




## (End-User) Auto-Generated Audit Trail



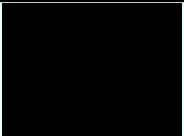



**Episode** : Canister Insertion Process





**Duration** : 24.11.2023, 11:29:43 - 24.11.2023, 11:30:04

**Status** : **--[Failed]-- / Successful / Interrupted / Pending**

**Confidence** : **93.0%**

Action Designator	Executive Module	Participants	Execution Timeslot	Status	Confidence Level	Verbal Explanation	Non-verbal Explanation
Fitting Insertable Into Insertee	Manipulation ; Planning ; Perception	<a href="http://knowrob.org/kb/PR2.owl#PR2_0">http://knowrob.org/kb/PR2.owl#PR2_0</a>	24.11.2023, 11:29:43 - 24.11.2023, 11:30:04	Failed	93.0%	At least one constitutive sub-action has failed or got interrupted.	
1. Parking Arms	Manipulation	<a href="http://knowrob.org/kb/PR2.owl#PR2_0">http://knowrob.org/kb/PR2.owl#PR2_0</a>	24.11.2023, 11:29:43 - 24.11.2023, 11:29:44	Successful	98.86%	Yet to be resolved	

2. Traceable Locating	Perception	SensorRange ZYDOIIRBK; HeadRobotCamera@435D EWPSDRJF; Patient UZCVSYPG; Canister;	24.11.2023, 11:29:44 - 24.11.2023, 11:29:52	Successful	98.56%	All constitutive sub-actions were successful. . The imagination of the detected objects at the given pose produce the same image as the bounded real image.. The imagination of the detected objects at the given pose produce the same image as the bounded real image.	
2.1. Locating	Perception	SensorRange GXBRPWFN: ; Patient WICGMYYOK: ;	24.11.2023, 11:29:44 - 24.11.2023, 11:29:52	Successful	98.8%	. The imagination of the detected objects at the given pose produce the same image as the bounded real image.. The imagination of the detected objects at the given pose produce the same image as the bounded real image.	
2.2. Verifying Pose	could not be inferred	Patient LYQOEZSP: ;	24.11.2023, 11:29:52 - 24.11.2023, 11:29:52	Successful	99.75%	Yet to be resolved	
3. Traceable Picking Up	Manipulation ; Planning	ActorRole XQSERMZG: RightRobotGripper@Robotiq YVWGLXED; Patient YIDBTFLP: Canister OTKDNGEQ;	24.11.2023, 11:29:52 - 24.11.2023, 11:30:04	Failed	95.45%	At least one constitutive sub-action has failed or got interrupted.	
3.1. Traceable Picking Up	Manipulation ; Planning	ActorRole IKDWPJNB: RightRobotGripper@Robotiq YVWGLXED; Patient WXVOMQUS: Canister OTKDNGEQ;	24.11.2023, 11:29:52 - 24.11.2023, 11:30:04	Failed	95.45%	At least one constitutive sub-action has failed or got interrupted.	
3.1.1. Setting Gripper	Manipulation	ActorRole NIDWVYJR: RightRobotGripper@Robotiq YVWGLXED;	24.11.2023, 11:29:52 - 24.11.2023, 11:29:54	Successful	98.64%	Yet to be resolved	

3.1.2. Reaching	Manipulation ; Planning	ActorRole GUIWZEKB: RightRobotGripper@Robotiq YVWGLXED; Patient JLQTXUVE: Canister OTKDNGEQ;	24.11.2023, 11:29:54 - 24.11.2023, 11:30:01	Successful	96.76%	All constitutive sub-actions were successful.	
3.1.2.1. Planning Motion	Planning	http: knowrob.org kb PR2.owl#PR2_0	24.11.2023, 11:29:54 - 24.11.2023, 11:29:55	Successful	99.9%	Yet to be resolved	
3.1.2.2. Reaching	Manipulation	ActorRole DMXRILNU: RightRobotGripper@Robotiq YVWGLXED;	24.11.2023, 11:29:55 - 24.11.2023, 11:30:00	Successful	98.53%	Yet to be resolved	
3.1.2.3. Reaching	Manipulation	ActorRole CNBFILQ: RightRobotGripper@Robotiq YVWGLXED;	24.11.2023, 11:30:00 - 24.11.2023, 11:30:01	Successful	98.3%	Yet to be resolved	
3.1.3. Grasping	Manipulation	ActorRole OQSYHVJI: RightRobotGripper@Robotiq YVWGLXED; Patient UYLNFGQO: Canister OTKDNGEQ;	24.11.2023, 11:30:01 - 24.11.2023, 11:30:04	Failed	100.0%	. Gripper opening outside expected region for grasping a canister: 0.8726646259971648 not in (0.4,0.5)	