V to VDD + 0.3 V

**Applied Output** 

Voltage

-0.5 V to VDD + 0.3 V

Applied Input

Voltage

-0.5 V to 7.0 V

**Power Dissipation** 

500 mW

Stresses above those listed may cause permanent damage to the device.

These are stress ratings only, functional operation of this device at these or any other conditions above those indicated

in this data sheet is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### DC CHARACTERISTICS: TA = 0°C to +70°C, VDD = 5 V ±5%, VSS = 0 V

Symbol	Parameter	Min	Max	Unit	Conditions
VIL	Input Low Voltage	-0.5	0.8	٧	TTL Level Inputs
VIH	Input High Voltage	2.0 2.4	VDD + 0.5 VDD + 0.5	V V	TTL Level Inputs, Note 1 TTL Level Inputs, Note 2
VOL	Output Low Voltage		0.4 0.4 0.4 0.4	V V V	IOL = 4.0 mA, Note 3A IOL = 8.0 mA, Note 4A IOL = 12.0 mA, Note 5 IOL = 24.0 mA, Note 6
VOH	Output High Voltage	2.4 2.4 2.4		V V V	IOH = 0.8 mA, Note 3B IOH = 1.4 mA, Note 4B IOH = 2.4 mA, Note 6
IIH	Input High Current		10	μА	VIN = VDD, Note 7
IIL	Input Low Current	-10 -500	50	μΑ μΑ	VIN = VSS + 0.2 V, Note 8 VIN = 0.8 V, Note 9
ILOL	Three-state Leakage Current	-50	50	μΑ μΑ	VOUT = VSS + 0.2 V, Note 10 VOUT = VDD, Note 11
СО	Output Capacitance		8	pF	
CI	Input Capacitance		8	pF	
CIO	Input/Output Capacitance		16	pF	
IDD	Operating Supply Current		40	mA	
IBAT	Supply Current, Standby Mode		5.0 5.0 50.0	μΑ μΑ μΑ	VBAT = 2.4 V VBAT = 3.0 V VBAT = 5.0 V
IDDQ	Static Supply Current		5.0	mA	

(Notes on next page.)



## VL82C113/VL82C113A

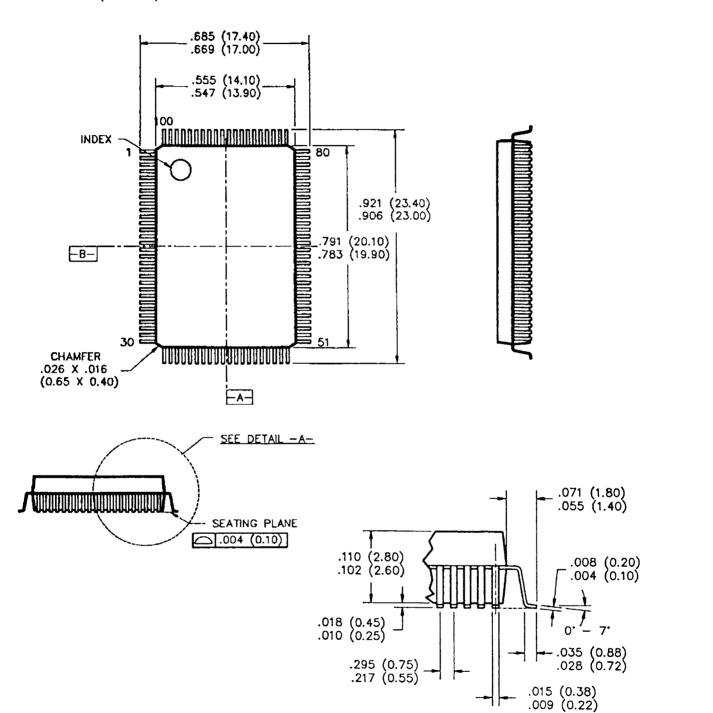
### DC CHARACTERISTICS (Cont.): $TA = 0^{\circ}C$ to $+70^{\circ}C$ , $VDD = 5 V \pm 5\%$ , VSS = 0 V

- Notes: 1. Pins: -REFRESH, SA0, -SBHE, -MASTER, -EALE, -BHE, HLDA, OSCI, KRSEL, KKSW, KCM, KI2/-TRI, -IOW, -IOR, SA19-SA1, A23-A1, LA23-LA17, SD7-SD0, KIRQ, -RTCIRQ, KI3, KI5.
  - 2. Pins: KHSE, KSRE, KDAT, KCLK, RSTDRV, PS.
  - 3A. Pins: KIRQ, MIRQ, KI5, KI3.
  - 3B. Pins: KIRQ, MIRQ, KI5, KI3, -RTCIRQ.
  - 4A. Pins: A23-A1, -BHE.
  - 4B. Pins: A23-A1, -BHE, KHSE/MDAT (PC/AT Mode only), KSRE/MCLK (PC/AT Mode Only).
  - 5. Pins: KHSE, -RTCIRQ, KSRE, KDAT, KCLK.
  - 6. Pins: -SBHE, SA19-SA1, LA23-LA17, SD7-SD0.
  - 7. Pins: -REFRESH, SA0, -MASTER, -EALE, HLDA, OSCI, KRSEL, KKSW, KCM, KI2/-TRI, PS, RSTDRV, -IOW, -IOR.
  - 8. Pins: -REFRESH, SAO, -MASTER, -EALE, HLDA, OSCI, KRSEL, PS, RSTDRV, -IOW, -IOR.
  - 9. Pins: KIRQ, KKSW, KCM, KI5, KI3, KI2/-TRI.
  - 10. Pins: SA19-SA1, -SBHE, LA23-LA17, A23-A1, SD7-SD0, KHSE/MDAT, KSRE/MCLK, MIRQ, KDAT, KCLK, -BHE, XTALIN, -RTCIRQ.
  - 11. Pins: SA19-SA1, -SBHE, LA23-LA17, A23-A1, -BHE, KIRQ, KI5, KI3, SD7-SD0, -RTCIRQ, MIRQ, KHSE/MDAT, KSRE/MCLK, KDAT, KCLK.



## **PACKAGE OUTLINE**

### 100-PIN METRIC (PLASTIC) QUAD FLAT PACK



- Notes: 1. Controlling dimension is MM.
  - 2. Dimensions are shown in inches (millimeters).

DETAIL -A-

⊕ .006 (0.15) TYP. (M) A B



### VL82C113/VL82C113A

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