

### Problem 1

We have worked out the elementary vision of Lagrange multipliers, assuming that, from  $g(x, y) = 0$ , we can find a function  $y = h(x)$  such that  $g(x, h(x)) = 0$ .

But sometimes, what we get is that there is an  $h$  such that  $g(x, h(x)) = 0$ . Rewrite the Lagrange multiplier analysis in the lecture slides under this assumption.

Consider  $f, g : \mathbb{R}^2 \rightarrow \mathbb{R}$ , and the following minimization problem:

$$\min f(x, y) \quad \text{s.t.} \quad g(x, y) = 0 \quad (1)$$

Now, we can use the **implicit function theorem** to find a dependence between the variables of the restriction. This theorem (not completely formally) **states** the following: let  $g : \mathbb{R}^{n+m} \rightarrow \mathbb{R}^m$  be a continuously differentiable function,  $(x, y) \in \mathbb{R}^{n+m}$  such that  $g(x, y) = 0$ . If the jacobian with respect to the variables in  $y$  is invertible, then there exists an open subset  $U$  such that  $h(x) = y$  and  $g(x, h(x)) = 0$  for all  $x \in U$ .

Assuming that the **conditions for this theorem are matched**, we can apply it to the **jacobian with respect to the variables in  $y$**  to obtain an  $U'$  where  $h(y) = x$  and  $f(h(y), y) = 0$  for all  $y \in U'$ . Thus, we can write:

$$f(x, y) = f(h(y), y) = \psi(y)$$

The, we can keep the procedure as it is done in the slides. Let us see this:

Consider that  $y^*$  is a minimum with  $x^* = h(y^*)$ . Then, we have:

$$0 = \psi'(y^*) = \frac{\partial f}{\partial x}(x^*, y^*)h'(y^*) + \frac{\partial f}{\partial y}(x^*, y^*).$$

Using that  $(x^*, y^*)$  is a minimum and that  $g(h(y), y) = 0$ , we have that:

$$0 = \frac{\partial g}{\partial x}(x^*, y^*)h'(y^*) + \frac{\partial g}{\partial y}(x^*, y^*) \implies h'(y^*) = -\frac{\frac{\partial g}{\partial y}(x^*, y^*)}{\frac{\partial g}{\partial x}(x^*, y^*)}$$

### Problem 2

We want to solve the following constrained restriction problem:

$$\begin{aligned} \min \quad & x^2 + 2xy + 2y^2 - 3x + y \\ \text{s.t} \quad & x + y = 1 \\ & x, y \geq 0. \end{aligned}$$

Argue first that  $f$  is convex and then:

1. Write its Lagrangian with  $\alpha, \beta$  the multipliers of the inequality constraints.
2. Write the KKT conditions.
3. Use them to solve the problem. For this consider separately the  $(\alpha = \beta = 0)$ ,  $(\alpha > 0, \beta = 0)$ ,  $(\alpha = 0, \beta > 0)$ ,  $(\alpha > 0, \beta > 0)$  cases.

Let us first see that  $f$  is convex. We know that a characterization of convex functions is that they have a definite positive hessian matrix  $Hf$ . Firstly, we observe that the gradient of  $f$  is

$$\nabla f(x, y) = (2x + 2y - 3, 2x + 4y + 1).$$

Hence, the hessian of  $f$  is

$$Hf = \begin{pmatrix} 2 & 2 \\ 2 & 4 \end{pmatrix}$$

This matrix is positive definite, since it is Hermitian (it is real-valued and symmetric) and we can apply the **Sylvester's criterion** to see that all the minor determinants (which are 2 and 4) are positive. Hence,  $f$  is convex. Now, given that  $f$  is convex, we can make use of the **theorem** that states that if  $f, g_i \in C^1$  and convex, and  $h_j$  are affine, then a KKT point  $x^*$  is an optimum of the original problem. Since our problem matches these conditions, we will find the candidates to KKT points.

The **Lagrangian** of  $f$  in terms of  $\alpha, \beta, \lambda$  is:

$$L(x, y, \alpha, \beta, \lambda) = x^2 + 2xy + 2y^2 - 3x + y + \lambda(x + y - 1) + \alpha x + \beta y.$$

Now, to write the KKT conditions. As a very brief summarization, the KKT conditions are:

$$\begin{aligned} \nabla f(x^*) + \sum_i^m \lambda_i \nabla g_i(x^*) + \sum_j^p \mu_j \nabla h_j(x^*) &= 0, \\ \lambda_i g_i(x^*) &= 0 \end{aligned}$$

With  $\lambda_i \geq 0$ . If we apply them to our problem, **our KKT conditions** are:

$$\begin{aligned} 2x + 2y - 3 + \lambda + \alpha &= 0 \\ 2x + 4y + 1 + \lambda + \beta &= 0 \\ \alpha x &= 0 \\ \beta y &= 0 \end{aligned}$$

Now, we want to solve this equations system to see if we can find a minimum of our problem. We have the following cases:

- Case  $\alpha = \beta = 0$ .  
In this case, the system is

$$\begin{aligned} 2x + 2y - 3 + \lambda &= 0 \\ 2x + 4y + 1 + \lambda &= 0 \end{aligned}$$

If we substitute  $2x$  from the first equation into the second one, we obtain

$$-2y + 3 - \lambda + 4y + 1 + \lambda = 0 \implies 2y = 4 \implies y = 2,$$

and, since  $x + y = 1$ , we obtain that our *KKT point* is  $(-1, 2)$ . However, using this point in the first KKT condition, we obtain:  $-2 + 4 - 3 + \lambda = 0$ ,  $\lambda = -1$ , which is **not a valid value** for  $\lambda$ , so we **discard** this KKT point.

- Case  $\alpha, \beta > 0$ .  
In this case, we obtain from the KKT conditions that  $x = y = 0$ , which does not match our initial conditions  $x + y = 1$ , so no *KKT candidate points* are obtained.
- Case  $\alpha > 0, \beta = 0$ .  
Looking at our KKT conditions, since  $\alpha > 0$ , we have that  $x = 0$ , resulting in  $y = 1$  and a possible *KKT point*  $(0, 1)$ . If we use this point in the second KKT condition, we obtain  $0 + 4 + 1 + \lambda = 0$ ,  $\lambda = -5$ , which is not a valid value for  $\lambda$ , so we discard again this KKT point.
- Case  $\alpha = 0, \beta > 0$ .  
Using the same reasoning, we obtain  $(1, 0)$  as a possible *KKT point*. We check the  $\lambda$  condition using the first KKT condition:  $1 + 0 - 3 + \lambda = 0$ ,  $\lambda = 2$ , so we obtain a **KKT factible point**.

Since we have a **unique** candidate,  $(1, 0)$ , making use of the previously stated theorem, this point is the **minimum**, with a value of  $f(1, 0) = -2$ .

### Problem 3

Let  $f : S \subset \mathbb{R}^d \rightarrow \mathbb{R}$  be a convex function on the convex set  $S$  and we extend it to an  $\tilde{f} : \mathbb{R}^d \rightarrow \mathbb{R}$  as:

$$\tilde{f}(x) = \begin{cases} f(x) & \text{if } x \in S \\ +\infty & \text{if } x \notin S \end{cases}$$

Show that  $\tilde{f}$  is a convex function on  $\mathbb{R}^d$ . Assume that  $a + \infty = \infty$  and  $a \cdot \infty = \infty$  for  $a > 0$ .

Let  $x, x' \in \mathbb{R}^d$  and consider the segment  $\lambda x + (1 - \lambda)x'$  with  $\lambda \in [0, 1]$ . We can consider two cases:

1. If  $x, x' \in S$ , since  $S$  is convex,  $\lambda x + (1 - \lambda)x' \in S$  for any  $\lambda \in [0, 1]$ . Also, we know that in  $S$  we have  $f(x) = \tilde{f}(x)$  and the same happens for  $x'$ . Then, for any  $\lambda \in [0, 1]$ :

$$\tilde{f}(\lambda x + (1 - \lambda)x') = f(\lambda x + (1 - \lambda)x') \stackrel{(1)}{\leq} \lambda f(x) + (1 - \lambda)f(x') = \lambda \tilde{f}(x) + (1 - \lambda)\tilde{f}(x')$$

where, in (1) we have used the convexity of  $f$ .

2. If  $x \in S$  and  $x' \notin S$ , the convexity inequality is trivial since  $\tilde{f}(x') = +\infty$ , so, using that we assume that  $a \cdot +\infty = +\infty$ , we see that for any  $\lambda \in [0, 1]$

$$\tilde{f}(\lambda x + (1 - \lambda)x') \leq \lambda \tilde{f}(x) + (1 - \lambda)\tilde{f}(x') = +\infty$$

The case where  $x' \in S$  and  $x \notin S$  is analogous.

We have seen that the definition of convexity is fulfilled for any  $x, x' \in \mathbb{R}^d$ , so  $\tilde{f}$  is convex.

#### Problem 4

Prove **Jensen's inequality** : if  $f$  is convex on  $\mathbb{R}^d$  and  $\sum_{i=1}^k \lambda_i = 1$ , with  $0 \leq \lambda_i \leq 1$ , we have for any  $x_1, \dots, x_k \in \mathbb{R}^n$

$$f\left(\sum_{i=1}^k \lambda_i x_i\right) \leq \sum_{i=1}^k \lambda_i f(x_i)$$

Hint: just write  $\sum_{i=1}^k \lambda_i x_i = \lambda_1 x_1 + (1 - \lambda_1) v$  for an appropriate  $v$  and apply repeatedly the definition of a convex function. Start with  $k = 3$  and carry on.

#### Problem 5

Prove that the following function is convex

$$f(x) = \begin{cases} x^2 - 1 & |x| > 1 \\ 0 & |x| \leq 1 \end{cases}$$

and compute its proximal. Which are the fixed points of this proximal?