

Advanced Numerical Methods for PDEs

Homework 3

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April 29, 2021

Consider the 2D problem

$$\begin{aligned}\partial_t u(x, y, t) + \partial_x f^x + \partial_y f^y &= 0, \quad x, y \in [0, 1] \\ f^x &= u - \partial_x u, \quad f^y = -\partial_y u\end{aligned}$$

with boundary conditions

$$\begin{aligned}f^x(x = 0, y, t) &= 0, \quad f^x(x = 1, y, t) = 0, \\ f^y(x, y = 0, t) &= 0, \quad f^y(x, y = 1, t) = 0,\end{aligned}$$

and initial conditions

$$u(x, y, t = 0) = u^I(x, y) = \delta(x - 0.5)\delta(y - 0.5)$$

Problem 1

1. Write a code which solves the problem using the implicit Cranck - Nicholson scheme (the trapezoidal rule in time), using an $M \times N$ grid with $\Delta x = \Delta y$. Explain how you solve the linear systems, using sparse Gauss elimination.

Solution: We can represent the PDE as

$$\frac{\partial u}{\partial t} + \frac{\partial u}{\partial x} - \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) = 0$$

Next, we discretize the equation using Forward Euler in time and Crank-Nicholson,

central differences in space:

$$\begin{aligned} \frac{u_{i,j}^{n+1} - u_{i,j}^n}{\Delta t} + \frac{1}{2} \left(\frac{u_{i+1,j}^{n+1} - u_{i-1,j}^{n+1}}{2\Delta x} + \frac{u_{i+1,j}^n - u_{i-1,j}^n}{2\Delta x} \right) \\ - \frac{1}{2} \left(\frac{u_{i+1,j}^{n+1} - 2u_{i,j}^{n+1} + u_{i-1,j}^{n+1}}{\Delta x^2} + \frac{u_{i+1,j}^n - 2u_{i,j}^n + u_{i-1,j}^n}{\Delta x^2} \right) \\ - \frac{1}{2} \left(\frac{u_{i,j+1}^{n+1} - 2u_{i,j}^{n+1} + u_{i,j-1}^{n+1}}{\Delta y^2} + \frac{u_{i,j+1}^n - 2u_{i,j}^n + u_{i,j-1}^n}{\Delta y^2} \right) = 0 \end{aligned}$$

Regrouping the $n + 1$ terms on the left and the n terms on the right we obtained

$$\begin{aligned} u_{i,j}^{n+1} + \frac{C}{4} (u_{i+1,j}^{n+1} - u_{i-1,j}^{n+1}) - \frac{\mu_x}{2} (u_{i+1,j}^{n+1} - 2u_{i,j}^{n+1} + u_{i-1,j}^{n+1}) - \frac{\mu_y}{2} (u_{i,j+1}^{n+1} - 2u_{i,j}^{n+1} + u_{i,j-1}^{n+1}) \\ = u_{i,j}^n - \frac{C}{4} (u_{i+1,j}^n - u_{i-1,j}^n) + \frac{\mu_x}{2} (u_{i+1,j}^n - 2u_{i,j}^n + u_{i-1,j}^n) + \frac{\mu_y}{2} (u_{i,j+1}^n - 2u_{i,j}^n + u_{i,j-1}^n), \end{aligned}$$

with $C = \Delta t / \Delta x$, $\mu_x = \Delta t / \Delta x^2$, and $\mu_y = \Delta t / \Delta y^2$.

Before we continue, let us define the grid with M and N horizontal and vertical cells, respectively. Note that the domain is then defined by $(M + 1)(N + 1)$ grid nodes. Hence the coordinates $x_i = (i - 2)\Delta x$ with $i \in [1, M + 3]$ and $y_j = (j - 2)\Delta y$ with $j \in [1, N + 3]$ include the *ghost nodes* at indices 1 and $M + 3$, $N + 3$ (chosen this way to match the *MATLAB* array indexing). We can collapse this 2D array into 1 column vector by stacking the columns one after another. We will obtain a vector of dimensions $(M + 3)(N + 3)$, including ghost nodes. Thus, our solution vector is $U_k = U_{i+(M+3)(j-1)} = u_{i,j}$. It is easy to show that

$$\begin{aligned} u_{i\pm 1,j} &= U_{i\pm 1+(M+3)(j-1)} = U_{k\pm 1}, \\ u_{i,j\pm 1} &= U_{i+(M+3)(j\pm 1-1)} = U_{k\pm(M+3)}. \end{aligned}$$

Then, we can turn our discretization to be in terms of the solution vector U ,

$$\begin{aligned} U_k^{n+1} + \frac{C}{4} (U_{k+1}^{n+1} - U_{k-1}^{n+1}) - \frac{\mu_x}{2} (U_{k+1}^{n+1} - 2U_k^{n+1} + U_{k-1}^{n+1}) - \frac{\mu_y}{2} (U_{k+M+3}^{n+1} - 2U_k^{n+1} + U_{k-M-3}^{n+1}) \\ = U_k^n - \frac{C}{4} (U_{k+1}^n - U_{k-1}^n) + \frac{\mu_x}{2} (U_{k+1}^n - 2U_k^n + U_{k-1}^n) + \frac{\mu_y}{2} (U_{k+M+3}^n - 2U_k^n + U_{k-M-3}^n). \end{aligned}$$

Reorganizing the equation we get

$$\begin{aligned} -\frac{\mu_y}{2} U_{k-M-3}^{n+1} - \left(\frac{C}{4} + \frac{\mu_x}{2} \right) U_{k-1}^{n+1} + (1 + \mu_x + \mu_y) U_k^{n+1} + \left(\frac{C}{4} - \frac{\mu_x}{2} \right) U_{k+1}^{n+1} - \frac{\mu_y}{2} U_{k+M+3}^{n+1} \\ = \frac{\mu_y}{2} U_{k-M-3}^n + \left(\frac{C}{4} + \frac{\mu_x}{2} \right) U_{k-1}^{n+1} + (1 - \mu_x - \mu_y) U_k^{n+1} + \left(\frac{\mu_x}{2} - \frac{C}{4} \right) U_{k+1}^{n+1} + \frac{\mu_y}{2} U_{k+M+3}^{n+1}, \end{aligned}$$

$$\begin{aligned} a_{-M-3} U_{k-M-3}^{n+1} + a_{-1} U_{k-1}^{n+1} + a_0 U_k^{n+1} + a_{+1} U_{k+1}^{n+1} + a_{M+3} U_{k+M+3}^{n+1} \\ = b_{-M-3} U_{k-M-3}^n + b_{-1} U_{k-1}^{n+1} + b_0 U_k^{n+1} + b_{+1} U_{k+1}^{n+1} + b_{M+3} U_{k+M+3}^{n+1}, \end{aligned}$$

This system of equations can be represented in matrix form, $AU^{n+1} = BU^n$, where A and B are sparse matrices defined by the 5 a diagonals and 5 b diagonals given in the equation above. To solve the system we use the *MATLAB* command backslash operator $U^{n+1} = A \backslash BU^n$. Lastly, we need to implement the boundary conditions after updating the solution. The boundary conditions in index form are:

- Bottom boundary: $\partial_y u|_{y=0} = 0$:

$$\begin{aligned} \left. \frac{u_{i,j+1} - u_{i,j-1}}{2\Delta y} \right|_{j=2} &= 0 \\ \frac{u_{i,3} - u_{i,1}}{2\Delta y} &= 0 \\ u_{i,1} = u_{i,3} &\Rightarrow \boxed{U_i = U_{i+2(M+3)}} \end{aligned}$$

- Top boundary: $\partial_y u|_{y=1} = 0$:

$$\begin{aligned} \left. \frac{u_{i,j+1} - u_{i,j-1}}{2\Delta y} \right|_{j=N+2} &= 0 \\ \frac{u_{i,N+3} - u_{i,N+1}}{2\Delta y} &= 0 \\ u_{i,N+3} = u_{i,N+1} &\Rightarrow \boxed{U_{i+(N+2)(M+3)} = U_{i+N(M+3)}} \end{aligned}$$

- Left boundary: $u|_{x=0} - \partial_x u|_{x=0} = 0$:

$$\begin{aligned} u_{i,j}|_{i=2} - \left. \frac{u_{i+1,j} - u_{i-1,j}}{2\Delta x} \right|_{i=2} &= 0 \\ u_{2,j} - \frac{u_{3,j} - u_{1,j}}{2\Delta x} &= 0 \\ u_{1,j} &= u_{3,j} - 2\Delta x u_{2,j} \\ \boxed{U_{1+(M+3)(j-1)} = U_{3+(M+3)(j-1)} - 2\Delta x U_{2+(M+3)(j-1)}} \end{aligned}$$

- Right boundary: $u|_{x=1} - \partial_x u|_{x=1} = 0$:

$$\begin{aligned} u_{i,j}|_{i=M+2} - \left. \frac{u_{i+1,j} - u_{i-1,j}}{2\Delta x} \right|_{i=M+2} &= 0 \\ u_{M+2,j} - \frac{u_{M+3,j} - u_{M+1,j}}{2\Delta x} &= 0 \\ u_{M+3,j} &= u_{M+1,j} + 2\Delta x u_{M+2,j} \\ \boxed{U_{(M+3)j} = U_{M+1+(M+3)(j-1)} + 2\Delta x U_{M+2+(M+3)(j-1)}} \end{aligned}$$

The four boundary conditions are imposed after updating the solution by solving $U^{n+1} = A \backslash BU^n$ every time-step.

Problem 2

1. Using the Crank - Nicholson scheme with a time and spatial step $\Delta t = \Delta x = 0.01$ for $0 < t < 1$. Solve the linear equations resulting from the implicit discretization in *MATLAB* sparse mode.

Solution:

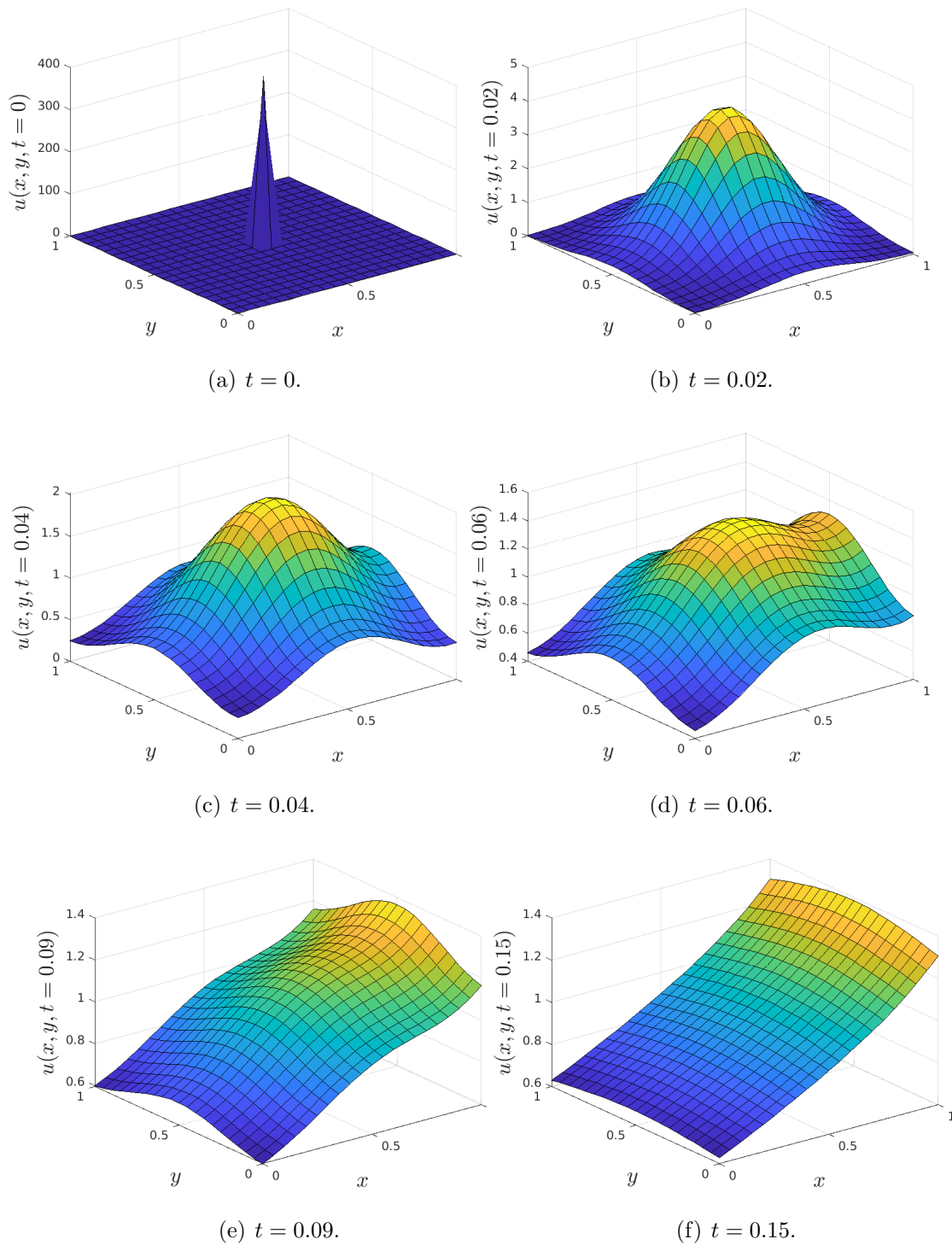


Figure 1: Solution $u(x, t)$ against x and t for different number of realizations.

```
1 clear all, close all, clc
2
```

```

3 format short
4
5 % Number of intervals
6 M = 20; % In x-direction
7 N = 20; % In Y-direction
8
9 % Define limits of domain
10 x_0 = 0;
11 x_F = 1;
12 y_0 = 0;
13 y_F = 1;
14 T = 0.2;
15
16 % Step sizes
17 dx = (x_F - x_0) / M;
18 dy = (y_F - y_0) / N;
19 dt = 0.0001;
20
21 % Define grid (including ghost nodes)
22 x = linspace (x_0-dx, x_F+dx, M+3); % x(1) and x(M+3) are ghost
    nodes
23 y = linspace (y_0-dy, y_F+dy, N+3); % y(1) and y(N+3) are ghost
    nodes
24
25 % Define useful constants
26 C = dt/dx;
27 mu_x = dt/(dx^2);
28 mu_y = dt/(dy^2);
29
30 % Define initial condition
31 U0 = kron((round(x,8) == 0.5),((round(y,8) == 0.5)))/dx/dy;
32 plot_sol(U0,x,y,0)
33
34 % Define big matrices size, including ghost nodes
35 S = (M + 3)*(N + 3);
36
37 %% Construct Matrix A
38 % Diagonal component
39 d = diag((1 + mu_x + mu_y) * ones(S,1));
40 % 1-lower diagonal component
41 l1 = diag((-C/4 - mu_x/2) * ones(S-1,1), -1);
42 % 1-upper diagonal component
43 u1 = diag(( C/4 - mu_x/2) * ones(S-1,1), 1);
44 % (M+3)-lower diagonal component
45 lM3 = diag(-mu_y/2 * ones(S-M-3,1), -M-3);
46 % (M+3)-upper diagonal component
47 uM3 = diag(-mu_y/2 * ones(S-M-3,1), M+3);
48 % Add them together
49 A = sparse(d + u1 + l1 + lM3 + uM3);
50
51 %% Construct Matrix B
52 % Diagonal component

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```

53 d = diag((1 - mu_x - mu_y) * ones(S,1));
54 % 1-lower diagonal component
55 l1 = diag(( C/4 + mu_x/2) * ones(S-1,1), -1);
56 % 1-upper diagonal component
57 u1 = diag((-C/4 + mu_x/2) * ones(S-1,1), 1);
58 % (M+3)-lower diagonal component
59 lM3 = diag(mu_y/2 * ones(S-M-3,1), -M-3);
60 % (M+3)-upper diagonal component
61 uM3 = diag(mu_y/2 * ones(S-M-3,1), M+3);
62 % Add them together
63 B = sparse(d + u1 + l1 + lM3 + uM3);
64
65 %% Compute solution
66
67 t_plots = 0.01:0.01:T
68
69 t = 0;
70 tstep = 0;
71 plot_idx = 1;
72 % Initialize
73 U = U0;
74
75 i = 1:M+3; % Horizontal array index
76 j = 1:N+3; % Vertical array index
77 while t < T
78
79     % Advance solution
80     rhs = B*U;
81     U = A\rhs;
82
83     % Impose boundary conditions
84     U(i) = U(i + 2*(M+3)); % Bottom
85     U(i + (N+2)*(M+3)) = U(i + N*(M+3)); % Top
86     U(1 + (M+3)*(j-1)) = U(3 + (M+3)*(j-1)) - 2*dx*U(2 + (M+3)*(j-1)
); % Left
87     U(M+3 + (M+3)*(j-1)) = U(M+1 + (M+3)*(j-1)) + 2*dx*U(M+2 + (M+3)
*(j-1)); % Right
88
89     % Advance time
90     t = round(t + dt,4); % avoid floating point error to compare
with ismember
91     tstep = tstep + 1;
92
93     if (mod(tstep,100) == 0)
94         plot_sol(U,x,y,t)
95         pause(0.15)
96     end
97
98 end
99
100 function plot_sol(U,x,y,t)
101     labelfontsize = 18;

```

```

102     Lx = length(x);
103     Ly = length(y);
104     u = reshape(U, [Lx Ly]);
105     figure(1)
106
107     surf(x(2:Ly-1),y(2:Lx-1),u(2:Lx-1,2:Ly-1)')
108
109     xlabel('$x$', 'interpreter', 'latex', 'fontsize', labelfontsize)
110     ylabel('$y$', 'interpreter', 'latex', 'fontsize', labelfontsize)
111     zlabel(append('$u(x, y, t = ', num2str(t), ')$'), 'interpreter', '
112     latex', 'fontsize', labelfontsize)
113     figName = create_figName(t);
114     saveas(gcf, figName, 'png')
115 end
116
117 function figName = create_figName(t)
118     if t == 0
119         exponent = 0;
120         base = 00;
121     else
122         exponent = -2;
123         base = t*100;
124     end
125
126     path = '../figures/';
127
128     if base > 9
129         figName = append(path, 'p2_u_t', num2str(base), 'e', num2str(
130         exponent));
131     else
132         figName = append(path, 'p2_u_t0', num2str(base), 'e', num2str(
133         exponent));
134     end
135 end

```


Consider an ensemble of cars, distributed on a circular course of length L (so $x \in [0, L]$), trying to travel at a desired speed $v_0(x)$. Assume that there is a minimal distance d between cars and a corresponding congestion density c . Simulate for a time $t \in [0, T]$. Plot a solution of the congestion backward wave and the distribution of cars at $t = T$.

Problem 3

Problem 4