TRACEBOT

(End-User) Auto-Generated Audit Trail
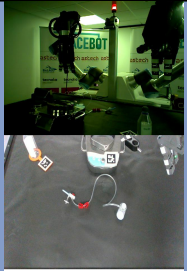
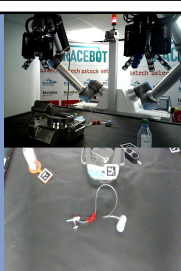**Episode** : Inserting Canister Into Drain Tray And Needle Into Bottle

Duration : 09.12.2024, 23:59:41 - 10.12.2024, 00:01:31

Status : Failed / --[Successful]-- / Interrupted / Pending

Confidence : 96.83%

Action Designator	Executive Module	Participants	Execution Timeslot	Status	Confidence Level	Verbal Explanation	Non-verbal Explanation	Recovery Explanation
Fitting Insertable Into Insertee	*Planning ; Reasoning ; Perception ; Manipulation*	PatientRole YULCZXKS: Canister XBYIDRWN; DestinationRole XTIOYCKN: DrainTray LNBKXVFU; ActorRole YITDQJVU: RightRobotGripper@CEA SXTYCNUB;	09.12.2024, 23:59:41 - 10.12.2024, 00:01:31	Successful	96.83%	*All constitutive subactions were successful. Also,, All constitutive subactions were feasible*		*Nothing to recover*

1. Parking Arms	*Manipulation*	ActorRole HBRPWFGL: RightRobotGripper@CEA VGYEITJD; ActorRole YQSUBIVD: LeftRobotGripper@CEA WBSQGCKI; SensorRole NPORMGKH: SceneRobotCamera@435D BUMCYNKE;	09.12.2024, 23:59:42 - 09.12.2024, 23:59:42	**Successful**	99.57%	*This action is feasible*		*Nothing to recover*
2. Traceable Locating	*Reasoning ; Perception*	StimulusRole PMGEYCUQ: Canister USVKHJTN; SensorRole FTREGVZC: HeadRobotCamera@435D DTEKVSUJ;	09.12.2024, 23:59:47 - 09.12.2024, 23:59:56	**Successful**	98.95%	*All constitutive subactions were successful. Also,, The imagination of the detected objects at the given pose produce the same image as the bounded real image.. Also,, All constitutive subactions were feasible*		*Nothing to recover*
2.1. Verifying Pose	*Reasoning*	Robot@TraceBot	09.12.2024, 23:59:47 - 09.12.2024, 23:59:49	**Successful**	99.27%	*This action is feasible*		*Nothing to recover*
3. Traceable Picking Up	*Manipulation*	PatientRole ESQDGMNW: Canister QHWLFKRC; ActorRole JSQKLDTF: RightRobotGripper@CEA DHJQPXRO;	10.12.2024, 00:00:02 - 10.12.2024, 00:00:08	**Successful**	99.18%	*All constitutive subactions were successful. Additionally, All constitutive subactions were feasible*		*Nothing to recover*

3.1. Holding	*Manipulation*	PatientRole LYHGSNUD: Canister JXQHWVRI; ActorRole BHFNJRDI: RightRobotGripper@CEA CILUKYMJ;	10.12.2024, 00:00:02 - 10.12.2024, 00:00:02	**Successful**	99.83%	*This action is feasible*		*Nothing to recover*
4. Traceable Locating	*Reasoning ; Perception*	Robot@TraceBot	10.12.2024, 00:00:13 - 10.12.2024, 00:00:21	**Successful**	98.87%	*All constitutive subactions were successful. Furthermore, The imagination of the detected objects at the given pose produce the same image as the bounded real image.. Also,, The imagination of the detected objects at the given pose produce the same image as the bounded real image.. Also,, All constitutive subactions were feasible*		*Nothing to recover*
4.1. Verifying Pose	*Reasoning*	Robot@TraceBot	10.12.2024, 00:00:13 - 10.12.2024, 00:00:15	**Successful**	99.48%	*This action is feasible*		*Nothing to recover*
5. Traceable Inserting	*Planning ; Reasoning ; Manipulation*	Robot@TraceBot	10.12.2024, 00:00:29 - 10.12.2024, 00:01:13	**Successful**	98.23%	*All constitutive subactions were successful. Additionally, The location of the inserted object matches with the pose of the destination insertee.. Additionally, All constitutive subactions were feasible*		*Nothing to recover*

5.1. Planning Insertion	*Reasoning ; Planning*	Robot@TraceBot	10.12.2024, 00:00:29 - 10.12.2024, 00:00:31	**Successful**	99.71%	*This action is feasible*		*Nothing to recover*
5.2. Pushing	*Manipulation*	PatientRole FBZKOUWH: Needle QJGPMKFC; ActorRole QCKGNYUH: LeftRobotGripper@CEA OPBUKWRE; DestinationRole BQUMTGJP: RinseBottleA NRHGXBQC;	10.12.2024, 00:00:36 - 10.12.2024, 00:00:40	**Successful**	99.43%	*This action is feasible*		*Nothing to recover*
5.3. Orienting	*Manipulation*	Robot@TraceBot	10.12.2024, 00:00:51 - 10.12.2024, 00:00:52	**Successful**	99.18%	*This action is feasible*		*Nothing to recover*
5.4. Releasing	*Manipulation*	Robot@TraceBot	10.12.2024, 00:00:57 - 10.12.2024, 00:00:58	**Successful**	99.76%	*This action is feasible*		*Nothing to recover*

5.5. Retracting	Manipulation	Robot@TraceBot	10.12.2024, 00:01:03 - 10.12.2024, 00:01:05	**Successful**	99.74%	*This action is feasible*		*Nothing to recover*