# **FOSTER MCLANE**

# **INFORMATION SECURITY ANALYST**

## ABOUT

I am a computer enthusiast and enjoy almost everything to do with computers, from low-level logic circuits to high-level programming. I am especially interested in embedded programming, operation systems, program security, network security, and network protocols. In addition to my computer enthusiasm, I have a large interest in high school level education in computational thinking.

# III WORK EXPERIENCE

# **Clemson University**

https://ccit.clemson.edu/about/departments/security-operations-center/

December 2017 - Present

# **Information Security Analyst**

Under the Office of Information Security and Privacy, I am a full-time analyst of Clemson's computer network for identifying potential cyber security threats, mitigating current threats, and preventing current threats from happening in the future.

#### FoosterNET, LLC

Attps://fooster.io/

November 2013 - Present

#### Owner

FoosterNET, LLC is a company I use for freelance work in cyber security consulting, system administration, and computer programming. It additionally sanctions all other services I provide for money including server hosting.

# **Clemson University**

• https://ccit.clemson.edu/about/departments/security-operations-center/ January 2017 – December 2017

# **Cybersecurity Intern**

Under the Office of Information Security and Privacy, I was a part-time analyst of Clemson's computer network for identifying potential cyber security threats, mitigating current threats, and preventing current threats from happening in the future.

#### **Clemson University**

January 2017 – May 2017

# **Virtual Reality Intern**

Under Dr. Stephen Moysey, I worked to bring virtual reality to the university in a variety of ways including setting up VR systems, coordinating generally available VR equipment for students and faculty, and creating demos for VR.

#### **Clemson University**

January 2016 - December 2016

# Virtual Reality Game Development Intern

Under Dr. Stephen Moysey, I researched teaching applications of geological sciences field techniques in a virtual reality video game. The game, titled Virtual Reality Field Experiences, features a trip to the Grand Canyon where the gamer learns rock identification techniques and builds the stratigraphic column of the canyon.

# **Clemson University**

# © CONTACT

•

423 Lindsay Rd. Apt. 404 Clemson, SC 29631 US

ſ.

(919) FOOSTER

 $\subseteq$ 

fkmclane@gmail.com

Ø

https://fooster.io/

0

**GitHub** fkmclane

# **m** EDUCATION

#### 2014 2019

# **Clemson University**

Bachelor of Science

Computer Science, with an interest in Education, Math, and Langauge

#### Courses

- Algorithms
- ◀ Software Engineering
- Operating Systems
- ◀ Network Programming
- ◀ Principles of Programming Languages
- ◀ Computer Security Principles
- Special Topics in Embedded Computing
- ◀ Foundations of Computer Science
- Distributed and Cluster Computing
- 2D Game Engine Construction
- ◀ Virtual Reality Systems

## 2012 2014

# SC Governor's School for Science and Mathematics

High School

Computer Science

#### Courses

- ◀ Advanced Computer Science
- ◆ Digital Logic
- ◀ Modern Physics



Master

#### http://people.clemson.edu/~yue6/

January 2015 - May 2016

# **Undergraduate Student Researcher in UAV and Manufacuring Robotics**

Under Dr. Yue Wang, I researched quadrotor control algorithms and trust aware manufacturing in the Interdisciplinary Intelligence Research Lab, or I<sup>2</sup>R Lab.

#### **AWARDS**

#### January 2019

#### **Global Information Assurance Certification**

₱ GIAC Certified Intrusion Analyst

The certification signifies a demonstrated knowledge of intrusion detection techniques as an information security analyst.

#### April 2014

# **SC Junior Academy of Science**

**♥** Outstanding Research and Presentation

Awards: 1st Oral Presentation - Computer Science, 1st Written Presentation - Computer Science. The awards included an invitation to the American Junior Academy of Science.

# **VOLUNTEER**

# **GIAC Advisory Board**

• https://www.giac.org/certified-professionals/advisory-board January 2019 – Present

# Member

After completing my GCIA certification from GIAC, I've been invited to the GIAC Advisory Board which takes an active role in the GIAC program and in SANS training.

# FRC - Metal in Motion 343

https://metalinmotion.com/

December 2018 - Present

## Mentor

After having several years volunteering with FIRST as a mentor and Field Technical Advisor (FTA), I mentor the nearby Oconee team, Metal in Motion.

# FTC - Star Bots 6170

 $\begin{tabular}{ll} \hline \textbf{Q} & \textbf{http://ehs.pickens.k12.sc.us/fine\_arts\_organizations/student\_life/robotics\_club} \\ \textbf{September 2016 - Present} \\ \hline \end{tabular}$ 

#### Mentor

After having three years of experience of participating in the FIRST Tech Challenge robotics competition, or FTC, including one year of which I was team captain and made it to the super regional competition, I mentor the nearby Easley team, Starbots.

# **SC Robotics Education Foundation**

http://scref.org/

January 2015 - Present

# Field Technical Advisor and Field Inspector

After three years of experience of participating in the FIRST Tech Challenge robotics competition, I volunteer to run the scrimmage hosted by the SC GSSM and am the main technical coordinator for the state competition.

## **Programming**

C C++ C# Python JavaScript

Java PHP

**Unix Administration** 

Website Deployment Virtual Machines

Networking General Services

RedHat Enterprise Linux Ubuntu Arch Linux

Gentoo Linux Debian FreeBSD

**Network Security** 

Cisco Palo Alto pfSense Endian

UniFi

Virtualization

libvirt oVirt Stateless Hypervisors PXE

Software Development

REST Robot Operating System GTK+

**Game Development** 

Unity 3D Pyglet

Web Development

HTML5 CSS3 JavaScript Semantic UI

PHP Python Django

**Computer Graphics** 

Blender GIMP Inkscape

**Text Editing** 

Neovim Vim Vi

Documentation

LaTeX Markdown VimWiki

## **Gentoo Overlay - fkmclane**

https://github.com/fkmclane/overlay

May 2013 - Present

#### Owner

I have a recognized overlay for my distribution of choice for my workstation, Gentoo. I maintain over 150 packages in this overlay that range from little X11 tools to the Unity Editor, from the game engine, for Linux to all of the Linux software associated with Plex. Additionally I have a few of my own tools that I wrote such as one to manage tty sessions intelligently without having a display manager.

## **CU Cyber**

https://cucyber.net/ August 2015 – April 2018

# **Level 5 Tech Support**

CU Cyber is the cyber security club at Clemson University. We participate in cyber defense competitions and hold weekly seminars involving cyber security. I was the secretary and then Level 5 Tech Support of CU Cyber where I maintained club organization, club preparation, and various technological aspects. I additionally helped create many of the weekly seminars given.

## **CU Rocket Engineering**

January 2017 – August 2018

#### **Lead Avionics**

As lead avionics, I coordinated the team that created the electronic internals of the rockets we flew at the Intercollegiate Rocket Engineering Competition. I did a lot of the design work and kept the team productive.

# **Clemson ACM**

https://www.cs.clemson.edu/acm/ September 2014 – January 2017

## Webmaster

ACM, the Association for Computing Machinery, is the world's largest society for scientific and educational computing. I was the webmaster of Clemson University's local chapter where I created and maintained their website.

## PUBLICATIONS

# Trust-Based Mixed-Initiative Teleoperation of Mobile Robots

■ American Control Conference 06 July 2016

• http://ieeexplore.ieee.org/abstract/document /7526640/

Trust-Based Mixed-Initiative Teleoperation of Mobile Robots is a scheme for the bilateral teleoperation of mobile robotic systems using a quadrotor, ground robot, and a haptic feedback device. In the scheme, control is shared between human and autonomous controllers with the human controller having force feedback cues. Two-way trust models are calculated to dynamically scale each control input for optimal performance and reduced physical workload of the human operator. The results indicate that the proposed scheme improves task performance by 31% and reduces the operator workload by 23.9%.

# Vision-Based Control of a Quadrotor

■ SC GSSM

01 February 2014

Vision-Based Control of a Quadrotor uses a quadrotor and its two mounted cameras to have the quadrotor perform basic analysis of its environment and make decisions based on it. It includes basic applications for following a marked path or object and an extensible interface for writing more complex autonomous logic.