弹性力学

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1 平面问题的极坐标解答

1.1 极坐标中的平衡微分方程

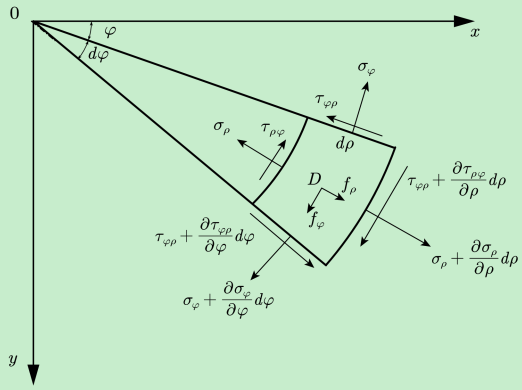

图 2

1.1.1 极坐标中的平衡微分方程

$$\begin{cases} \frac{\partial\sigma_\rho}{\partial\rho}+\frac{1}{\rho}\frac{\partial\tau_{\rho\varphi}}{\partial\varphi}+\frac{\sigma_\rho-\sigma_\varphi}{\rho}+f_\rho=0 \\ \frac{1}{\rho}\frac{\partial\sigma_\varphi}{\partial\varphi}+\frac{\partial\tau_{\rho\varphi}}{\partial\rho}+\frac{2\tau_{\rho\varphi}}{\rho}+f_\varphi=0 \end{cases} \tag{1}$$

1.2 极坐标中的几何方程和物理方程

1.2.1 极坐标中的几何方程

$$\begin{cases} \varepsilon_\rho=\frac{\partial u_\rho}{\partial\rho} \\ \varepsilon_\varphi=\frac{u_\rho}{\rho}+\frac{1}{\rho}\frac{\partial u_\rho}{\partial\varphi} \\ \gamma_{\rho\varphi}=\frac{1}{\rho}\frac{\partial u_\rho}{\partial\varphi}+\frac{\partial u_\rho}{\partial\rho}-\frac{u_\varphi}{\rho} \end{cases} \tag{2}$$

1.2.2 极坐标中的物理方程

$$\begin{cases} \varepsilon_\rho=\frac{1}{E}\left(\sigma_\rho-\mu\sigma_\varphi\right) \\ \varepsilon_\varphi=\frac{1}{E}\left(\sigma_\varphi-\mu\sigma_\rho\right) \\ \gamma_{\rho\varphi}=\frac{1}{G}\tau_{\rho\varphi}=\frac{2(1+\mu)}{E}\tau_{\rho\varphi} \end{cases} \tag{3}$$

平面应变的情况下，需将上式中的E换为$\frac{E}{1-\mu^2}$，μ换为$\frac{\mu}{1-\mu}$。

1.3 坐标变换

1.3.1 位移分量的坐标变换

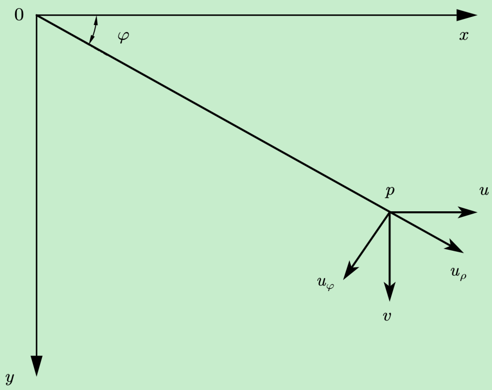

图 3

$$\begin{cases} u_\rho = u\cos\varphi + v\sin\varphi \\ u_\varphi = -u\sin\varphi + v\cos\varphi \end{cases} \Longrightarrow \begin{pmatrix} u_\rho \\ u_\varphi \end{pmatrix} = \begin{bmatrix} \cos\varphi & \sin\varphi \\ -\sin\varphi & \cos\varphi \end{bmatrix}, \begin{pmatrix} u \\ v \end{pmatrix} = \begin{bmatrix} \cos\varphi & -\sin\varphi \\ \sin\varphi & \cos\varphi \end{bmatrix} \begin{pmatrix} u_\rho \\ u_\varphi \end{pmatrix} \tag{4}$$

1.3.2 应力分量的坐标变换

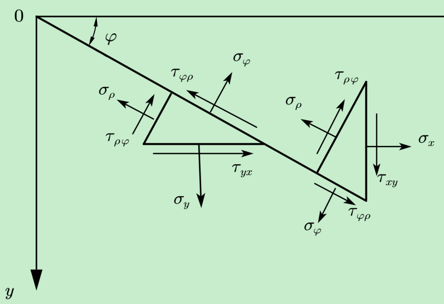

图 4

$$\begin{cases} \sigma_x = \sigma_\rho\cos^2\varphi + \sigma_\varphi\sin^2\varphi - 2\tau_{\rho\varphi}\sin\varphi\cos\varphi \\ \sigma_y = \sigma_\rho\sin^2\varphi + \sigma_\varphi\cos^2\varphi + 2\tau_{\varphi\rho}\sin\varphi\cos\varphi \\ \tau_{xy} = \frac{\sigma_\rho-\sigma_\varphi}{2}\sin 2\varphi + \tau_{\rho\varphi}\cos 2\varphi \end{cases} \tag{5}$$

$$\begin{cases} \sigma_x = \frac{\sigma_\rho+\sigma_\varphi}{2} + \frac{\sigma_\rho-\sigma_\varphi}{2}\cos 2\varphi - \tau_{\rho\varphi}\sin 2\varphi \\ \sigma_y = \frac{\sigma_\rho+\sigma_\varphi}{2} - \frac{\sigma_\rho-\sigma_\varphi}{2}\cos 2\varphi - \tau_{\rho\varphi}\sin 2\varphi \\ \tau_{xy} = \frac{\sigma_\rho-\sigma_\varphi}{2}\sin 2\varphi + \tau_{\rho\varphi}\cos 2\varphi \end{cases} \tag{6}$$

$$\begin{bmatrix} \sigma_x & \tau_{xy} \\ \tau_{yx} & \sigma_y \end{bmatrix} = \begin{bmatrix} \cos\varphi & \sin\varphi \\ -\sin\varphi & \cos\varphi \end{bmatrix} \begin{bmatrix} \sigma_\rho & \tau_{\varphi\rho} \\ \tau_{\rho\varphi} & \sigma_\varphi \end{bmatrix} \begin{bmatrix} \cos\varphi & \sin\varphi \\ -\sin\varphi & \cos\varphi \end{bmatrix}^T \tag{7}$$

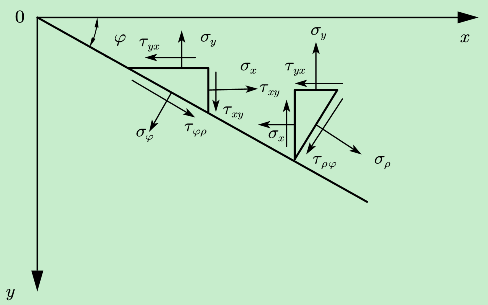

图 5

$$\begin{cases} \sigma_\rho = \sigma_x\cos^2\varphi + \sigma_y\sin^2\varphi + 2\tau_{xy}\sin\varphi\cos\varphi \\ \sigma_\varphi = \sigma_x\sin^2\varphi + \sigma_y\cos^2\varphi - 2\tau_{xy}\sin\varphi\cos\varphi \\ \tau_{\rho\varphi} = \left(\sigma_y - \sigma_x\right)\sin\varphi\cos\varphi + \tau_{xy}\left(\cos^2\varphi - \sin^2\varphi\right) \end{cases} \tag{8}$$

$$\begin{cases} \sigma_\rho = \frac{\sigma_x+\sigma_y}{2} + \frac{\sigma_x-\sigma_y}{2}\cos 2\varphi + \tau_{xy}\sin 2\varphi \\ \sigma_\varphi = \frac{\sigma_x+\sigma_y}{2} - \frac{\sigma_x-\sigma_y}{2}\cos 2\varphi - \tau_{xy}\sin 2\varphi \\ \tau_{\varphi\rho} = \frac{\sigma_x-\sigma_y}{2}\sin 2\varphi + \tau_{xy}\cos 2\varphi \end{cases} \tag{9}$$

$$\begin{bmatrix} \sigma_\rho & \tau_{\varphi\rho} \\ \tau_{\rho\varphi} & \sigma_\varphi \end{bmatrix} = \begin{bmatrix} \cos\varphi & \sin\varphi \\ -\sin\varphi & \cos\varphi \end{bmatrix}^T \begin{bmatrix} \sigma_x & \tau_{xy} \\ \tau_{yx} & \sigma_y \end{bmatrix} \begin{bmatrix} \cos\varphi & \sin\varphi \\ -\sin\varphi & \cos\varphi \end{bmatrix} \tag{10}$$

1.4 极坐标中的应力函数与相容方程

当$f_\rho = f_\varphi = 0$时：

$$\begin{cases} \sigma_\rho = \frac{1}{\rho}\frac{\partial\Phi}{\partial\rho} + \frac{1}{\rho^2}\frac{\partial^2\Phi}{\partial\varphi^2} \\ \sigma_\varphi = \frac{\partial^2\Phi}{\partial\rho^2} \\ \tau_{\rho\varphi} = -\frac{\partial}{\partial\rho}\left(\frac{1}{\rho}\frac{\partial\Phi}{\partial\varphi}\right) \end{cases} \tag{11}$$

1.4.1 相容方程

$$\left(\frac{\partial^2}{\partial\rho^2}+\frac{1}{\rho}\frac{\partial}{\partial\rho}+\frac{1}{\rho^2}\frac{\partial^2}{\partial\varphi^2}\right)^2\Phi=0 \tag{12}$$

1.5 轴对称应力和相容的位移

所谓轴对称问题，是指物体几何形状或某物理量是绕某一轴对称的，凡通过此轴的任何面均为对称面。如果该物体所受外部荷载也对称于该轴，那么相应所产生的应力也必对称该轴。

令$\Phi=\Phi(\rho)$

$$\sigma_\rho=\frac{1}{\rho}\frac{d\Phi}{d\rho},\sigma_\varphi=\frac{d^2\Phi}{d\rho^2},\tau_{\rho\varphi}=0 \tag{13}$$

$$\left(\frac{\partial^2}{\partial\rho^2}+\frac{1}{\rho}\frac{\partial}{\partial\rho}\right)\Phi=0 \tag{14}$$

即

$$\Phi=A\ln\rho+B\rho^2\ln\rho+C\rho^2+D \tag{15}$$

应力分量

$$\begin{cases}\sigma_\rho=\frac{A}{\rho^2}+B(1+2\ln\rho)+2C\\ \sigma_\varphi=-\frac{A}{\rho^2}+B(3+2+\ln\rho)+2C\\ \tau_{\rho\varphi}=0\end{cases} \tag{16}$$

代入物理方程和几何方程可得位移分量

$$\begin{cases}u_\rho=\frac{1}{E}\left[-(1+\mu)\frac{A}{\rho}+2(1-\mu)B\rho(\ln\rho-1)+(1-3\mu)B\rho+2(1-\mu)C\rho\right]+I\cos\varphi+K\sin\varphi\\ u_\varphi=\frac{4B\rho\varphi}{E}+H\rho-I\sin\varphi+K\cos\varphi\end{cases} \tag{17}$$

(1). 在轴对称应力条件下，应力、应变和位移的通解，适用于任何轴对称应力问题。
(2). 在轴对称应力条件下，应变也是轴对称的，但位移不一定是轴对称的。
(3). 实现轴对称应力的条件是：物体形状、体力和面力应是轴对称的。
(4). 轴对称应力及对应的位移的通解已满足相容方程，它们还需满足边界条件及多连体中的位移单值条件，并由此求出系数A、B、C。

注 欧拉方程：

$$x^ny^{(n)}+P_1x^{n-1}y^{(n-1)}+\cdots+P_{n-1}xy'+P_ny=0$$

特征方程为：

$$[k(k-1)\cdots(k-n+1)+P_1[k(k-1)\cdots(k-n+2)]+\cdots+P_{n-1}k+P_n]=0$$

关于K的n次代数方程，可解得n个特征根k_1、k_2、$\cdots k_n$

(1). 当它们是互不相等的实根时，通解具有幂函数的形式

$$y = C_1x^{k_1} + C_2x^{k_2} + \cdots + C_nx^{k_n}$$

(2). 每当出现重根时，每多一重根，就多乘一个$\ln x$

如：当k_1为$m\,(m < n)$重根时，通解为

$$y = C_1x^{k_1} + C_2x^{k_2}\ln x + \cdots + C_mx^{k_1}\ln^{m-1} x + C_{m+1}x^{k_{m+1}} + \cdots + C_nx^{k_n}$$

(3). 出现共轭复根时，则虚部是三角函数因子

如：当$k_{1,2} = \alpha \pm i\beta$，通解为

$$y = C_1x^{\alpha}\cos(\beta\ln x) + C_2x^{\alpha}\sin(\beta\ln x) + C_3x^{k_3} + \cdots + C_nx^{k_n}$$

(4). 当出现复重根，则实部要多乘因子$\ln x$

如：$k_{1,2} = \alpha \pm i\beta$为$m\left(m < \frac{n}{2}\right)$重共轭复根时，通解为

$$\begin{aligned} y = &\left[C_1x^{\alpha} + C_2x^{\alpha}\ln x + \cdots + C_mx^{\alpha}\ln^{m-1} x\right]\cos(\beta\ln x) + \\ &\left[C_{m+1}x^{\alpha} + C_{m+2}x^{\alpha}\ln x + \cdots + C_{2m}x^{\alpha}\ln^{m-1} x\right]\sin(\beta\ln x) + \\ &C_{2m+1}x^{k_{2m+1}} + \cdots + C_nx^{k_n} \end{aligned}$$

例 1.1 试求解平面轴对称应力问题的相容方程

$$\rho^4\Phi^{(4)} + 2\rho^3\Phi^{(3)} - \rho^2\Phi'' + \rho\Phi' = 0$$

解 特征方程：

$$k(k-1)(k-2)(k-3) + 2k(k-1)(k-2) - k(k-1) + k = 0$$

解得：

$$k_{1,2} = 0, k_{3,4} = 2$$

得：

$$\Phi = A\ln\rho + B\rho^2\ln\rho + C\rho^2 + D$$