

# Chapter 03

# Processes

The programs in execution

# Outline

- ◆ Process Concept
- ◆ Process Scheduling
- ◆ Operations on Processes
- ◆ Interprocess Communication
- ◆ IPC in Shared-Memory Systems
- ◆ IPC in Message-Passing Systems

# Objectives

- ◆ Identify the separate components of a process and illustrate how they are represented and scheduled in an operating system.
- ◆ Describe how processes are created and terminated in an operating system, including developing programs using the appropriate system calls that perform these operations.
- ◆ Describe and contrast interprocess communication using shared memory and message passing.

# Process Concept

- ◆ An operating system executes a variety of programs:
  - Batch system – **jobs**
  - Time-shared systems – **user programs** or **tasks**
- ◆ Textbook uses the terms ***job*** and ***process*** almost interchangeably

# Process Concept (Cont.)

執行中的程式 → 程序

◆ **Process** – a program in execution; process execution must progress in **sequential fashion**

❑ Current activity including **program counter**, processor registers

❑ Multiple parts

● The executable code, also called **text section**

● **Data section** containing global variables (全域變數)

● **Heap** containing memory dynamically allocated during run time (低 → 高)

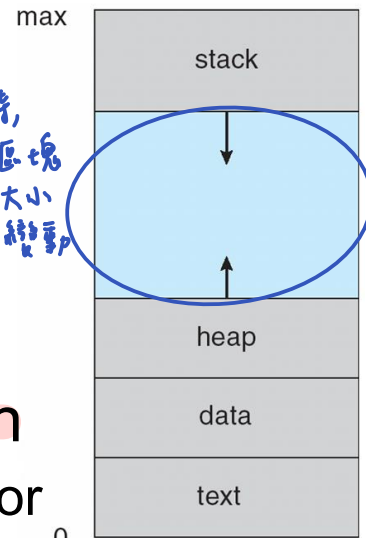
● **Stack** containing temporary data (高 → 低) 區域變數, return address

➤ **Activation record** (Function parameters, return addresses, local variables) pushed onto stack

❑ Fixed: Text and data section

❑ Dynamic: Heap and stack

● Do not overlapped under the control of OS



執行時，  
只有這一區塊  
記憶體大小  
會變動  
順序執行

執行程式碼 (可執行碼)

Process in Memory

# Process Concept (Cont.)

- ◆ Program is **passive** entity stored on disk (**executable file**), process is **active**
  - Program becomes process when executable file loaded into memory
- ◆ Execution of program started via GUI mouse clicks, command line entry of its name, etc
- ◆ One program can be several processes
  - Consider multiple users executing the same program
- ◆ Process as execution environment (Java as example)
  - **Java virtual machine (JVM)** as a process 程序也可以變成環境
  - Executable Java program is executed within JVM
  - E.g. run a java program Program.class by  
java Program

# Process Conce

## ◆ Memory Layout of a C Program

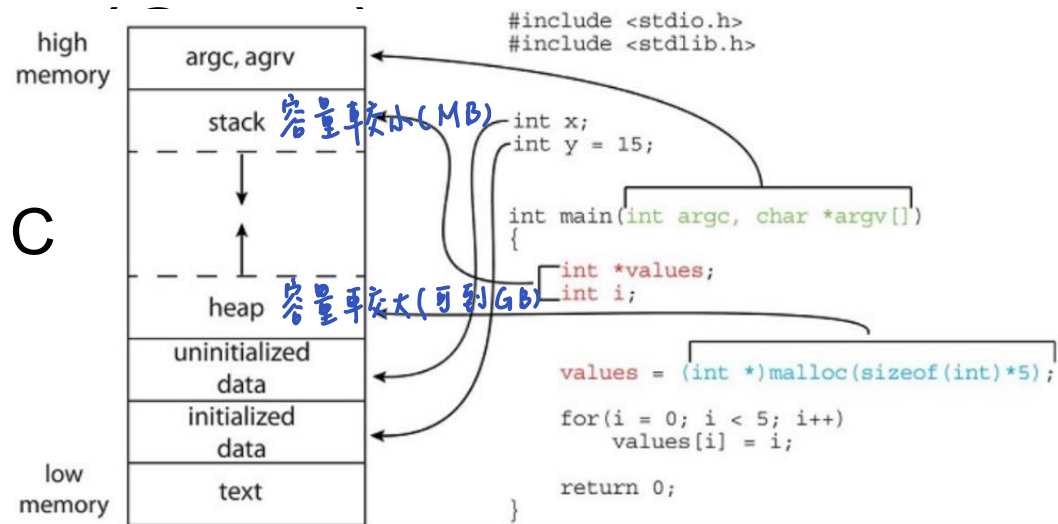
### □ Global data section

- Initialized data
- Uninitialized data

### □ Separate section for argc and argv

### □ GNU size command for determining the size. For example, size memory results in

text	data section		dec	hex	filename
1158	data	bss	1450	5aa	memory
	284	8			



# Exercises

- ◆ When a process creates a new process using the `fork()` operation, which of the following states is shared between the parent process and the child process?
- ☐ Stack
  - ☐ Heap
  - ☒ Shared memory segments
- } 每個程序獨自擁有



# Process State

- ◆ As a process executes, it changes **state**
  - ❑ **New**: The process is being created
  - ❑ **Running**: Instructions are being executed
  - ❑ **Waiting**: The process is waiting for some event to occur
  - ❑ **Ready**: The process is waiting to be assigned to a processor
  - ❑ **Terminated**: The process has finished execution

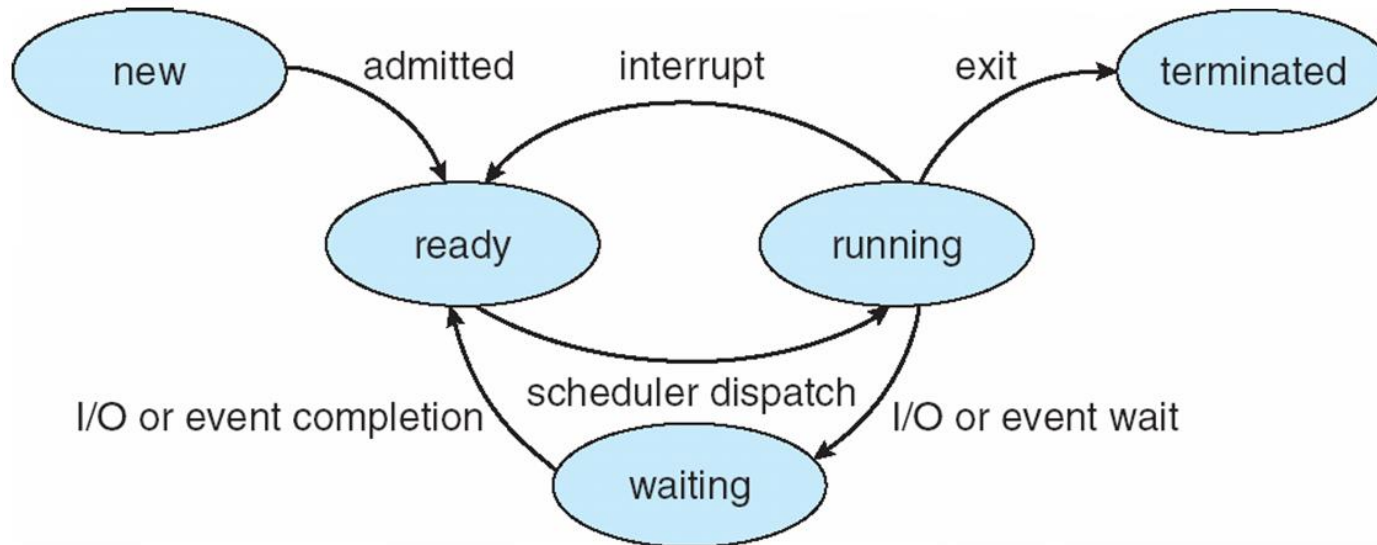


Diagram of Process State

# Process State

## Process State Changes

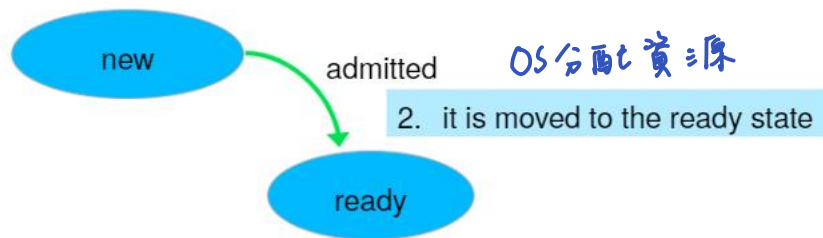


new

1. a new process is created

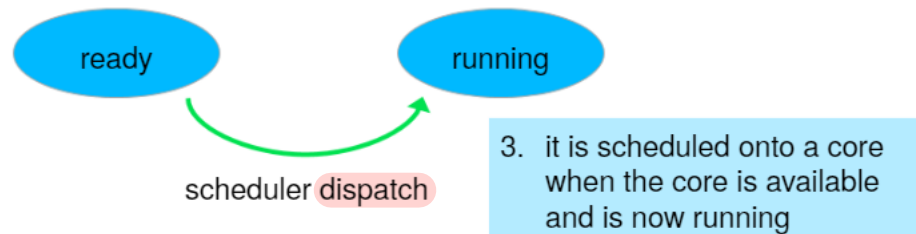
# Process State

## Process State Changes



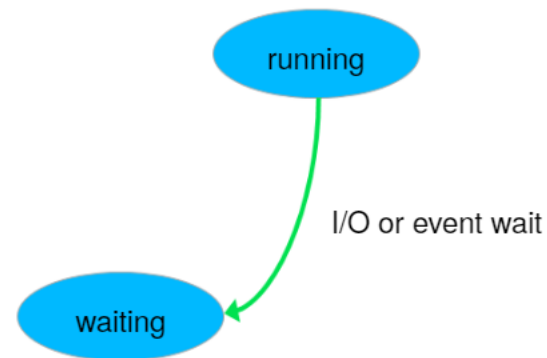
# Process State

## Process State Changes



# Process State

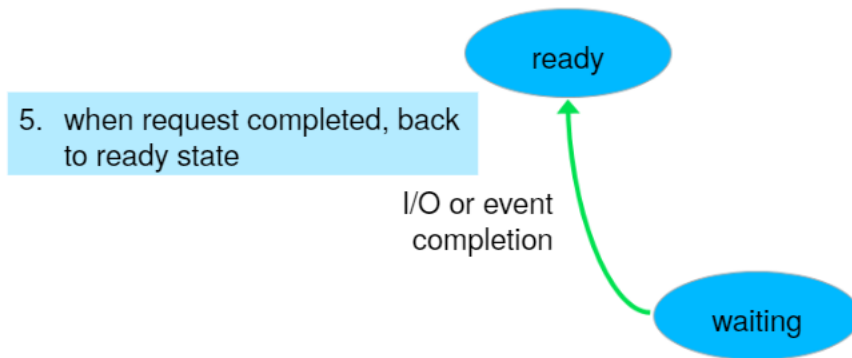
## Process State Changes



4. if an I/O request or event request occurs, moves to waiting state

# Process State

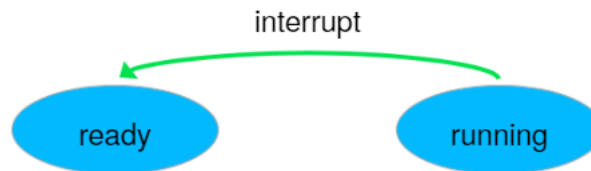
## Process State Changes



# Process State

## Process State Changes

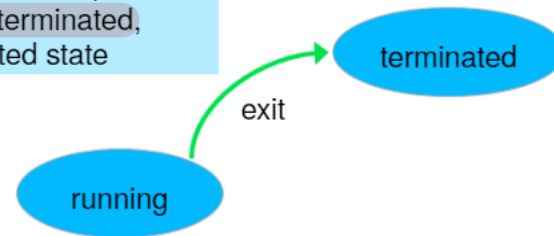
6. if running and the core is needed (say for an interrupt), back to the ready state



# Process State

## Process State Changes

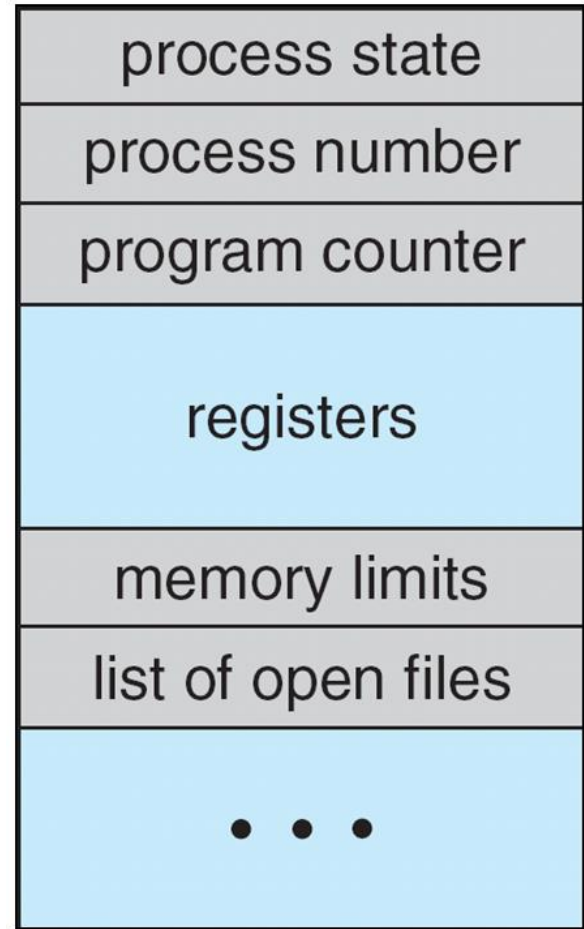
7. cycle continues until the process exists, fails, or is terminated, moves to terminated state





# Process Control Block (PCB)

- ◆ Information associated with each process
  - ❑ (also called **task control block**)
  - ❑ **Process state** – running, waiting, etc
  - ❑ **Program counter** – location of instruction to **next execute**
  - ❑ **CPU registers** – contents of all process-centric registers
  - ❑ **CPU scheduling information** – priorities, scheduling queue pointers
  - ❑ **Memory-management information** – memory allocated to the process
  - ❑ **Accounting information** – CPU used, clock time elapsed since start, time limits
  - ❑ **I/O status information** – I/O devices allocated to process, list of open files



# Threads (執行緒)

- ◆ So far, process has a single thread of execution
- ◆ Consider having multiple program counters per process
  - Multiple locations can execute at once
    - Multiple threads of control → threads
- ◆ Must then have storage for thread details, multiple program counters in PCB

# Exercise

- ◆ Some computer systems provide multiple register sets. Describe what happens when a context switch occurs if the new context is already loaded into one of the register sets. What happens if the new context is in memory rather than in a register set and all the register sets are in use? 程式切換

# Process Representation in Linux

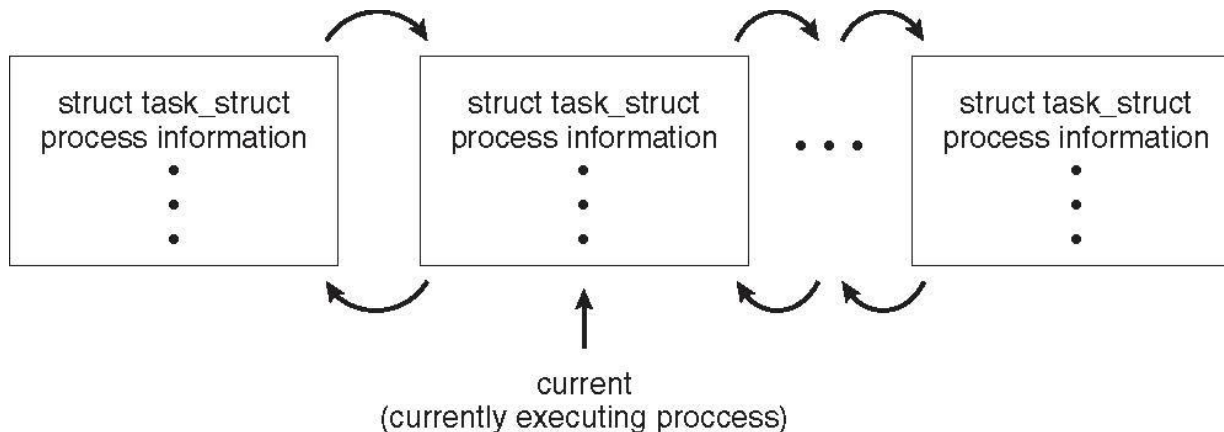
- ◆ Represented by the C structure `task_struct`:

```
pid_t pid; /* process identifier */
long state; /* state of the process */
unsigned int time_slice /* scheduling information */
struct task_struct *parent; /* this process's parent */
struct list_head children; /* this process's children */
struct files_struct *files; /* list of open files */
struct mm_struct *mm; /* address space of this process */
```

指向父程序  
(单一) →  
link list, 子程序  
(每个都有)

- ◆ Change a process's state by assigning the member of state a new value

```
current->state = new_state;
```



# Process Scheduling

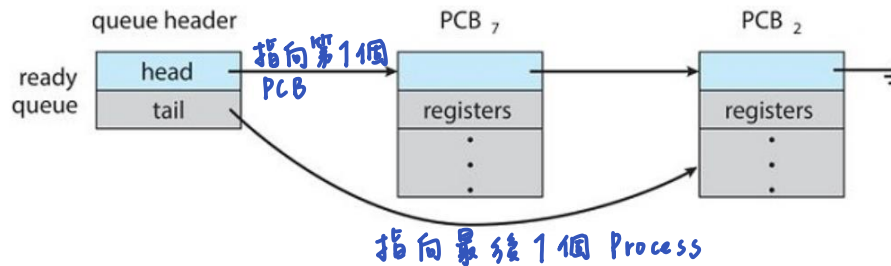
- ◆ Maximize CPU use, quickly switch processes onto CPU for time sharing
- ◆ Process scheduler selects among available processes for next execution on a core
  - Each CPU core for one process
- ◆ Degree of multiprogramming - the number of processes in memory 影響 CPU utilization
- ◆ Types of processes
  - I/O-bound process – more time on I/O
  - CPU-bound process – more time on computation

# Process Scheduling

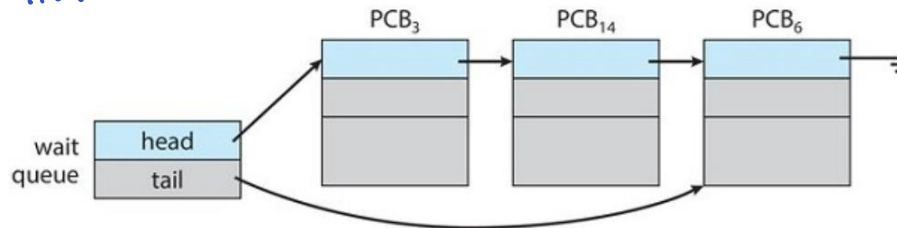
## ◆ Maintains **scheduling queues** of processes

□ **Ready queue** – set of all processes residing in main memory, ready and waiting to execute

- Stored in a linked list, header to first PCB



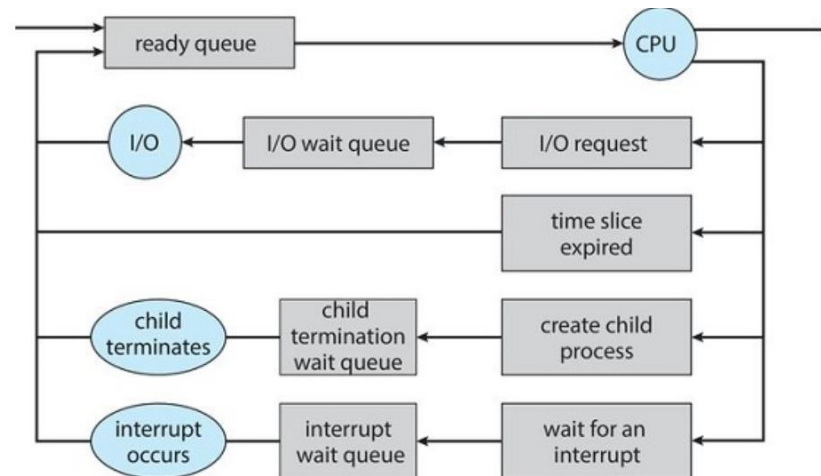
□ **Wait queue** – processes wait for event occur  
link list



# Process Scheduling

◆ **Queueing diagram** represents queues, resources, flows

- ❑ New process is put into ready queue until it is **dispatched**
- ❑ When executing, the process could
  - Issue an I/O request and go to I/O wait queue
  - Create a child process and go to wait queue
  - Be removed forcibly due to interrupt or expiring time slice
- ❑ Remove from all queues when process terminated
  - Deallocate resources and PCB



# Process Scheduling

## ◆ CPU Scheduling

- CPU scheduler selects from among the processes that are in the ready queue and allocate a CPU core to one of them
- Frequently executes
  - Every 100 milliseconds or more
- Intermediate scheduling
  - A.k.a. swapping
  - Remove a process from memory to reduce the degree of multiprogramming, and re-enter into memory later
  - Necessary when memory is overcommitted



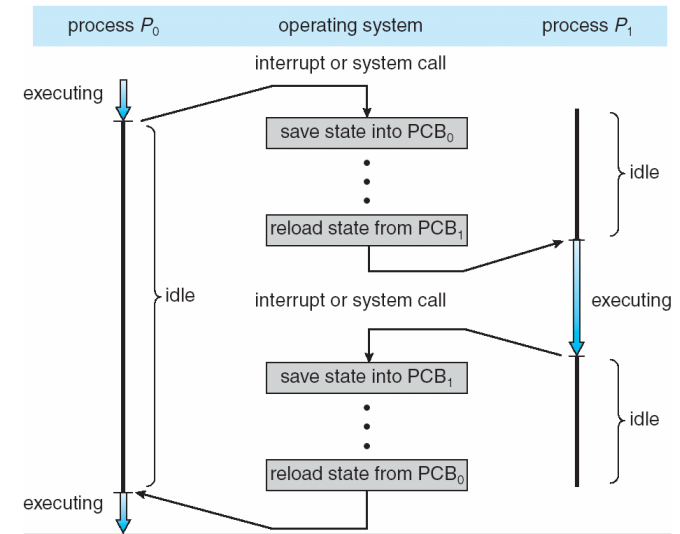
# Process Scheduling

程序間進行切换

## ◆ Context Switch

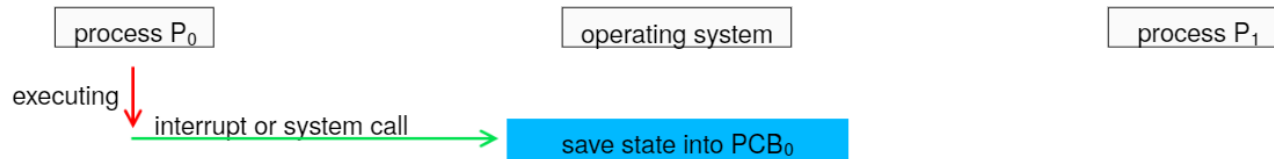
- ❑ When CPU switches to another process, the system must **save the context** of the old process and load the **saved context** for the new process via a **context switch**
- ❑ **Context** of a process represented in the PCB
  - Value of CPU registers, process state, memory-management information
- ❑ **State save** of the current state, and **state restore** to resume operations
- ❑ Time dependent on **hardware support**
  - Some hardware provides multiple sets of registers per CPU → multiple contexts loaded at once
- ❑ Context-switch time is overhead; the system does no useful work while switching
  - The more complex the OS and the PCB → the longer the context switch

如果 Context-switch 太频繁, ⇒ CPU utilization ↓



# Process Scheduling

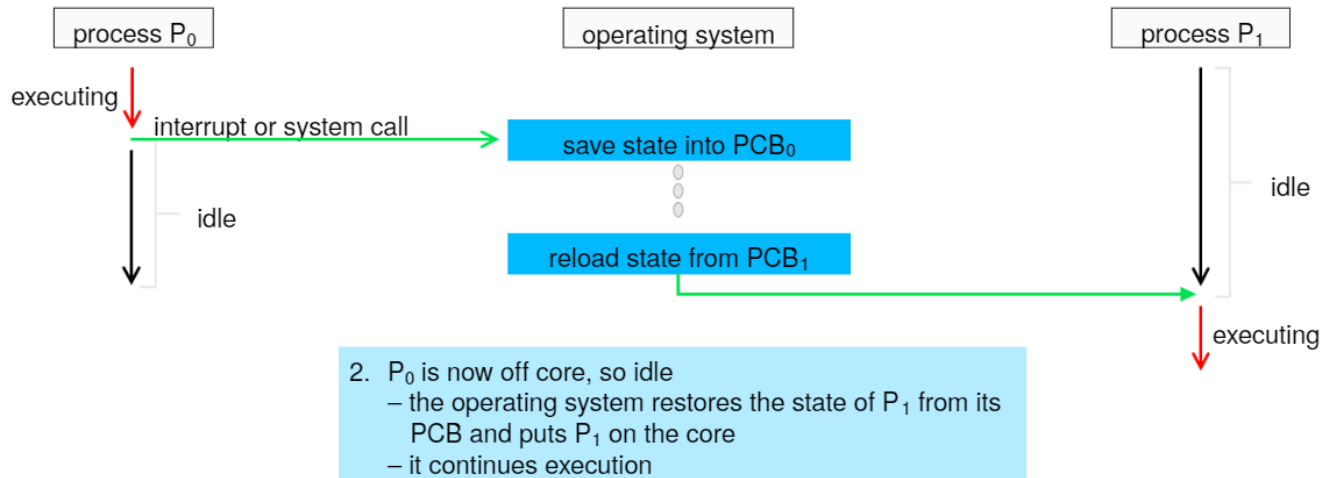
## Context Switch from Process to Process



1. the system has two processes,  $P_0$  and  $P_1$ 
  - $P_1$  is idle,  $P_0$  is executing and executes a system call, or the system receives an interrupt
  - the operating system saves the state of  $P_0$  in its PCB

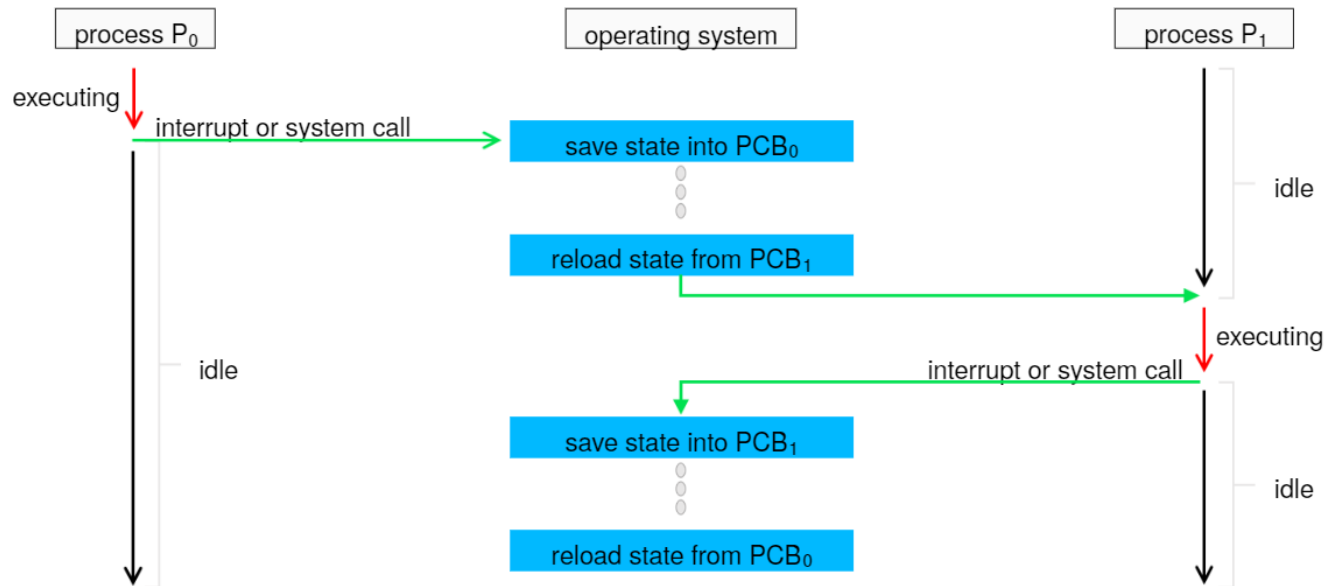
# Process Scheduling

## Context Switch from Process to Process



# Process Scheduling

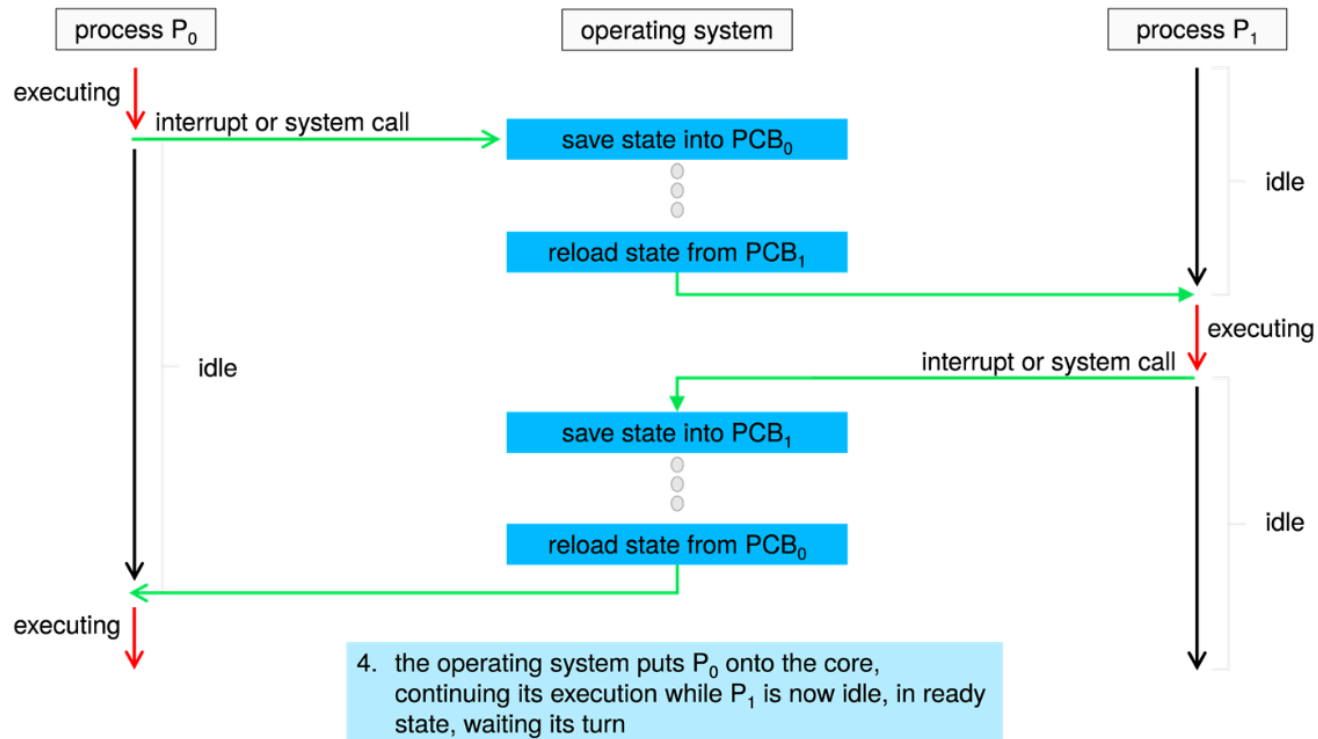
## Context Switch from Process to Process



3. P<sub>1</sub> execution is interrupted, the operating system saves its state to its PCB and restores the next process's state (P<sub>0</sub> in this case) to prepare it to continue execution

# Process Scheduling

## Context Switch from Process to Process



# Process Scheduling

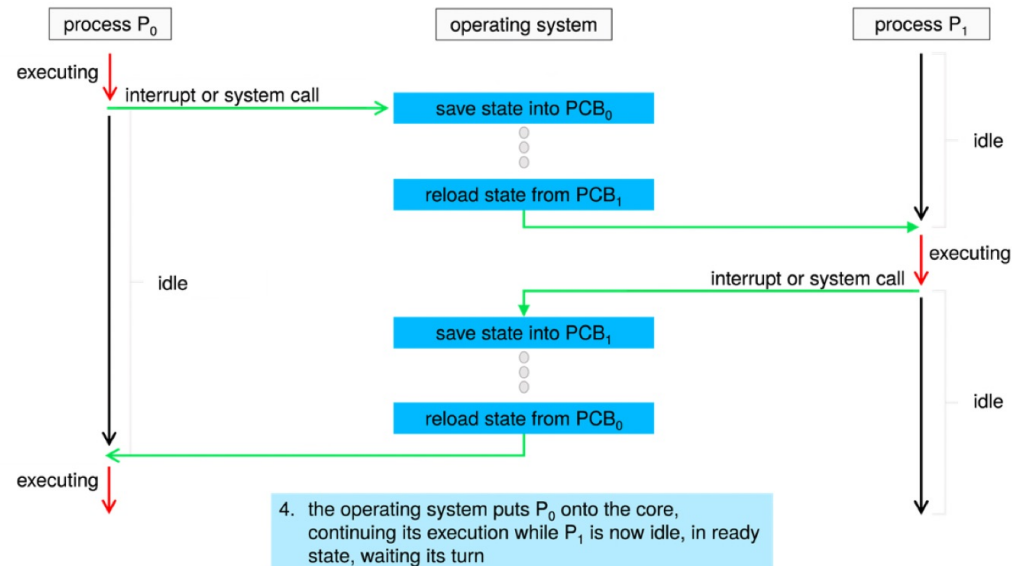
## ◆ Multitasking in Mobile Systems

- ❑ Some mobile systems (e.g., early version of iOS) allow only one process to run, others suspended
- ❑ Due to screen real estate, user interface limits iOS provides for
  - Single foreground process- controlled via user interface
  - Multiple background processes– in memory, running, but not on the display, and with limits
  - Limits include single, short task, receiving notification of events, specific long-running tasks like audio playback
  - Fewer restrictions as the hardware progress. For example, the iPad tablets allow split-screen – running two foreground apps at a time
- ❑ Android runs foreground and background, with fewer limits
  - Background process uses a service to perform tasks
  - Service can keep running even if background process is suspended
  - Service has no user interface, small memory use

# Exercise

- ◆ Describe the actions taken by a kernel to context-switch between processes.

## Context Switch from Process to Process



# Operations on Processes

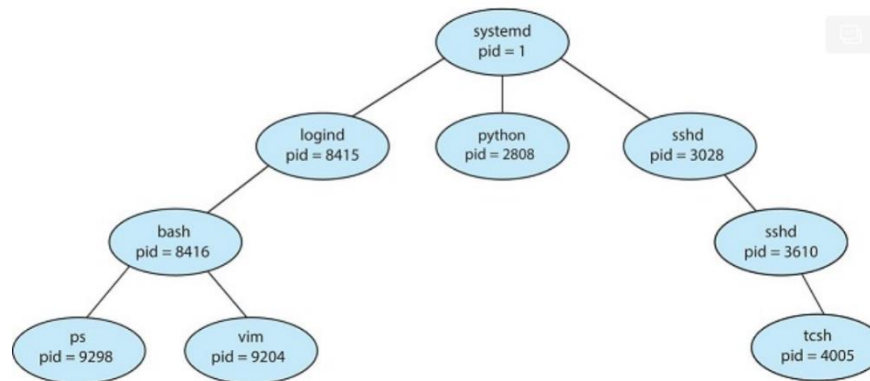
- ◆ System must provide mechanisms for:
  - Process creation
  - Process termination
  - ...



# Operations on Processes

## ◆ Process Creation

- Parent process create children processes, which, in turn create other processes, forming a tree of processes
- Generally, process identified and managed via a process identifier (pid)
  - Using command `ps` for listing processes in UNIX and Linux:  
`ps -el`
  - Linux provide `pstree` command



# Operations on Processes

## ❑ Resource sharing options

- Parent and children share **all** resources 全部
- Children share **subset** of parent's resources 部分
- Parent and child share **no** resources 沒有

## ❑ Pass input from parent to child process

## ❑ Execution options

- Parent and children execute **concurrently**
- Parent **waits** until children terminate

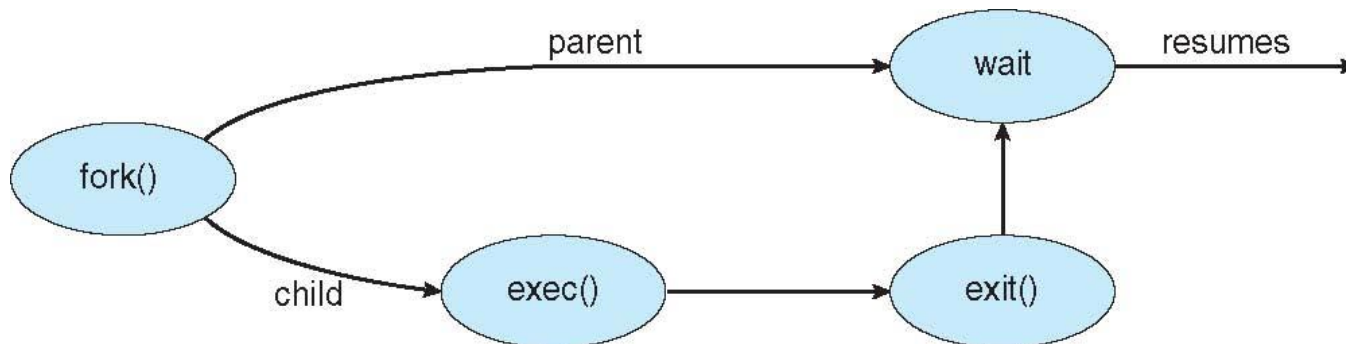
## ❑ Address space options

- Child **duplicate** of parent
- Child has a **program** loaded into it

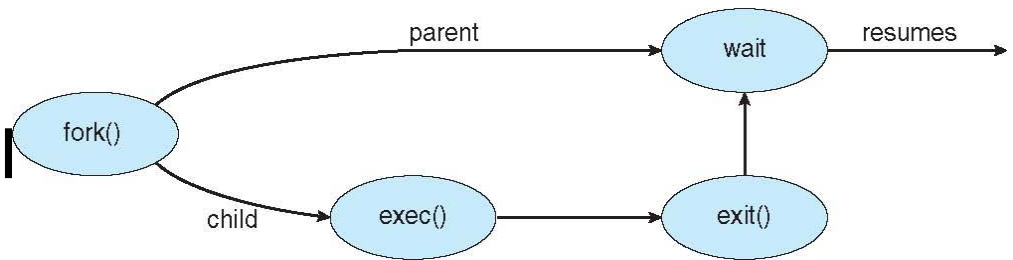
# Operations on Processes

## □ UNIX Example

- Process identifier pid for each process
- **fork()** system call creates new process 判斷是否是 child process
  - Both parent and child processes run concurrently
  - Return child's pid for parent process { 0 , child process
  - Return 0 for the child process { child's pid, parent process
- **exec()** system call used after a **fork()** to replace the process' memory space with a new program
  - Loads executable file into memory and starts execution
  - Parent process can do something or just wait by **wait()**
  - Does not return until an error occurs



# Operations on Pr



## □ UNIX Example

- **fork()** creates child process
  - pid < 0: error
  - pid = 0: child
  - pid > 0: parent
- Child inherits from parent
  - Privileges and scheduling attributes
  - Resources
- **execvp()** runs a UNIX command
  - A version of **exec()**
- **wait()** lets parent wait child process to terminate

```
#include <sys/types.h>
#include <stdio.h>
#include <unistd.h>
```

```
int main()
{
    pid_t pid;
```

```
    /* fork a child process */
    pid = fork(); 產生 child process

    if (pid < 0) { /* error occurred */
        fprintf(stderr, "Fork Failed");
        return 1;
    }
    else if (pid == 0) { /* child process */
        execvp("/bin/ls", "ls", NULL);
    } exec
    else { /* parent process */
        /* parent will wait for the child to complete */
        wait(NULL);
        printf("Child Complete");
    }
```

```
    return 0;
```

```
}
```

C Program Forking Separate Process

# Exercise

- ◆ Including the initial parent process, how many processes are created by the program shown below?

```
#include <stdio.h>
```

```
#include <unistd.h>
```

```
int main() {
```

```
for (int i = 0; i < 4; i++) fork();
```

```
return 0;
```

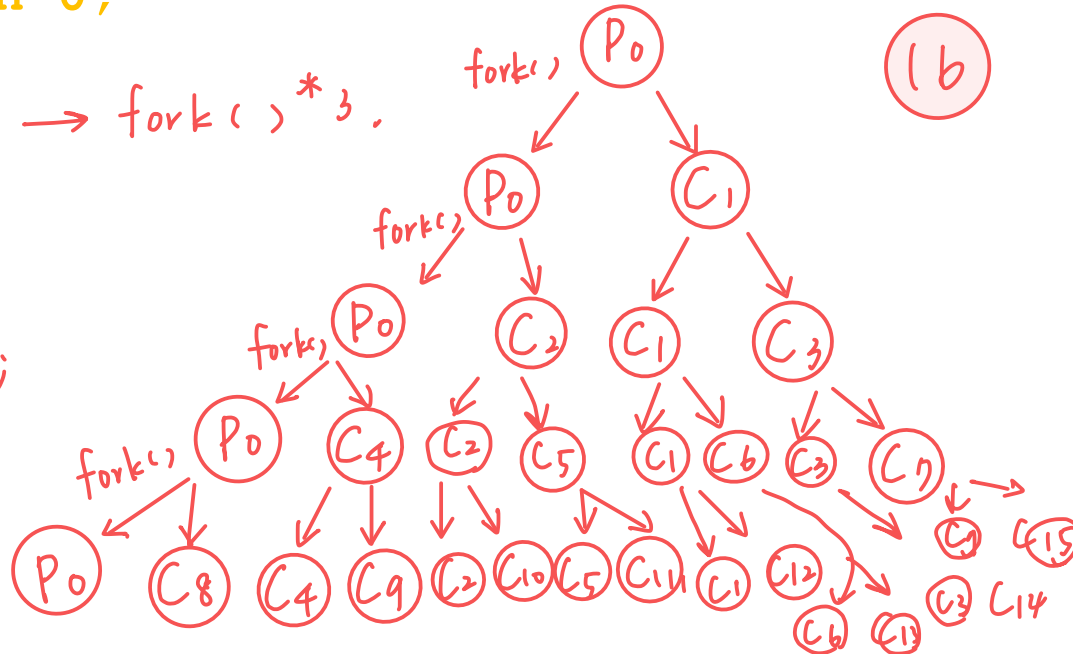
}

$\text{fork}(\quad); \rightarrow \text{fork}(\quad)^*3.$

```
for k ( );
```

```
for k ( );
```

```
for k ( );
```



# Operations on Processes

## ◆ Process Termination

- ❑ Process executes last statement and then asks the operating system to delete it using the **exit()** system call.
  - Returns status data from child to parent (via **wait()**)
  - Process' resources are deallocated by operating system
- ❑ Parent may terminate the execution of children processes using proper system call.
  - **TerminateProcess()** in Windows
  - **abort()** in UNIX
  - Need to know the process identifiers to be terminated

# More Exercises

- ◆ Explain the circumstances under which the line of code marked `printf("LINE J");` will be reached.

```
#include <sys/types.h>
#include <stdio.h>
#include <unistd.h>
int main() {
    pid_t pid;
    pid = fork(); //fork a child process
    if (pid < 0) { //error occurred
        fprintf(stderr, "Fork Failed");
        return 1;
    }
    else if (pid == 0) { //child process
        execlp("/bin/ls", "ls", NULL); → TRUE, 永遠不會 print "LINE J"
        printf("LINE J"); → Error message
    }
    else { //parent process
        wait(NULL); // parent waits for child
        complete
        printf("Child Complete");
    }
}
```

# Operations on Processes

- ❑ Some reasons for doing so:
  - Child has exceeded allocated resources
  - Task assigned to child is no longer required
  - The parent is exiting and the operating systems does not allow a child to continue if its parent terminates
- ❑ Some operating systems do not allow child to exists if its parent has terminated. *OS 不允許沒有父程序之子程序.*
  - If a process terminates, then all its children must also be terminated. This is known as **cascading termination**.
  - The termination is initiated by the operating system.
- ❑ Terminate via **exit()** system call
  - **exit(1)**: exit with status 1
  - Called directly or indirectly



# Operations on Processes

- ❑ The parent process may wait for termination of a child process by using the `wait()` system call. The call returns status information and the pid of the terminated process

```
pid_t pid;  
int status;  
pid = wait(&status);
```

- ❑ If no parent waiting (did not invoke `wait()`) process is a **zombie** 僵屍

- Only exists briefly

- ❑ If parent terminated without invoking `wait`, process is an **orphan** 孤兒

作為  
parent

- `init` (root of UNIX system) as the new parent in UNIX
- `systemd` or other processes in Linux systems

# Exercise

- ◆ Explain the role of the **init** (or **systemd**) process on UNIX and Linux systems in regard to process termination.

**init** (root of UNIX system) as the new parent in UNIX  
**systemd** or other processes in Linux systems

# Operations on Processes

## ◆ Android Process Hierarchy

- ❑ Terminate process to **reclaim memory** due to resource constraints
- ❑ According to importance hierarchy in increasing order
- ❑ From most to least important processes are
  - **Foreground process**—The process the user is currently interacting with and visible on the screen
  - **Visible process**—The process not directly visible but performing an activity referred to the foreground process
  - **Service process**—A process running on the background with apparent activity to the user
    - E.g. streaming music
  - **Background process**—A process performing an activity not apparent to the user.
  - **Empty process**—A process holding no active components
- ❑ Assign as high rank as possible

高  
易  
中  
止

高



# Interprocess Communication

- ◆ Processes within a system may be ***independent*** or ***cooperating***
- ◆ Cooperating process can affect or be affected by other processes, including sharing data
- ◆ Reasons for cooperating processes:
  - Information sharing *ex, copy and paste.*
  - Computation speedup *工作分割*
  - Modularity *模組化*

# Interprocess Communication

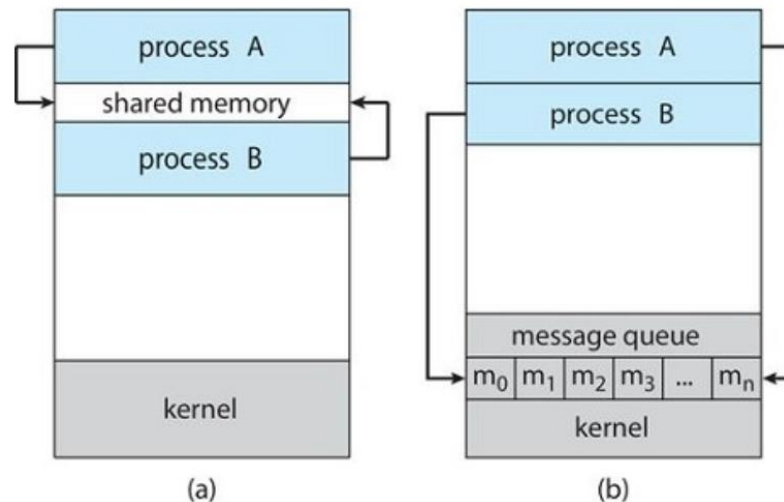
## ◆ Cooperating processes need **interprocess communication (IPC)** with two models

### □ **Shared memory** – read / write to shared memory

- Faster due to shared-memory regions
- No kernel intervention for memory accesses 不用透過 kernel

### □ **Message passing**

- Exchange small data due to no conflict 不用注意同步的問題
- Easy to implement 容易實作




# IPC in Shared-Memory Systems

- ◆ Shared memory requires that two or more processes agree to remove the constraint of accessing another process's memory.
- ◆ **Producer-Consumer Problem** (生產者 V.s. 消費者)
  - Paradigm for cooperating processes, *producer* process produces information that is consumed by a *consumer* process
  - Must have a buffer of items filled by producer and emptied by consumer
    - Need to **synchronize** for using item before filling it
    - **Unbounded-buffer** places **no practical limit on the size of the buffer**: Continue producing without waiting consuming 不限制緩存大小
    - **Bounded-buffer** assumes that there is a fixed buffer size: Producer should wait for consuming 限制緩存大小

# IPC in Shared-Memory Systems

## ◆ Bounded-Buffer – Shared-Memory Solution

### □ Shared data

```
#define BUFFER_SIZE 10
typedef struct {
    . . .  Consumer 消費 item
} item;
```

```
item buffer[BUFFER_SIZE];
```

```
int in = 0; 生產
```

```
int out = 0; 消費
```

### □ Solution is correct, but can only use BUFFER\_SIZE-1 elements

- **Empty** if `in == out`

- **Full** if `((in + 1) % BUFFER_SIZE) == out`

# IPC in Shared-Memory Systems

## ◆ Bounded-Buffer – Producer *產生 item*

```
item next_produced;
while (true) {
    /* produce an item in next produced */
    while (((in + 1) % BUFFER_SIZE) == out)
        ; /* do nothing */
    buffer[in] = next_produced;
    in = (in + 1) % BUFFER_SIZE;
}
```



# IPC in Shared-Memory Systems

## ◆ Bounded-Buffer – Consumer 使用 item

```
item next_consumed;
while (true) {
    while (in == out)
        ; /* do nothing */
    next_consumed = buffer[out];
    out = (out + 1) % BUFFER_SIZE;

    /* consume the item in next consumed */
}
```

# IPC in Shared-Memory Systems

- ◆ An area of memory shared among the processes that wish to communicate
- ◆ The communication is under the control of the users processes not the operating system.
- ◆ Major issues is to provide mechanism that will allow the user processes to synchronize their actions when they access shared memory.

# IPC in Message-Passing Systems

- ◆ Mechanism for processes to **communicate** and to synchronize their actions
- ◆ Message system – processes communicate with each other without resorting to shared variables
  - Useful in **distributed system**
  - E.g. internet chat room
- ◆ Message-passing facility provides two operations:
  - **send(message)**
  - **receive(message)**
- ◆ The message size is either
  - **Fixed**: easy for system implementation but difficult to programming, or
  - **Variable**: easy for programming but require more complex system implementation

# IPC in Message-Passing Systems

- ◆ If processes P and Q wish to communicate, they need to:

使用 send & receive

- Establish a communication link between them
- Exchange messages via send/receive

- ◆ Implementation issues

- Physical

- Shared memory
- Hardware bus
- Network

- Logical

- Direct or indirect communication
- Synchronous or asynchronous communication
- Automatic or explicit buffering

# IPC in Message-Passing Systems

## ◆ Naming

- Communication can be direct or indirect

- Direct communication

- Processes must name each other explicitly:

- **send** (*P*, *message*) – send a message to process *P*

- **receive**(*Q*, *message*) – receive a message from process *Q*

- Properties of communication link

- Links are established automatically

- A link is associated with exactly one pair of communicating processes

- Between each pair there exists exactly one link

- **Symmetry** in addressing- sender process and receiver process must name the other.

# IPC in Message-Passing Systems

- **Asymmetry** in addressing- only the sender names the recipient
- Processes for communication are
  - `send(P, message)` —Send a message to process P
  - `receive(id, message)` —Receive a message from any process
- Disadvantages of direct communication
  - Limited **modularity** due to the use of **hard-coding** techniques
  - Need to check all process definitions when changing the identifier of one process

↘ 不對稱只有這種傳輸方式!!

{ 傳送資訊給特定的人  
  不限制資訊來源(來者不拒)

# IPC in Message-Passing Systems

## □ Indirect Communication

- Messages are directed and received from **mailboxes** (also referred to as **ports**) 埠 號
  - Each mailbox has a unique id
  - Processes can communicate only if they **share a mailbox**
- Primitives are defined as:
  - **send**(*A, message*) – send a message to mailbox A
  - **receive**(*A, message*) – receive a message from mailbox A
- Properties of communication link
  - Link established only if processes share a common mailbox
  - A link may be associated with many processes
  - Each pair of processes may **share several communication links**
  - Link may be unidirectional or bi-directional

# IPC in Message-Passing Systems

- Mailbox sharing
  - $P_1$ ,  $P_2$ , and  $P_3$  share mailbox A
  - $P_1$  sends;  $P_2$  and  $P_3$  receive
  - Who gets the message?
- Solutions
  - Allow a link to be associated with at most two processes
  - Allow only one process at a time to execute a receive operation
  - Allow the system to select arbitrarily the receiver. Sender is notified who the receiver was.



# IPC in Message-Passing Systems

- A mailbox may be owned either by a **process** or by the **operating system**.
- Owned by **process**
  - Owner: receive messages
  - User: send messages
  - Disappear when owner process terminates
- Owned by **operating system**
  - Independent to process
  - Allow process to do 主動建立與移除 mailbox
    - ✓ Create a new mailbox (port)
    - ✓ Send and receive messages through mailbox
    - ✓ Destroy a mailbox
  - Ownership
    - ✓ Creator
    - ✓ Pass to other processes through proper system calls

# IPC in Message-Passing Systems

## ◆ Synchronization

□ Message passing may be either blocking or non-blocking

□ **Blocking** is considered **synchronous**

- Blocking send -- the sender is blocked until the message is received
- Blocking receive -- the receiver is blocked until a message is available

□ **Non-blocking** is considered **asynchronous**

- Non-blocking send -- the sender sends the message and continue
- Non-blocking receive -- the receiver receives:
  - A valid message, or
  - Null message

# IPC in Message-Passing Systems

## □ Different combinations possible

會合

- If both send and receive are blocking, we have a rendezvous

- Producer

```
message next_produced;  
while (true) {  
    /* produce an item in next_produced */  
    send(next_produced);  
}
```

- Consumer

```
message next_consumed;  
while (true) {  
    receive(next_consumed);  
    /* consume the item in next_consumed */  
}
```

# IPC in Message-Passing Systems

## ◆ Buffering

- ❑ Queue of messages attached to the link.
- ❑ implemented in one of three ways
  1. **Zero capacity** – no messages are queued on a link.  
Sender must wait for receiver (rendezvous)
  2. **Bounded capacity** – finite length of  $n$  messages  
Sender must wait if link full 空間固定
  3. **Unbounded capacity** – infinite length  
Sender never waits
- ❑ Zero capacity is known as no buffering
- ❑ Bounded or unbounded capacity as automatic buffering

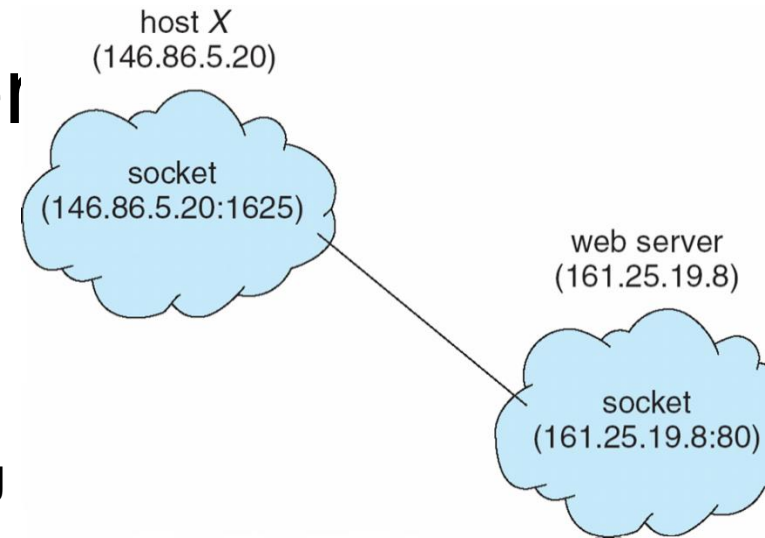
# Communications in Client-Server Systems

- ◆ Shared Memory
- ◆ Message Passing
- ◆ **Sockets**
- ◆ **Remote Procedure Calls**

# Communications in Client Systems

## ◆ Sockets

- ❑ An endpoint for communication
  - A pair of sockets for communicating processes
- ❑ Concatenation of IP address and **port** – a number included at start of message packet to differentiate network services on a host
  - Socket **161.25.19.8:1625** == port **1625** on host **161.25.19.8**
- ❑ Client–server architecture: server waits clients by listening to a specified port.
- ❑ All ports below 1024 are **well known**, used for standard services for server
  - E.g. port 22 for SSH, port 21 for FTP, port 80 for HTTP
- ❑ Clients use **arbitrary** port number greater than 1024.



# Communications in Client-Server Systems

- ❑ Special IP address 127.0.0.1 (**loopback**) to refer to system on which process is running
  - Allow communication between client and server on the same machine
- ❑ Common and efficient
- ❑ Low-level communication
  - Only allow **unstructured** stream of bytes
  - Structure on data should be imposed by client or server

# Remote Procedure Calls

- ◆ Remote procedure call (RPC) abstracts procedure calls between processes on networked systems
  - Again uses **ports** for service differentiation
- ◆ **Stubs**
  - Client-side proxy for the actual procedure on the server
  - The client-side stub locates the server and **marshals** the parameters
  - The server-side stub receives this message, unpacks the marshalled parameters, and performs the procedure on the server



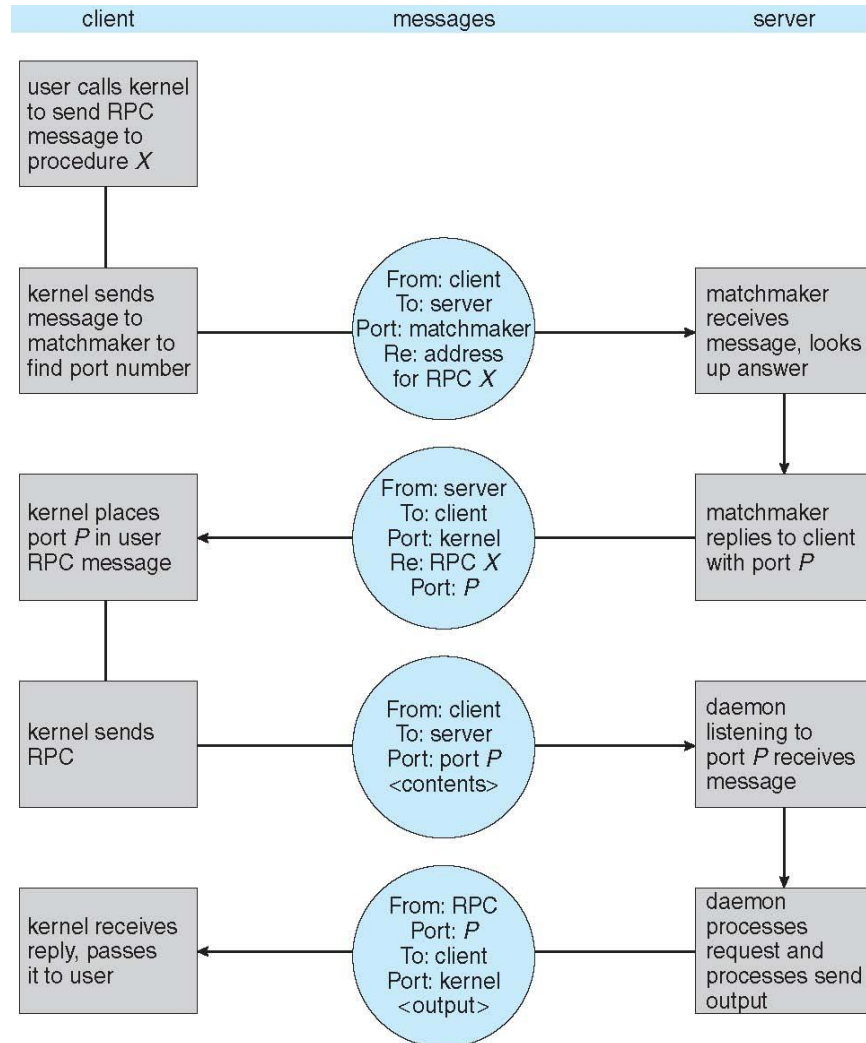
# Remote Procedure Calls

- ◆ Data representation handled via **External Data Representation (XDR)** format to account for different architectures
  - **Big-endian** and **little-endian**
  - Client-side parameter marshaling involves converting machine-dependent data into XDR.
- ◆ Remote communication has more failure scenarios than local
  - Due to duplication or more than once execution
  - Ensure messages are delivered ***exactly once*** rather than ***at most once***
    - ***At most once***: attaching a timestamp to each message
    - ***Exactly once***: use at most once with acknowledge mechanism (ACK messages)

# Remote Procedure Calls

- ◆ The RPC scheme requires a binding of the client and the server port. But how?
- ◆ Two approaches:
  - **Statically** bind by fixed port address
    - An RPC call has a fixed port number
  - **Dynamically** bind by rendezvous mechanism
    - OS typically provides a rendezvous (or **matchmaker**) service to connect client and server
    - Rendezvous service on a fixed RPC port
    - Client sends request to rendezvous daemon for port address of RPC
    - Overhead of the initial request but more flexible

# Remote Procedure Calls



Execution of RPC