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```
clear all; close all; format long; clc
axisSize=14;
markersize=20;
linewidth=5;
Lx = 4;
Ly = 2;
Mv = [2 1 0.5]*128;
Nv = [2 1 0.5]*64;
CFL = 20;
Re = 2;
Sc = 0.25;
p1(1)=0;
p2(1)=0;
p3(1)=0;
for i=1:3
```

```
    M=Mv(i);
    N=Nv(i);
    if (M==128 && N==64)
        outputTime=[0.1 0.5 1 10];
    else
        outputTime=[0.1 0.5 1];
    end
    endtime=outputTime(end);
    hx = Lx/M;
    hy = Ly/N;
    if hx~=hy
        error('Cells not square')
    end
    time=0;
    dt = min(CFL*0.25*hx^2*Re,CFL*0.25*hx^2*Re*Sc);
    n=1;
    % Define the points of the different meshes
    xu=linspace(0,4,M+1);
    yu=linspace(-hy/2,2+hy/2,N+2);
    xv=linspace(-hx/2,4+hx/2,M+2);
    yv=linspace(0,2,N+1);
    xY=linspace(-hx/2,4+hx/2,M+2);
    yY=linspace(-hy/2,2+hy/2,N+2);

    [u,v,Y]=initialization(M,N,hx,hy);
    iter=1;
    t=0;
    while time < endtime
```

```
    if (time < outputTime(n) && time+dt >= outputTime(n))
        dt=outputTime(n)-time;
        n=n+1;
    else
        dt = min(CFL*0.25*hx^2*Re,CFL*0.25*hx^2*Re*Sc);
    end
```

Solve for u(x,y,t)

```
u=ADI_u(u,M,N,dt,hx,hy,Re);
```

Solve for v(x,y,t)

```
v=ADI_v(v,M,N,dt,hx,hy,Re);
```

Solve for Y(x,y,t)

```
Y=ADI_Y(Y,M,N,dt,hx,hy,Re,Sc);
```

Next time step

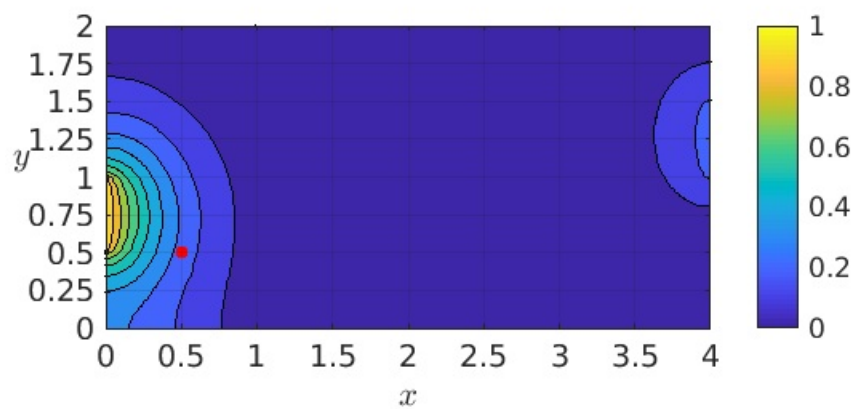
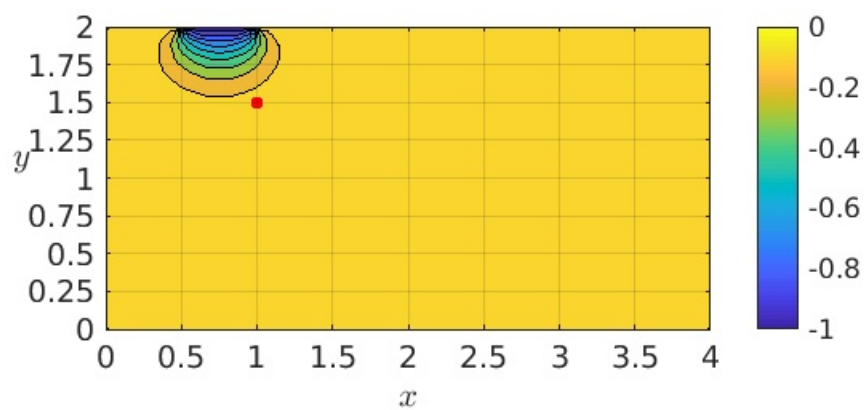
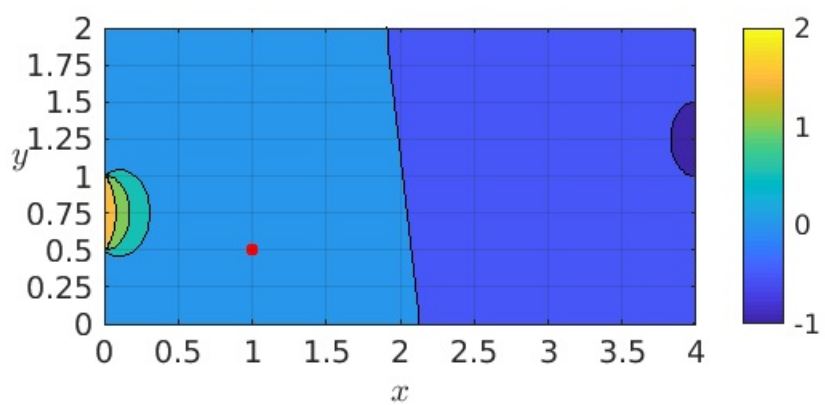
```
time=time+dt;
```

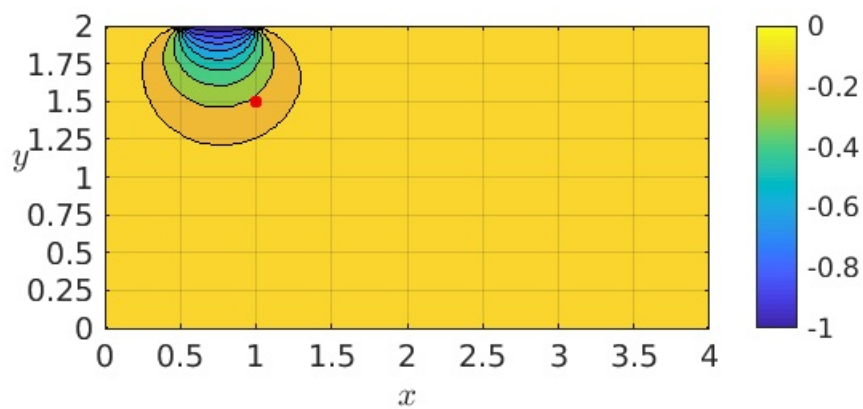
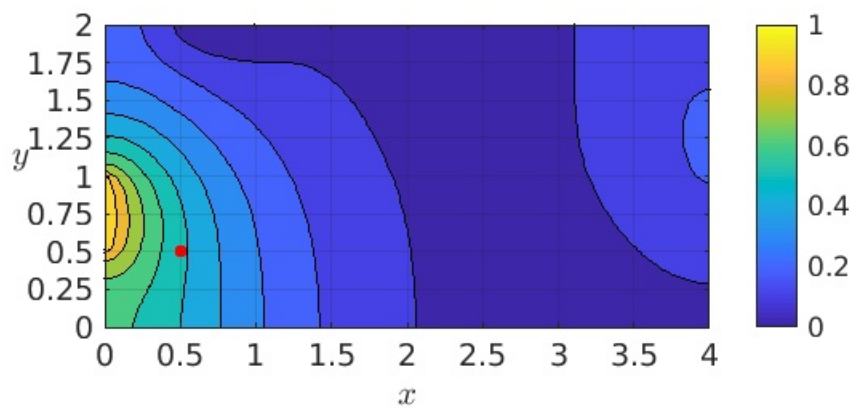
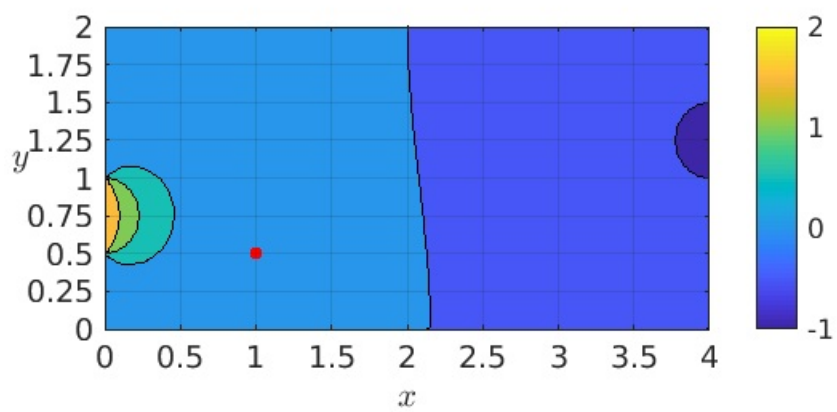
Filled contour plots, only for M=128 and N=64

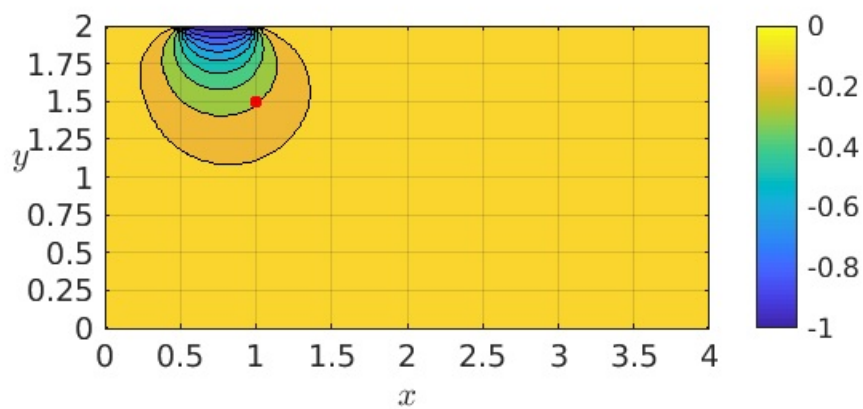
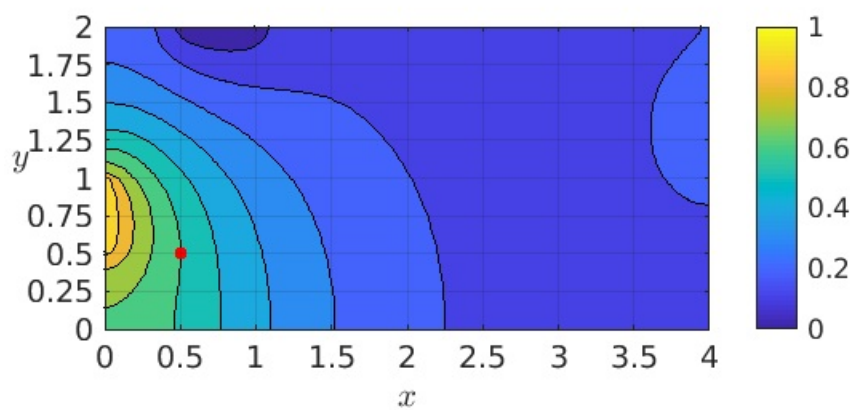
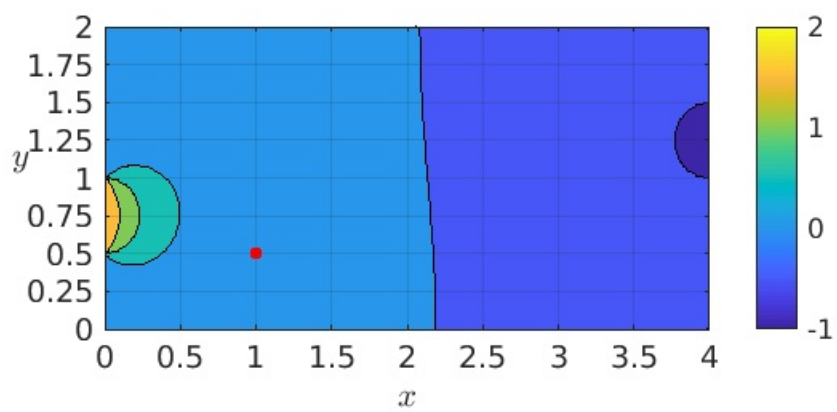
```
if (M==128 && N==64 && ismember(time,outputTime))
% Plot u
figure(n-1)
contourf(xu,yu,u')
hold on
plot(1,0.5,'r.','markersize',markersize,'linewidth',linewidth)
axis([0 4 0 2])
caxis([-1 2])
colorbar
xlabel('$x$', 'Interpreter', 'latex')
ylabel('$y$', 'Interpreter', 'latex')
yticks([0 0.25 0.50 0.75 1.0 1.25 1.50 1.75 2.0]);
xticks([0 0.50 1.0 1.50 2.0 2.50 3.0 3.50 4.0]);
set(get(gca,'ylabel'),'rotation',0)
set(gca,'fontsize',axisSize)
pbaspect([2 1 1])
grid on
txt=['Latex/FIGURES/u_' num2str(n)];
saveas(gcf,txt,'eps')

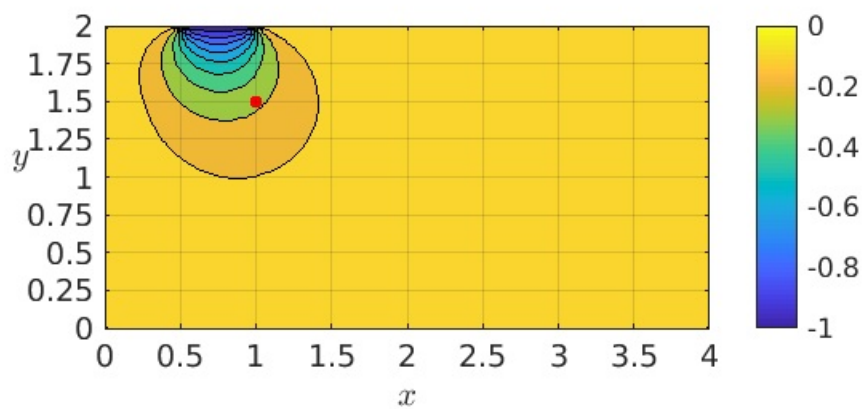
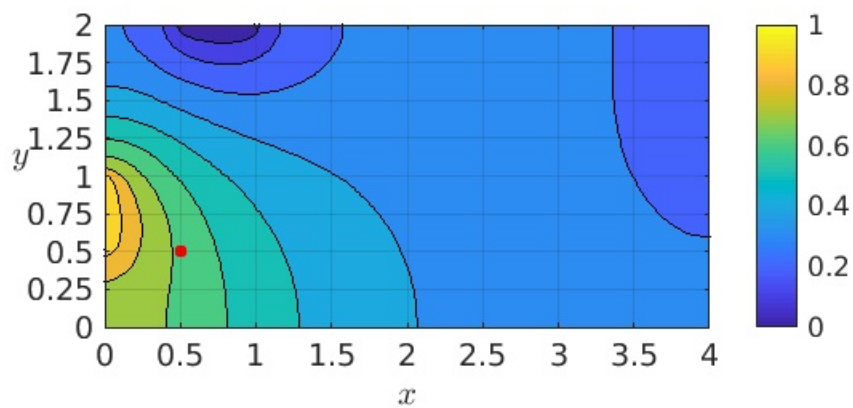
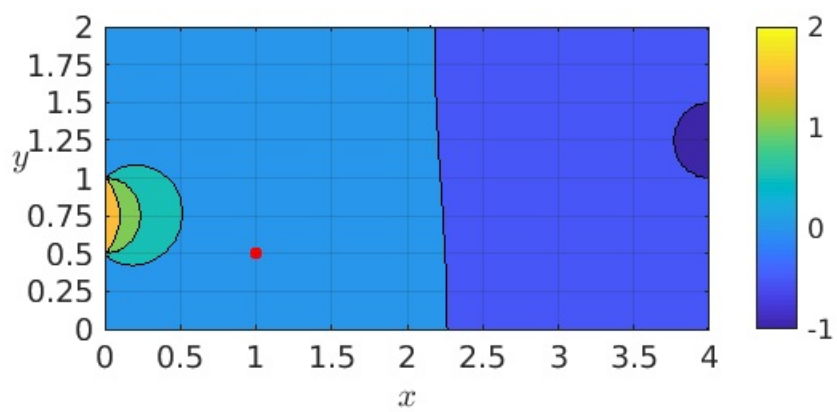
% Plot v
figure(n+3)
contourf(xv,yv,v')
hold on
plot(1,1.5,'r.','markersize',markersize,'linewidth',linewidth)
axis([0 4 0 2])
caxis([-1 0])
colorbar
xlabel('$x$', 'Interpreter', 'latex')
ylabel('$y$', 'Interpreter', 'latex')
yticks([0 0.25 0.50 0.75 1.0 1.25 1.50 1.75 2.0]);
xticks([0 0.50 1.0 1.50 2.0 2.50 3.0 3.50 4.0]);
set(get(gca,'ylabel'),'rotation',0)
set(gca,'fontsize',axisSize)
pbaspect([2 1 1])
grid on
txt=['Latex/FIGURES/v_' num2str(n)];
saveas(gcf,txt,'eps')

% Plot Y
figure(n+7)
contourf(xY,yY,Y')
hold on
plot(0.5,0.5,'r.','markersize',markersize,'linewidth',linewidth)
axis([0 4 0 2])
caxis([0 1])
colorbar
xlabel('$x$', 'Interpreter', 'latex')
ylabel('$y$', 'Interpreter', 'latex')
yticks([0 0.25 0.50 0.75 1.0 1.25 1.50 1.75 2.0]);
xticks([0 0.50 1.0 1.50 2.0 2.50 3.0 3.50 4.0]);
set(get(gca,'ylabel'),'rotation',0)
set(gca,'fontsize',axisSize)
pbaspect([2 1 1])
grid on
txt=['Latex/FIGURES/Y_' num2str(n)];
saveas(gcf,txt,'eps')
end
```









```

if (M==128 && N==64)
    iter=iter+1;
    t=[t;time];
    p1(iter) = (u (find(xu==1),find(yu<=0.5,1,'last'))...
        +u (find(xu==1),find(yu>=0.5,1)))/2;
    p2(iter) = (v (find(xv<=1,1,'last'),find(yv==1.5))...
        +v (find(xv>=1,1),find(yv==1.5)))/2;
    p3(iter) = (Y (find(xY<=0.5,1,'last'),find(yY<=0.5,1,'last'))...
        +Y (find(xY<=0.5,1,'last'),find(yY>=0.5,1))...
        +Y (find(xY>=0.5,1),find(yY<=0.5,1,'last'))...
        +Y (find(xY<=0.5,1),find(yY<=0.5,1)))/4;
end

```

Probes value for u, v and Y at t=1

```

if time==1
    p1l(i)= (u (find(xu==1),find(yu<=0.5,1,'last'))...
        +u (find(xu==1),find(yu>=0.5,1)))/2;
    p2l(i)= (v (find(xv<=1,1,'last'),find(yv==1.5))...
        +v (find(xv>=1,1),find(yv==1.5)))/2;
    p3l(i)= (Y (find(xY<=0.5,1,'last'),find(yY<=0.5,1,'last'))...
        +Y (find(xY<=0.5,1,'last'),find(yY>=0.5,1))...
        +Y (find(xY>=0.5,1),find(yY<=0.5,1,'last'))...
        +Y (find(xY<=0.5,1),find(yY<=0.5,1)))/4;
end

```

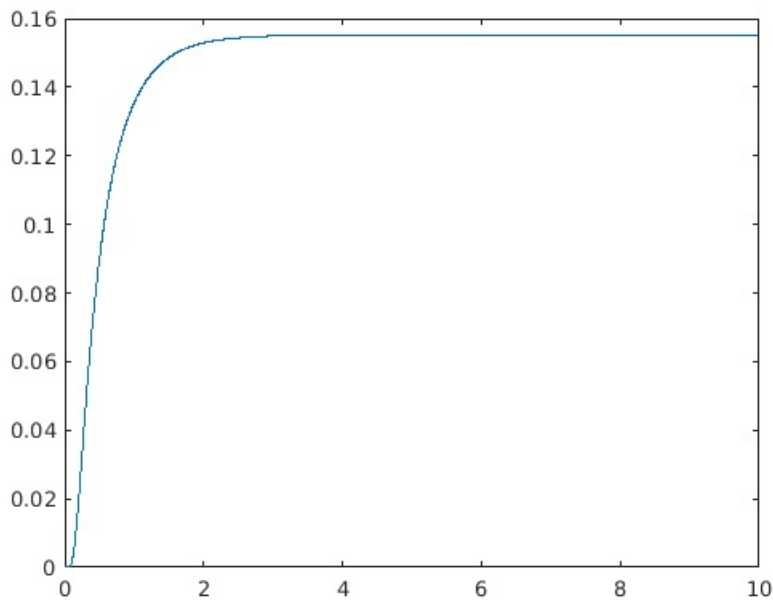
```
end
```

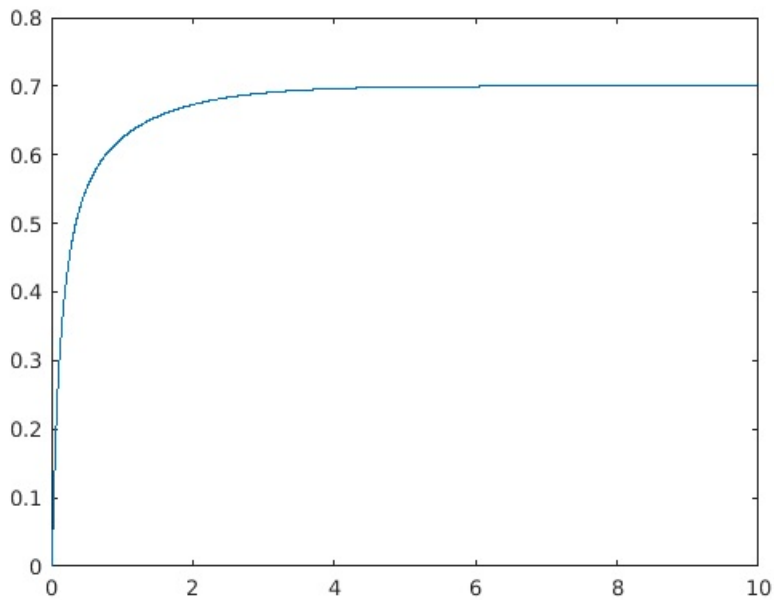
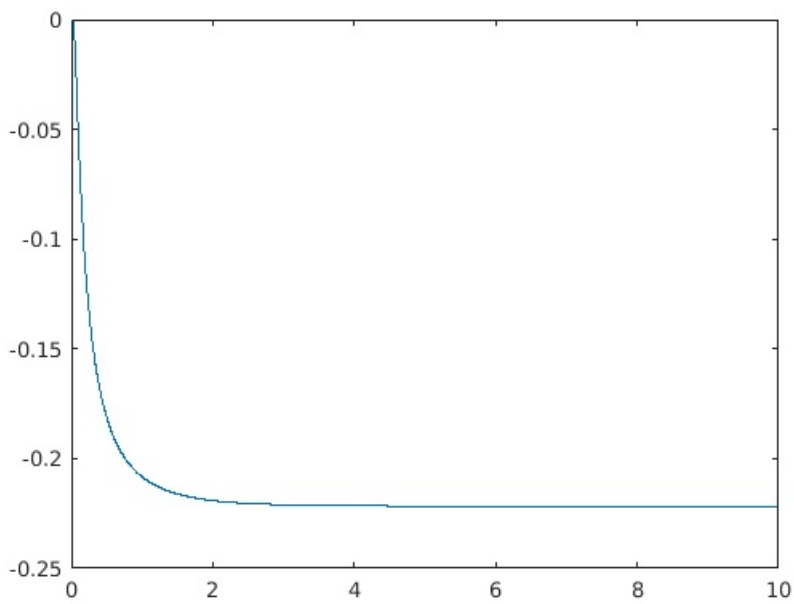
Plot the probes, only for M=128 and N=64

```

if (M==128 && N==64)
    figure
    plot(t,p1)
    figure
    plot(t,p2)
    figure
    plot(t,p3)
end

```





end

GCI analysis

```
clc
r=2
Fsec=1.25
% Probe 1
p_u=log((p11(3)-p11(2))/(p11(2)-p11(1)))/log(r)
u_h0=p11(1)+(p11(1)-p11(2))/(r^p_u-1)
GCI21_u=Fsec*(p11(2)-p11(1))/(p11(1)*(r^p_u-1))
GCI32_u=Fsec*(p11(3)-p11(2))/(p11(2)*(r^p_u-1))
coeff_u=GCI21_u*r^p_u/GCI32_u
percent_u=GCI21_u*100
% pause

% Probe 2
p_v=log((p21(3)-p21(2))/(p21(2)-p21(1)))/log(r)
v_h0=p21(1)+(p21(1)-p21(2))/(r^p_v-1)
GCI12_v=Fsec*(p21(1)-p21(2))/(p21(1)*(r^p_v-1))
GCI23_v=Fsec*(p21(2)-p21(3))/(p21(2)*(r^p_v-1))
coeff_v=GCI12_v*r^p_v/GCI23_v
percent_v=GCI12_v*100
% pause

% Probe 3
p_Y=log((p31(3)-p31(2))/(p31(2)-p31(1)))/log(r)
Y_h0=p31(1)+(p31(1)-p31(2))/(r^p_Y-1)
```



```
GCI12_Y=Fsec*(p31(1)-p31(2))/(p31(1)*(r^p_Y-1))
GCI23_Y=Fsec*(p31(2)-p31(3))/(p31(2)*(r^p_Y-1))
coeff_Y=GCI12_Y*r^p_Y/GCI23_Y
percent_Y=GCI12_Y*100
```

```
load gong.mat;
sound(y);
```

```
r =
```

```
2
```

```
Fsec =
```

```
1.2500000000000000
```

```
p_u =
```

```
1.997009899696340
```

```
u_h0 =
```

```
0.135440502299368
```

```
GCI21_u =
```

```
1.045042006401645e-04
```

```
GCI32_u =
```

```
4.170470158182023e-04
```

```
coeff_u =
```

```
1.000250117700815
```

```
percent_u =
```

```
0.010450420064016
```

```
p_v =
```

```
2.012841410009195
```

```
v_h0 =
```

```
-0.208331420237975
```

```
GCI12_v =
```

```
1.030687806447006e-05
```

```
GCI23_v =
```

```
4.159715708335120e-05
```

```
coeff_v =
```

```
0.999974968609772
```

```
percent_v =
```

```
0.001030687806447
```

```
p_Y =
```

```
1.023405387089959
```

Y_h0 =
0.628929392741961

GCI12_Y =
0.004628023636959

GCI23_Y =
0.009443544004055

coeff_Y =
0.996176469846528

percent_Y =
0.462802363695942