



(End-User) Auto-Generated Audit Trail

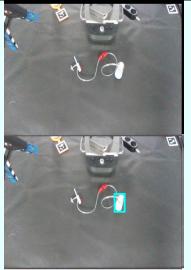
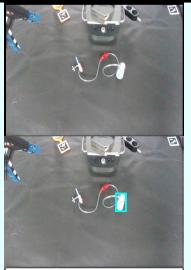
Episode : Canister Insertion Process

Duration : 21.11.2024, 11:19:05 - 21.11.2024, 11:22:02

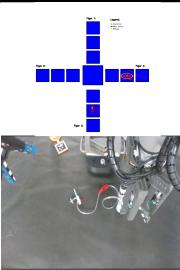
Status : Failed / --[Successful]-- / Interrupted / Pending

Confidence : 98.01%

Action Designator	Executive Module	Participants	Execution Timeslot	Status	Confidence Level	Verbal Explanation	Non-verbal Explanation	Recovery Explanation
Fitting Insertable Into Insertee	Perception ; Planning ; Manipulation	Robot@TraceBot	21.11.2024, 11:19:05 - 21.11.2024, 11:22:02	Successful	98.01%	All constitutive subactions were successful. Furthermore, All constitutive subactions were feasible		Nothing to recover

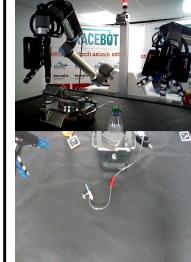
1. Parking Arms	<i>Manipulation</i>	Robot@TraceBot	21.11.2024, 11:19:05 - 21.11.2024, 11:19:10	Successful	99.61%	<i>This action is feasible</i>		<i>Nothing to recover</i>
2. Traceable Locating	<i>Perception</i>	SensorRange VMQBLCXN: HeadRobotCamera@435D; BDKHYNJX; Patient XSDVWTRC; Canister;	21.11.2024, 11:19:11 - 21.11.2024, 11:19:23	Successful	99.48%	<i>All constitutive subactions were successful. Additionally, The imagination of the detected objects at the given pose produce the same image as the bounded real image.. Furthermore, The imagination of the detected objects at the given pose produce the same image as the bounded real image.. Additionally, This action is feasible</i>		<i>Nothing to recover</i>
2.1. Locating	<i>Perception</i>	SensorRange SMIBTQJN: Patient YFLHDMNB;;	21.11.2024, 11:19:11 - 21.11.2024, 11:19:20	Successful	99.72%	<i>The imagination of the detected objects at the given pose produce the same image as the bounded real image.. Furthermore, The imagination of the detected objects at the given pose produce the same image as the bounded real image.. Furthermore, This action is feasible</i>		<i>Nothing to recover</i>
2.2. Verifying Pose	<i>could not be inferred</i>	Patient XLEKSZQR:;	21.11.2024, 11:19:22 - 21.11.2024, 11:19:22	Successful	99.43%	<i>This action is feasible</i>		<i>Nothing to recover</i>

3. Traceable Picking Up	<i>Planning ; Manipulation</i>	ActorRole QEGXJYRB: RightRobotGripper@CEA TEFHZXUW; Patient WXJUGNOI; Canister QUNRCLSD;	21.11.2024, 11:19:25 - 21.11.2024, 11:20:33	Successful	99.24%	All constitutive subactions were successful. Additionally, This action is feasible		Nothing to recover
3.1. Traceable Picking Up	<i>Planning ; Manipulation</i>	ActorRole BKXXGDJYL: RightRobotGripper@CEA TEFHZXUW; Patient XSOJTGHI; Canister QUNRCLSD;	21.11.2024, 11:19:25 - 21.11.2024, 11:20:25	Successful	99.16%	All constitutive subactions were successful. Also,, This action is feasible		Nothing to recover
3.1.1. Setting Gripper	<i>Manipulation</i>	ActorRole CIEMUJKS: RightRobotGripper@CEA TEFHZXUW;	21.11.2024, 11:19:25 - 21.11.2024, 11:19:28	Successful	99.91%	This action is feasible		Nothing to recover
3.1.2. Reaching	<i>Planning ; Manipulation</i>	ActorRole TKJBWZNO: RightRobotGripper@CEA TEFHZXUW; Patient XJNZBKTQ; Canister QUNRCLSD;	21.11.2024, 11:19:29 - 21.11.2024, 11:20:03	Successful	98.81%	All constitutive subactions were successful. Also,, This action is feasible		Nothing to recover

3.1.2.1. Planning Motion	<i>Planning</i>	Robot@TraceBot	21.11.2024, 11:19:29 - 21.11.2024, 11:19:29	Successful	99.48%	<i>This action is feasible</i>		<i>Nothing to recover</i>
3.1.2.2. Reaching	<i>Manipulation</i>	ActorRole CVLYJEFZ: RightRobotGripper@CEA TEFHZXUW;	21.11.2024, 11:19:50 - 21.11.2024, 11:19:58	Successful	99.31%	<i>This action is feasible</i>		<i>Nothing to recover</i>
3.1.2.3. Reaching	<i>Manipulation</i>	ActorRole UMDIGHLY: RightRobotGripper@CEA TEFHZXUW;	21.11.2024, 11:19:59 - 21.11.2024, 11:20:02	Successful	99.52%	<i>This action is feasible</i>		<i>Nothing to recover</i>
3.1.3. Grasping	<i>Manipulation</i>	ActorRole IKJDYCTW: RightRobotGripper@CEA TEFHZXUW; Patient KYTROUSP; Canister QUNRCLSD;	21.11.2024, 11:20:05 - 21.11.2024, 11:20:13	Successful	100.0%	<i>The right gripper is in contact with an object with confidence 1.0000. In fact, initially, no target patient object could be found for this action</i>		<i>Set the target patient object (to be grasped) before proceeding. Only in this manner can the feasibility verification proceed</i>

3.2. Lifting	<i>Manipulation</i>	ActorRole LXIZVDOE: RightRobotGripper@CEA TEFHZXUW; Patient MEJHFXK: Canister QUNRQLSD;	21.11.2024, 11:20:27 - 21.11.2024, 11:20:32	Successful	99.24%	<i>All constitutive subactions were successful. Also, This action is feasible</i>		<i>Nothing to recover</i>
3.2.1. Reaching	<i>Manipulation</i>	ActorRole MIYQXOWK: RightRobotGripper@CEA TEFHZXUW;	21.11.2024, 11:20:28 - 21.11.2024, 11:20:31	Successful	99.69%	<i>This action is feasible</i>		<i>Nothing to recover</i>
4. Traceable Inserting	<i>Planning ; Manipulation</i>	Robot@TraceBot	21.11.2024, 11:20:36 - 21.11.2024, 11:21:58	Successful	99.2%	<i>All constitutive subactions were successful. Additionally, This action is feasible</i>		<i>Nothing to recover</i>
4.1. Traceable Inserting	<i>Planning ; Manipulation</i>	Robot@TraceBot	21.11.2024, 11:20:36 - 21.11.2024, 11:21:55	Successful	98.46%	<i>All constitutive subactions were successful. Furthermore, This action is feasible</i>		<i>Nothing to recover</i>

4.1.1. Planning Insertion	<i>Planning</i>	Robot@TraceBot	21.11.2024, 11:20:36 - 21.11.2024, 11:20:37	Successful	99.12%	<i>This action is feasible</i>		<i>Nothing to recover</i>
4.1.2. Delivering	<i>Manipulation</i>	ActorRole DQWEGJFO: RightRobotGripper@CEA TEFHZXUW; Patient RBQTFODN; Canister QUNRCLSD;	21.11.2024, 11:20:57 - 21.11.2024, 11:21:04	Successful	99.16%	<i>This action is feasible</i>		<i>Nothing to recover</i>
4.1.3. Pushing	<i>Manipulation</i>	ActorRole KEQSDFHG: RightRobotGripper@CEA TEFHZXUW; Patient XZEOFNSV; Canister QUNRCLSD; Destination VMPHSXW; DrainTray UZTCVIYQ;	21.11.2024, 11:21:07 - 21.11.2024, 11:21:15	Successful	99.53%	<i>This action is feasible</i>		<i>Nothing to recover</i>
4.1.4. Pushing	<i>Manipulation</i>	ActorRole JWLRVMDS: RightRobotGripper@CEA TEFHZXUW; Patient CSGRIFTJ; Canister QUNRCLSD; Destination NDJSOQLB; DrainTray UZTCVIYQ;	21.11.2024, 11:21:22 - 21.11.2024, 11:21:28	Successful	99.62%	<i>This action is feasible</i>		<i>Nothing to recover</i>

4.1.5. Releasing	<i>Manipulation</i>	ActorRole LPMDERNO: RightRobotGripper@CEA TEFHZXUW; Patient XILCOYPG; Canister QUNRCLSD;	21.11.2024, 11:21:36 - 21.11.2024, 11:21:50	Successful	99.67%	<i>This action is feasible</i>		<i>Nothing to recover</i>
4.1.6. Retracting	<i>Manipulation</i>	ActorRole MBNPSELV: RightRobotGripper@CEA TEFHZXUW; SourceMaterialRole ZPDQYKFB; Canister QUNRCLSD;	21.11.2024, 11:21:52 - 21.11.2024, 11:21:54	Successful	99.39%	<i>This action is feasible</i>		<i>Nothing to recover</i>